

Heaps - III

Priority queue

↳ is a data structure for maintaining a set S of elements, each with an associated value called the key (or priority)

→ A max-priority queue uses a max-heap

Operations: Insert(S, x, k) :

insert element x with key k

$$\Rightarrow S = S \cup \{x\}$$

Maximum(S) : returns the element with largest key

Extract-Max(S) : removes & returns element with largest key

Increase-Key(S, x, k):

increases value of x 's key to new value k
(assumed that $k \geq x.key$)

— Applications of max-priority queue:

↳ Schedule job on a computer, keeping priorities of jobs
a) once a job is finished, the scheduler selects the highest priority job by calling Extract-Max

b) New jobs are added with Insert()

Max-Heap-Maximum (A)

if $A.\text{heap-size} < 1$
error "heap underflow"
return $A[1]$

$\rightarrow \Theta(1)$

Max-Heap-Extract-Max (A)

max = Max-Heap-Maximum (A)

$A[1] = A[A.\text{heap size}]$

$A.\text{heapsize} = A.\text{heapsize} - 1$

$\rightarrow O(\lg n)$

Max-Heapify ($A, 1$)

return max

→ When we implement a priority queue, we treat each array element as the keys to be sorted and assume that the satellite data moves with corresponding keys.

Max-Heap-Increase-Key (A, x, k)

if $k < x.key$

error "New key is smaller than the existing"

$x.key = k$

Find the index i in array A where object x occurs

while $i > 1$ and $A[\text{parent}(i)].key < A[i].key$

exchange $A[i]$ with $A[\text{parent}(i)]$,
(update info that maps priority queue
objects to array indices)

$i = \text{parent}(i)$

$\Theta(\lg n)$

+ overhead of mapping priority queue object to indices

Max-Heap-Insert (A, x, n)

if $A.\text{heap-size} == n$

error "heap overflow"

$A.\text{heap-size} = A.\text{heap-size} + 1$

$k = x.key$

$x.key = -\infty$

$A[A.\text{heap-size}] = x$

map x to index heap-size in the array

Max-Heap-Increase-Key (A, x, k)

$\Theta(\lg n) + \text{overhead of mapping objects to indices.}$