COMPILER DESIGN

UNIT 1

PART 3

GRAMMAR

- the formal definition of the syntax of a programming language is usually called 'Grammar'
- A Grammar consist of a set of rules to specify the sequence of characters that form allowable program in the language being defined.
- Formal Grammar: A Grammar specified using a strictly defined notations
- Equivalent Grammar: two grammar are equivalent if they produce the same language.

$$S -> bS$$

 $S -> bS$
 $S -> bS$
 $S -> bS$
 $T -> bT$
 $T -> c$

- Regular Grammar: Regular grammar are special cases of BNF grammar that turn out to be equivalent to the finite state automata.
- Regular Expression: a form of language definition that is equivalent to FSA and regular grammar.
 - a special text string for describing a search pattern.

FINITE AUTOMATA

- Regular expressions = specification
- ♦ Finite automata = implementation
- •A finite automaton consists of
 - An input alphabet Σ
 - A set of states S
 - A start state n
 - A set of accepting states $F \subseteq S$
 - A set of transitions state → input state

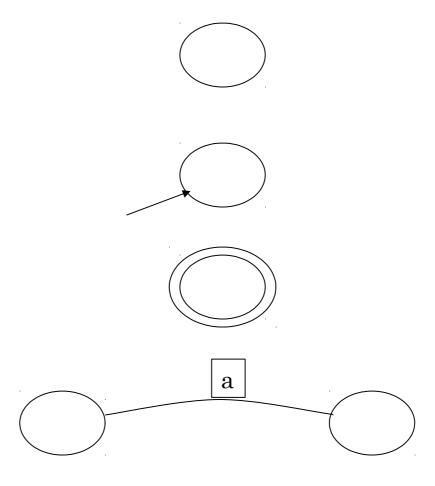
FINITE AUTOMATA STATE GRAPHS

• A state



An accepting state

A transition



A SIMPLE EXAMPLE

•A finite automaton that accepts only "1"



- •A finite automaton accepts a string if we can follo
- •w transitions labeled with the characters in the string from the start to some accepting state

EPSILON MOVES

•Another kind of transition: ε-moves

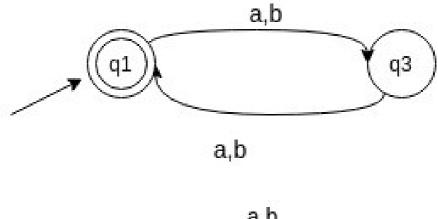


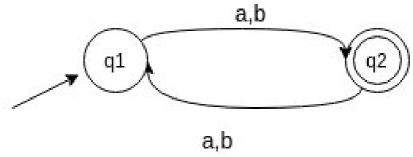
Machine can move from state A to state B without reading input

A SIMPLE EXAMPLE

DFA for W \leftarrow a,b |w| mod 2=0

DFA for W \leftarrow a,b |w| mod 2=1





DFA for W \leftarrow a,b |w| mod 3=0

DETERMINISTIC AND NONDETERMINISTIC AUTOMATA

- Deterministic Finite Automata (DFA)
 - One transition per input per state
 - No ε-moves
- Nondeterministic Finite Automata (NFA)
 - Can have multiple transitions for one input in a given state
 - Can have ε-moves

ARDEN'S THEOREM STATE THAT:

If P and Q are two regular expressions over Σ , and if P does not contain ε , then the

following equation in R given by $\mathbf{R} = \mathbf{Q} + \mathbf{RP}$

has an unique solution i.e.,

$$R = QP*$$

Let's start by taking this equation as equation (i)

$$R = Q + RP \dots (i)$$

Now, replacing R by $R = QP^*$, we get,

$$R = Q + QP*P$$

Taking Q as common,

$$R = Q(\epsilon + P*P)$$

$$R = QP^*$$

Initial and final state-q1

Step-01:

equations are

$$q1=q1 a + q3 a + \epsilon$$
 (1
 $q2=q1 b + q2 b + q3 b$ (2
 $q3=q2 a$ (3

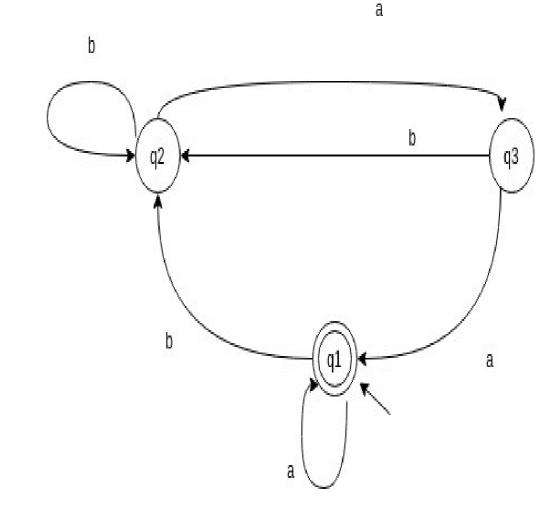
Bring state q2 in the form R = Q + RP.

$$q2 = q1 b + q2 b + (q2 a) b$$

= $q1 b + q2(b + a b)$

by arden's theorem

$$q2=q1 b (b+ab)*$$
 (4



Using (3) in (1), we get-

$$q1=q1 a + q3 a + \epsilon$$

= $q1a+(q2 a)a + \epsilon$

Using (4) in (1), we get-

=q1 a+q1 b (b+ab)* a a +
$$\epsilon$$

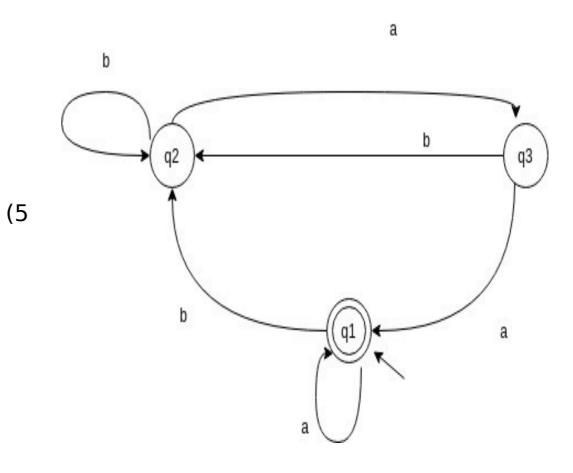
=q1 (a+b (b+ab)* a a) + ϵ

Using Arden's Theorem in (5), we get-

$$q1 = \epsilon + q1 (a+b (b+ab)* a a)$$

 $q1 = (a+b(b+ab)*aa)*$

Thus, Regular Expression for the given DFA = (a+b(b+ab)*aa)*



ARD Entroct The Goren DFA

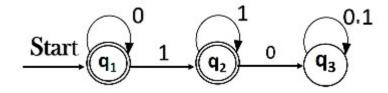
Solution:

Let us write down the equations

$$q1 = q10 + \epsilon$$

Since q1 is the start state, so ϵ will be added, and the input 0 is coming to q1 from q1 hence we write

State = source state of input × input coming to it



Similarly,

$$q2 = q1 1 + q2 1$$

 $q3 = q2 0 + q3$
 $(0+1)$

Since the final states are q1 and q2, we are interested in solving q1 and q2 only. Let us see q1 first

$$q1 = q10 + \epsilon$$

We can re-write it as

$$q1 = \epsilon + q10$$

$$R = Q + R P$$

Which is similar to R = Q + RP,

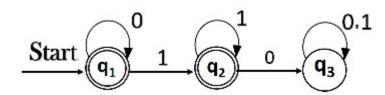
and gets reduced to $R = OP^*$.

Assuming R = q1, $Q = \epsilon$, P = 0

We get

$$q1 = \epsilon.(0)$$
*

$$q1 = 0*$$



$$q1 = 0*$$

Substituting the value into q2, we will get

$$q2 = q1 1 + q2 1$$

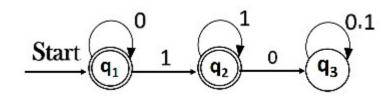
$$q2 = 0*1 + q21$$

$$R = Q + R P$$

 $q_{2} = 0*1(1)* (R = Q + RP \rightarrow Q)$ The regular expression is quiven by

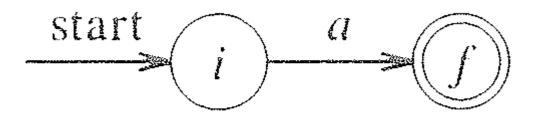
$$r = q1 + q2$$

= 0* + 0* 1(1)*
 $r = 0* + 0* 1 1*$

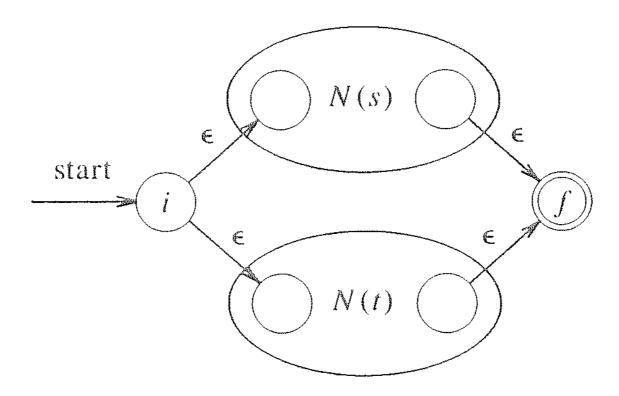


Construction of an NFA from a Regular Expression

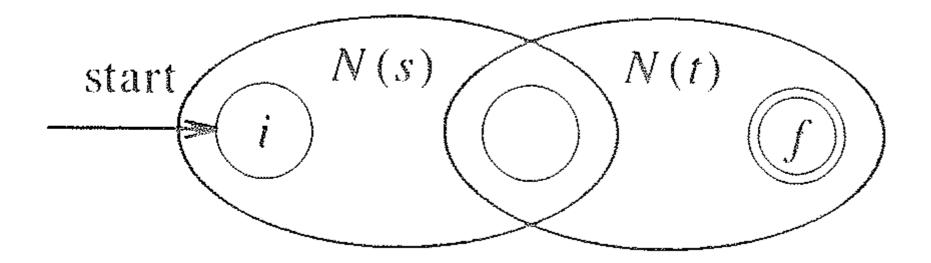
BASIS: For expression a construct the NFA



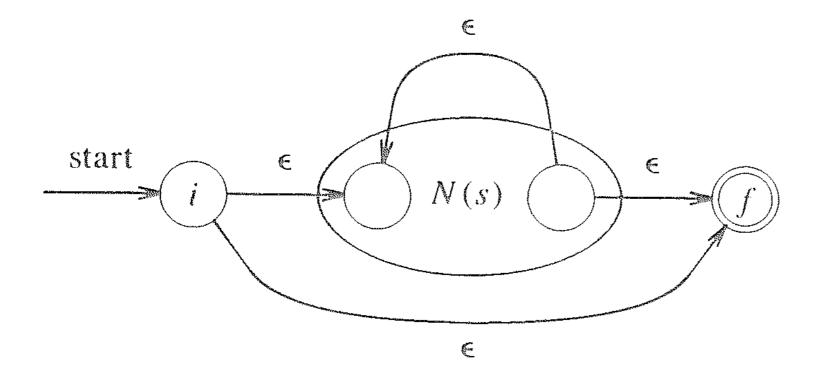
For the regular expression s|t,



For the regular expression st,

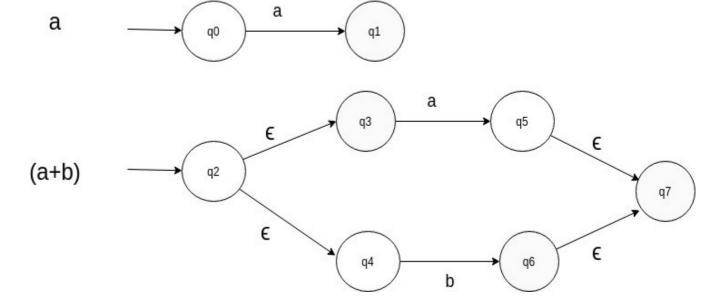


For the regular expression S*,



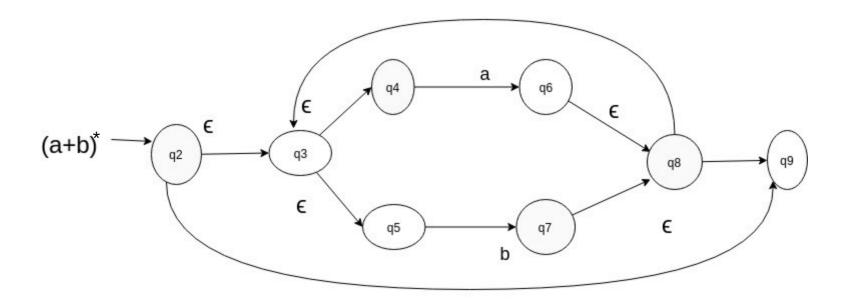
construct an NFA for r=

a(a+b)*bb



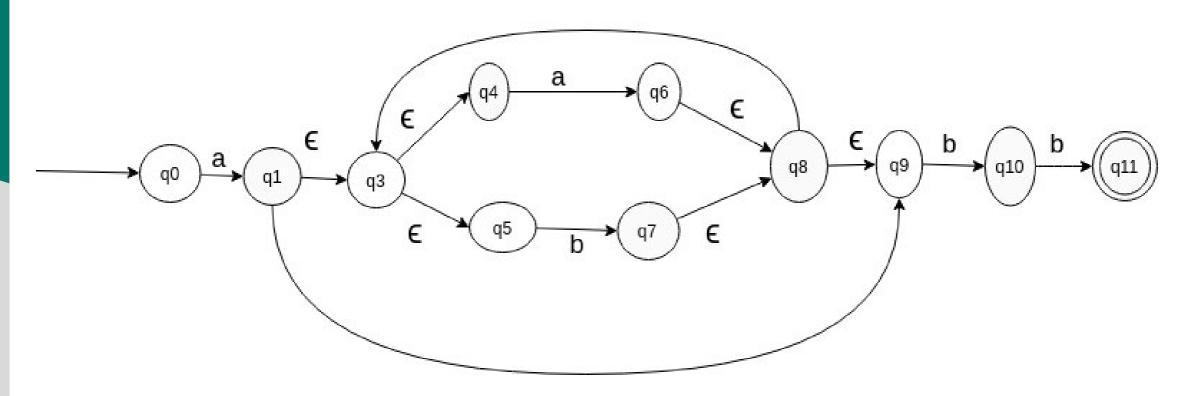
EXAMPLF

a(a+b)*bb

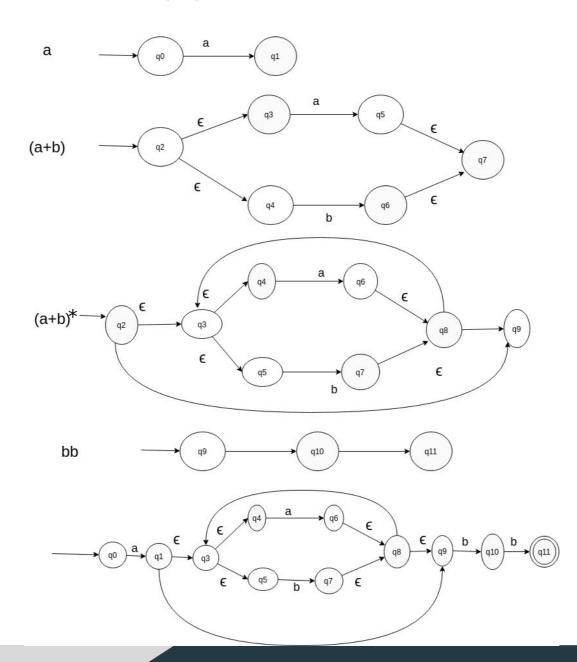




a(a+b)*bb



EXAMPLE



- (a|b)*a
- (b+ab*a)*
- **0***10*

THE SUBSET CONSTRUCTION ALGORITHM

The algorithm for constructing a DFA from a given NFA such that it recognizes the same language is called subset construction.

Operation	Definition
\in -closure(s)	set of NFA states reachable from state s on \in -transition
\in -closure(T)	set of NFA states reachable from some s in T on \in -transition
move(T, a)	set of NFA states to which there is transition on input a from some state s in the set T

THE SUBSET CONSTRUCTION ALGORITHM

```
Initialize: Let \in-closure(s_0) be the only state in Dstates (of the
DFA)
         while there are unmarked states T in Dstates do
Repeat:
         mark T
         for each symbol a do
            U = \in -closure(move(T, a))
            if U is not in Dstates then
               add U as unmarked state in Dstates
            Dtran[T, a] = U
         end
      end
```

Steps to Convert NFA with ϵ -move to DFA :

Step 1 : Take \in closure for the beginning state of NFA as beginning state of DFA.

Step 2: Find the states that can be traversed from the present for each input symbol

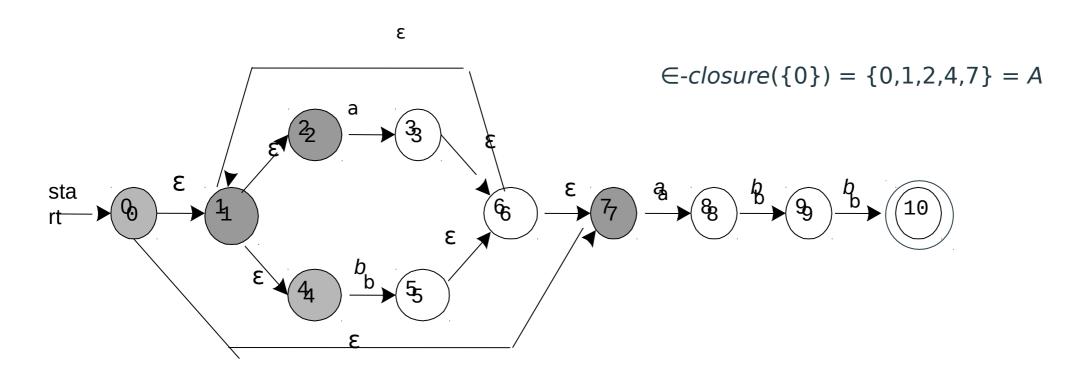
(union of transition value and their closures for each states of NFA present in current state of DFA).

Step 3 : If any new state is found take it as current state and repeat step 2.

Step 4 : Do repeat Step 2 and Step 3 until no new state present in DFA transition table.

Step 5 : Mark the states of DFA which contains final state of NFA as final states of DFA.

Convert the NFA for the expression: $(a \mid b)*abb$ into a DFA using the subset construction algorithm.



 \in -closure({3, 8})= \in -closure(3) U \in -closure(8) \in -closure(3)={,1,2,3,4,6,7} \in -closure(8)={8} \in -closure({3, 8})={1,2,3,4,6,7,8}

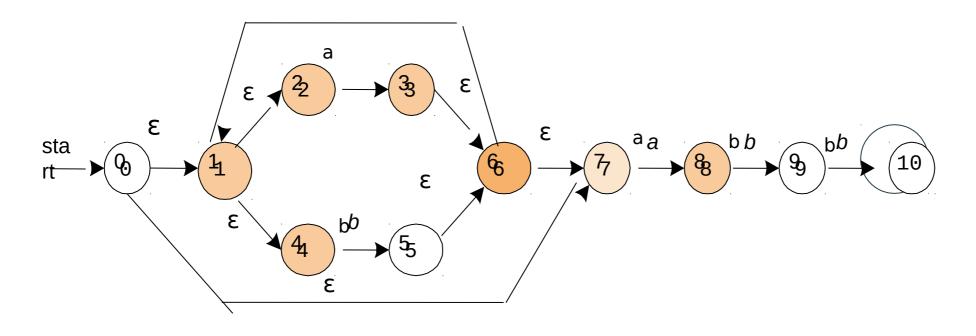
```
\delta'(A,a) = \in -closure(move(A,a))

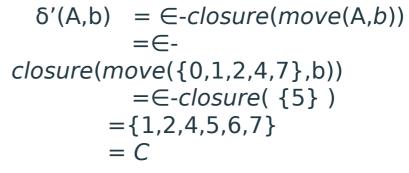
= \in -closure(move(\{0,1,2,4,7\},a))

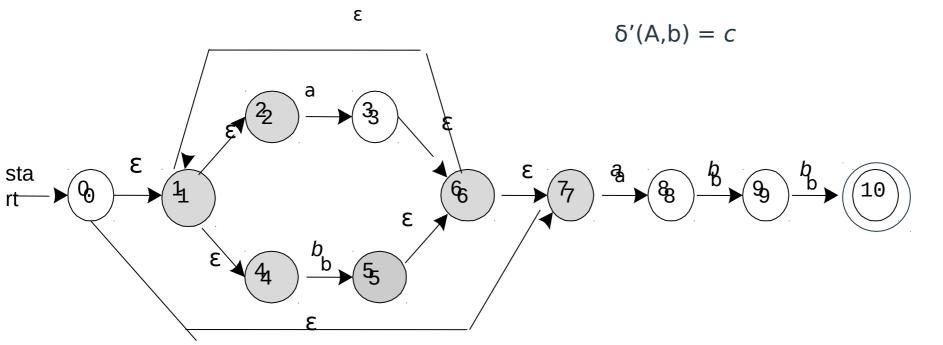
= \in -closure(\{3,8\})

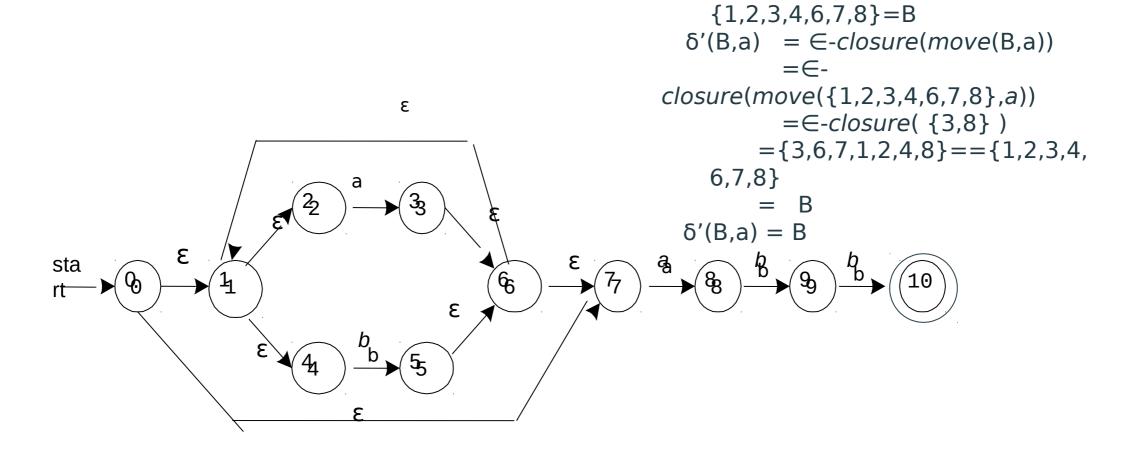
= \{1,2,3,4,6,7,8\}

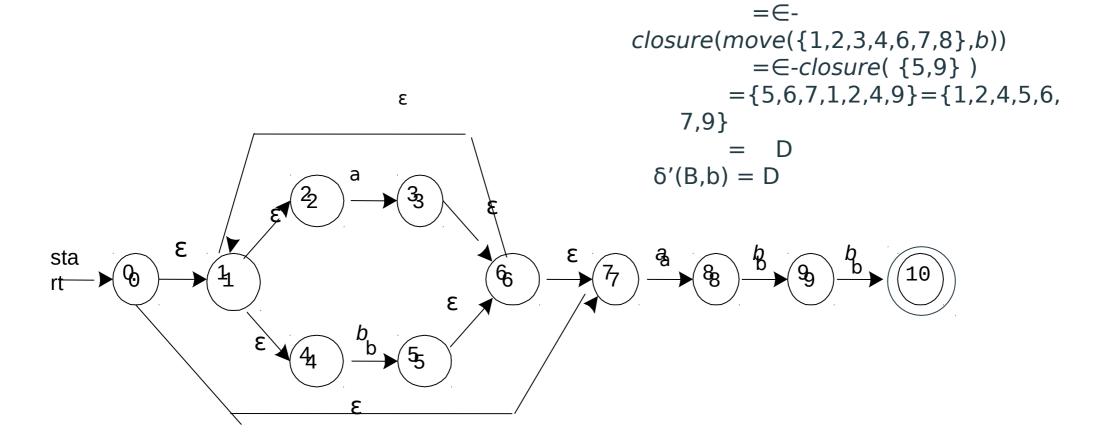
\delta'(A,a) = B
```





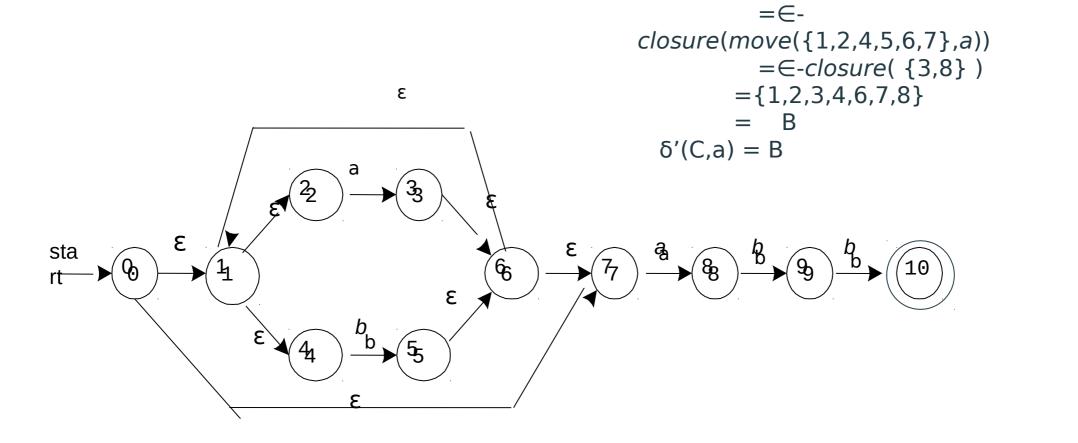






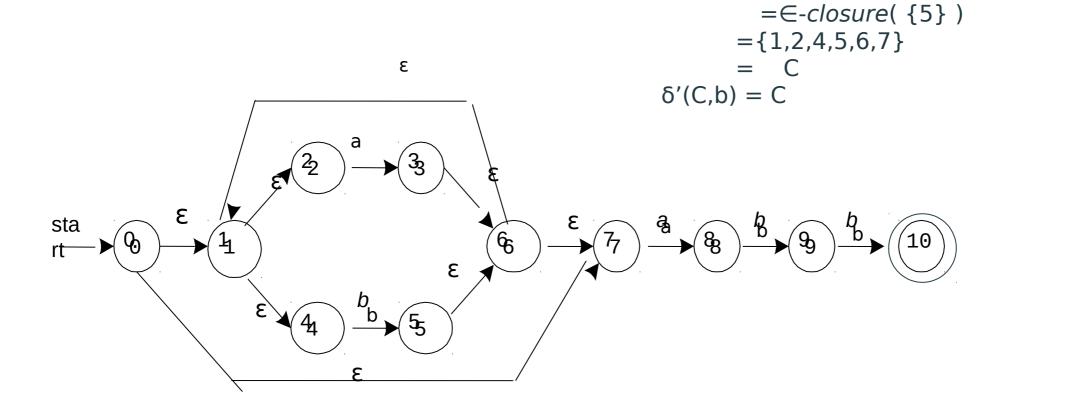
 $\{1,2,3,4,6,7,8\} = B$

 $\delta'(B,b) = \in -closure(move(B,b))$



{1,2,4,5,6,7}

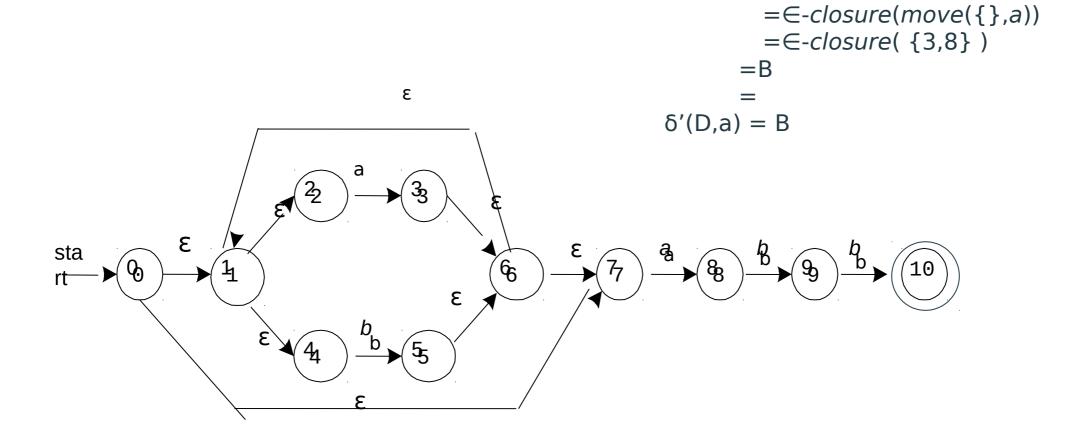
 $\delta'(C,a) = \in -closure(move(C,a))$



{1,2,4,5,6,7}

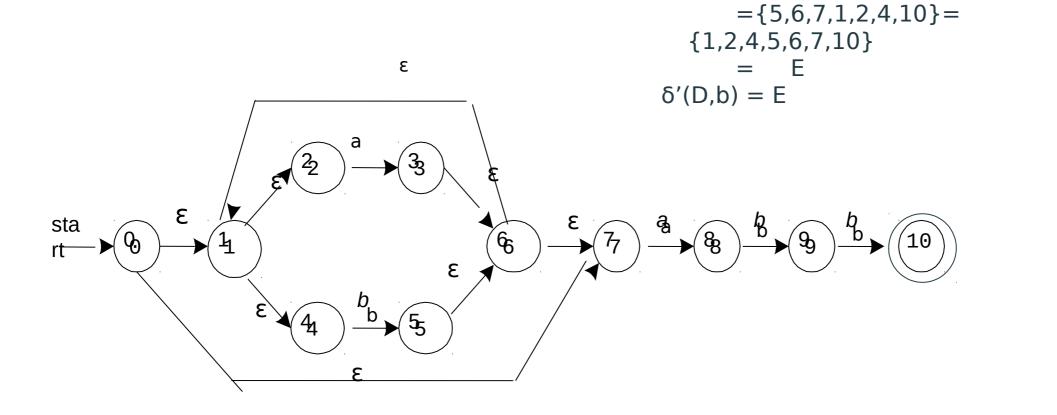
 $\delta'(C,b) = \in -closure(move(C,b))$

 $= \in -closure(move(\{\},b))$



{1,2,4,5,6,7,9}

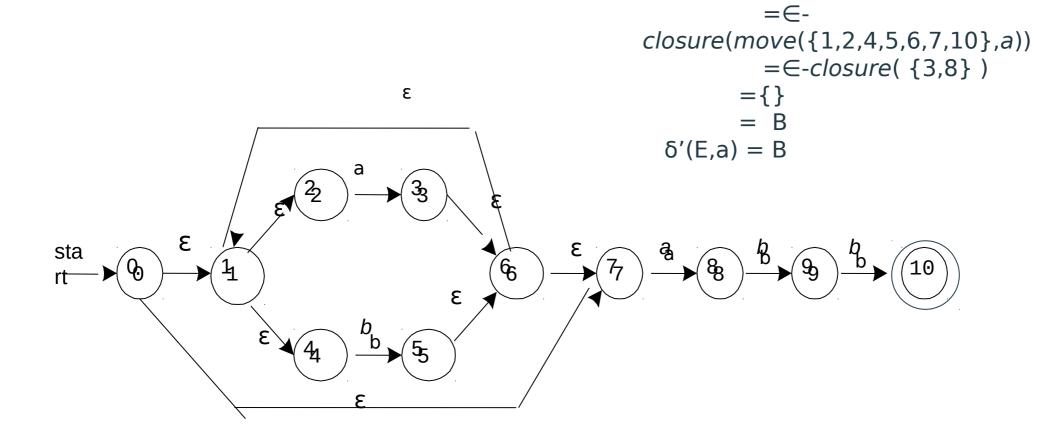
 $\delta'(D,a) = \in -closure(move(D,a))$



 $\delta'(D,b) = \in -closure(move(D,b))$

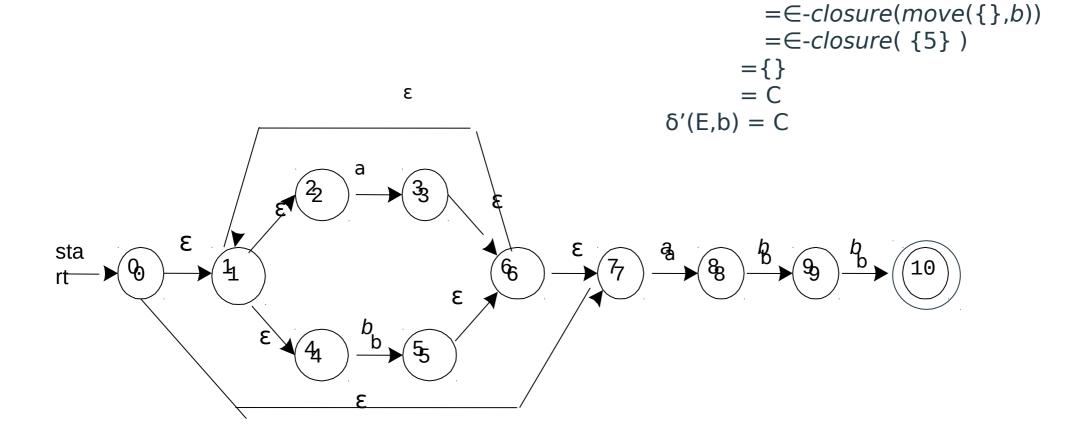
 $= \in -closure(move(\{\},b))$

 $= \in -closure(\{5,10\})$



{1,2,4,5,6,7,10}

 $\delta'(E,a) = \in -closure(move(E,a))$



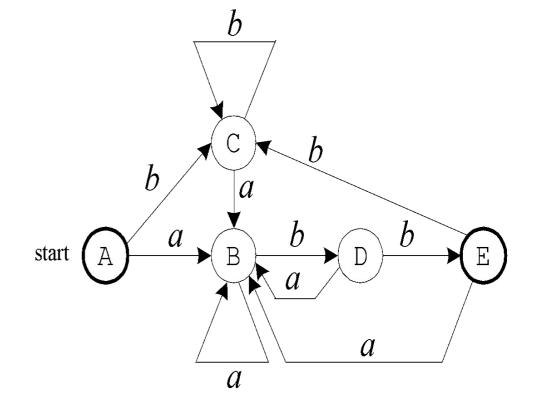
{1,2,4,5,6,7,10}

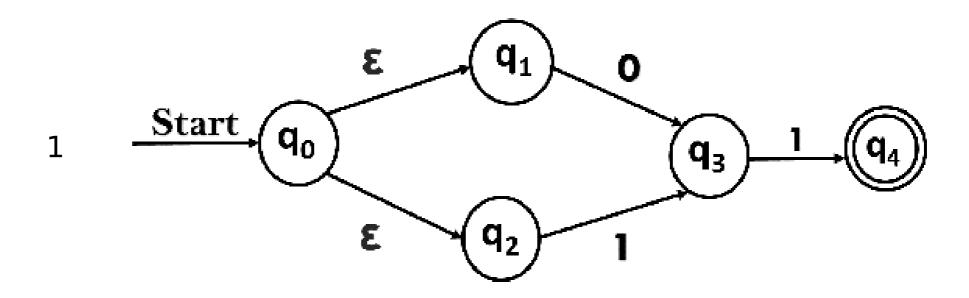
 $\delta'(E,b) = \in -closure(move(E,b))$

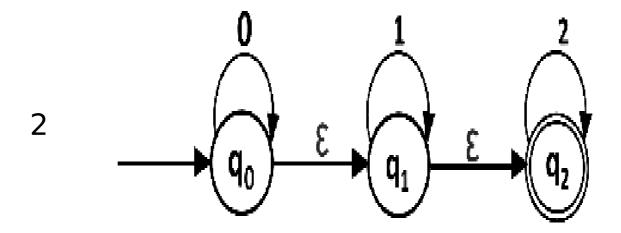
```
\in-closure({0}) = {0,1,2,4,7} = A
\in-closure(move({0,1,2,4,7},a))=\in-closure({3,8})={1,2,3,4,6,7,8}=B
\in-closure(move({1,2,4,7},b))=\in-closure({5})={1,2,4,5,6,7}= C
\in-closure(move({1,2,3,4,6,7,8},a) = \in-closure({3,8}) = B
\in-closure(move({1,2,3,4,6,7,8},b) = \in-closure({5, 9})={1,2,4,5,6,7,9}=D
\in-closure(move({1,2,4,5,6,7},a))=\in-closure({3,8})=B
\in-closure(move({1,2,4,5,6,7},b))=\in-closure({5})=C
\in-closure(move({1,2,4,5,6,7,9},a))=\in-closure({3,8})=B
\in-closure(move({1,2,4,5,6,7,9},b))=\in-closure({5,10})={1,2,4,5,6,7,10}=E
\in-closure(move({1,2,4,5,6,7,10},a))=\in-closure({3,8})=B
\in-closure(move({1,2,4,5,6,7,10},b))=\in-closure({5}) = C
```

The transition table for this DFA becomes:

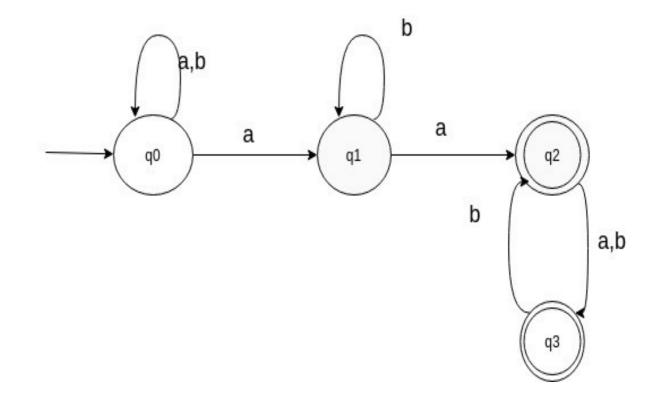
state	а	b
A	В	С
В	В	D
С	В	С
D	В	E
E	В	С







```
\delta(q0,a) = \{q0,q1\}
                                 В
\delta(q0,b)=q0
\delta(B,a)=\delta(\{q0,q1\},a)
\delta(\{q0,q1\},a) = \delta(q0,a) \cup \delta(q1,a)
             = \{q0,q1\} \cup q2
             = \{q0,q1,q2\}
                                              C
\delta(B,b)=\delta(\{q0,q1\},b)
\delta(\{q0,q1\},b) = \delta(q0,b) \cup \delta(q1,b)
             =q0 U q1
             = \{q0,q1\}
                                              В
\delta(\{q0.q1,q2\},a)=\{q0,q1,q2,q3\}
                                                      D
\delta(\{q0.q1,q2\},b)=\{q0,q1,q3\}
\delta(\{q0,q1,q2,q3\},a)=\{q0,q1,q2,q3\}
\delta(\{q0,q1,q2,q3\},b)=\{q0,q1,q2,q3\}
\delta(\{q0,q1,q3\},a)=\{q0,q1,q2\}
\delta(\{q0.q1,q3\},b)=\{q0,q1,q2\}
```



δ/Σ	a	b
А	В	Α
В	С	В
С	D	E
D	D	D
Е	С	С

δ/Σ	a	b
q0	q0,q1	q0
q0,q1	q0,q1,q2	q0,q1
q0,q1,q2	q0,q1,q2,q3	q0,q1,q3
q0,q1,q2,q3	q0,q1,q2,q3	q0,q1,q2,q3
q0,q1,q3	q0,q1,q2,q3	q0,q1,q2,q3

δ/Σ	a	b
А	В	А
В	С	В
С	D	Е
D	D	D
Е	D	D

DFA

