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● 65 Commanda Way, Ottawa K1M 1E7

SUMMARY OF QUALIFICATIONS

- First-year MEng in mechanical engineering student at the University of Ottawa.
- Excellent individual and teamwork skills honed through years of experience in various projects.
- o Research and analysis skills developed by working on my Bachelor of Science thesis for two years.
- The broad scope of robotics expertise allows for a rapid and complete comprehension of projects.

EDUCATION

• Master of Engineering, Mechanical Engineering (Robotics)

University of Ottawa, ON

SEP 2022 - Until now

o Relevent Courses: Biomechanics of Movements, Digital Signal Processing, Applied Artificial Intelligence

• Bachelor of Science, Mechanical Engineering (Robotics)

University of Isfahan, Isfahan

SEP 2016 - OCT 2020

- Bachelor's Theses: Using Deep Reinforcement Learning algorithms to push an object with robotic Manipulators Supervisor: Dr. Karimpour Grade:20/20
- o Overall GPA: 3.46
- Relevent Courses: Computer Programming, Dynamics, Dynamics of Mechanics, Mechanical Vibration, Automatic Control, Robotics, Artificial Intelligence and Expert Systems, Simulation of Dynamic Systems, and Control
- o Relevent Courses from MSc Programs(voluntary Participation): Digital Image Processing, Robotics

SKILLS

• Engineering Skills

- o Robotics: Robot Operating System(ROS), Gazebo, MoveIt, MuJoCo, OpenSim, LabVIEW
- Machine Learning: TensorFlow, PyTorch, scikit-learn
- o Computer Vision: OpenCV, Matlab Image Processing Toolbox
- o Digital Signal Processing: MATLAB DSP System Toolbox, FIR and IIR filters, FMCW Radars
- o Linear control system design: Lead-Lag and PID Controllers
- o Embedded Systems: Raspberry Pi, NVIDIA Jetson TX1, Arduino
- o Operating Systems: Ubuntu, Windows, Debian
- o Familiarity with Web, and Android development: Tailwind CSS, React, Django, SQL, Android Studio

Languages

- o **Programming:** Python, JavaScript, C++, Java
- Markup: LATEX, HTML, CSS, XML, YAML, SQL

Soft Skills

- o Quick Learner: Constantly keen to learn new things, especially in my area of interest.
- Passionate to work in teams: With numerous projects completed in teams and experience with Git and Docker to speed up and organize DevOps in groups, teamwork skills have advanced.

RESEARCH INTERESTS

- Machine Learning
- Computer vision
- Robotics and Simulation
- Digital Signal Processing

- Control System Design
- Biomechanics
- Autonomous vehicles
- Embedded systems programming

RELEVANT WORK EXPERIENCE

• Robotics Researcher

Research Team Member — University Of Isfahan, Isfahan

JAN 2019 - JAN 2021

- Reconstruction of a homemade 3 DOF robot and servo motor drivers connection to Advantech PCI cards.
- o Operation of the robot with ROS and its simulation in the Gazebo software.
- Development of a controller and motion planner for it in the ROS environment.

• Computer Vision Engineer

Internship — Novinilya Company, Isfahan

JUN 2019 - AUG 2019

- Examination of the surface quality of the parts on the mass production at the plants.
- o Object recognition with embedded boards like Jetson TX1 and industrial Basler cameras in the company's R&D team.

ACADEMIC PROJECTS

• Artificial Intelligence

- o Twin Delayed DDPG (TD3) algorithm implementation for the Ant robot in MuJoCo (in Gym library) to run forward.
- Evolutionary algorithms Implementation, including the Differential Evolution Algorithm (DE) and the Multi-Verse Optimizer (MVO).
- Implementation of DDPG and TD3 algorithms in my B.Sc. thesis to push objects to their desired goal in a simulated environment with the help of hindsight experience replay paper.
- Implementation of deep Q-Networks in a four-player fruit-eating game for an Al competition.
- o Using K-means and KNN in Scikit-Learn for the Classification of cities' weather as dry or humid using unlabeled data

• Image Processing and Computer Vision

- o Implementation of the AlexNet architecture for image classification on the MNIST and CIFAR-10 datasets.
- Designing filters in the frequency and spatial domain in both OpenCV and MATLAB.
- Android software development to recognize chosen cap colors and program an Arduino board to sort plastic bottle caps.

Robotics

- Building a line-following robot with an Android phone and an Arduino to find road directions by image processing.
- o Worked with KUKA LBR iiwa at Isfahan University of Technology (IUT)

• Digital Signal Processing

• FMCW radar simulation for autonomous vehicles to detect objects' movement within 300 meters.

• Systems and Controls

- o Designing a PID controller for a simulated 3-DOF robot in ROS (used in the B.Sc. thesis).
- Using LabVIEW for the implementation of keyboard-based control with PID control.
- \circ Controlling servomotors in torque mode using MATLAB for system identification and the design of a PID and lead-lag controller.

LANGUAGES

• English

o IELTS Academic: 6.5 Overall DEC 2021

REFERENCE

•Dr. Karimpour

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• Dr. Karshenas

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