

# Computational Methods for Ideal Magnetohydrodynamics

Andrew Kercher

A defense of the dissertation submitted in partial fulfillment of the requirements  
for the degree of Doctor of Philosophy  
George Mason University

25 August 2014

# Introduction

- Compound wave formation in MHD bow shock simulations.

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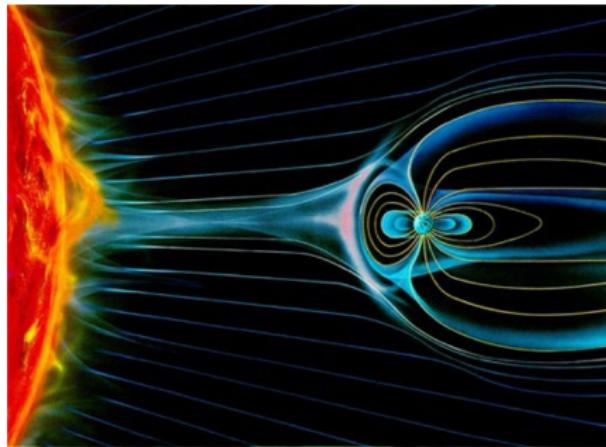
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- Compound wave product of numerical diffusion.
- Slow convergence with finite volume schemes.
- Compound wave modification (CWM).
  - ▶ Modification to the HLLD approximate Riemann solver.
  - ▶ Removes compound wave, correctly computes rotational discontinuity.
  - ▶ Converges at all grid resolutions.
  - ▶ FAST! HLLD intermediate states are already calculated.

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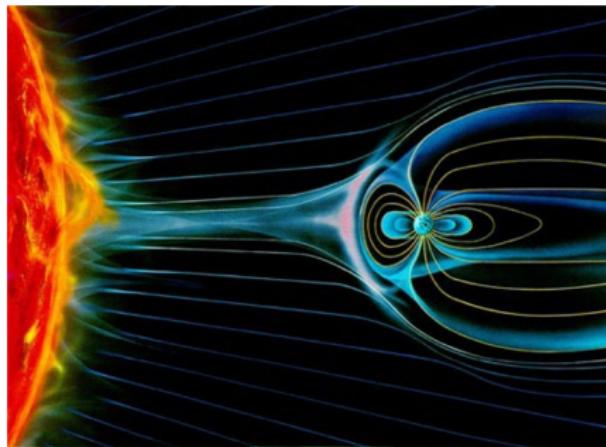
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- Description multi-dimensional fluid solver capable of shared memory parallelism.
  - ▶ Hydrodynamics and ideal MHD.
  - ▶ Algorithms implemented for unstructured grids.

# Space Weather



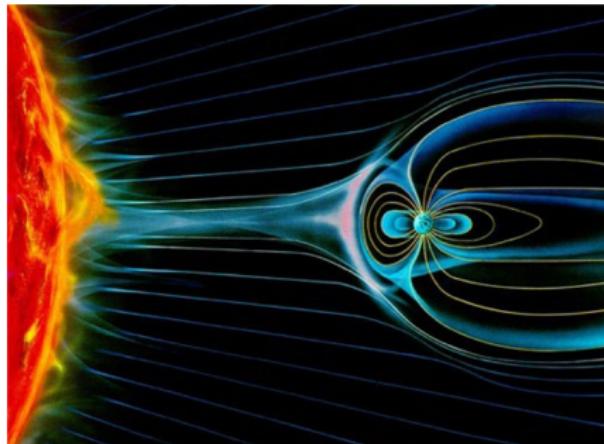
- Sun-earth interaction:

# Space Weather



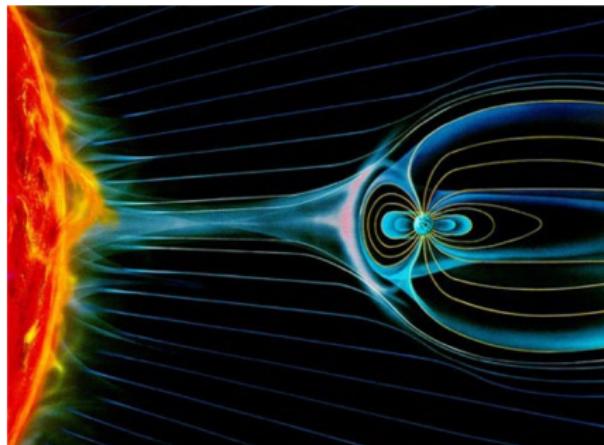
- 2D ideal MHD bow shock simulation. [1]
  - ▶ Results contained intermediate shocks.

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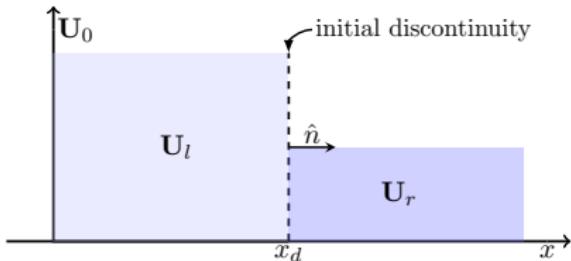
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# Space Weather



- 2D ideal MHD bow shock simulation. [1]
  - ▶ Results contained intermediate shocks.
  - ▶ Intermediate shocks considered inadmissible in ideal MHD [5]
  - ▶ Cause?

# Riemann Problems

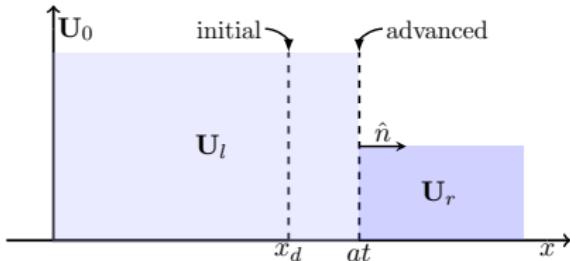


$$\frac{\partial \mathbf{U}}{\partial t} + \frac{\partial \mathbf{F}}{\partial \mathbf{x}} = \mathbf{0},$$

$$\mathbf{U}_0 = \begin{cases} \mathbf{U}_l & \text{if } x < x_d, \\ \mathbf{U}_r & \text{if } x > x_d, \end{cases}$$

- Initial discontinuity at  $x_d$  separates two constant states.

# Riemann Problems



$$\frac{\partial \mathbf{U}}{\partial t} + \frac{\partial \mathbf{F}}{\partial \mathbf{x}} = \mathbf{0},$$

$$\mathbf{U}_0 = \begin{cases} \mathbf{U}_l & \text{if } x < x_d, \\ \mathbf{U}_r & \text{if } x > x_d, \end{cases}$$

- Solution at time  $t$ .
- Wave speed:  $a$ .

$$\mathbf{U} = \begin{cases} \mathbf{U}_l & \text{if } x < at, \\ \mathbf{U}_r & \text{if } x > at, \end{cases}$$

## Compressible hydrodynamics

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0 ,$$

$$\frac{\partial(\rho \mathbf{v})}{\partial t} + \nabla \cdot [\rho \mathbf{v} \otimes \mathbf{v} + p_g] = 0 ,$$

$$\frac{\partial E}{\partial t} + \nabla \cdot [(E + p_g) \mathbf{v}] = 0 ,$$

where the energy density is defined as

$$E = \frac{p_g}{\gamma - 1} + \frac{\rho v^2}{2} ,$$

# Compressible hydrodynamics

The Euler equations are strictly hyperbolic.

1D conservative form

$$\frac{\partial \mathbf{U}}{\partial t} + \frac{\partial \mathbf{F}}{\partial x} = 0.$$

Jacobian  $\mathbf{J}(\mathbf{U}) = \partial \mathbf{F} / \partial \mathbf{U}$  has three real and distinct eigenvalues:

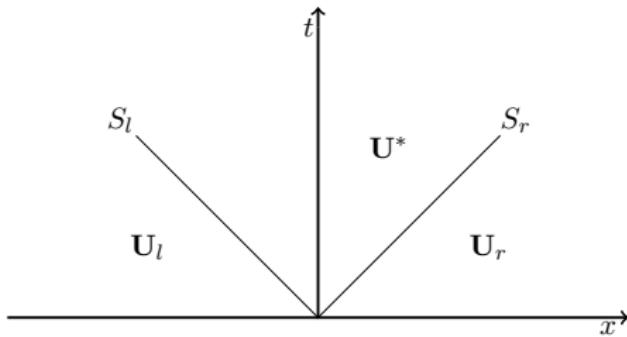
$$\lambda_3 = v_n + a : \text{rarefaction or shock}$$

$$\lambda_2 = v_n : \text{contact discontinuity}$$

$$\lambda_1 = v_n - a : \text{rarefaction or shock}$$

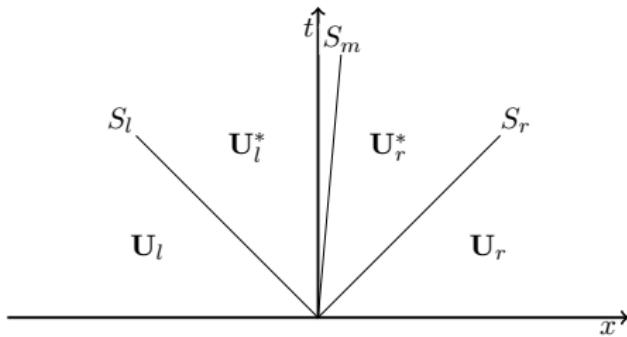
where  $a = \sqrt{\gamma p_g / \rho}$  is the speed of sound.

## HLL family of approximate Riemann solvers



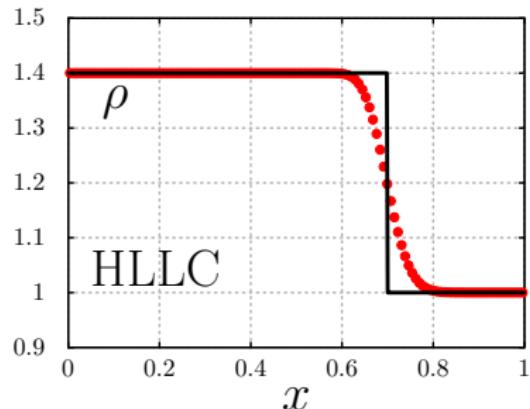
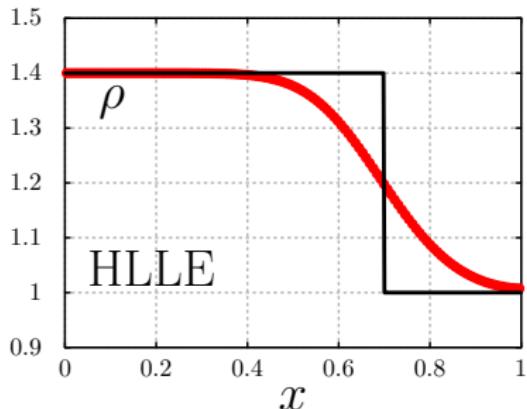
- The solver of Harden-Lax-van Leer-Einfeldt (HLLE) [2] assumes a one state solution.
- The solution approximated as weighted average of the left and right states.

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- HLLC [9] (C for *contact*) restores the contact discontinuity.

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- The solution approximated as weighted average of the left and right states.
- HLLC [9] (C for *contact*) restores the contact discontinuity.
- HLLC less diffuse at contact discontinuity.

## Ideal magnetohydrodynamics

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0 ,$$

$$\frac{\partial(\rho \mathbf{v})}{\partial t} + \nabla \cdot \left[ \rho \mathbf{v} \otimes \mathbf{v} + \left( p_g + \frac{B^2}{2} \right) \mathbf{I} - \mathbf{B} \otimes \mathbf{B} \right] = 0 ,$$

$$\frac{\partial E}{\partial t} + \nabla \cdot \left[ \left( E + p_g + \frac{B^2}{2} \right) \mathbf{v} - \mathbf{v} \cdot \mathbf{B} \otimes \mathbf{B} \right] = 0 , \text{ and}$$

$$\frac{\partial \mathbf{B}}{\partial t} + \nabla \cdot [\mathbf{v} \otimes \mathbf{B} - \mathbf{B} \otimes \mathbf{v}] = 0 ,$$

where the energy density is defined as

$$E = \frac{p_g}{\gamma - 1} + \frac{\rho v^2}{2} + \frac{B^2}{2} ,$$

## Ideal magnetohydrodynamics

The ideal MHD equations are non-strictly hyperbolic. 1D conservative form

$$\frac{\partial \mathbf{U}}{\partial t} + \frac{\partial \mathbf{F}}{\partial x} = 0.$$

Jacobian  $\mathbf{J}(\mathbf{U}) = \partial \mathbf{F} / \partial \mathbf{U}$  has seven real, but not necessarily distinct eigenvalues:

$v_n$  : contact or tangential discontinuity (entropy),

$v_n \pm c_s$  : slow rarefaction or shock,

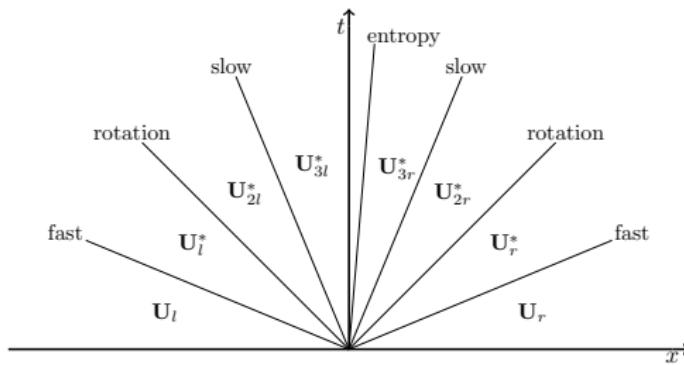
$v_n \pm c_a$  : rotational discontinuity (Alfvén), and

$v_n \pm c_f$  : fast rarefaction or shock,

$$c_{f,s}^2 = \frac{1}{2} \left[ a^2 + c_a^2 + c_t^2 \pm \sqrt{(a^2 + c_a^2 + c_t^2)^2 - 4a^2 c_a^2} \right],$$

$$c_a^2 = \frac{B_n^2}{\rho}, \text{ and } c_t^2 = \frac{B_t^2}{\rho}.$$

# Ideal magnetohydrodynamics



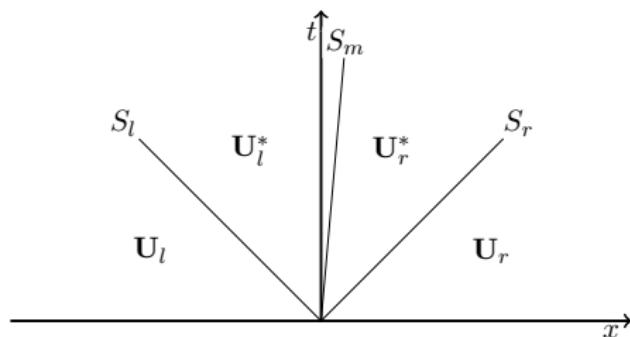
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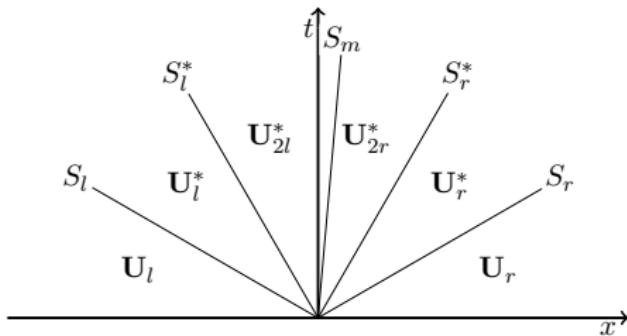
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# Extension of HLLC for MHD



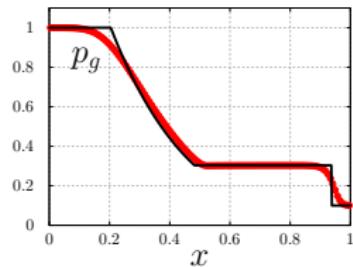
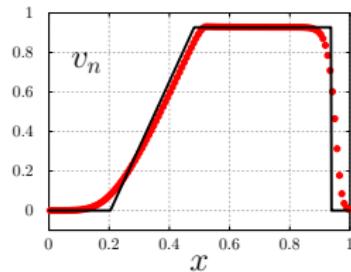
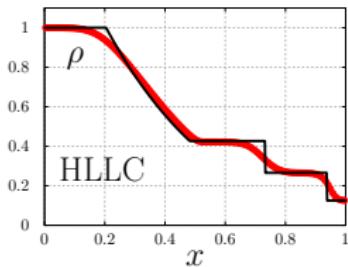
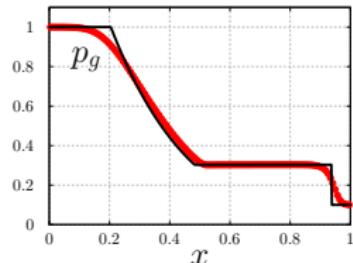
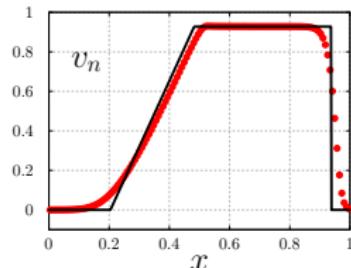
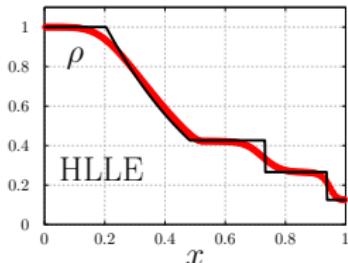
- HLLD [6] (D for *discontinuities*) extention of HLLC to MHD.

# Extension of HLLC for MHD



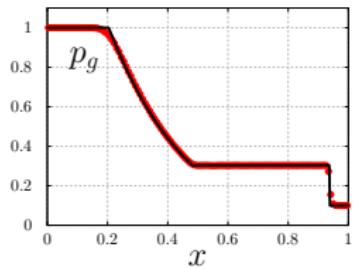
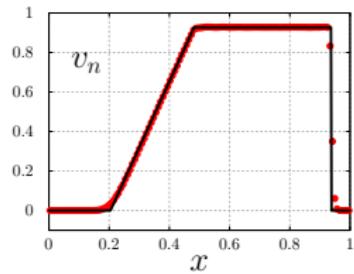
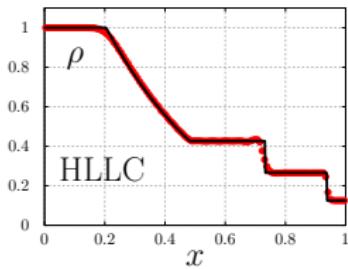
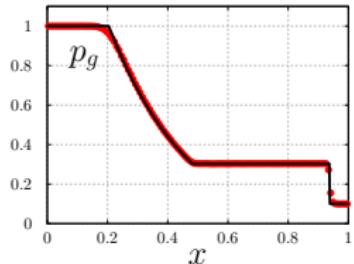
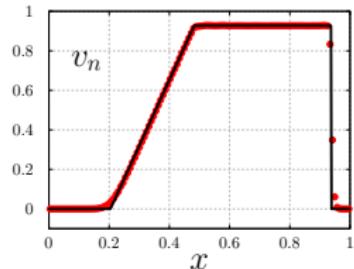
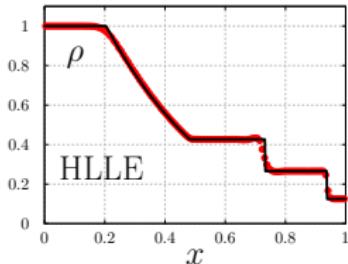
- HLLD [6] (D for *discontinuities*) extention of HLLC to MHD.
- Captures all linear discontinuities, contact and rotational.

# Higher order extensions



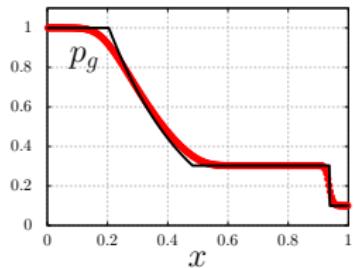
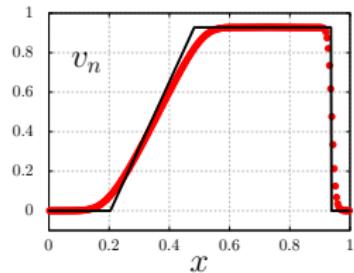
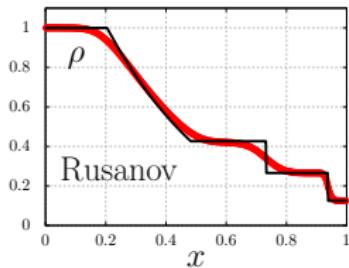
- Increase accuracy and preserve monotonicity.
- Total variation diminishing (TVD).
- Limit slope to ensure no new extrema are created.

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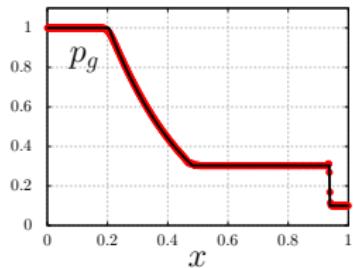
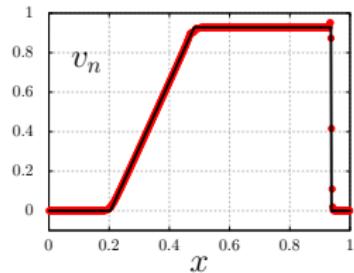
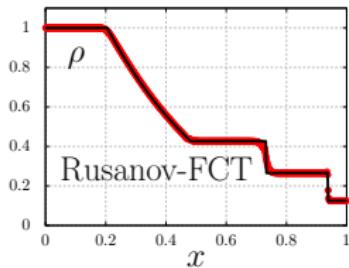
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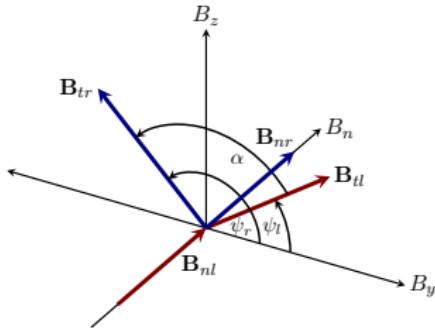
- Increase accuracy and preserve monotonicity.
- Flux corrected transport (FCT).
- Limit fluxes so that no new extrema are created.

# Higher order extensions



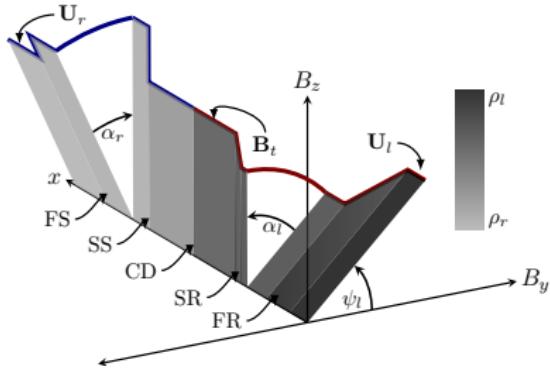
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# Riemann problems of ideal MHD



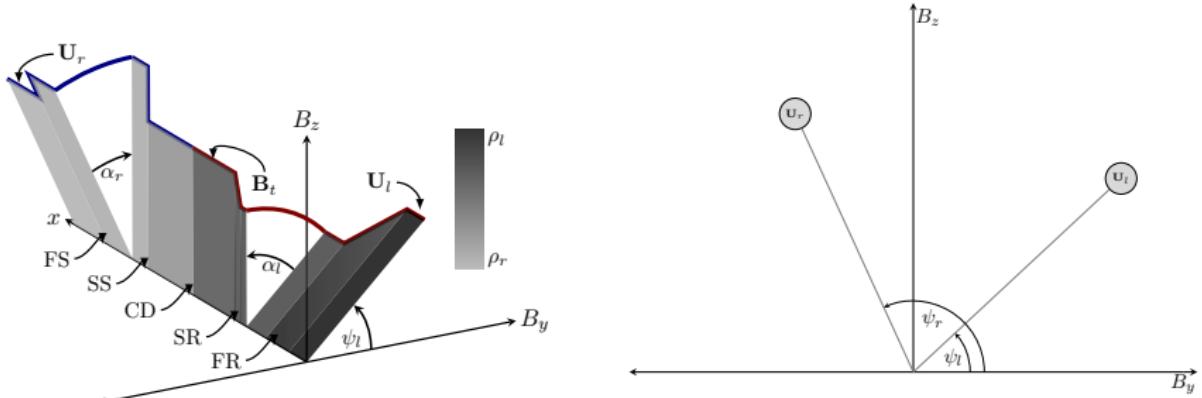
- Initial discontinuity separates two states.
- Rotation angle  $\arctan B_z/B_y$ .
- The initial twist angle  $\alpha = \psi_r - \psi_l$ .

# Riemann problems of ideal MHD



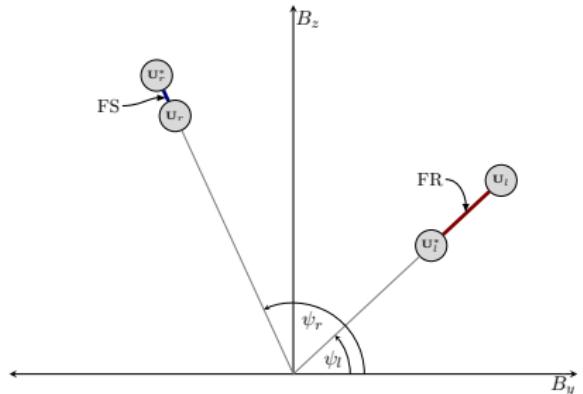
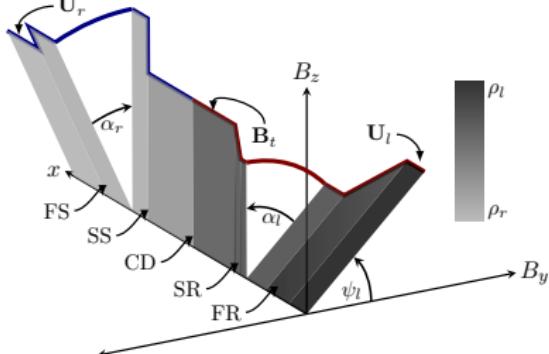
- Seven waves propagate away from initial discontinuity creating eight distinct states.

# Riemann problems of ideal MHD



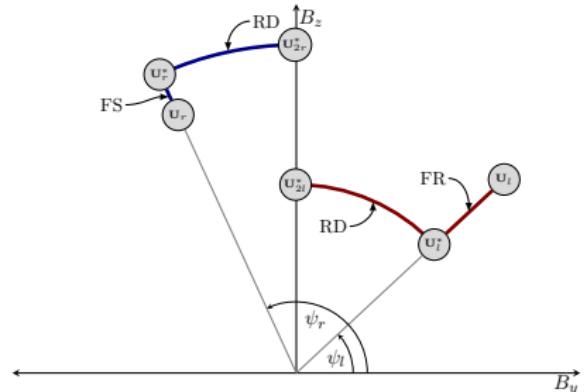
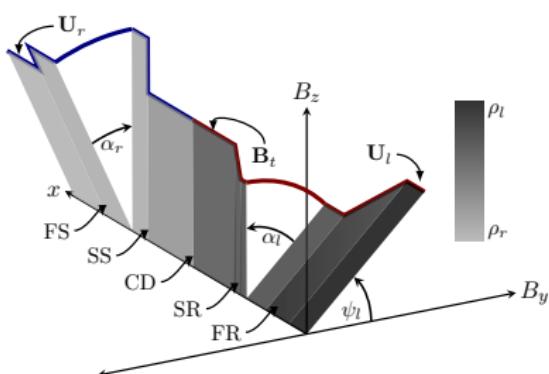
- Regular waves only alter the magnitude or orientation of  $B_t$ .

# Riemann problems of ideal MHD



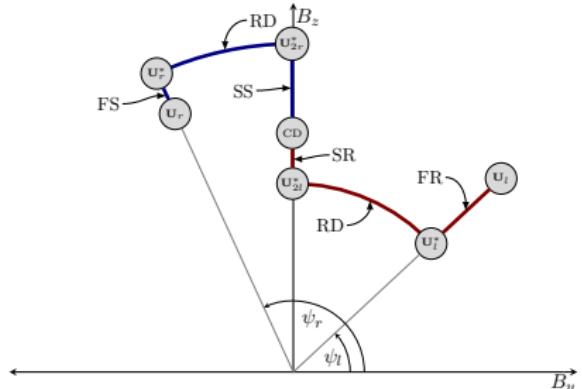
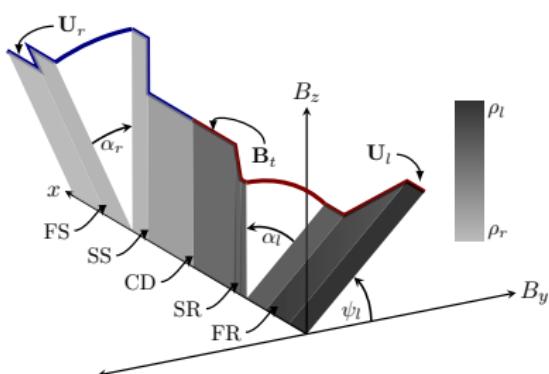
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- $B_t$  increases across fast shock, decreases across fast rarefaction.

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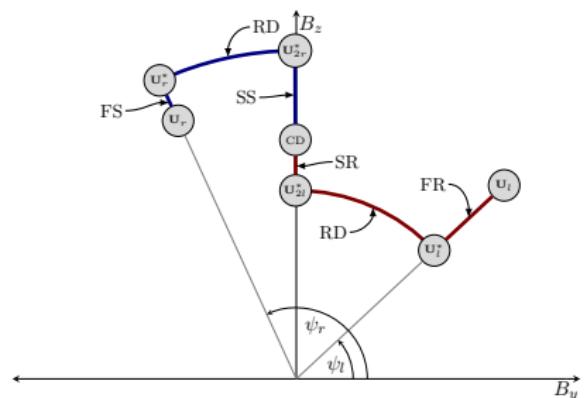
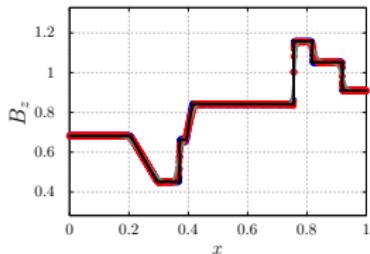
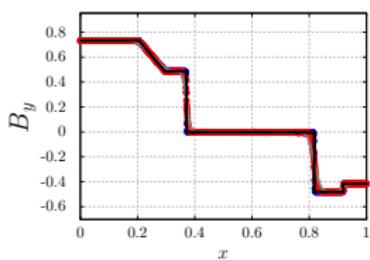
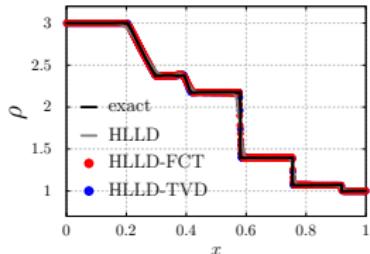
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# Riemann problems of ideal MHD

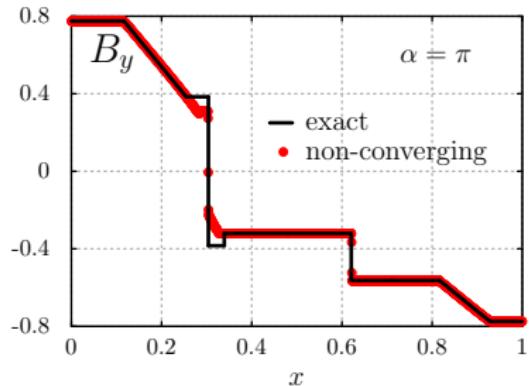
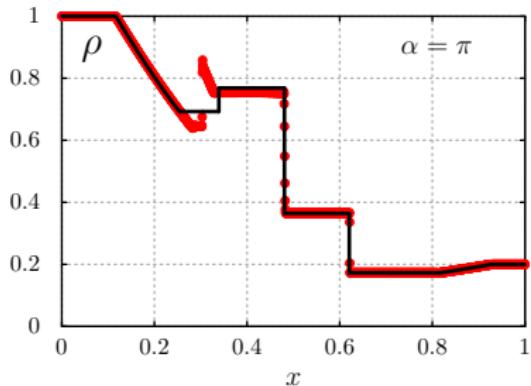


- Regular waves only alter the magnitude or orientation of  $B_t$ .
- $B_t$  increases across fast shock, decreases across fast rarefaction.
- $B_t$  changes orientation across a rotational discontinuity.
- $B_t$  decreases across slow shock, increases across slow rarefaction.

# Riemann problems of ideal MHD

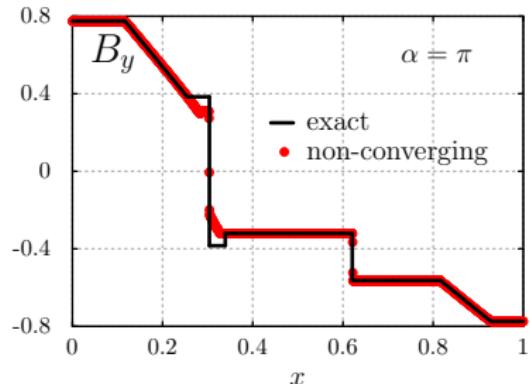
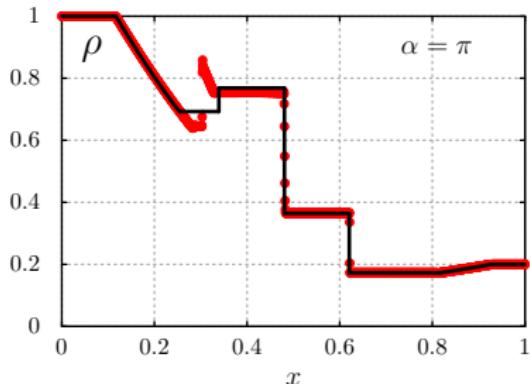


## Non-unique solutions



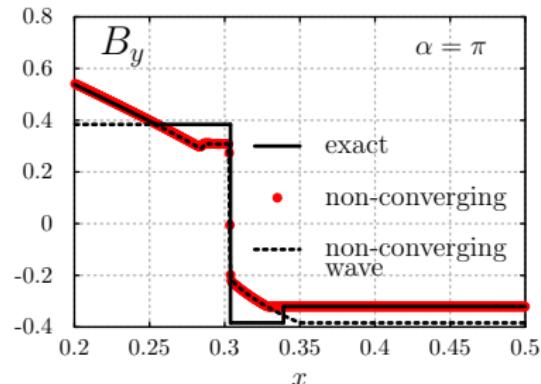
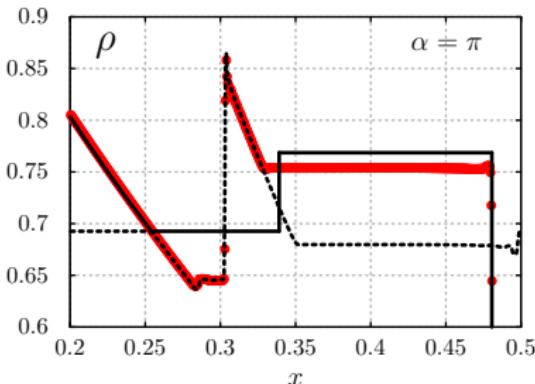
- Solutions to coplanar Riemann problems of ideal MHD are non-unique.
- At  $x = 0.303$ , rotational discontinuity  $\rightarrow$  compound wave.

# Non-unique solutions



- Solutions to coplanar Riemann problems of ideal MHD are non-unique.
- At  $x = 0.303$ , rotational discontinuity  $\rightarrow$  compound wave.
- Compound wave is composed of an intermediate shock and a slow rarefaction.
- Physical?
- Unstable for under small perturbations [5].
- Satisfies jump conditions in the coplanar case.

# Non-unique solutions



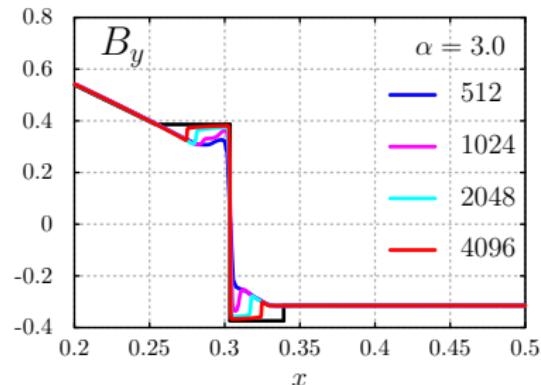
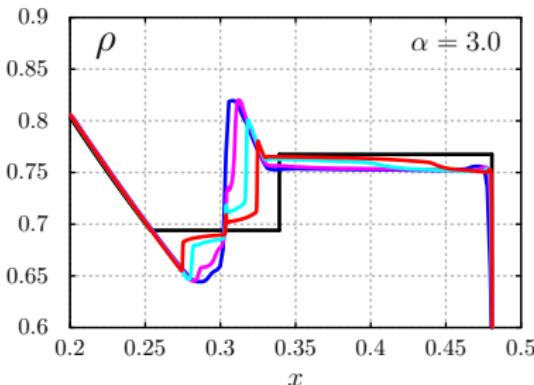
- An intermediate shock is a non-regular, i.e., not a Lax shock, wave that changes the orientation of the magnetic field.
- Slow compound wave: super-Alfvénic  $\rightarrow$  sub-slow.
- In shock frame upstream:  $c_a < v_n < c_f$

$$v_n = 1.0174, c_a = 0.9661, c_f = 1.1295$$

- In shock frame downstream:  $v_n < c_s, c_a$

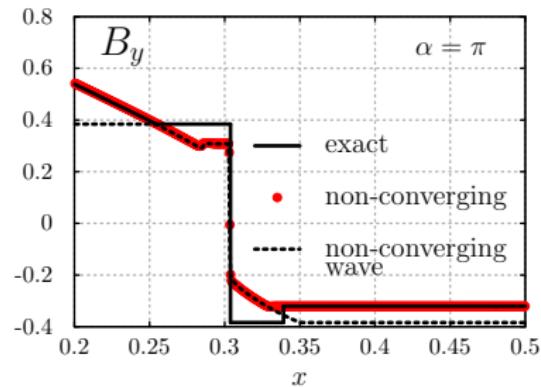
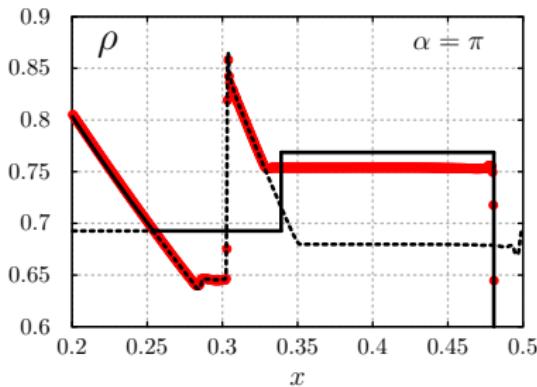
$$v_n = 0.7341, c_s = 0.8033, c_a = 0.8222$$

# Pseudo-convergence



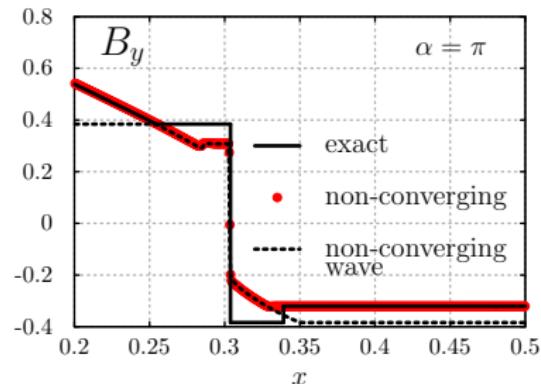
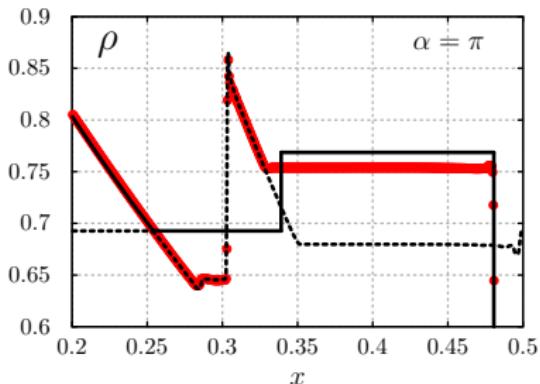
- Near-coplanar case, compound waves present at lower resolutions.
- Pseudo-convergence: increasing resolution produces convergence to regular wave solution [10].
- The compound waves begin to break apart between 1024 and 2048 grid points.
- As  $\alpha \rightarrow \pi$ , grid resolution increases.
- When  $\pi = \alpha$ , compound wave at all resolutions.

# Compound Wave modification



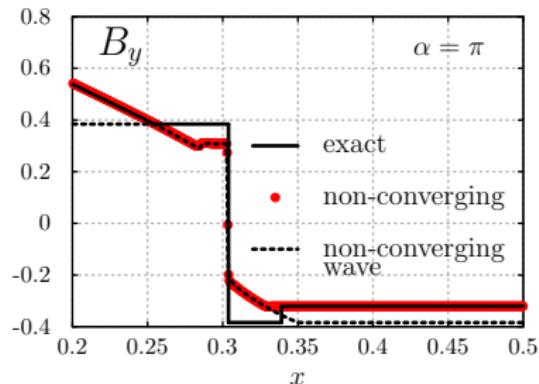
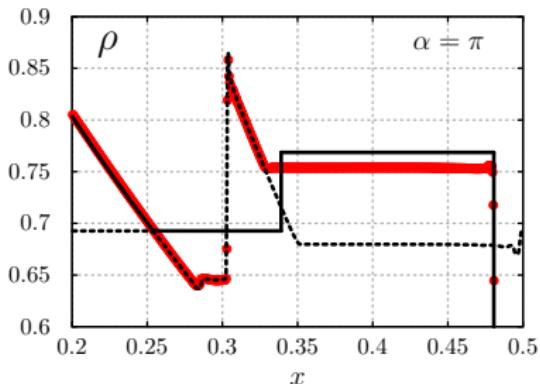
- Compound waves are product of numerical diffusion for near coplanar problems.
- Reduce diffusion to recover correct solution. How?

# Compound Wave modification



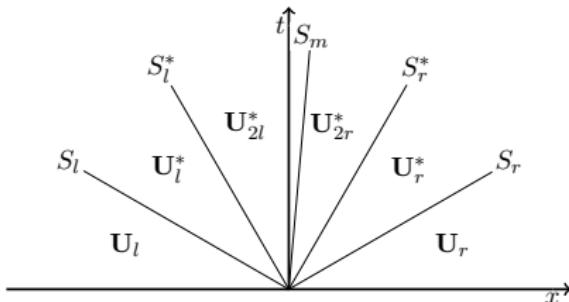
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- $\rho$  and  $B_t$  should remain constant across the rotational discontinuity  $x = 0.303$ .

# Compound Wave modification

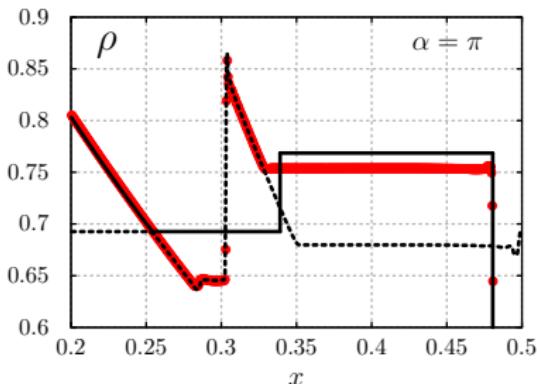


- Compound waves are product of numerical diffusion for near coplanar problems.
- Reduce diffusion to recover correct solution. How?
- $\rho$  and  $B_t$  should remain constant across the rotational discontinuity  $x = 0.303$ .
- Limit flux associated with the compound wave.

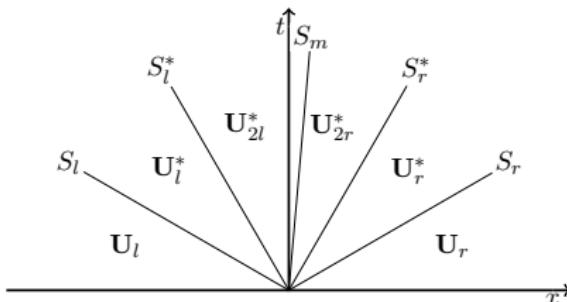
# Compound Wave modification



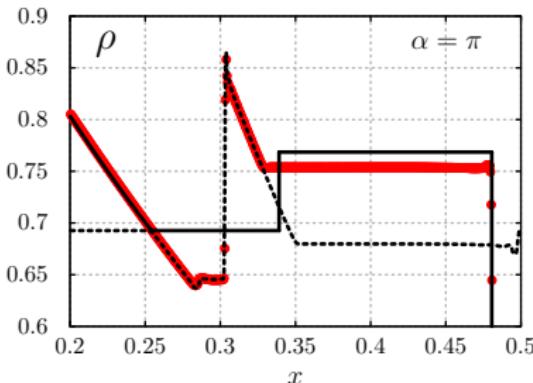
- Use HLLD to approximate intermediate states upstream and downstream of rotational discontinuity, i.e.,  $\mathbf{U}_l^*$  and  $\mathbf{U}_{2l}^*$ .



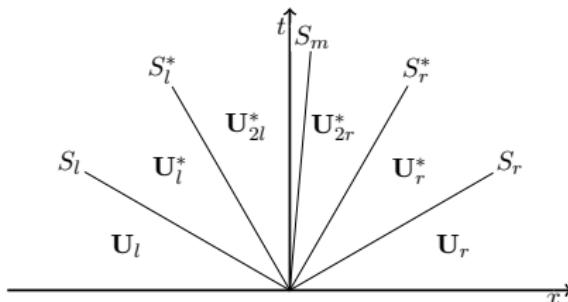
# Compound Wave modification



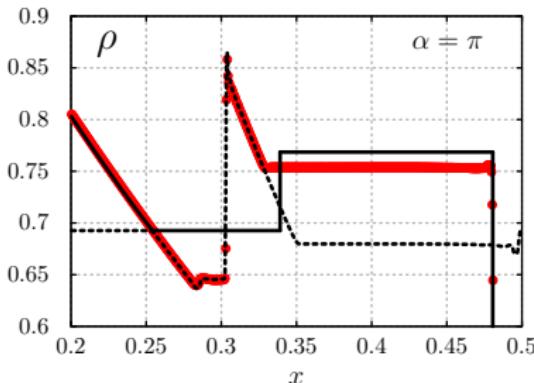
- Use HLLD to approximate intermediate states upstream and downstream of rotational discontinuity, i.e.,  $\mathbf{U}_l^*$  and  $\mathbf{U}_{2l}^*$ .
- Calculate flux  $\mathbf{F}^c$  between  $\mathbf{U}_l^*$  and  $\mathbf{U}_{2l}^*$  responsible for formation of the compound wave.



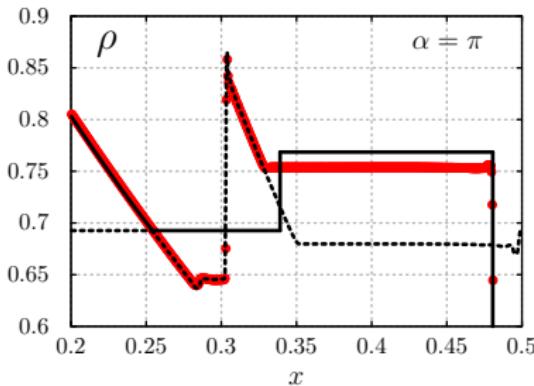
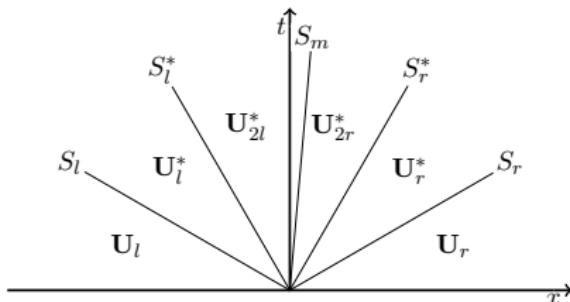
# Compound Wave modification



- Use HLLD to approximate intermediate states upstream and downstream of rotational discontinuity, i.e.,  $\mathbf{U}_l^*$  and  $\mathbf{U}_{2l}^*$ .
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- Reduce the contribution of  $\mathbf{F}^c = \mathbf{F}_{hlld}(\mathbf{U}_l^*, \mathbf{U}_{l/2}^*)$  to the total flux.

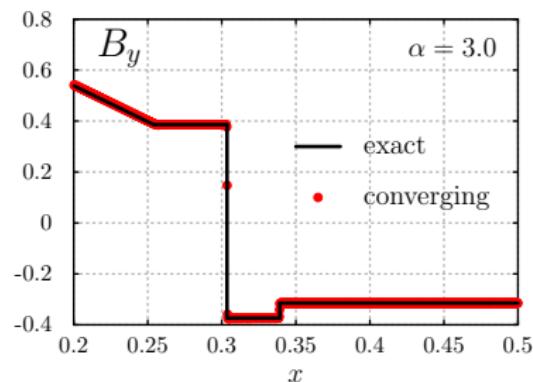
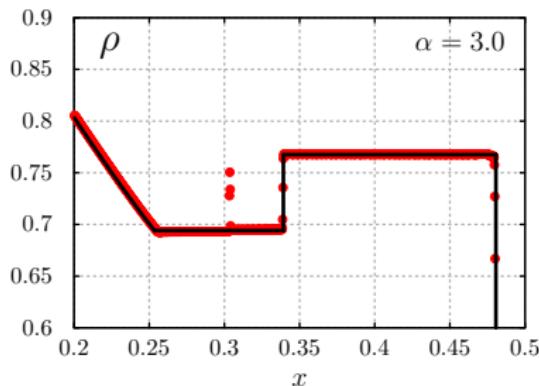


# Compound Wave modification



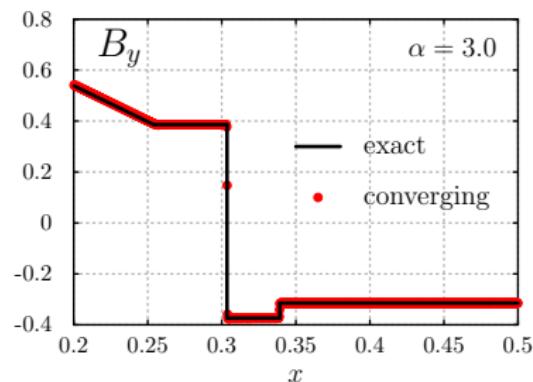
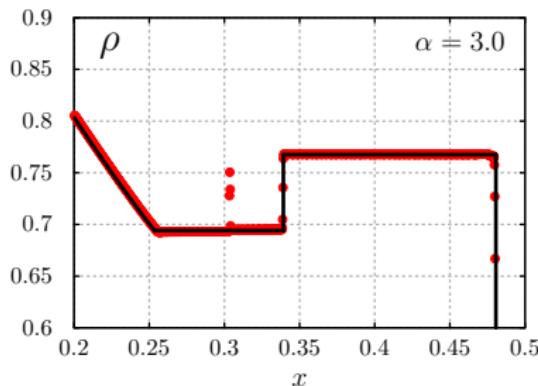
- Use HLLD to approximate intermediate states upstream and downstream of rotational discontinuity, i.e.,  $\mathbf{U}_l^*$  and  $\mathbf{U}_{2l}^*$ .
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- Reduce the contribution of  $\mathbf{F}^c = \mathbf{F}_{hlld}(\mathbf{U}_l^*, \mathbf{U}_{l/2}^*)$  to the total flux.
- $\mathbf{F}_{cwm} = \mathbf{F}_{hlld}(\mathbf{U}_l, \mathbf{U}_r) - A\mathbf{F}^c$ , where  $A < 0.5$ .

# CWM Results



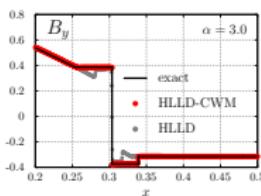
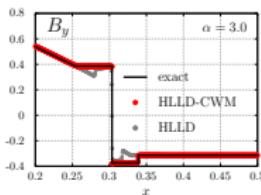
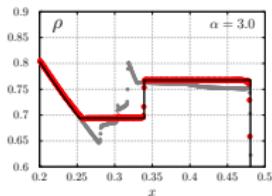
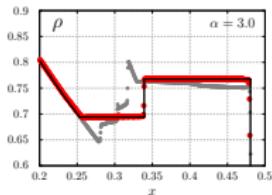
- CWM recovers the correct solution upstream and downstream of rotational discontinuity.
- Transition across rotational discontinuity is unresolved.
- Resolve it?

# CWM Results



- CWM recovers the correct solution upstream and downstream of rotational discontinuity.
- Transition across rotational discontinuity is unresolved.
- Resolve it?
- Simple but non-conservative.

# CWM Resolving the transition



- Jump conditions in Lagrangian mass coordinates,  $V = 1/\rho$ ,  $W$  is wave speed.
- Brackets denote difference across discontinuity.

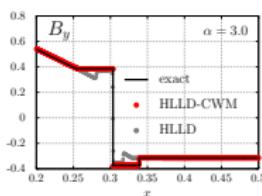
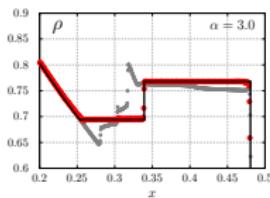
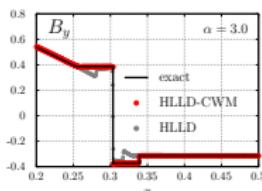
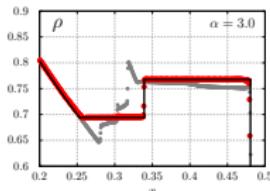
$$W[V] = -[v_n],$$

$$W[v_n] = -[P - B_n^2],$$

$$W[\mathbf{v}_t] = -B_n[\mathbf{B}_t],$$

$$W[V\mathbf{B}_t] = -B_n[\mathbf{v}_t],$$

# CWM Resolving the transition



- Across rotational discontinuity

$$[V] = 0,$$

$$[v_n] = 0,$$

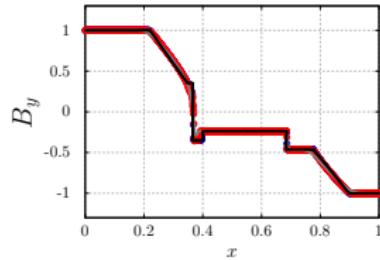
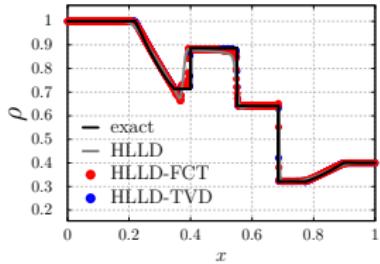
$$[p_g] = 0,$$

$$[B_t] = 0,$$

$$W[\mathbf{v}_t] = -B_n[\mathbf{B}_t],$$

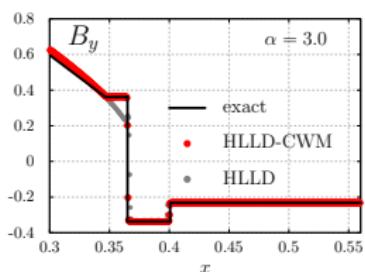
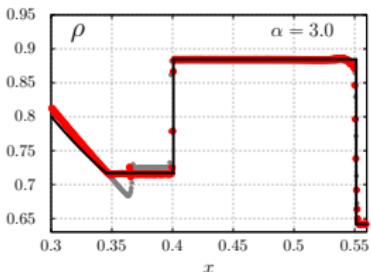
- $W = \sqrt{\rho}B_n$  is Lagrangian speed of linear wave.

# Results



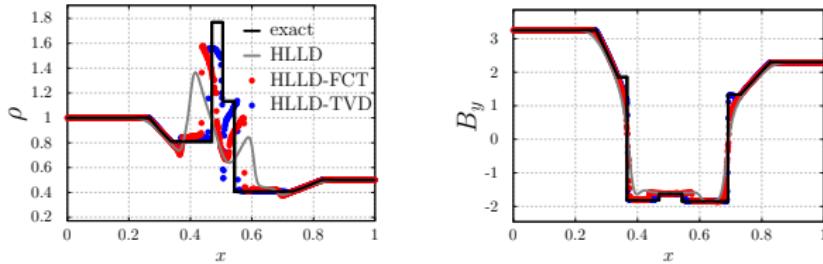
- Near coplanar initial conditions.
- Fast compound wave at  $x = 0.365$

# Results



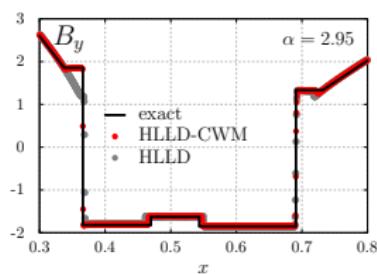
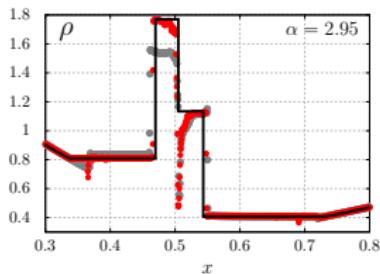
- Near coplanar initial conditions.
- Fast compound wave at  $x = 0.365$
- Small deviation for weak intermediate shocks.

# Results



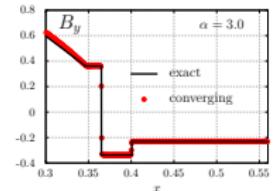
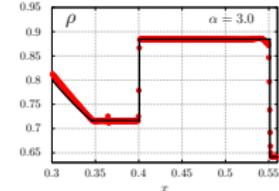
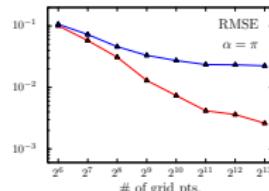
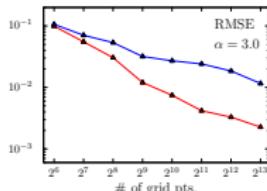
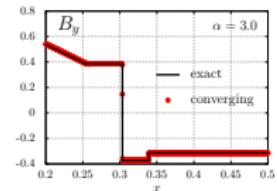
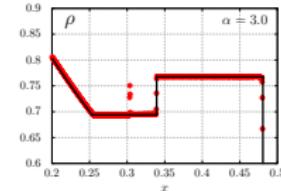
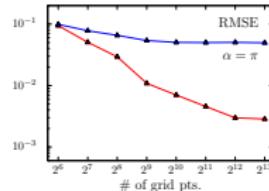
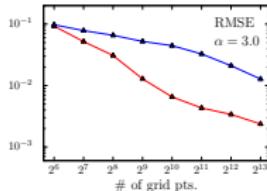
- Non-planar initial conditions.
- Fast compound waves at  $x = 0.366$  and  $x = 0.691$

# Results



- Non-planar initial conditions.
- Fast compound waves at  $x = 0.366$  and  $x = 0.691$
- Small deviation for weak intermediate shocks.

# Error analysis

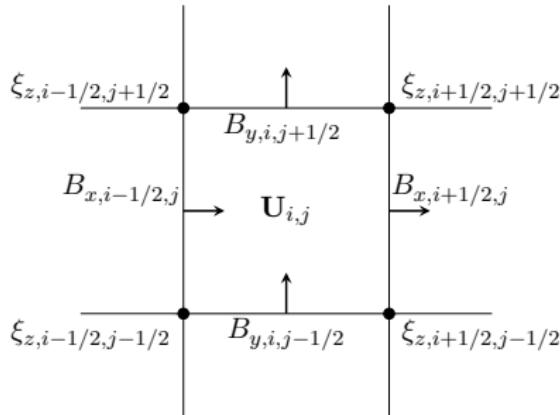


- Error calculation without applying the correction at the rotational discontinuity.
- Without CWM, the compound wave starts to break apart between  $2^{10}$  and  $2^{11}$ .
- CWM produces convergence at low grid resolutions.

# Higher dimensions

Maintaining  $\nabla \cdot \mathbf{B} = 0$  with constrained transport [3].

- Staggered grid.
- Hydrodynamical variables at cell centers.
- Magnetic field at interface.
- $\mathbf{E} = -\mathbf{v} \times \mathbf{B}$  at corners.
- Denote z-component of the emf as  $\xi_z$ .



Finite area integration of interface  $\mathbf{B}$

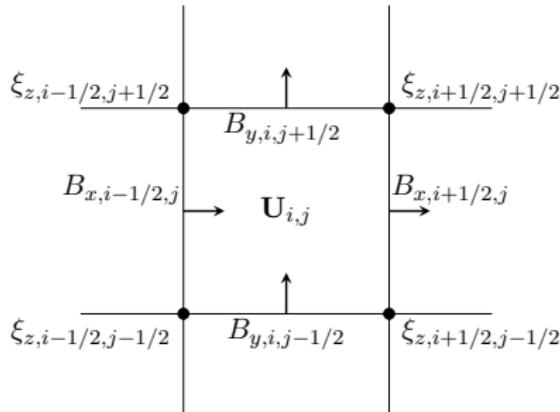
$$B_{x,i+1/2,j}^{n+1} = B_{x,i+1/2,j}^n - \frac{\delta t}{\delta y} (\xi_{z,i+1/2,j+1/2} - \xi_{z,i+1/2,j-1/2})$$

$$B_{y,i,j+1/2}^{n+1} = B_{y,i,j+1/2}^n + \frac{\delta t}{\delta x} (\xi_{z,i+1/2,j+1/2} - \xi_{z,i-1/2,j-1/2})$$

# Higher dimensions

Maintaining  $\nabla \cdot \mathbf{B} = 0$  with constrained transport [3].

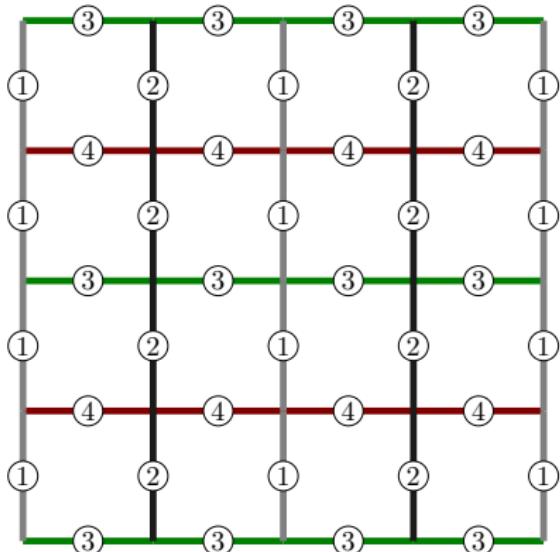
- Staggered grid.
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- Magnetic field at interface.
- $\mathbf{E} = -\mathbf{v} \times \mathbf{B}$  at corners.
- Denote z-component of the emf as  $\xi_z$ .



Due to perfect cancellation, the numerical divergence in the cell remains zero to machine precision.

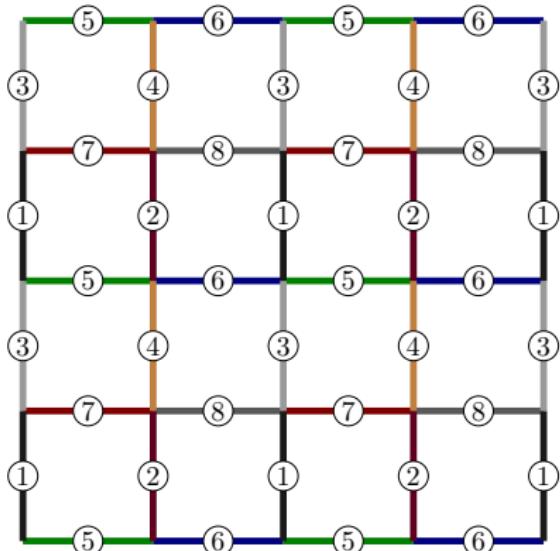
$$(\nabla \cdot \mathbf{B})_{i,j} = \frac{1}{\delta x} (B_{x,i+1/2,j} - B_{x,i-1/2,j}) + \frac{1}{\delta y} (B_{y,i,j+1/2} - B_{y,i,j-1/2})$$

# Shared memory parallelism



- Faces must be grouped by color to avoid memory contention.
- Loop over the faces becomes loop over the colors.

# Shared memory parallelism



- Faces must be grouped by color to avoid memory contention.
- Loop over the faces becomes loop over the colors.
- Constrained transport, faces and edges must be colored.

## Efficient algorithms

```
thrust::device_vector<float> x(n);    // independent  
                                         variable  
thrust::device_vector<float> y(n);    // y = f(x)  
thrust::device_vector<float> z(n);    // z = g(y)  
  
// compute y = f(x)  
thrust::transform(x.begin(),x.end(),y.begin(),f());  
  
// compute z = g(y)  
thrust::transform(y.begin(),y.end(),z.begin(),g());
```

- Function composition [4].
- $3n$  floats,  $2n$  reads,  $2n$  writes, and uses  $n$  temporary floats.

# Efficient algorithms

```
thrust::device_vector<float> x(n);    // independent
                                         variable
thrust::device_vector<float> z(n);    // z = g(y) = g(
                                         f(x))

// compute z = g(f(x))
thrust::transform(make_transform_iterator(x.begin(),
                                         f()),
                  make_transform_iterator(x.end(),
                                         () ),
                  z.begin(),
                  g());
```

- Function composition [4].
- $2n$  floats,  $n$  reads,  $n$  writes, and no temporary storage.

# Efficient algorithms

```
thrust::device_vector<float> x(n);    // independent
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                  z.begin(),
                  g());
```

- Function composition [4].
- $2n$  floats,  $n$  reads,  $n$  writes, and no temporary storage.

# Memory access

```
struct
    conservative_variables{
        float density;
        float momentum_x;
        float energy;
    }

    conservative_variables
    *state; // AoS

    state[i].density =
        some_number;
    state[i].momentum_x =
        another_number;
    state[i].energy =
        one_more_number;
```

```
struct
    conservative_variables{
        float *density;
        float *momentum_x;
        float *energy;
    }

    conservative_variables
    state; // SoA

    state.density[i] =
        some_number;
    state.momentum_x[i] =
        another_number;
    state.energy[i] =
        one_more_number;
```

- Memory coalescing occurs when multiple memory addresses are accessed with a single transaction.
- Memory does not coalesce with AoS (left).
- Memory does coalesce with SoA (right).

## Memory access

```
thrust::device_vector<primitive_variables>
    primitive_state(n); // AoS
thrust::device_vector<conservative_variables>
    conservative_state(n); // AoS
thrust::transform_n(primitive_state.begin(),
                   primitive_state.size(),
                   conservative_state.begin(),
                   convert_primitive_to_conservative(
                       gamma));
```

- Converting from primitive variables  $(\rho, v_x, p_g)$  to conservative variables  $(\rho, \rho v_x, en)$ .
- No coalescing.

## Memory access

```
thrust::device_vector<float> d(n), vx(n), pg(n);
thrust::device_vector<float> mx(n), en(n);
thrust::transform_n(
    thrust::make_zip_operator(
        make_tuple(d.begin(),
                   vx.begin(),
                   pg.begin())),
    n,
    thrust::make_zip_operator(
        make_tuple(d.begin(),
                   mx.begin(),
                   en.begin())),
    convert_primitive_to_conservative(gamma));
```

- Converting from primitive variables ( $\rho, v_x, p_g$ ) to conservative variables ( $\rho, \rho v_x, en$ ).
- Arrays can be combined on the fly with a `zip_operator` to achieve coalescing.

# Performance Comparison

Table: Performance comparison for Orszag-Tang [7] test.

grid size	cells/second (GPU)	cells/second (CPU)	ratio
$64 \times 64$	$4.1894 \times 10^6$	$7.3955 \times 10^5$	5
$128 \times 128$	$1.6540 \times 10^7$	$7.5060 \times 10^5$	22
$256 \times 256$	$4.4497 \times 10^7$	$7.3155 \times 10^5$	60
$512 \times 512$	$6.3286 \times 10^7$	$7.9437 \times 10^5$	79
$1024 \times 1024$	$7.2134 \times 10^7$	$8.3354 \times 10^5$	86

- Dell Precision 7500 workstation with a (Dual CPU)
- CPU Intel Xeon E5645 @ 2.40 Ghz.
- GPU GeForce GTX TITAN with a memory bandwidth of 288.4 GB/sec and 2688 CUDA cores.
- Almost a factor of three increase of speed ratio from  $128 \times 128$  to  $256 \times 256$ .

# Conclusion

- Provided new benchmarks for MHD model development.
- Released\* a nonlinear solver for ideal MHD.
- Developed the compound wave modification:
  - ▶ First method able to produce the rotational discontinuity for coplanar Riemann problems of ideal MHD without using a nonlinear solver.
  - ▶ First method to avoid pseudo-convergence for near coplanar problems of ideal MHD.
  - ▶ FAST! HLLD intermediate states are already calculated, modification for little cost.
  - ▶ Produces the correct result when other numerical inaccuracies are present.
- Released\* a high-order multi-dimensional fluid solver.
  - ▶ Algorithms implemented for general geometry on unstructured grids.
  - ▶ Capable of shared memory parallelism on GPU and CPU.
  - ▶ Can be used as blueprint or benchmark by anyone in computational physics and space weather communities wishing to increase performance.

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- [8] G. A. Sod. "A survey of several finite difference methods for systems of nonlinear hyperbolic conservation laws". In: *J. Comp. Phys.* 27 (Apr. 1978), pp. 1–31.
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