

Divide&Conquer: MergeSort

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Divide-and-Conquer Algorithms

- * Divide-and-conquer algorithms work according to the following general plan:
 - 1. A problem's instance is divided into several smaller instances of the same problem, ideally of about the same size.
 - 2. The smaller instances are solved (typically recursively, though sometimes a different algorithm is employed when instances become small enough).
 - 3. If necessary, the solutions obtained for the smaller instances are combined to get a solution to the original instance.

Sorting

- * Given a list L of n elements, we want to sort them in ascending order.
- * The most basic brute-force algorithm would go through every permutation of the n elements, and return one that is sorted in ascending order.
- * In the worst case, this algorithm takes $O(n \cdot n!)$ time, since there are O(n!) permutations, and for each one, it takes O(n) to check if it is sorted in ascending order.
- Can we do better? Of course; much better!

MergeSort: Verbal Description

- * MergeSort divides the list L[0..n-1] into two halves L[0..[n/2]-1] and L[[n/2]..n-1], sorting each of them recursively, and then merging the two smaller sorted arrays into a single sorted one.
- Question: How do we sort each of the two halves?
 - * Answer: by dividing each into two halves, sorting them, and then merging.
- Question: When do we stop dividing the list?
 - * Answer: When we reach a list of size 1 (since we know how to sort it).

MergeSort: Pseudo-Code The Divide Phase

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MergeSort

Input: List L of ``orderable" elements

Modifies: List L is sorted in-place in ascending order

Output: None

```
If n>1
  copy L[0..[n/2]-1] to A[0..[n/2]-1];
  copy L[[n/2]..n-1] to B[0.. [n/2]-1];
  MergeSort(A[0..[n/2]-1]);
  MergeSort(B[0..[n/2]-1]);
  Merge(A,B,L);
```

MergeSort: Pseudo-Code The Combine Phase

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Merge

```
Input: Two sorted lists A[0..p-1] and B[0..q-1], and list L
Modifies: List L contains the elements of A and B sorted in ascending order
Output: None
i\leftarrow 0; j\leftarrow 0; k\leftarrow 0;
While i<p and j<q
   If A[i] \leq B[j]
       L[k] \leftarrow A[i];
       i\leftarrow i+1;
   Else
       L[k] \leftarrow B[j];
       j←j+1;
   k \leftarrow k+1;
If i=p
   copy B[j..q-1] to L[k..p+q-1]
Else
   copy A[i..p-1] to L[k..p+q-1]
```

What Is The Running Time of MergeSort?

- * For simplicity, let us assume n is a power of 2 (that is, n=2^m for some m).
- * Let C(n) be the number of steps **MergeSort** takes on a list L that has n elements.
- * Then, we have the <u>recurrence</u>

$$C(n) = 2C(n/2) + C_{merge}(n)$$
 for $n>1$, and $C(1)=1$.

- * Notice that $C_{merge}(n)=O(n)$.
- * Question: What function g(n) gives us C(n) = O(g(n))?

- * A (numerical) <u>sequence</u> is an ordered list of numbers.
- * Examples: 1,1,2,3,5,8,13,21,...
- * A sequence can also be viewed as a function x(n): its argument n indicates a position of a number in the list, while the function's value x(n) stands for that number itself.
- * x(n) is called the generic term of the sequence.

- * There are two principal ways to define a sequence:
 - * by an explicit formula expressing its generic term as a function of n; e.g., x(n) = 2n for $n \ge 0$,
 - * by an an equation relating its generic term to one or more other terms of the sequences, combined with one or more explicit values for the first term(s); e.g.,

$$x(n) = x(n-1) + n$$
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* To solve a given recurrence subject to a given initial condition means to find an explicit formula for the generic term of the sequence that satisfies both the recurrence and the initial condition or to prove that such a sequence does not exist.

Common Recurrence Types in Algorithm Analysis

- * There are a few recurrence types that arise in the analysis of algorithms with remarkable regularity.
- * This happens because they reflect one of the fundamental design techniques.
- * Of particular interest to us is a recurrence that arises when analyzing the running time of divide&conquer algorithms.

Common Recurrence Types in Algorithm Analysis

* Assuming all smaller instances (resulting from the divide phase) have the same size n/b, with a of them being actually solved, we get the following recurrence valid for $n=b^k$, k=1,2,...:

$$T(n) = aT(n/b) + f(n)$$

where $a \ge 1$, $b \ge 2$, and f(n) is a function that accounts for the time spent on dividing the problem into smaller ones and combining their solutions.

The Master Theorem

* Let T(n) be an eventually nondecreasing function that satisfies the recurrence

$$T(n) = aT(n/b) + f(n)$$
 for $n = b^k$, $k = 1, 2, ...$
 $T(1) = c$,

where $a \ge 1$, $b \ge 2$, c > 0.

* If $f(n)=O(n^d)$ where $d\ge 0$, then

$$T(n) = \begin{cases} O(n^d) & \text{if } a < b^d \\ O(n^d \log n) & \text{if } a = b^d \\ O(n^{\log_b a}) & \text{if } a > b^d \end{cases}$$

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- * Thus, we have: a=2, b=2, c=1, and $f(n)=O(n^1)$, i.e., d=1.
- * Since we have $a=b^d$, it follows from the Master Theorem that

$$T(n) = O(n^1 \log n) = O(n \log n)$$