Unit-6 Global Data flow Analysis

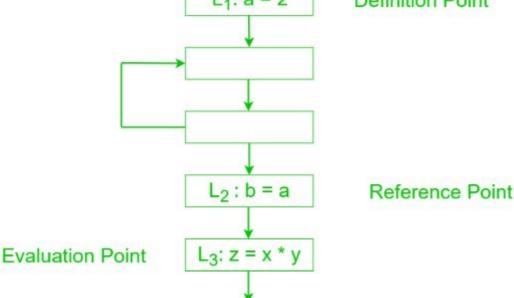
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Introduction to Data Flow Analysis

- In order to do code optimization and a good job of code generation , compiler needs to collect information about the program as a whole and to distribute this information to each block in the flow graph.
- Data flow information that can be optimizing compiler collects by a process Data Flow Analysis.
- The generation and killing of process depends on the desired information on the Data Flow Analysis to be solved.
- Data Flow Analysis is affected by the control construct in a problem.

- Within each basic block, a point is assigned between two adjacent statements, before the first statement, and after the last statement
- A path from p1 to pn is a sequence of points p1, p2, ..., pn such that for each i, 1 <= i <= n-1, either pi is the point immediately preceding a statement and pi+1 is the point immediately following that statement in the same block, or pi is the end of some block and pi+1 is the beginning of a successor block
- **Definition Point:** a point in a program containing some definition.
- Reference Point: a point in a program containing a reference to a data item.

• Evaluation Point: a point in a program containing evaluation of expression. $L_1: a = 2$ Definition Point

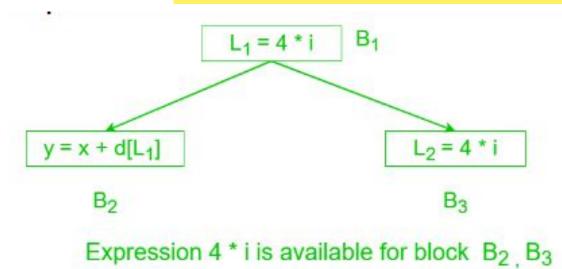


 Available Expression – A expression is said to be available at a program point x iff along paths its reaching to x. A Expression is available at its evaluation point.

A expression a+b is said to be available if none of the operands gets modified before their use.

Advantage –

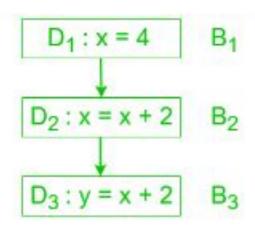
It is used to eliminate common sub expressions.



Reaching Definition – A definition D is reaches
 a point x if there is path from D to x in which D
 is not killed, i.e., not redefined.

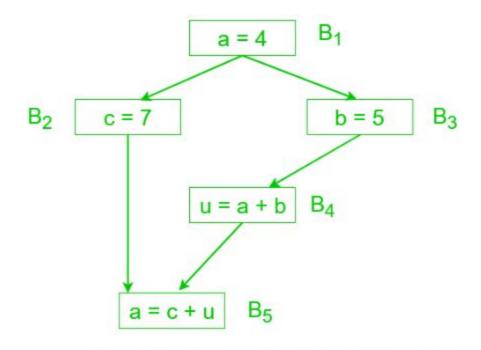
Advantage –

It is used in constant and variable propagation.



D₁ is reaching definition for B₂ but not for B₃ since it is killed by D₂

- Live variable A variable is said to be live at some point p if from p to end the variable is used before it is redefined else it becomes dead.
- Advantage –
- It is useful for register allocation.
- It is used in dead code elimination.



a is live at block B₁, B₃ B₄ but killed at B₅

 Busy Expression – An expression is busy along a path iff its evaluation exists along that path and none of its operand definition exists before its evaluation along the path.

Advantage –

It is used for performing code movement optimization.

Information for Reaching Definitions

- gen[S]: definitions generated within S and reaching the end of S
- kill[S]: definitions killed within S
- in[S]: definitions reaching the beginning of S
- out[S]: definitions reaching the end of S

Data Flow Equation

 Data flow information can be collected by setting up and solving systems of equations that relate information at various points

out[S] = gen[S] U (in[S] - kill[S])

 Let S be a statement, the information at the end of a statement (out[S]) is either generated within the statement (gen[S]) or enters at the beginning (in[S]) and is not killed as control flows through the statement

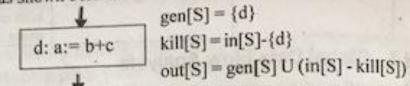
The Iterative Algorithm

- Repeatedly compute in and out sets for each node in the control flow graph simultaneously until there is no change
- in[B] = Up ∈ pred(B) out[P]
- out[B] = gen[B] U (in[B] kill[B])

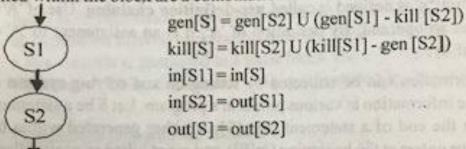
S

The data flow equations for reaching definitions for different types of statements are given below:

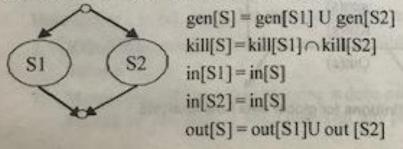
If a block has only one simple statement represented by S. Here the definition of 'a', namely 'd' is killed as shown below.



If a block has a sequence of simple statements S1 and S2. Hence out[S1] becomes in[S2]. Also in[S] is in[S1] and out[S2] is out[S]. Definitions generated and killed within the block are a combination of those for S1 and S2.



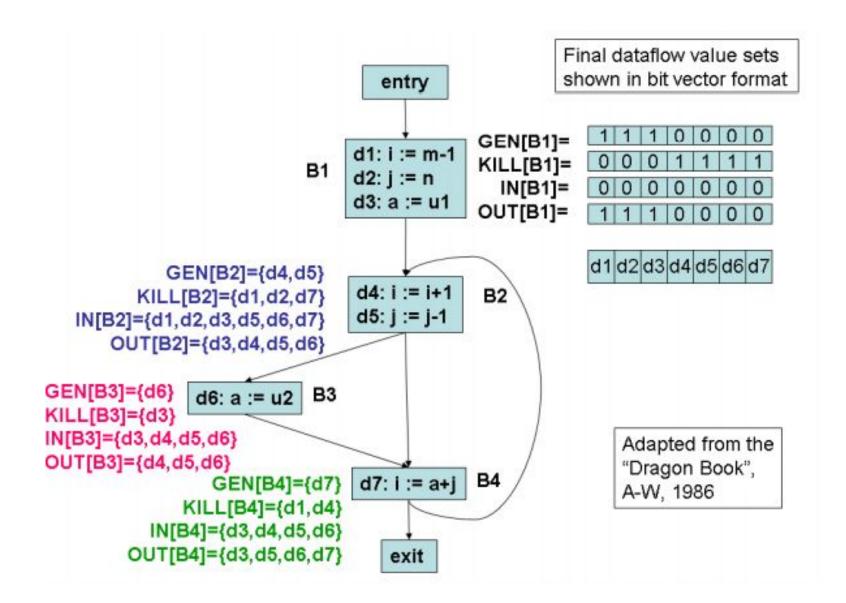
c. If a block has a decision to choose one of the paths of either S1 or S2, in[S] is in[S1] and in[S2]. Also, out[S] is union of out[S1] and out[S2]. Definitions generated within the block are a combination of those for S1 and S2. Definitions killed within the block are the intersection of those in S1 and S2.



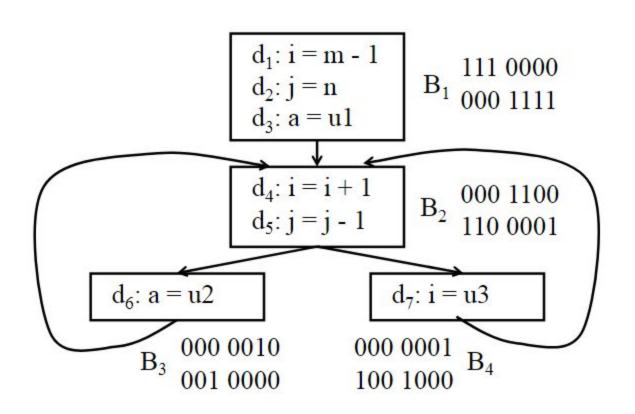
Algorithm: Reaching Definitions

```
/* Assume in[B] = \emptyset for all B */
for each block B do out[B] := gen[B]
change := true;
while change do begin
   change := false;
   for each block B do begin
      in[B] := \bigcup_{p \in pred(B)} out[p]
      oldout := out[B]
      \operatorname{out}[B] := \operatorname{gen}[B] \cup (\operatorname{in}[B] - \operatorname{kill}[B])
      if out[B] ≠ oldout then change := true
   end
end
                                                             14
```

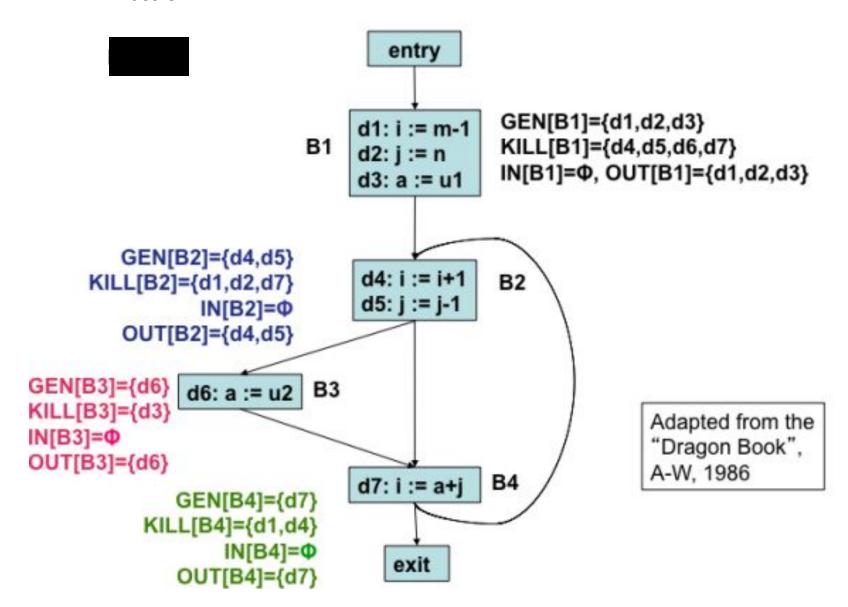
Reaching Definitions: Bit Vector Representation

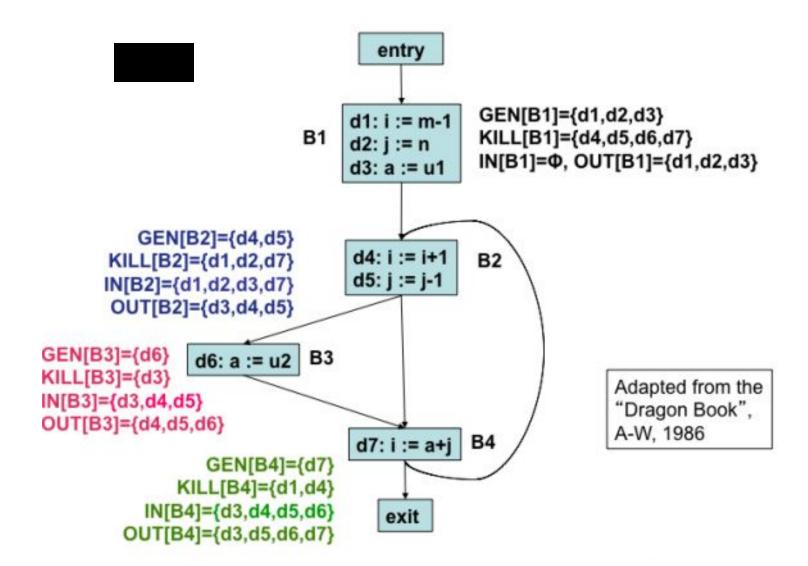


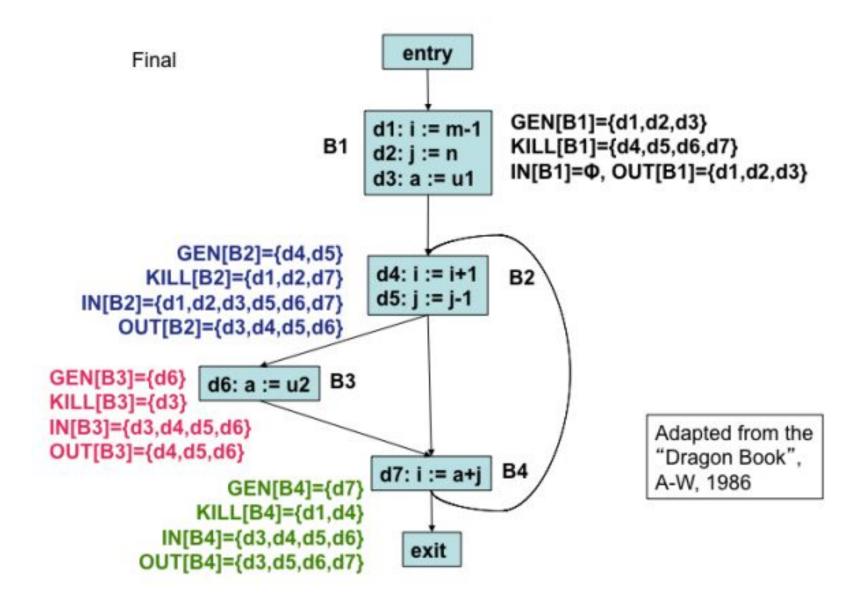
An Example



Pass 0

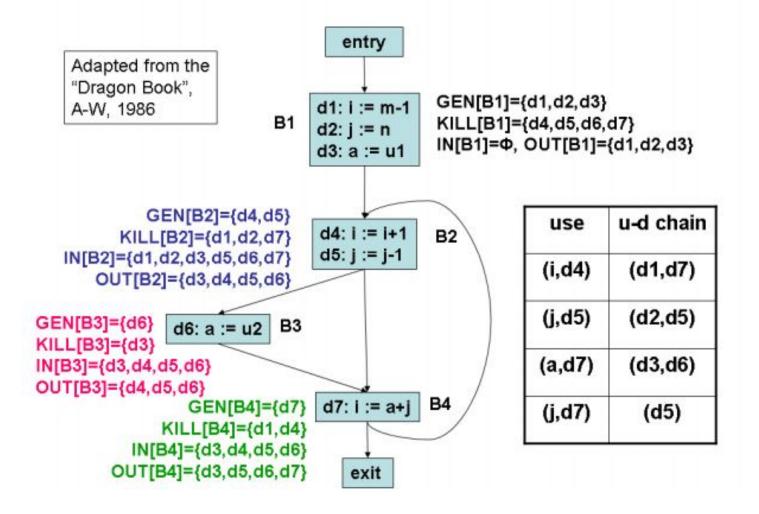






An Example

Block	Initial		Pass 1		Pass 2	
	In[B]	Out[B]	In[B]	Out[B]	In[B]	Out[B]
B_1	000 0000	111 0000	000 0000	111 0000	000 0000	111 0000
B_2	000 0000	000 1100	111 0011	001 1110	111 1111	001 1110
\mathbf{B}_3	000 0000	000 0010	001 1110	000 1110	001 1110	000 1110
B_4	000 0000	000 0001	001 1110	001 0111	001 1110	001 0111



Block B2 $In[B2]=1110011 \ (d1,d2,d3,d6,d7) \ From \ program \ flow \ graph \ \{d2,d3,d6\} \ do \ not \ define \ i.$ Hence ud-chain for I defined in B2 is only \{d1,d7\}

Thank You

- https://tutorialspoint.dev/computer-science/c ompiler-design/data-flow-analysis-compiler
- https://slideplayer.com/slide/3418022/