EEE 208 – Programming for EEE Assist. Prof. Dr. Engin Mendi

Application: Polynomial Roots I

In general, to solve the polynomial $a_n x^n + a_{n-1} x^{n-1} + a_{n-2} x^{n-2} + ... + a_1 x + a_0 = 0$, we can enter <u>all</u> the coefficients (including the 0 ones) in a row vector and then use the function roots.

```
>> coeff = [a_n, a_{n-1}, a_{n-2}, ..., a_1, a_0]
>> roots(coefff)
```

Question: How many roots does a polynomial of order n have?

Application: Polynomial Roots 2

Example: To find the roots of $x^3 - 7x^2 + 40x - 34 = 0$, enter coefficients in a row vector (from the highest power to the lowest one)

So, the roots are x = 1 and $x = 3 \pm 5i$.

Element-by-element multiplication for Arrays, Example

$$\begin{bmatrix} 1 & 2 & 3 \end{bmatrix} \cdot * \begin{bmatrix} 4 \\ 2 \\ 1 \end{bmatrix} = ERROR$$

$$\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \cdot * \begin{bmatrix} 4 \\ 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 4 \\ 4 \\ 3 \end{bmatrix}$$

$$3 \times 1 \cdot * 3 \times 1 = 3 \times 1$$

$$\begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 3 & 3 & 3 \end{bmatrix} \cdot \begin{bmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \\ 1 & 2 & 3 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 3 & 6 & 9 \end{bmatrix}$$
$$3 \times 3. * 3 \times 3 = 3 \times 3$$

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} . ^2 = \begin{bmatrix} 1^2 & 2^2 \\ 3^2 & 4^2 \end{bmatrix}$$

Can be any dimension

Creating Matrices from Vectors

- Suppose a = [2,4,6] and b = [8,10,12] (two
 row vectors)
- > What is the difference between the results given by [a b] and [a;b]?

```
>> c = [a b];
c =
2 4 6 8 10 12
>> d = [a;b]
d =
2 4 6
8 10 12
```

Matrices: an Example

- Suppose we have 3 row vectors, each with 4 columns. Each vector shows <u>a year</u> and each column shows <u>a season</u>. The elements show the <u>average temperature</u> in that season. The whole data arrangement is called a Matrix; here called mean_temp
- Remember, spaces or commas separate elements in different columns, but semicolons separate elements in different rows.

Matrices - Concatenation

$$y1 = [22 \ 30 \ 13 \ 6]$$

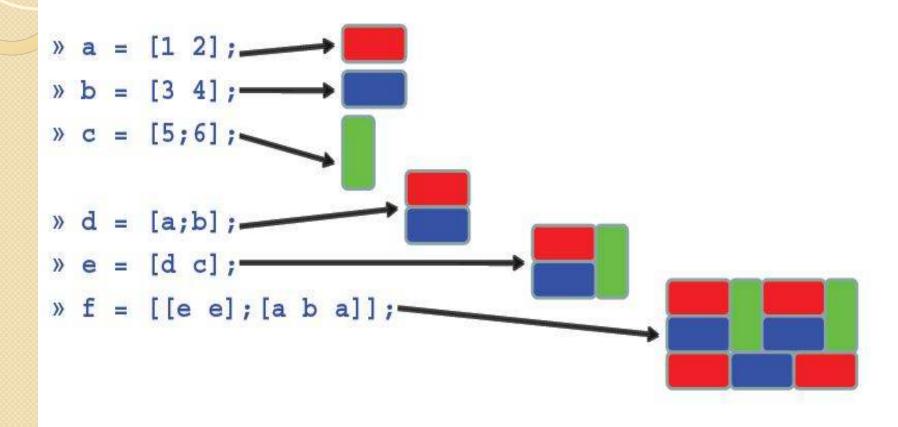
 $y2 = [23 \ 29 \ 12 \ 4]$
 $y3 = [21 \ 31 \ 15 \ 8]$

- > Defining the matrix using row vectors
- $mean_temp = [y1;y2;y3]$
- > Defining the matrix using column vectors

$$s1 = \begin{bmatrix} 22 \\ 23 \\ 21 \end{bmatrix} \qquad s2 = \begin{bmatrix} 30 \\ 29 \\ 31 \end{bmatrix} \qquad s3 = \begin{bmatrix} 13 \\ 12 \\ 15 \end{bmatrix} \qquad s4 = \begin{bmatrix} 6 \\ 4 \\ 8 \end{bmatrix}$$

 \triangleright mean temp = [s1,s2,s3,s4]

Concatenation & Dimension



Size of Matrices

- Size of a matrix is in general expressed in mby-n, where m is the number of rows and n is the number of columns
- \bullet >> size(mean temp) = 3 4
- size (mean temp, 1): number of rows
- size (mean_temp, 2): number of columns
- Length of a matrix= its largest dimension
- >> length(mean_temp) = 4

Element-by-element Multiplication for Matrices

If we have two matrices A and B

$$\mathbf{A} = \begin{bmatrix} 11 & 5 \\ -9 & 4 \end{bmatrix} \qquad \mathbf{B} = \begin{bmatrix} -7 & 8 \\ 6 & 2 \end{bmatrix}$$

• Then C = A.*B equals

$$\mathbf{C} = \begin{bmatrix} 11(-7) & 5(8) \\ -9(6) & 4(2) \end{bmatrix} = \begin{bmatrix} -77 & 40 \\ -54 & 8 \end{bmatrix}$$

Matrix-Matrix Multiplication

- •In the product of two matrices **AB**, the number of *columns* in **A** must equal the number of *rows* in **B**. The row-column multiplications form column vectors, and these column vectors form the matrix result. The product **AB** has the same number of *rows* as **A** and the same number of *columns* as **B**.
- •In summary, if A is a matrix with m rows and n columns, and B is a matrix with n rows and p columns, then C=A*B is a matrix with m rows and p columns

Matrix-Matrix Multiplication: Examples

$$\begin{bmatrix} 6 & -2 \\ 10 & 3 \\ 4 & 7 \end{bmatrix} \begin{bmatrix} 9 \\ -5 \\ 12 \end{bmatrix} = \begin{bmatrix} (6)(9) + (-2)(-5) \\ (10)(9) + (3)(-5) \\ (4)(9) + (7)(-5) \end{bmatrix} (6)(8) + (-2)(12) \\ (10)(8) + (3)(12) \\ (4)(9) + (7)(-5) \end{bmatrix}$$

$$= \begin{bmatrix} 64 & 24 \\ 75 & 116 \\ 1 & 116 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 3 \end{bmatrix} * \begin{bmatrix} 4 \\ 2 \\ 1 \end{bmatrix} = 11$$
$$1 \times 3 * 3 \times 1 = 1 \times 1$$

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} ^2 = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} * \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$$
Must be square to do powers

$$\begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 3 & 3 & 3 \end{bmatrix} * \begin{bmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \\ 1 & 2 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 6 & 9 \\ 6 & 12 & 18 \\ 9 & 18 & 27 \end{bmatrix}$$
$$3 \times 3 \times 3 \times 3 = 3 \times 3$$

Inverse of a Matrix

>> inv(A) returns inverse of the square matrix A.

If A is not a square matrix or if it's a singular matrix, MATLAB returns an error message.

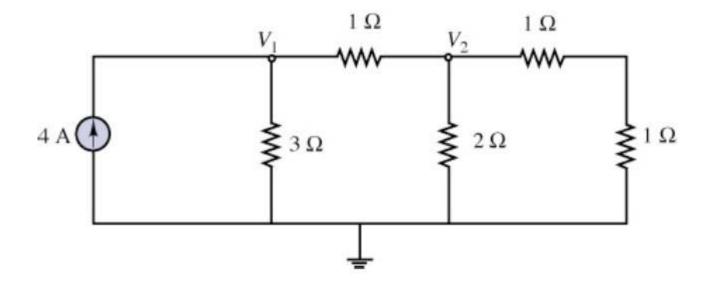
Application: Solving Linear Equations

```
6x + 12y + 4z = 70
7x - 2y + 3z = 5
2x + 8y - 9z = 64
>> A = [6,12,4;7,-2,3;2,8,-9]; \% a 3-by-3
   matrix
>> b = [70;5;64]; % a 3-by-1 vector
>> Solution=inv(A) *b; % a 3-by-1 vector
Or
>> Solution = A\b
Solution =
      3
      -2
```

The solution is x = 3, y = 5, and z = -2.

Class Exercise I

Problem: Find voltages v1 and v2 in the following circuit using the KCL rule.



Class Exercise I, Instructions

- 1. Write two KCL equations for nodes 1 and 2.
- 2. Simplify the equations to find V1 and V2 and write the equations in the matrix form.
- 3. Open a new m-file, define a matrix for coefficients (left-side) and another one for constants (right-side).
- 4. Use matrix operations to find the vector of unknowns.

Special Matrices, I

- >> zeros (m, n) or zeros (n)
- \bullet >> ones(m,n) or ones(n)
- >> eye (m, n) or eye (n): Identity matrix
- Example:
- >> A = [2 -3 0; -1 4 2]
- >> eye(2)*A
- >> B=zeros(size(A))

Special Matrices, 2

•>> diag(v,k): if v is a vector with n components, this is a square matrix of order n+abs(k) with the elements of v on the k-th diagonal. k = 0 is the main diagonal, k > 0 is above the main diagonal and k < 0 is below the main diagonal.

- diag(2)
- diag (3,1)
- diag([2 3],0)
- diag([1 -1 2],2)

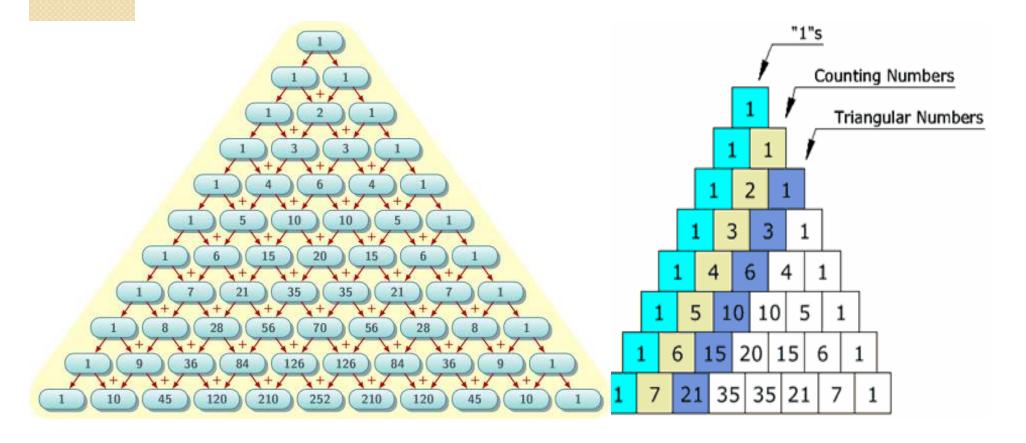
Special Matrices, 3

- >> magic (n): an n-by-n matrix constructed from the integers 1 through n^2 with equal row, column, and diagonal sums. Produces valid magic squares for all n > 0 except n=2.
 >> open magic to see the algorithm and documentation
- Example:

```
for n=1:3
    magic(n)
end
```

Special Matrices, 4

• >> pascal (n) is the Pascal matrix of order N: a symmetric positive definite matrix with integer entries, made up from Khayyam-Pascal triangle. Its inverse has integer entries.



Array Addressing, I

First generate two vectors

```
\circ >> u = 0:0.1:10;
```

- \circ >> w = 5*sin(u);
- >> length(u)
- plot(u,w)

Accessing a Vector's Single Element

Note: MATLAB indexing starts with 1,
 not 0

- >> u (21)
- >> w (90)
- You can also assign values to a single element of a matrix:
- u(50) = 2 * exp(-3);

Array Addressing, 2

• The colon operator selects individual elements, rows, columns, or "subarrays" of arrays.

```
>> v = exp(linspace(1, 2, 10))
```

- v(:) represents all the row or column elements of the vector v.
- v(2:5) represents the second through fifth elements

Array Addressing, 3

- \bullet >> D = [2 4 6; 8 10 12; 14 16 18]
- D(1,3) shows the element on the $1^{\rm st}$ row and $3^{\rm rd}$ column
- D(:,3) denotes all the elements in the third column of the matrix D.
- D(:,1:2) denotes all the elements in the first to second columns of D.
- D(2:3,1:3) denotes all the elements in the second and third rows that are also in the first through third columns.
- u = D(:) creates a vector u consisting of all the columns of D stacked from first to last.
- D (end, :) shows the last row in D, and D(:,end) shows the last column.

Array Addressing, 4

You can use array indices to extract a smaller array from another array.

$$>> C = B(2:3, 3:4)$$

Then C =

 $A = [6 \ 2; -10 \ -5; 3 \ 0]$

array

- >> length (A) computes either the number of elements of A if A is a vector or the largest value of m or n if A is an m×n matrix.
- >> size(A) returns a row vector [m n] containing the sizes of the m-by-n array A.
 Try size(A, 1) and size(A, 2)
- >> find returns indices ...
 find(A>0) or find(x) where x is a logical

```
A = [6 \ 2; -10 \ -5; 3 \ 0]
```

- >> sort (A) Sorts each column of the array A in ascending order and returns an array the same size as A.
- >> sum (A) Sums the elements in each column of the array A and returns a row vector containing the sums.
- >> prod(A) For vectors, prod(A) is the product of the elements of A. For matrices, prod(A) is a row vector with the product over each column.

```
Example: prod(A) and prod(A(1, :))
```

Class Exercise 2

Problem. Open a new m-file and write the codes to create the following vectors:

- Vector a = 2, 4, 6, ..., 20
- Vector b = 1, 1/2, 1/3, ..., 1/9
- Vector c = 0, 1/2, 2/3, 3/4, ..., 8/9
- Vector $d = [10^0 \ 10^1 \ 10^2 \dots \ 10^{0.99} \ 10^1]$ **Hint**. Use the **logspace** command.
- Vector $e = log_{10} (1/d)$

Class Exercise 3

Problem. Open a new m-file and write the codes to create the following vectors. Assign each value to the right variable.

Let $x = [-3 \ 2 \ 6.5 \ -1]$. Create the following vectors:

- x1. Add 13 to each element
- x2. Add 4 to just the odd-index elements
- x3. Compute the square root of each element
- x4. Compute the sum of vector elements.

Class Exercise 4

Problem: Open a new m-file and generate these matrices using zeros, ones, diag, or a combination of them.

•
$$mat_E = \begin{bmatrix} 2 & ... & 2 \\ ... & ... & ... \\ 2 & ... & 2 \end{bmatrix}$$

a 5x5 matrix full of 2's

a 5x5 matrix with 0's everywhere, and elements 1 2 3 2 1 on the diagonal

 $A = [6 \ 2; -10 \ -5; 3 \ 0]$

- >> max (A) Returns the algebraically largest element in A if A is a vector, and returns a row vector containing the largest elements in each column if A is a matrix.
- If any of the elements are complex, max(A) returns the elements that have the largest magnitudes.
- >> [x,k] = max(A) Similar to max(A) but stores the maximum values in the row vector x and their indices in the row vector k.
- >> min(A) and [x,k] = min(A) are similar to max but returns minimum values.

- $B = [2 \ 3i; 2-4i \ 5]$
- >> transpose (B) or B.' returns the non-conjugate transpose of B.
- >> B' returns the transpose and the conjugate of complex elements
- >> rand (m, n) returns an m-by-n matrix with pseudorandom values drawn from the standard uniform distribution on the open interval(0,1)
- >> nan(m,n) or NaN(m,n) returns a matrix of
 NaNs (useful for representing uninitialized variables)

- >> reshape (x,m,n) returns the m-by-n matrix whose elements are taken columnwise from x.
- Try reshape (A, 6, 1) and reshape (A, 2, 3)
- reshape changes the size, but not the values or order of the data in memory.

```
- >> C = [ 3  4.2  8 ; -6.7  12  0.75 ];
```

 \blacksquare >> D = reshape(C, [3 2]);

Name =
$$'C'$$
 Name = $'D'$

Size =
$$[2\ 3]$$
; Size = $[3\ 2]$;

>> round(3.4), round(5.65)

round (A) rounds the elements of A to the nearest integers.

>> floor(3.4), floor(5.65)

floor (A) rounds the elements of A to the nearest integers towards $-\infty$.

>> ceil(3.4), ceil(5.65)

ceil (A) (ceiling) rounds the elements of A to the nearest integers towards $+\infty$.

>> rand(n) or rand(m,n) return values drawn from the standard uniform distribution on the open interval(0,1).

Example:

- >> mat = rand(4,5);
- >> mat(end, end) % gives the last element
- >> mat([1 end],[end-2:end]) % from the first and last row, gives elements from the last 3 columns

>> randn(n) or rand(m,n) return values drawn from the standard normal distribution

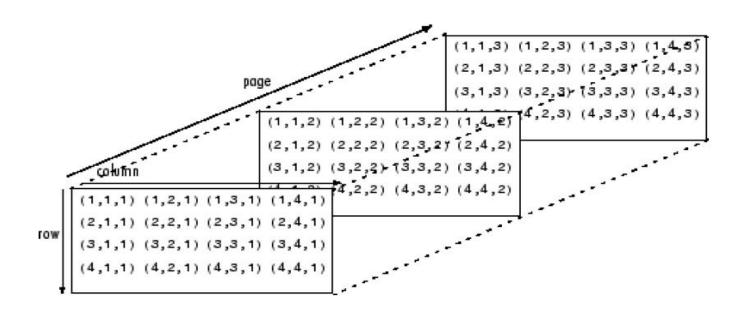
Array Functions: Practice

```
>> M = magic(4)
>> vec = reshape(M, 1, prod(size(M)))
%Finds the number of elements in M, and
 puts them in a row vector
>> [min value, min index] = min(vec)
%extracts the values and index of minimum
 elements
\gg N = rand(4,3)
\rightarrow ind=find(N>0.5)
>> [rowind, colind] = find(N>0.5)
```

Multidimensional Arrays - Pages

- The row and column vectors have one dimension (1D), like the axis of real number
- Matrices have two dimensions (2D), like the Cartesian plane
- But sometimes we need to use a database with more than 2 features (properties). In this case, we can create an array with 3 or more dimensions. Think of it as a book with several pages.

Multidimensional Arrays - Pages



Consists of two-dimensional matrices "layered" to produce a third dimension. Each "layer" is called a page

cat (n, A, B, C, ...) creates a new array by concatenating the arrays A, B, C, and so on along the dimension n.

Multidimensional Arrays: Example

```
>> A = eye(4)
>> B = magic(4)
>> page_mat = cat(3,A,B)

>> size(page_mat) = 4 4 2
This size shows the number of rows, columns, and pages
```

 $>> page_2 = cat(4,A,B)$

What is the size now?

With these two matrices, one dimension becomes extra

Function rat

- rat returns the *rational fraction approximation*
- In Rational numbers, the nominator and denominators are integers.
- >> rat(0.3333)
- >> rat(pi)
- >> rat(e)

Function rats

- rats returns a string containing *simple rational* approximations
- >> rats(0.3333)
- >> rats(pi)
- >> rats(e)
- In CE_08, compare rat and rats:

```
>> b = 1./[1:9]
```

- >> rat(b)
- >> rats(b)
- >> c = [0:8]./[1:9]
- >> rat(c)
- >> rats(c)