## Task-C: Regression outlier effect.

Objective: Visualization best fit linear regression line for different scenarios

```
# you should not import any other packages
import matplotlib.pyplot as plt
import warnings
warnings.filterwarnings("ignore")
import numpy as np
from sklearn.linear model import SGDRegressor
import numpy as np
import scipy as sp
import scipy.optimize
def angles in ellipse(num,a,b):
    assert(num > 0)
    assert(a < b)</pre>
    angles = 2 * np.pi * np.arange(num) / num
    if a != b:
        e = (1.0 - a ** 2.0 / b ** 2.0) ** 0.5
        tot size = sp.special.ellipeinc(2.0 * np.pi, e)
        arc size = tot size / num
        arcs = np.arange(num) * arc size
        res = sp.optimize.root(
            lambda x: (sp.special.ellipeinc(x, e) - arcs), angles)
        angles = res.x
    return angles
a = 2
b = 9
n = 50
phi = angles_in_ellipse(n, a, b)
e = (1.0 - a^{**}2.0 / b^{**}2.0) ** 0.5
arcs = sp.special.ellipeinc(phi, e)
fig = plt.figure()
ax = fig.gca()
ax.axes.set aspect('equal')
ax.scatter(b * np.sin(phi), a * np.cos(phi))
plt.show()
```

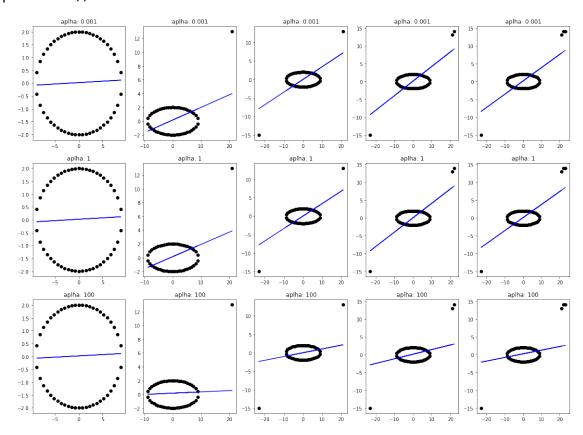
```
2
   0
  -2
          -7.5
                       -2.5
                               0.0
                                            5.0
                                     2.5
                                                   7.5
X = b * np.sin(phi)
Y= a * np.cos(phi)
print(X.shape)
print(Y.shape)
print(type(X))
(50,)
(50,)
<class 'numpy.ndarray'>
#Reference for this code:
https://stackoverflow.com/questions/59367939/how-to-correct-the-
position-of-hyper-plane-in-python
#Define Parameters: alpha and outlier points
alphas = [0.001, 1, 100]
outlier points = [(0,2),(21,13),(-23,-15),(22,14),(23,14)]
plt.figure(figsize = (20,20))
for j,alpha in enumerate(alphas):
    # Re-define X and Y to remove the added outliers in the bellow
step
    X= b * np.sin(phi)
    Y= a * np.cos(phi)
    \#print(range(5*j+1, 5*(j+1)+1))
    #Here range is to provide 3*5 grid subplots. we take (1,5); (6,10),
(11,15) ranges for this
    for c,k in enumerate(range(5*j+1, 5*(j+1)+1)):
        #Adding Outlier for each iteration
        X= np.append(X,outlier_points[c][0])
        Y= np.append(Y,outlier_points[c][1])
        #training the model after updating the outliers
        clf = SGDRegressor(alpha = alpha, eta0=0.001,
learning rate='constant',random state=10)
        clf.fit(X.reshape(-1,1), Y)
```

```
#Get the predicted values of Y to plot prediction hyper-plane
Y_pred =clf.predict(X.reshape(-1,1))
```

```
#print(type(Y_pred))
#print(X.reshape(-1,1).shape)
#print(Y_pred.shape)
#print("Y Actual: ",Y)
#print("Y Pred: ", Y_pred)

plt.subplot(4,5,k)
plt.scatter(X,Y,color = 'black')
plt.plot(X,Y_pred, color = 'blue')
plt.title("aplha: "+str(alpha))
```

## plt.show()



## **Observation:**

- Here alpha is a constant that multiplies the regularization term. The higher the value, the stronger the regularization.
- Therefore, High the value of alpha, more is the regularization hence less is the effect of outliers on the predictions.

- When alpha = 0.001: With one outlier point we found that the angular deviation of prediction hyper-plane is more. Therefore, the model less regularized when alpha = 0.001.
- When alpha = 1: With one outlier point we found that the angular deviation of prediction hyper-plane is more. Therefore, the model less regularized even when alpha is 1
- When alpha = 100: With one outlier point we found that the angular deviation of prediction hyper-plane is more same as the one without outliers. Therefore, the model is more regularized when alpha is 100
- When alpha = 100: With 2/3/4 outlier points we found that the angular deviation of prediction hyper-plane is slightly different as the one without outliers. But, compared to alpha =0.001 and 1, deviation is very less. Therefore, the model is more regularized when alpha is 100.