

# Generative Models



Analytics Club, IIT Madras

# Quick Recap!

## Supervised vs Unsupervised Learning

### Supervised Learning

**Given:**  $(x, y)$  where  $x$  is data,  $y$  is label

**Goal:** Learn a function mapping from  $x$  to  $y$

**Examples:** Classification, regression, object detection, semantic segmentation, image captioning, **Conditional density estimation i.e  $P(X | Y)$**

### Unsupervised Learning

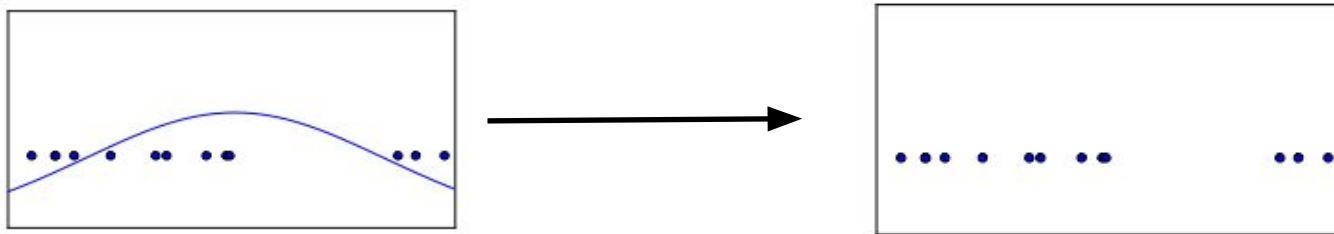
**Given:**  $x$  - unlabelled data

**Goal:** Learn some underlying hidden structure of the data

**Examples:** Clustering, dimensionality reduction, feature learning, **marginal density estimation i.e.  $P(x)$**

# Introduction

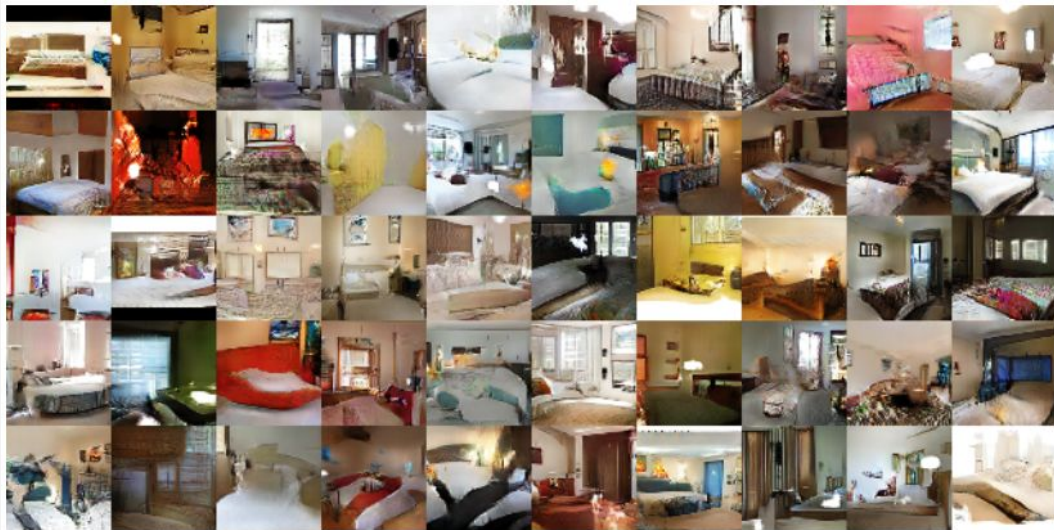
## 1-d density estimation



**Generative Models:** Given training data, generate new samples from same distribution

Training data  $\sim p_{\text{data}}(x)$ , Generated samples  $\sim p_{\text{model}}(x)$ , Want to learn  $p_{\text{model}}(x)$  similar to  $p_{\text{data}}(x)$

# What can Generative Models do?



# What can Generative Models do?

Labels to Street Scene



input

output

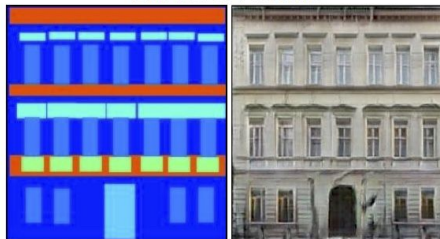
Aerial to Map



input

output

Labels to Facade



input

output

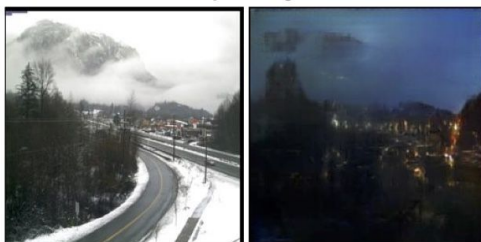
BW to Color



input

output

Day to Night



input

output

Edges to Photo

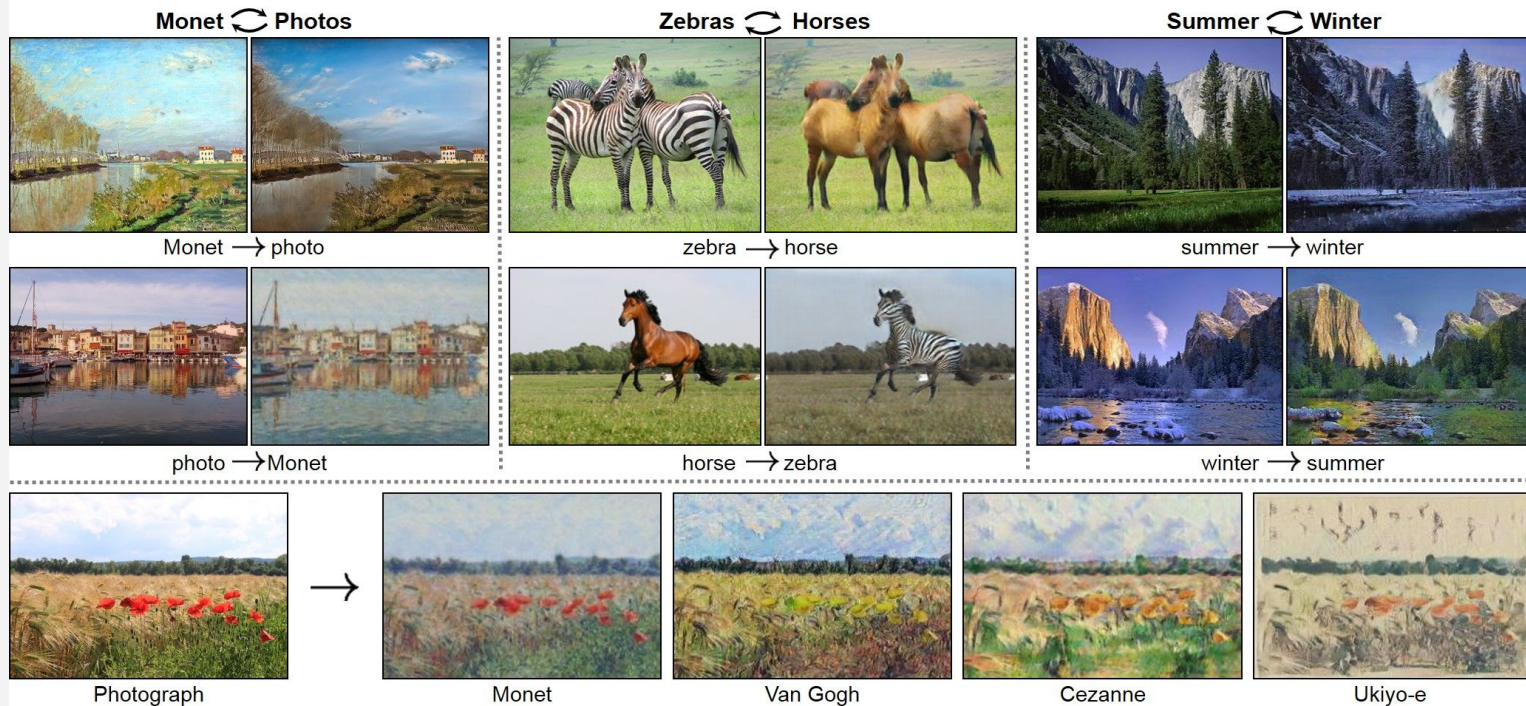


input

output



# What can Generative Models do?



# Some Math Basics

- **A Divergence** is a metric to measure how much probability distributions  $p$ ,  $q$  differ from each other.
- $KL(p||q) = \int p(x)(\log(p(x)) - \log(q(x))) dx$

Minimum value of KL divergence: 0

Maximum value of KL divergence:  $\infty$

KL divergence is 0 iff  $p = q$ .

- Is KL divergence a symmetric metric?  
What happens to the KL divergence in the following cases?  
 $p(x) = 0$  but  $q(x) \neq 0$ . Nothing much.  
 $q(x) = 0$  but  $p(x) \neq 0$ . It explodes.

# Some Math Basics

- $KL(p||q) = \int p(x) \log(p(x)) - \int p(x) \log(q(x))$   
 $= -\text{Entropy}(p) + \text{CrossEntropy}(p, q).$
- For many unsupervised learning problems we maximize the log-likelihood of the training data  $P$ 

$$\begin{aligned} \max LL(\text{real data}) &= \max \sum_{x \in D} \log(p_{\text{model}}(x)) * 1/N \\ &\equiv \max -\text{CrossEntropy}(p_{\text{data}}, p_{\text{model}}) \\ &\equiv \min \text{CrossEntropy}(p_{\text{data}}, p_{\text{model}}) \\ &\equiv \min KL(p_{\text{data}} || p_{\text{model}}) \end{aligned}$$
- Therefore given enough samples of real data, if we maximize log-likelihood, we end up minimizing  $KL(p_{\text{data}} || p_{\text{model}}).$



# Some Math Basics

- The **Jensen-Shannon Divergence** (JSD) is a symmetric version of KL divergence defined as

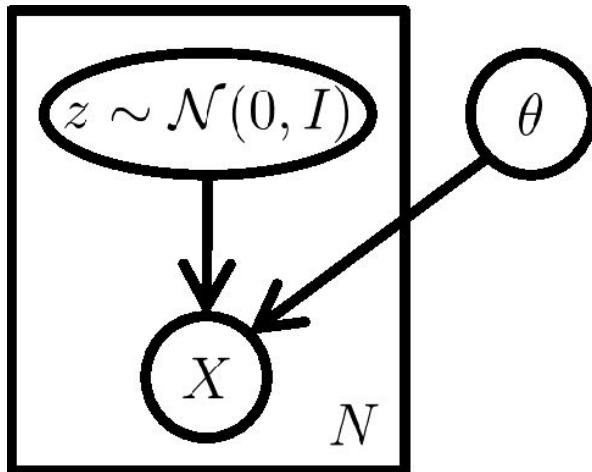
$$\text{JSD}(P \parallel Q) = \frac{1}{2} \text{KL}(P \parallel (P+Q)/2) + \frac{1}{2} \text{KL}(Q \parallel (P+Q)/2)$$

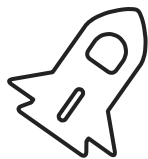
## Properties:

- $0 \leq \text{JSD} \leq \log 2$ .
- JSD is 0 iff  $p = q$ .
- If  $p$  and  $q$  have disjoint supports, the  $\text{JSD}(P \parallel Q) = \log 2$

# Latent Variable Models

- The Generative model makes a decision on what it is going to generate beforehand with the help of latent variables, eg MNIST digit generation





# Variational Autoencoders (VAEs)<sup>90</sup>

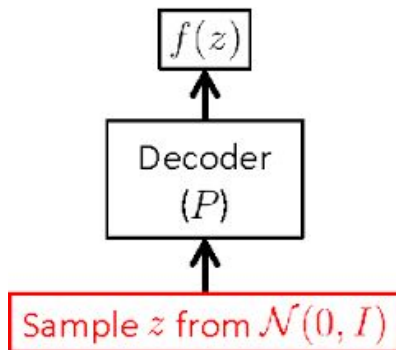
Maximum likelihood learning  
(KL Divergence)





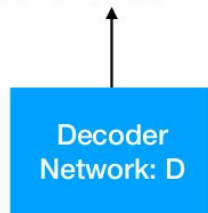
$$P(X) = \int P(X|z; \theta) P(z) dz$$

- $P(z)$  - Prior distribution - high dimensional standard gaussian
- In VAEs, output distribution is often Gaussian, i.e.,  $P(X|z; \theta) = N(X|f(z; \theta), \sigma^2 * I)$ . That is, it has mean  $f(z; \theta)$  and covariance equal to the identity matrix  $I$  times some scalar  $\sigma$
- Integral is Intractable

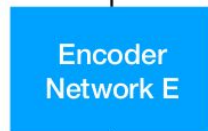


# VAEs

Reconstructed image



Latent code



Input image

Ideally, we would like to maximize

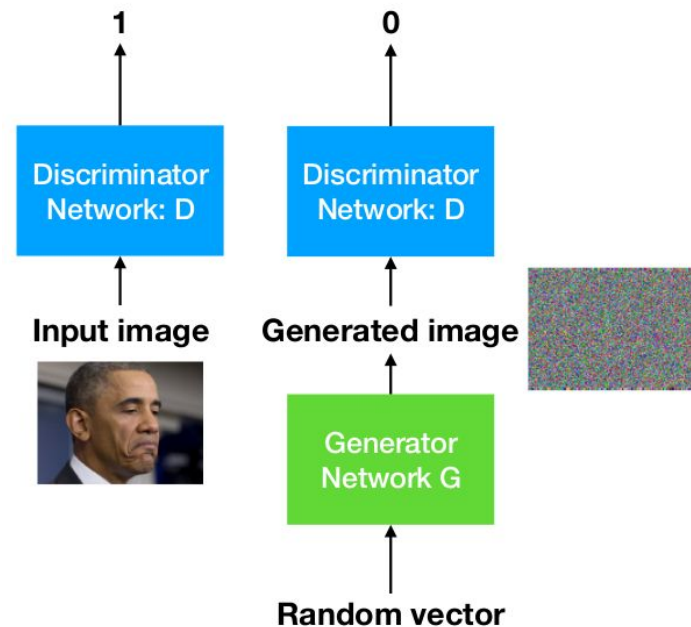
$$\max_{\theta} L(\theta|\text{Dataset}) \equiv \sum_{x^{(j)}} \log p(\theta|x^{(j)})$$

But we maximize a lower bound for tractability

$$\begin{aligned} \max_{\theta} L_V(\theta|\text{Dataset}) \equiv & \sum_{x^{(j)}} -\text{KL}(q_{\theta}(z|x^{(j)})||\mathcal{N}(z|0, I)) + \\ & E_{z \sim (q_{\theta}(z|x^{(j)}))} [\log p_{\theta}(x^{(j)}|z)] \\ & \leq L(\theta|\text{Dataset}) \end{aligned}$$

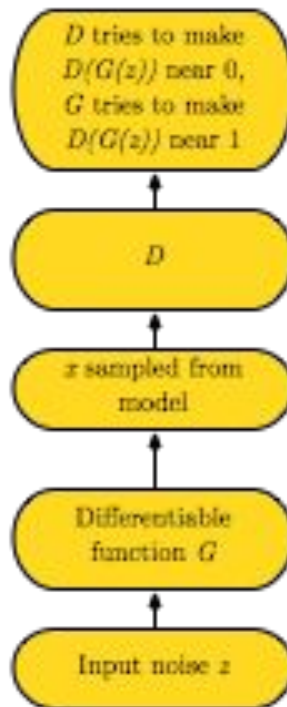
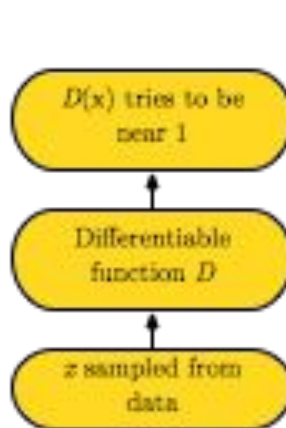
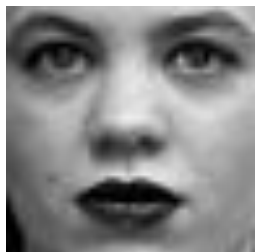
# GANs

- Goodfellow et al. NIPS 2014
- Forget about designing a perceptual loss.  
Let's train a discriminator to differential real and fake image





# GANs



# GANs Objective

**GANs solve a minimax objective**

$$\min_G \max_D E_{x \sim p_X} [\log D(x)] + E_{z \sim p_Z} [\log(1 - D(G(z)))]$$

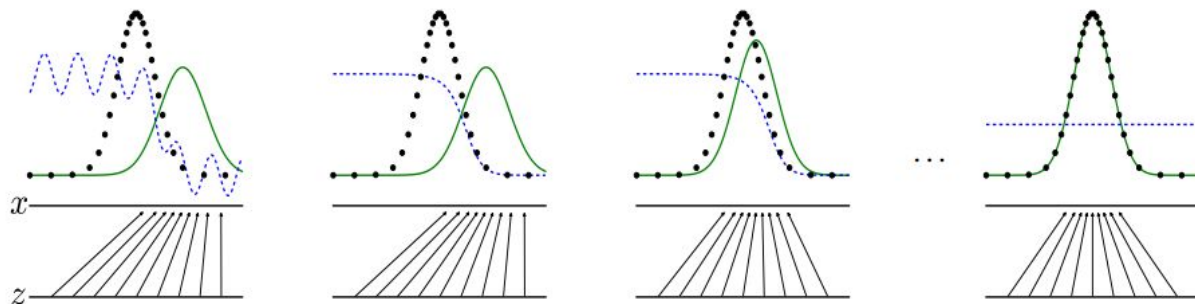
$p_X$  : Data distribution,  
usually represented by samples.

$p_{G(Z)}$  : Model distribution, where  
 $Z$  is usually modeled as uniform or Gaussian.

# Discriminator strategy

Optimal discriminator (non-parametric)

$$D(x) = \frac{p_X(x)}{p_X(x) + p_{G(Z)}(x)}$$



# JS Divergence

**Under an ideal discriminator, the generator minimizes the Jensen-Shannon divergence between  $p_x$  and  $p_{G(z)}$ . This also requires that D and G have sufficient capacity and a sufficiently large dataset.**

# GANs in practice

- Step 1: Fix G and perform a gradient step to

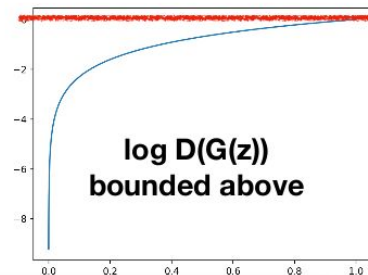
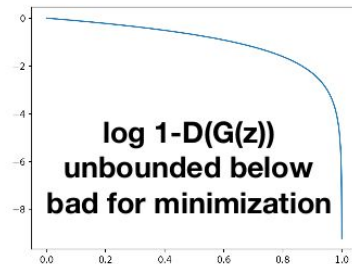
$$\max_D E_{x \sim p_X} [\log D(x)] + E_{z \sim p_Z} [\log(1 - D(G(z)))]$$

- Step 2: Fix D and perform a gradient step to (in theory)

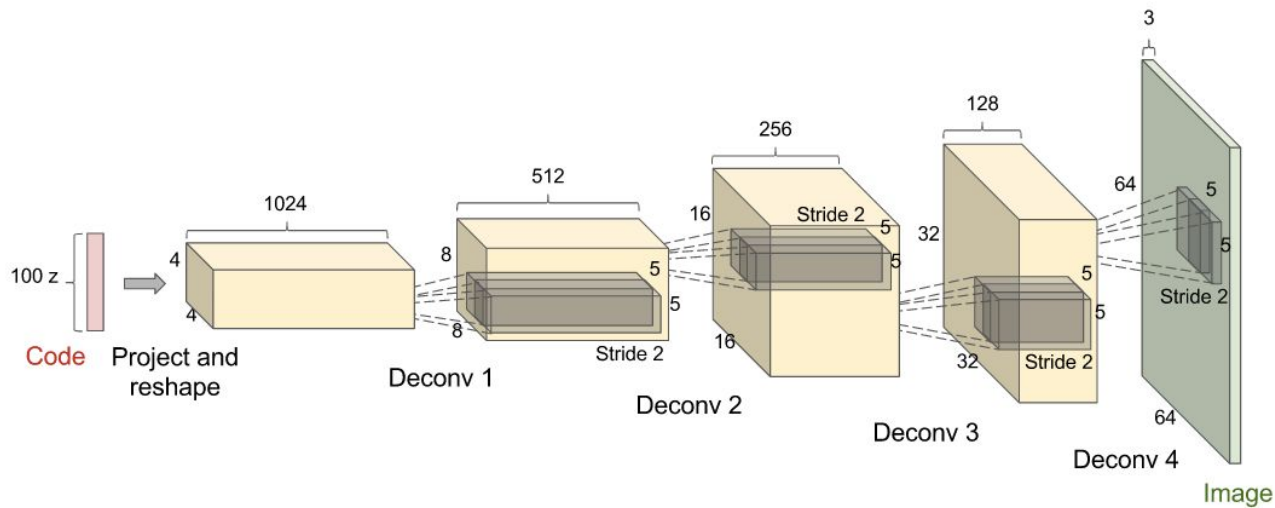
$$\min_G E_{z \sim p_Z} [\log(1 - D(G(z)))]$$

(in practice)

$$\max_G E_{z \sim p_Z} [\log D(G(z))]$$



# DC-GAN Architecture





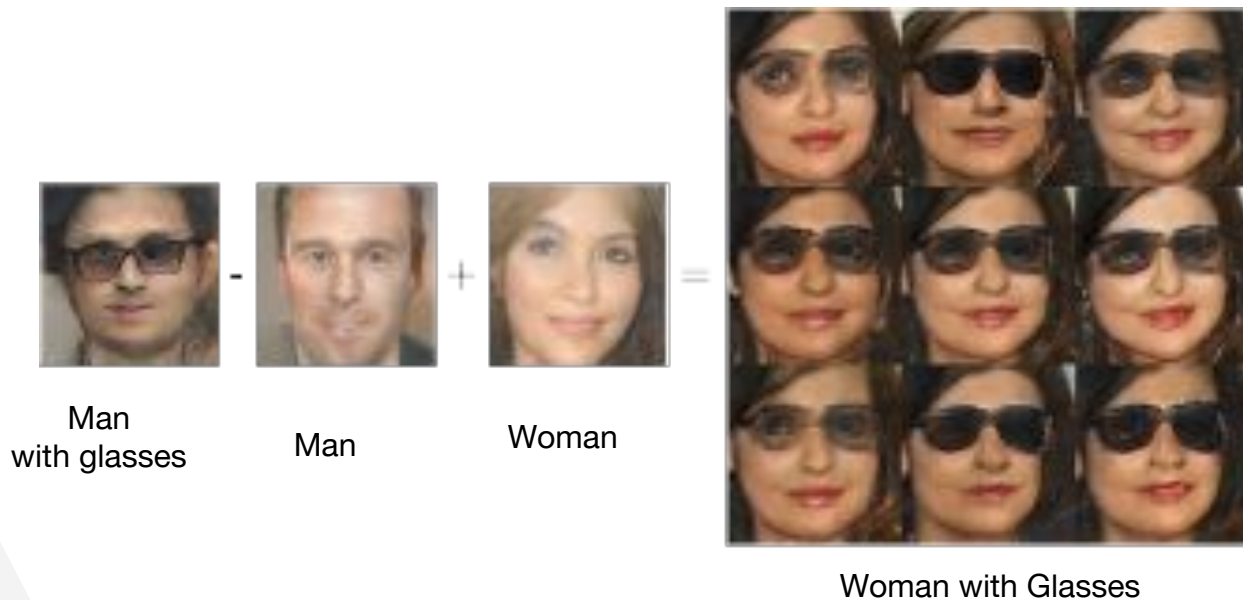
# Results

DCGANs for LSUN Bedrooms



# Results

## Vector Space Arithmetic



# Wasserstein GAN

M. Arjovsky, S. Chintala, L. Bottou “Wasserstein GAN” 2016

Replace classifier with a critic function

## Discriminator

**GAN**  $\max_D E_{x \sim p_X} [\log D(x)] + E_{z \sim p_Z} [\log(1 - D(G(z)))]$



**WGAN**  $\max_D E_{x \sim p_X} [D(x)] - E_{z \sim p_Z} [D(G(z))]$

## Generator

**GAN**  $\max_G E_{z \sim p_Z} [\log D(G(z))]$



**WGAN**  $\max_G E_{z \sim p_Z} [D(G(z))]$

# WGAN

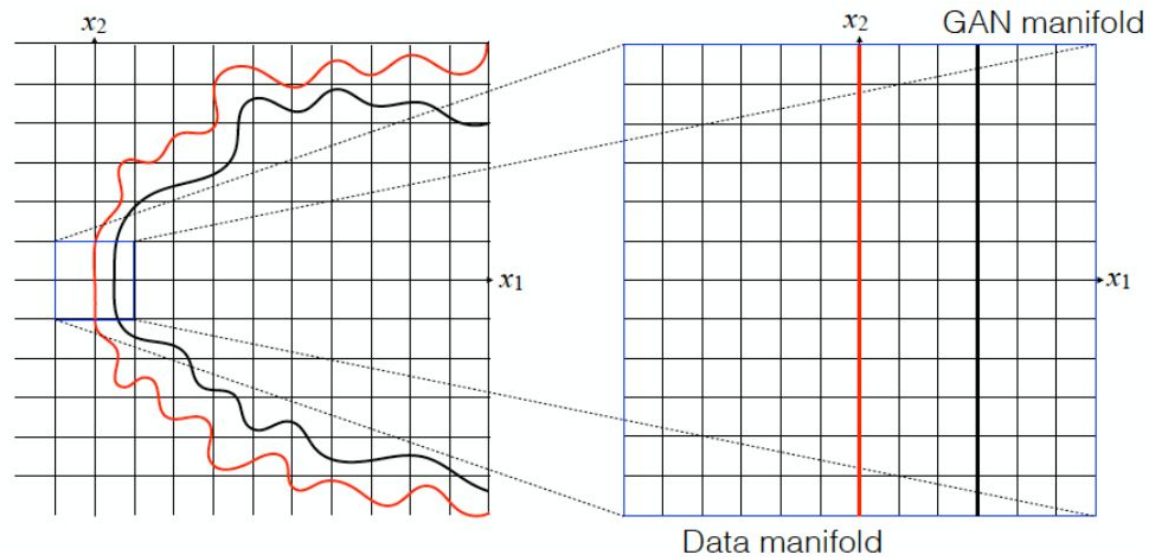
**GAN:** minimize Jensen-Shannon divergence between  $p_X$  and  $p_{G(Z)}$

$$JS(p_X || p_{G(Z)}) = KL(p_X || \frac{p_X + p_{G(Z)}}{2}) + KL(p_{G(Z)} || \frac{p_X + p_{G(Z)}}{2})$$

**WGAN:** minimize earth mover distance between  $p_X$  and  $p_{G(Z)}$

$$EM(p_X, p_{G(Z)}) = \inf_{\gamma \in \Pi(p_X, p_{G(Z)})} E_{(x,y) \sim \gamma} [|x - y|]$$

# WGAN

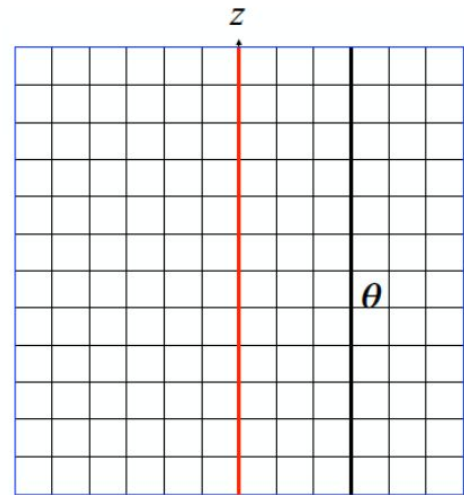
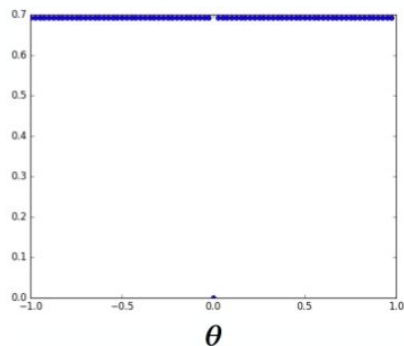


# WGAN VS GAN

$$JS(p_X || p_{G(Z)}) = KL(p_X || \frac{p_X + p_{G(Z)}}{2}) + KL(p_{G(Z)} || \frac{p_X + p_{G(Z)}}{2})$$

Jesen-Shannon divergence in this example

$$JS(p_X || p_{G(Z)}) = \begin{cases} \log 2 & \text{if } \theta \neq 0, \\ 0 & \text{if } \theta = 0, \end{cases}$$



Example from Arjovsky et al. 2017

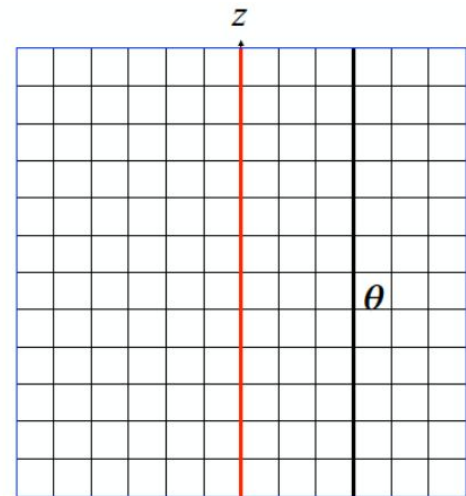
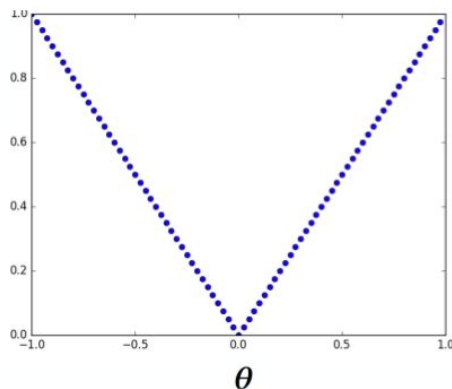


# WGAN Vs GAN

$$EM(p_X, p_{G(Z)}) = \inf_{\gamma \in \Pi(p_X, p_{G(Z)})} E_{(x,y) \sim \gamma} [|x - y|]$$

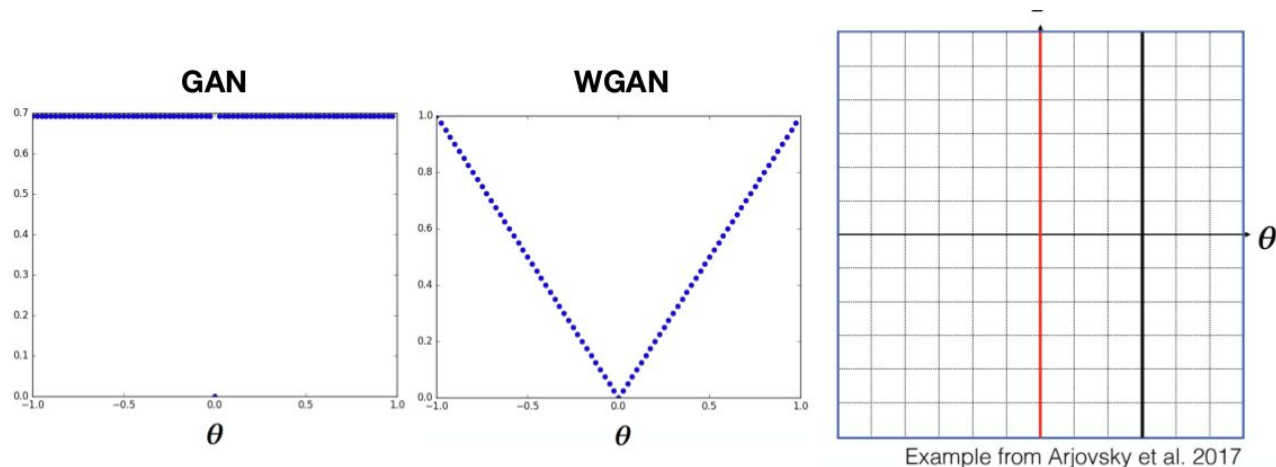
Earth Mover distance in this example

$$EM(p_X, p_{G(Z)}) = |\theta|$$



Example from Arjovsky et al. 2017

# WGAN Vs GAN



- If we can directly change the density shape parameter, the Earth Mover distance is smoother.
- But we do not directly change the density shape parameter, we change the generation function.

# WGAN-GP

I. Gulrajani, F. Ahmed, M. Arjovsky, V. Domoulin, A. Courville “Improved Training of Wasserstein GANs” 2017

$$\min_G \max_D E_{x \sim p_X} [D(x)] - E_{z \sim p_Z} [D(G(Z))] + \lambda E_{y \sim p_Y} [(\|\nabla_y D(y)\|_2 - 1)^2]$$

$$y = ux + (1 - u)G(z) \quad \bullet \text{ } y: \text{imaginary samples}$$

Optimal critic has unit gradient norm almost everywhere

**DCGAN**

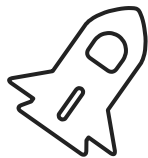
**LSGAN**

**WGAN (clipping)**

**WGAN-GP (ours)**

Baseline ( $G$ : DCGAN,  $D$ : DCGAN)



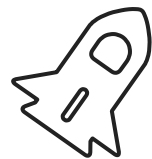


# pix2pix



## Paired Image-to-Image Translation





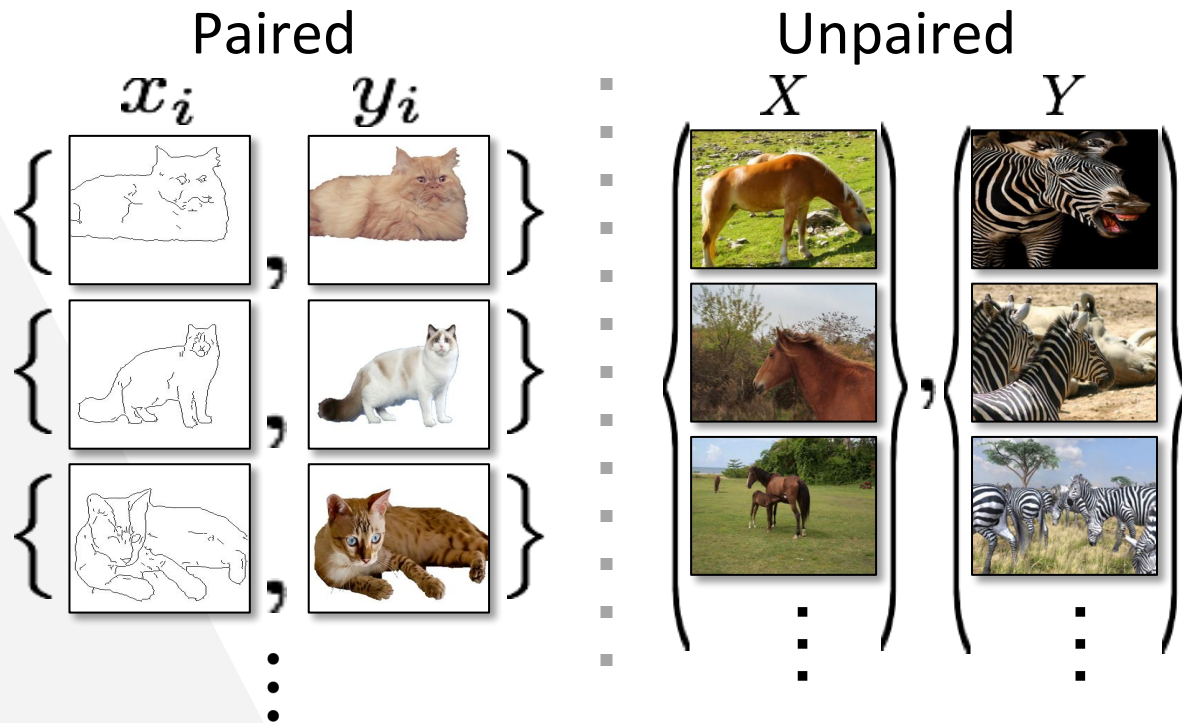
# Cycle GANs



**Unpaired Image-to-Image Translation  
with CycleGAN**



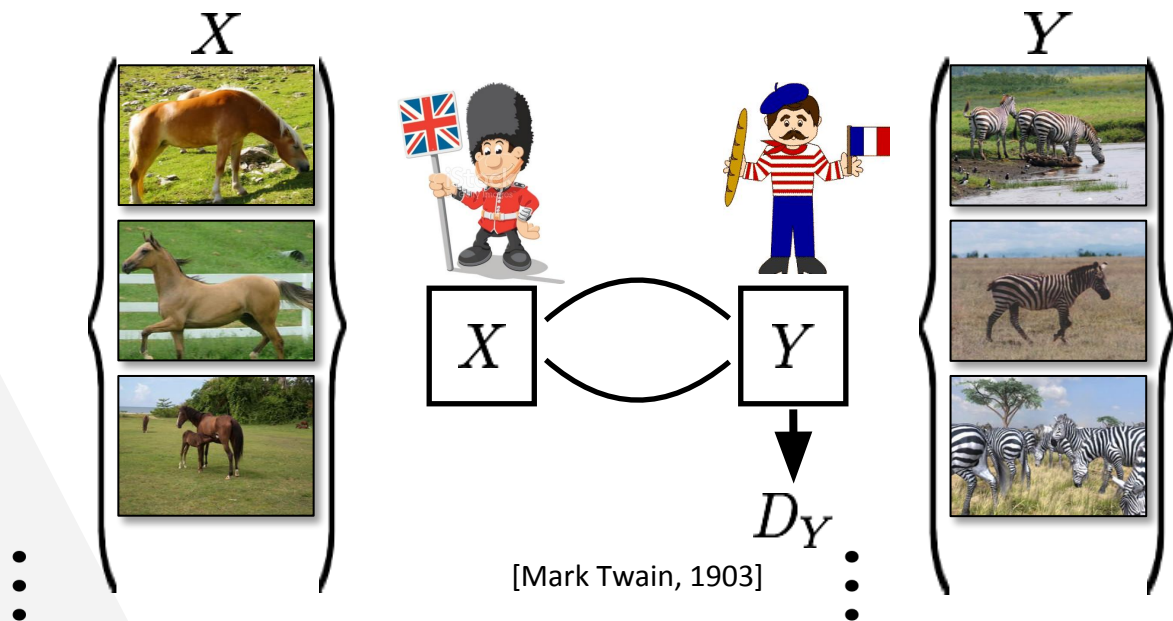
# Cycle GANs





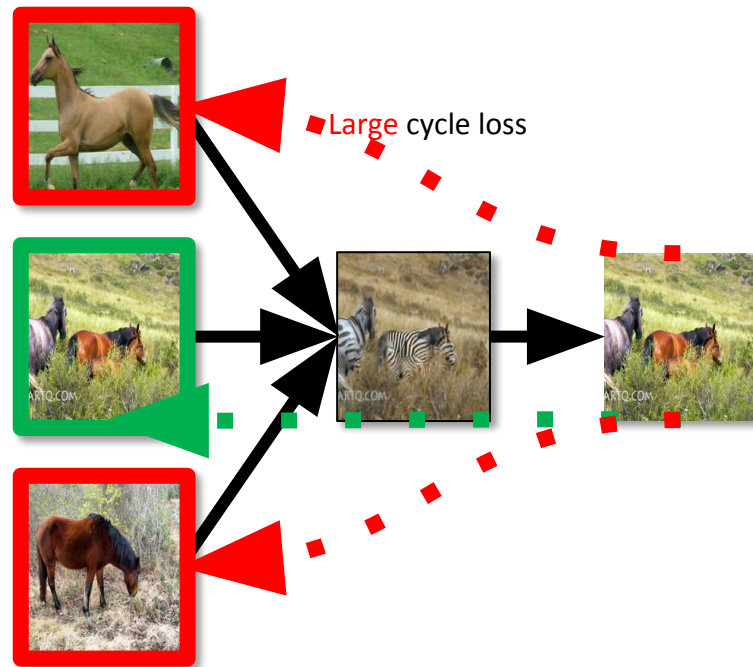
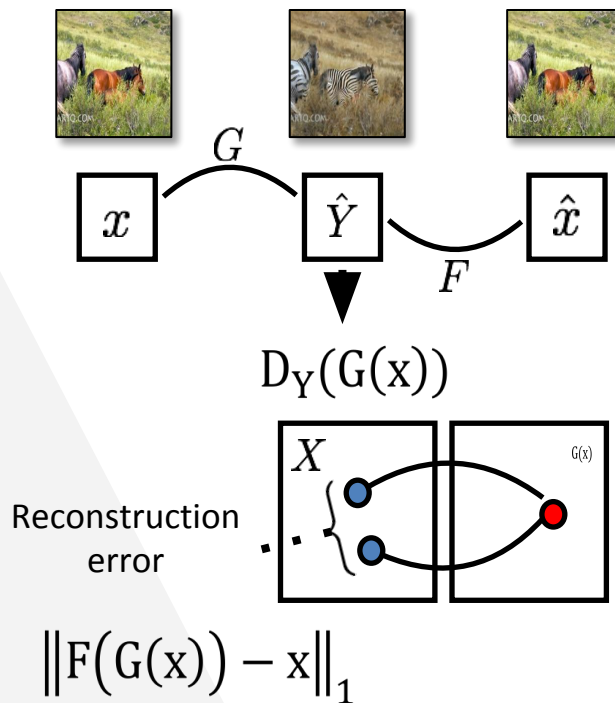
# Cycle GANs

## Cycle-Consistent Adversarial Networks

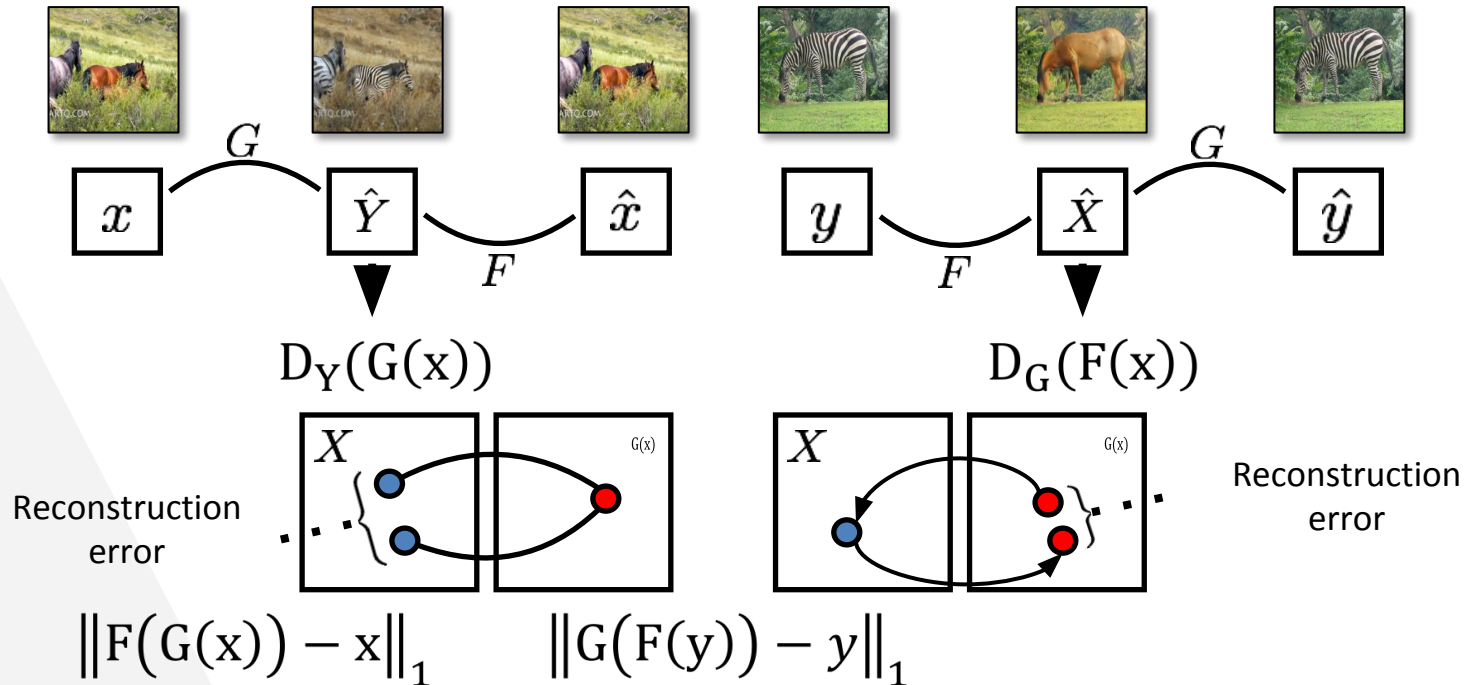


# Cycle Consistency Loss

X

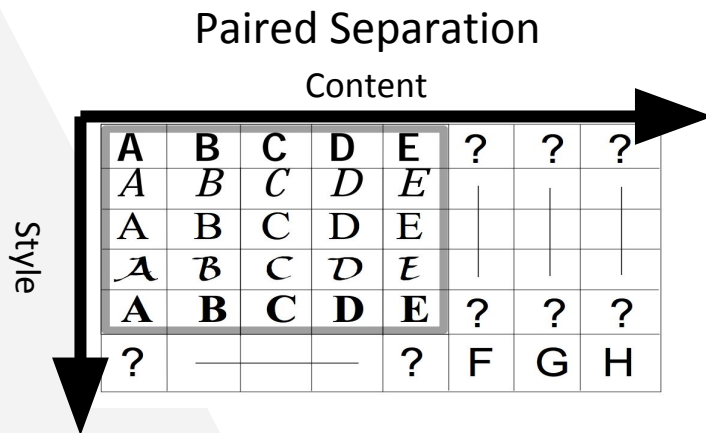


# Cycle Consistency Loss



# How do Cycle GANs Work?

## Style and Content Separation



Separating Style and Content with  
Bilinear Models  
[Tenenbaum and Freeman 2000']

## Unpaired Separation

Adversarial Loss: change the Style

$$\mathcal{L}_{\text{GAN}}(G, D_Y, X, Y) = \mathbb{E}_{y \sim p_{\text{data}}(y)} [\log D_Y(y)] \\ + \mathbb{E}_{x \sim p_{\text{data}}(x)} [\log(1 - D_Y(G(x)))]$$

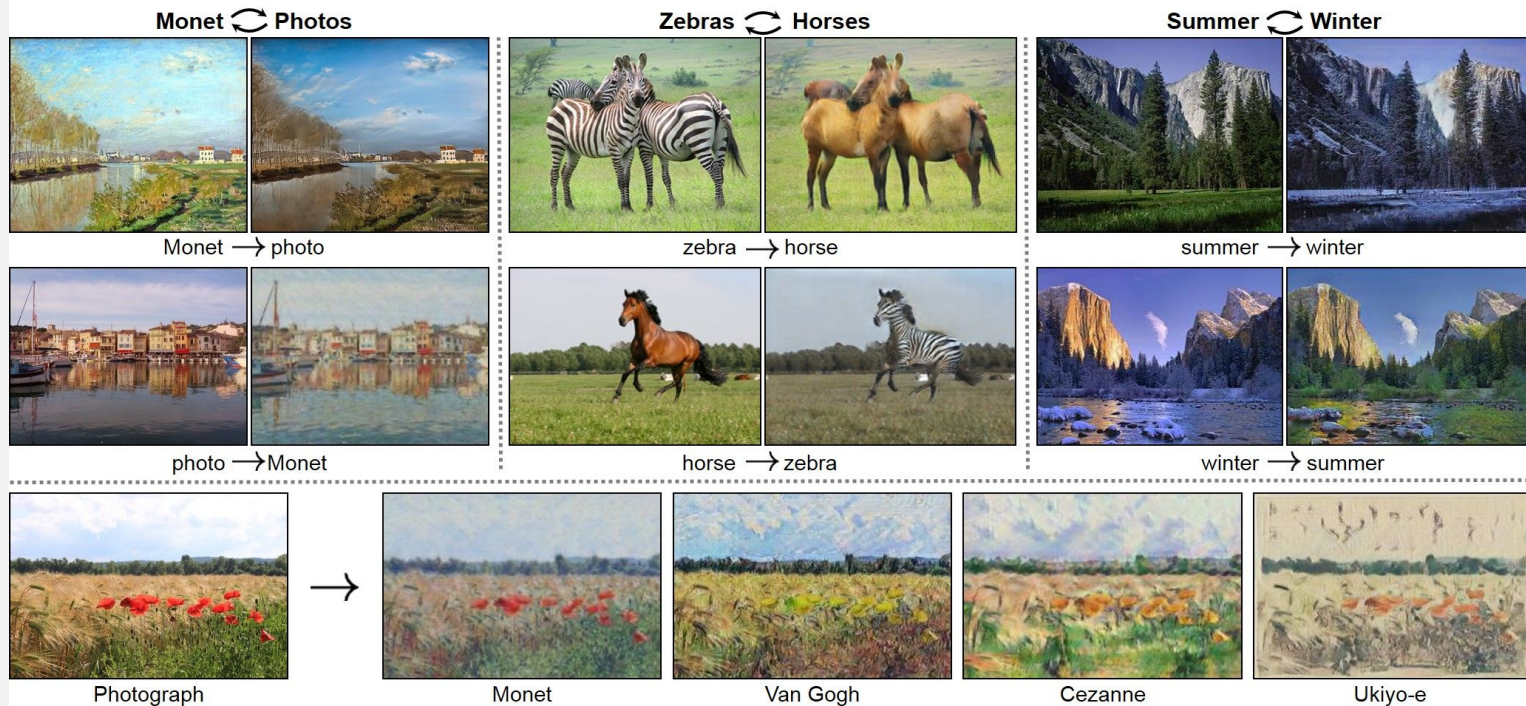
Cycle Consistency Loss: preserve the  
con

$$\mathcal{L}_{\text{cyc}}(G, F) = \mathbb{E}_{x \sim p_{\text{data}}(x)} [\|F(G(x)) - x\|_1] \\ + \mathbb{E}_{y \sim p_{\text{data}}(y)} [\|G(F(y)) - y\|_1]$$

Two empirical assumptions:

- content is easy to keep.
- style is easy to change.

# Results





# Results

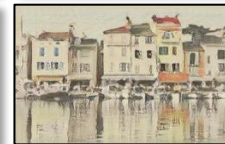
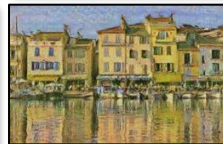
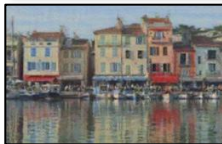
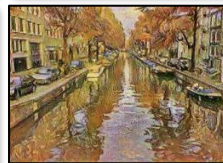
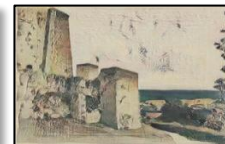
Input

Monet

Van Gogh

cezanne

Ukiyo-e



# THANKS!

**Any questions?**

You can find us at [analyticsclub.iitm@gmail.com](mailto:analyticsclub.iitm@gmail.com)