Suppose you fit a Bayesian model to a set of data and your posterior includes three variables X, Y, and Z whose joint posterior is Multivariate Normal with mean (0,0,0) and covariance matrix

$$\begin{pmatrix} 1 & 0.9 & 0.1 \\ 0.9 & 1 & 0.1 \\ 0.1 & 0.1 & 1 \end{pmatrix},$$

One of the problems with Gibbs sampling is that it moves very slowly when posterior variables are highly correlated. This lab explores this issue.

- 1. What are the posterior complete conditionals for X, Y, and Z?
- 2. Write a Gibbs sampler that alternates updating each of the variables. Provide a trace plot of 1,000 draws for either X or Y. Comment on the trace plot.
- 3. One option for dealing with this high correlation is doing block updates, where multiple variables are updated at once. Give the complete conditionals for (X,Y)|Z and Z|(X,Y), and code a Gibbs sampler where X and Y are updated together (using a random from from a Multivariate Normal), alternating with Z being updated. Provide a trace plot of 1,000 draws for either X or Y and comment on the plot.
- 4. Comment on the difference between the performance of the two Gibbs samplers. Why is the second more efficient?