

Contents

1	Basic Terminologies	4
1.1	Population	4
1.2	Sample	4
1.3	Histogram	4
2	Law of large numbers	5
2.0.1	Weak Law of large numbers	5
2.0.2	Strong Law of large numbers	5
3	Central-Limit Theorem	6
4	Types of Data	6
4.1	Qualitative Data	6
4.1.1	Nominal	6
4.1.2	Ordinal	6
4.2	Quantitative Data	6
4.2.1	Discrete	6
4.2.2	Continuous	6
5	Measure of Central Tendency	7
5.1	Mean/Expected Value	7
5.2	Median	7
5.3	Mode	7
6	Measure of Spread	7
6.1	Variance	7
6.2	Standard Deviation	8
6.3	Inter Quartile Range(IQR)	8
7	Probability Distributions	8
7.1	Discrete Distributions	8
7.2	Continuous Distributions	9
8	Discrete Probability Distributions	9
8.1	Benoulli Distribution	9
8.1.1	Probability Mass Function(PMF)	9
8.1.2	Statistical Parameters	9

8.1.3	Examples	10
8.2	Binomial	10
8.2.1	Probability Mass Function(PMF)	10
8.2.2	Statistical Parameters	11
8.2.3	Examples	11
8.3	Negative-Binomial	12
8.4	Multinomial	12
8.5	Geometric	12
8.6	Hypergeometric	12
8.7	Poisson	12
8.8	Discrete Uniform	12
8.8.1	Use cases	12
9	Shape fo the Distributions	12
9.1	Skewness	12
9.1.1	Right-skewed	12
9.1.2	Left-skewed	12
10	Evaluation Metrics for Regression	12
10.1	Mean Absolute Error	12
10.1.1	Gradient of MAE	13
10.2	Mean Squared Error	13
10.2.1	Gradient of MSE	13
10.3	Root Mean Squared Error(RMSE)	13
10.3.1	Gradient of RMSE	14
10.4	R-Square(R^2)	14
10.5	Adjusted R^2	15
10.6	Mean Absolute Percentage Error(MAPE)	15
10.7	Huber Loss	16
10.7.1	Gradient of Huberloss	16
11	Evaluation Metrics for Classification	16
11.1	Basic Terminologies	16
11.2	Accuracy	17
11.3	Precision	17
11.4	Negative Predicted Value (NPV)	17
11.5	Recall	18
11.6	Specificity	18

11.7 F-score	18
11.7.1 Derivation	18
12 AUC-ROC curve	19
12.1 (ROC)	19
13 Regularization	19
13.1	19
14 Hypothesis Testing	19
15 TODO	19

Statistics For Data Science

Akash Tesla

July 2025

1 Basic Terminologies

1.1 Population

An entire set of items you want to study

1.2 Sample

A subset of population used to estimate statistical behavior of the whole population

1.3 Histogram

A histogram is a graphical representation of numerical data that groups the data into bins and displays the frequency of data points within each bin as bars

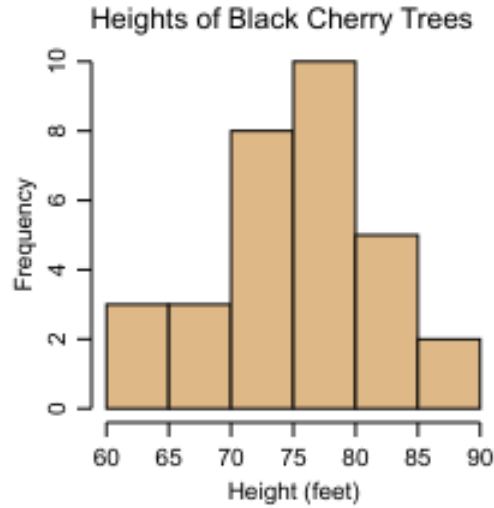


Figure 1: Example of a Histogram

2 Law of large numbers

As the number of trials (or samples) increases, the sample average (or empirical mean) will converge to the expected value (or population mean).

2.0.1 Weak Law of large numbers

The weak law states that the sample average of a sequence of independent identically distributed (i.i.d.) random variables converges in probability to the expected value as the number of samples goes to infinity

$$\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i \xrightarrow{p} \mu \quad \text{as } n \rightarrow \infty$$

which means,

$$\forall \varepsilon > 0, \lim_{n \rightarrow \infty} \mathbf{P}(|\bar{X}_n - \mu| > \varepsilon) = 0$$

2.0.2 Strong Law of large numbers

The strong law states that the sample average of a sequence of i.i.d. random variables converges almost surely to the expected value as the number of samples goes to infinity

$$\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i \xrightarrow{a.s.} \mu \quad \text{as } n \rightarrow \infty$$

Which means,

$$P(\lim_{n \rightarrow \infty} \bar{X}_n = \mu) = 1$$

3 Central-Limit Theorem

4 Types of Data

4.1 Qualitative Data

Describes Qualities, Characteristics, or categories

4.1.1 Nominal

Pure categories without order, Example: blood type(A,B,AB,O), brand names

4.1.2 Ordinal

Categories with meaningful order, Examples: Rank, Survey rating

4.2 Quantitative Data

Measurable quantities, Numbers have meaningful terms in terms of magnitude

4.2.1 Discrete

Countable values, no in-betweens. Examples: number of cars

4.2.2 Continuous

Continuous measurements; can take any value within a range, Examples: Height, weight, temperature

5 Measure of Central Tendency

5.1 Mean/Expected Value

Average of all data points, sensitive to outliers since a single large outlier could easily skew mean

$$\mu = \frac{\sum x_i}{n}$$

5.2 Median

The middle data point when data are stored, robust to outliers

5.3 Mode

The most frequent data point of the dataset

6 Measure of Spread

Range: Difference between minimum value and maximum value

$$Range = x_{max} - x_{min}$$

6.1 Variance

Average squared deviation, Variance represents Expected variance between mean and data points, It's basically MSE of a model that just predicts mean, that kinda gives an intuitive understanding of how it measures spread

$$\sigma^2 = E[(X - \mu)^2]$$

$$\sigma^2 = E[(X - E[X])^2]$$

$$\sigma^2 = E[X^2] - (E[X])^2$$

$$\sigma^2 = \frac{\sum (x_i - \mu)^2}{n} (Population)$$

$$s^2 = \frac{\sum (\bar{x}_i - \mu)^2}{n - 1} (Sample)$$

6.2 Standard Deviation

Root of Variance, RMSE of a model that just predicts mean, standard deviation gives in interpretable terms like RMSE

$$\sigma = \sqrt{\sigma^2}$$

6.3 Inter Quartile Range(IQR)

Difference between 75th Percentile/3rd Quartile and 25th Percentile/1st Quartile, it is used for outlier detection

$$IQR = Q_3 - Q_1$$

We calculate lower bounds and upper bounds to detect the outliers

$$\text{lower bound} = Q_1 - 1.5 \times IQR$$

$$\text{upper bound} = Q_3 + 1.5 \times IQR$$

the data points which values outside of the bounds is considered to be outliers, for more extreme detection $3 \times IQR$ is also used

7 Probability Distributions

7.1 Discrete Distributions

A discrete probability distribution describes the probability of occurrence of each value of a discrete random variable

- Discrete random variable: Countable values like 1,2,3
- Each individual value has an associated probability
- The sum of probabilities for all possible values is 1

$$\sum_i P(X = x_i) = 1$$

7.2 Continuous Distributions

8 Discrete Probability Distributions

8.1 Benoulli Distribution

The benouli distribution is a discrete probability distribution for a random variable which takes only two possibilities, Sucess or a failure

8.1.1 Probability Mass Function(PMF)

$$P(X = x) = \begin{cases} p & \text{if } x=1 \\ 1 - p & \text{if } x=0 \\ 0 & \text{Otherwise} \end{cases}$$

Also written as

$$P(X = x) = p^x(1 - p)^{1-x}, \quad \text{for } x \in \{0, 1\}$$

8.1.2 Statistical Parameters

Mean

Mean is the expected value over many repetitions of the same single-trial experiment, thus it would be p since, p is probability of 1 appearing and $(1-p)$ is probability of 0 appearing

$$\mu = 1 \times (p) + 0 \times (1 - p)$$

$$\mu = p$$

Variance

Variance can be defined as $\sigma^2 = E(X^2) - (E(x))^2$, Refer Variance chapter. For Bernoulli distribution, $E(X^2) = p$, $E(X) = p$, substituting we get

$$\sigma^2 = p - p^2$$

$$\sigma^2 = p(1 - p)$$

Mode

Mode for Bernoulli would what ever the outcome which is more favored, which can be defined as

$$Mode = \begin{cases} 1 & \text{If } p > 0.5 \\ 0 & \text{If } p < 0.5 \end{cases}$$

8.1.3 Examples

- Will it rain tomorrow?
- Will this patient recover?
- Will this product be defective?

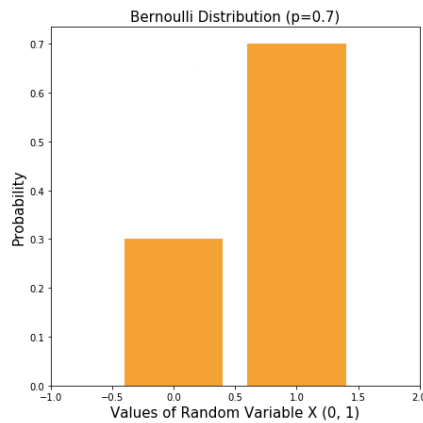


Figure 2: Example of a Bernoulli Distribution

8.2 Binomial

Binomial Distribution is a discrete probability distribution that models the probability of obtaining a specific number of successes in a fixed number of independent trials(n), these independent trials are just Bernoulli trials, you could see the similarity between them in statistical parameters

8.2.1 Probability Mass Function(PMF)

$$P(X = x) = nCx \times p^x \times (1 - p)^{(n-x)}$$

where,

n - no of trials,

p - probability of success

x - number of success

8.2.2 Statistical Parameters

Mean

Mean represents Average number of success from your trials which would be number of trials (n) times probability of success (p)

$$\mu = n \times p$$

Variance

Variance represents Expected variance between mean and data points,

$$\sigma^2 = n \times p \times (1 - p)$$

Mode

$$Mode = \begin{cases} \text{floor}((n+1)p) & \text{if } (n+1)p \text{ is not an Integer} \\ \text{floor}((n+1)p), \text{floor}((n+1)(1-p)) & \text{if } (n+1)p \text{ is an Integer} \end{cases}$$

$$\text{Mode(if } p = 0.5) = \begin{cases} \frac{n}{2} & \text{if } (n+1)p \text{ is not an Integer} \\ \frac{(n-1)}{2}, \frac{(n+1)}{2} & \text{if } (n+1)p \text{ is an Integer} \end{cases}$$

8.2.3 Examples

- How many patients will recover out of 50?
- How many rainy days this month?
- How many defective products in a batch of 1000?

8.3 Negative-Binomial

8.4 Multinomial

8.5 Geometric

8.6 Hypergeometric

8.7 Poisson

8.8 Discrete Uniform

8.8.1 Use cases

- When there is only one trial
- When the outcome is binary True/False Yes/No

9 Shape fo the Distributions

9.1 Skewness

Measure of Asymmetry

9.1.1 Right-skewed

tail on the right (*mean* > *median*)

9.1.2 Left-skewed

tail on the left (*mean* < *median*)

10 Evaluation Metrics for Regression

10.1 Mean Absolute Error

$$MAE = \frac{1}{n} \sum |y_i - \hat{y}_i|$$

- Robust to outliers, treats all errors equally doesn't square the errors like RMSE,MSE..etc

- It's used when your model can tolerate moderate outliers
- Interpretability - Has same unit as the thing you are predicting/easy to understand
- Gives out constant gradient (bad for gradient based loss function)

10.1.1 Gradient of MAE

$$\frac{d}{d\hat{y}}|y - \hat{y}| = \begin{cases} +1 & \text{if } \hat{y} < y \\ -1 & \text{if } \hat{y} > y \\ \text{undefined} & \text{if } \hat{y} = y \end{cases}$$

As you can see no matter how far the error is from true value it always gives a constant gradient as it treats every error as same stics

10.2 Mean Squared Error

$$MSE = \frac{1}{n} \sum (y_i - \hat{y}_i)^2$$

- Penalizes large errors/outliers
- Gives out strong gradient signals

10.2.1 Gradient of MSE

$$\frac{dMSE}{d\hat{y}} = -\frac{2}{n}(y - \hat{y})$$

It points in the direction of the error, and it grows linearly with size of the error Larger the gradient, when prediction are more wrong → model adjusts faster

10.3 Root Mean Squared Error(RMSE)

$$RMSE = \sqrt{MSE}$$

- It combines interpretability of MAE and sensitive to errors of MSE
- It has smooth gradient curves just like MSE, and it's preferred for gradient descent

10.3.1 Gradient of RMSE

$$\frac{dRMSE}{\hat{y}_i} = \frac{1}{n \times RMSE}(\hat{y}_i - y_i)$$

1. The gradient strength changes with RMSE, if your RMSE is very large the gradient becomes small, and if your RMSE is very small the gradient becomes large.
2. It makes RMSE a Non-constantly scaled loss
3. MSE is preferred over RMSE in training, but RMSE is preferred while reporting for interpretability

10.4 R-Square(R^2)

R^2 is the coefficient of determination. it tells how well your regression model explains the variation in the dependent variable(Y) using independent variables(X)

$$R^2 = 1 - \frac{SS_{res}}{SS_{tot}}$$

where,

- $SS_{res} = \sum(y_i - \hat{y}_i)^2 \rightarrow$ Residual sum of squares(error)/MSE
- $SS_{tot} = \sum(y_i - \bar{y}_i)^2 \rightarrow$ Total sum of squares (total variability)

$$R^2 = 1 - \frac{\sum(y_i - \hat{y}_i)^2}{\sum(y_i - \bar{y}_i)^2}$$

Or, it can also be written more intuitively as

$$R^2 = 1 - \frac{MSE}{\sigma^2}$$

- Let us understand the formula (1-) operator just switches from maximizing to minimizing so you can ignore that.
- $\frac{MSE}{\sigma^2}$ Explains how well our model performs to a model that just predicts mean everytime, so if the ratio is 1, then our model is same as the dumb model, we have to reduce the ratio but the world likes "more the better" approach add (1-) operator we have to maximize the error and it's called as R^2

- R^2 ranges from $(-\infty, 1]$

10.5 Adjusted R^2

$$R_{adj}^2 = 1 - \left(\frac{(1 - R^2)(n - 1)}{n - k - 1} \right)$$

The above mentioned is textbook formula but we use our simplified representation for R^2

$$R^2 = 1 - \frac{MSE}{\sigma^2}$$

so, R_{adj}^2 would be

$$R_{adj}^2 = 1 - \frac{MSE_{adj}}{\sigma_{adj}^2}$$

MSE adjusted accounts for the number of freedoms used up to predict the data, which is K, represents number of parameters like number of predictors, number of bias

$$MSE_{adj} = \frac{\sum (y_i - \hat{y}_i)^2}{n - k}$$

Variance adjusted for number of freedoms used up which is 1 (mean), thus it'd be n-1 insted of n

$$\sigma_{adj}^2 = \frac{\sum (y_i - \mu)^2}{n - 1}$$

Substituting we get,

$$R_{adj}^2 = 1 - \left(\frac{MSE}{\sigma^2} \times \frac{n - 1}{n - k} \right)$$

where

- n - number of samples/ training samples
- k - number of parameters

10.6 Mean Absolute Percentage Error(MAPE)

MAPE is a metric used to measure accuracy of a predictive model. It expresses the prediction error as the percentage of actual values

$$MAPE = \frac{1}{n} \sum_{i=1}^n \left| \frac{y_i - \hat{y}_i}{y_i} \right| \times 100$$

MAPE is just like MAE but it gives out the error in percentage thus it's easier to interpret

10.7 Huber Loss

Huber loss is a robust loss function/evaluation metric that has both strengths of MAE and MSE

$$L_{\delta} = \begin{cases} \frac{1}{2}(y - \hat{y})^2 & \text{for } |y - \hat{y}| \leq \delta \\ \delta \cdot (|y - \hat{y}| - 1/2\delta) & \text{otherwise} \end{cases}$$

where,

- δ is a hyperparameter that controls the behavior between MSE and MAE behavior

10.7.1 Gradient of Huberloss

$$\frac{\partial L}{\partial \hat{y}} = \begin{cases} -(y - \hat{y}) & \text{if } |y - \hat{y}| \leq \delta \\ -\delta \cdot \text{sign}(y - \hat{y}) & \text{otherwise} \end{cases}$$

example graph goes here

11 Evaluation Metrics for Classification

11.1 Basic Terminologies

True Positive

Correctly predicted positive class

False Positive

Falsely Predicted Positive class, actually negative

True Negative

Correctly predicted negative class

False Negative

Falsely predicted negative class, actually positive

11.2 Accuracy

Out of all predictions how many are correct, ratio between correct predictions and total predictions is accuracy

$$Accuracy = \frac{\text{Correct predictions}}{\text{Total predictions}}$$

can also be written as,

$$Accuracy = \frac{TP + TN}{TP + TN + FP + FN}$$

11.3 Precision

Out of all my positive class prediction how much did I get correctly, ratio between correct positive class prediction and total positive class predicted

$$\text{Precision} = \frac{\text{No of correct positive class predicted}}{\text{No of positive class predicted}}$$

can also be written as,

$$\text{Precision} = \frac{TP}{TP + FP}$$

Use when FP is costly, when you want every positive prediction to be trust worthy, measures reliability

11.4 Negative Predicted Value (NPV)

Out of all my negative predictions how much did I get correctly, ratio between

$$NPV = \frac{\text{No of correct negative class predicted}}{\text{No of negative class predicted}}$$

can also be written as,

$$NPV = \frac{TN}{TN + FN}$$

Use when FN is costly, when you want every negative class to be trust worthy

11.5 Recall

Out of all positive cases how many did I predict correctly, ratio of correctly predicted positive class and total positive cases

$$\text{Recall} = \frac{\text{No of correctly predicted positive class}}{\text{No of actual positive class}}$$

$$\text{Recall} = \frac{TP}{TP + FN}$$

Use when FN is costly/ wrongly classifying , did it recall everything, predict all positive cases

11.6 Specificity

Out of all negative cases how many did I predict correctly, Basically Recall for negative class

$$\text{Specificity} = \frac{\text{No of correctly predicted negative class}}{\text{No of actual negative class}}$$

$$\text{Specificity} = \frac{TN}{TN + FP}$$

Use when FP is costly, when predicting negative class is important

11.7 F-score

It's a harmonic mean between precision and recall

$$F_{\beta} = \frac{(1 + \beta^2) \cdot \text{Precision} \cdot \text{Recall}}{(\beta^2 \cdot \text{Precision}) + \text{Recall}}$$

11.7.1 Derivation

$$\frac{1}{F_{\beta}} = \frac{w_p}{\text{Precision}} + \frac{w_r}{\text{Recall}}$$

We want harmonic ratio of precision and recall,

$$\frac{w_r}{w_p} = \beta^2$$

We want the weights to add up to one

$$w_r + w_p = 1$$

By solving we get

$$w_r = \frac{\beta^2}{1 + \beta^2}$$
$$w_p = \frac{1}{1 + \beta^2}$$

12 AUC-ROC curve

12.1 (ROC)

13 Regularization

13.1

14 Hypothesis Testing

15 TODO

1. types of data, pca
2. complete the Distributions, some intro to probability
3. p-value and how to make conclusions with stats
4. central limit theorem,
5. Time series, ML, other stuff