19Z601- MACHINE LEARNING

UNIT-1 INTRODUCTION

INTRODUCTION: Types of Learning - Designing a learning system - concept learning - Find-s Algorithm - Candidate Elimination - Data Preprocessing - Cleaning - Data Scales - Transformation - Dimensionality Reduction. (9)

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TYPES OF LEARNING

- Learning = Improving with experience at some task
 - Improve over Task T
 - With respect to performance measure P
 - Based on Experience E
- Examples of Learning Problems:

Checkers Learning Problem	Task T: Playing Checkers Performance Measure P: Percent of games won against opponents Training Experience E: Playing practice games against itself
Handwriting Recognition Learning Problem	Task T: Recognizing and classifying handwritten words within images Performance Measure P: Percent of words classified correctly Training Experience E: A database of handwritten words with given classification.

DESIGNING A LEARNING SYSTEM

- 1. Choosing a Training Experience
- 2. Choosing the Target Function
- 3. Choosing the Representation of the Target Function
- 4. Choosing a Function Approximation Algorithm
 - 4.1 Estimating Training Values
 - 4.2 Adjusting weights
- 5. The Final Design

CONCEPT LEARNING

 Concept Learning is the learning process carried out by inferring a Boolean valued function from training examples of its input and output.

FIND S ALGORITHM

- 1. Initialize h to the most specific hypothesis in H
- 2. For each positive training instance x
 - For each attribute constraint a_i in hIf the constraint a_i in h is satisfied by xThen do nothing

 Else replace a_i in h by the next more general constraint that is satisfied by x
- 3. Output hypothesis h

CANDIDATE ELIMINATION ALGORITHM

- Input: Set of instances in the training dataset
- Output: Hypothesis G and S
- Step 1: Initialize G, to the maximally general hypotheses.
- Step 2: Initialize S, to the maximally specific hypotheses.
 - Generalize the initial hypothesis for the first positive instance
- Step 3: For each subsequent new training instance
- If the instance is positive
 - Generalize S to include the positive instance
 - > Check the attribute value of the positive instance and S
 - If the attribute value of positive instance and S are difference, fill that field value with '?'
 - If the attribute value of positive instance and S are same, then do no change
- If the instance is negative
 - Specialize G to exclude the negative instance,
 - Add to G all minimal specialization to exclude the negative example and be consistent with S
 - If the attribute value of S and the negative instance are different, then fill that attribute value with S value
 - If the attribute value of S and negative instance are same, no need to update 'G' and fill that attribute value with '?
 - Remove from S all inconsistent hypotheses with the negative instance.

CANDIDATE ELIMINATION METHOD - PROBLEM

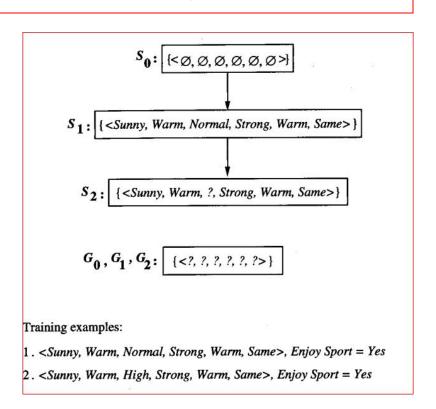
PROBLEM (QUESTION):

Example	Sky	AirTemp	Humidity	Wind	Water	Forecast	EnjoySport
1	Sunny	Warm	Normal	Strong	Warm	Same	Yes
2	Sunny	Warm	High	Strong	Warm	Same	Yes
3	Rainy	Cold	High	Strong	Warm	Change	No
4	Sunny	Warm	High	Strong	Cool	Change	Yes

STEP 1 (CANDIDATE ELIMINATION TRACE 1):

Define the initial boundary sets S_o and G_o corresponding to the most specific and most general hypotheses.

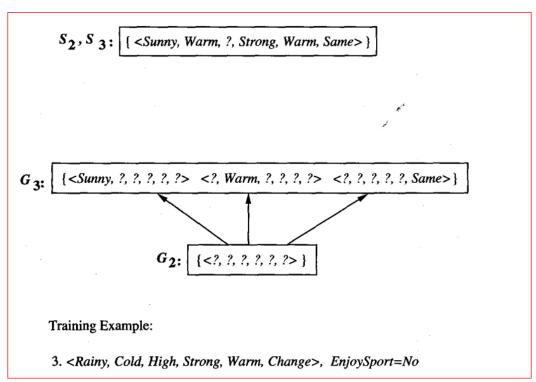
Training examples 1 and 2 are positive and force the S boundary to be more general and has no effect on G boundary.



CANDIDATE ELIMINATION METHOD – PROBLEM (CONTD..)

STEP 2 (CANDIDATE ELIMINATION TRACE 2):

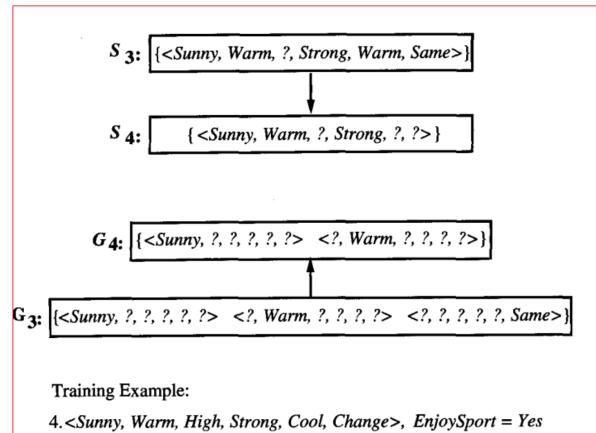
- Training example 3 is a negative example that forces G₂ boundary to be more specialized.
- Maximally general hypothesis are included in G₃.



CANDIDATE ELIMINATION METHOD – PROBLEM (CONTD..)

STEP 3 (CANDIDATE ELIMINATION TRACE 3):

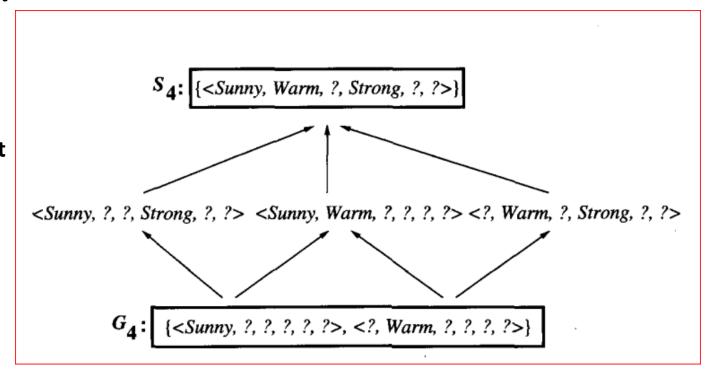
- Training example 4 is a positive example, positive training example generalize the S boundary from S_3 to S_4
- One member of G₃ must also be deleted, because it is no longer more general than the S₄ boundary.



CANDIDATE ELIMINATION METHOD – PROBLEM (CONTD..)

FINAL STEP (FINAL VERSION SPACE)

The final version space for the EnjoySport concept learning problem.



DATA PREPROCESSING

- Data cleaning :
 - Handling Missing data Data imputation
 - Handling Noisy data Data filtration
- Data Transformation :
 - One Hot Encoding
 - Binning
 - Normalization
 - Standardization
- Data Reduction
 - Feature Selection
 - Feature Extraction

CLEANING

- Handling Missing Values Data Imputation
 - Replacing the missing values with mean or median.
 - Replacing the missing values with constants.
 - Replacing the missing values with information from other columns.
- Handling Noisy Data Denoising or filtering (Removes outliers)
 - Smoothing
 - Binning

DATA SCALES

- Nominal Scale: Named Variables
- Ordinal Scale: Named + Ordered Variables
- Interval Scale: Named + Ordered + Proportionate Intervals between variables
- Ratio Scale: Named + Ordered + Proportionate Interval between Intervals + accommodate absolute zero

TRANSFORMATION

• The problem of transforming raw data into dataset is called feature engineering.

One Hot Encoding	Transformation of categorical feature into several binary codes is called One Hot Encoding. Example: Categorical Feature "Colors" with three possible values: Red, Yellow and Green, Transform this feature into a vector of three numerical values. Red = [1,0,0] Yellow = [0,1,0] Green = [0,0,1]
Binning	Transformation of numerical feature into categorical one. Binning is also called bucketing is the process of converting a continuous feature into multiple binary features called bines or buckets.
Normalization	Process of converting an actual range of values which a numerical feature can take into a standard range of values, typically in the interval [-1,1] or [0,1]
Standardization	Z-score Normalization is the procedure during which the feature values are rescaled so that they have the properties of a standard normal distribution with mean = 0 and standard deviation =1.

DIMENSIONALITY REDUCTION

• There are two methods for dimensionality reduction :

METHODS	DESCRIPTION
Feature Selection	Finding K of the d dimension which gives more information and discard (d-k) dimension. Example: Subset Feature Selection
Feature Extraction	Finding new set of k dimensions which is a combination of original d dimensions. Examples:
	Linear Projection Methods:
	 Principal Component Analysis (PCA) – Unsupervised Learning
	 Linear Discriminant Analysis – Supervised Learning