## **AKASH CHAUTE**

## **PROJECTS**

#### **Voice Assistant**

**O** GitHub

- This voice assistant is made in the python programming language. It takes input in the form of voice and outputs in voice and text format.
- It has various features which include reading audiobooks, surfing on Wikipedia, opening different sites, etc.

# Motion Planning IvLabs. VNIT

**O** GitHub

[Video]

[Video]

- Implemented the A-star path planning Algorithm on a custom differential drive the mobile robot in a custom Gazebo environment.
- Designed a path follower using a PID controller for the bot to follow the path generated by A-star.
- Extended the A-star Algorithm to receive a smooth path using RDP and B-splines algorithms.

# Quadcoptor Trajectory Follower IvLabs, VNIT G GitHub

 Implemented a PID-based controller to follow Trajectories, including Hovering at a particular height, Straight line, Sine Curve, and Helix curve.

## **MINI PROJECTS**

#### Tic-Tac-Toe(CPP)

**O** GitHub

Developed a Tic-Tac-Toe game. A simple game of 2 players played on a 3X3 board.

#### Path Planning

GitHub

Worked on a global path planner algorithm to find the shortest path between two points using A-star Algorithm.

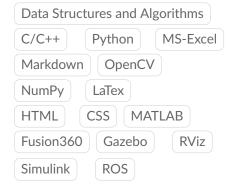
## **EDUCATION**

Visvesvaraya National Institute of Technology B.Tech in Mechanical Engineering CGPA: 8.32/10

December 2020 - May 2024(expected)

Nagpur, India

## **TECHNICAL SKILLS**



#### **RELEVANT COURSES**

#### **MOOC**

- Data Structures and Algorithms
- Python Programming
- Aerial Robotics -[Certificate]

#### **Department Courses**

- Differential Calculus (MAL101, MAL102)
- Integral Transform and Partial Differential Equations(MEL201)

## **EXTRACURRICULARS**

- Conducted and volunteered for workshops under the IEEE VNIT Student Branch.
- Member of Team Velocity, a team of enthusiasts from VNIT Nagpur working to design and fabricate a Formula Student racecar.