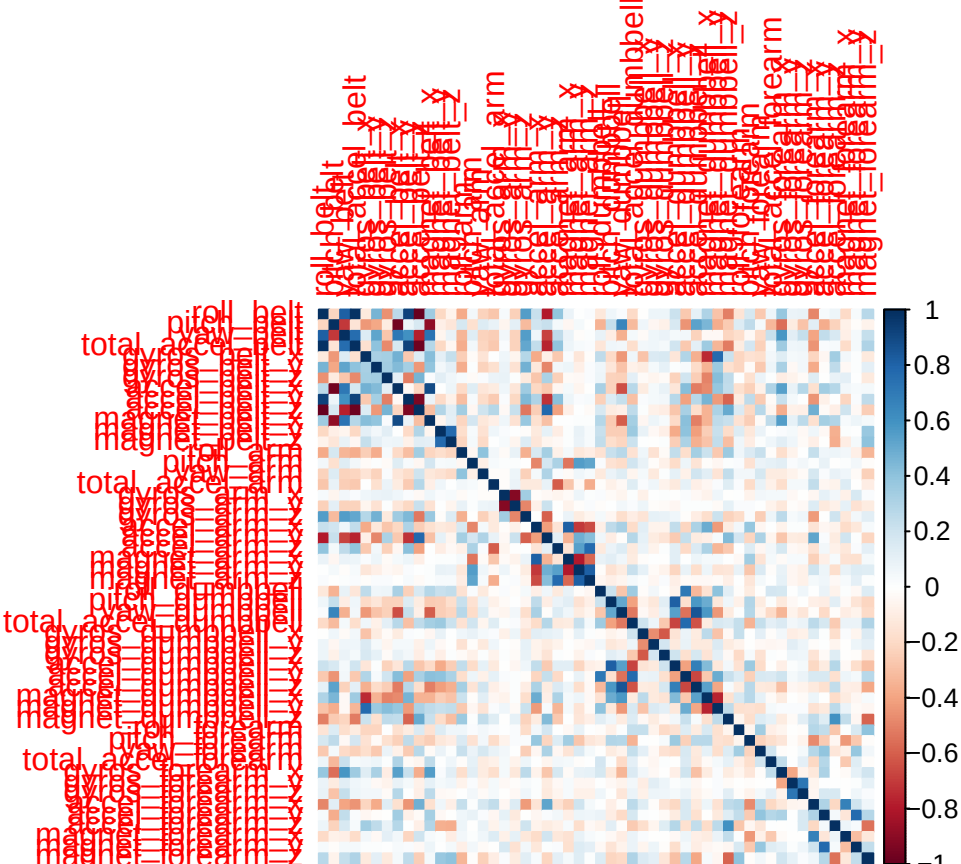
roll_belt
pitch_belt
yaw_belt
total_accel_belt
gyros_belt_x
gyros_belt_y
gyros_belt_z
accel_belt_x
accel_belt_y
accel_belt_z
magnet_belt_x
magnet_belt_y
magnet_belt_z
roll_arm
pitch_arm
yaw_arm
total_accel_arm
gyros_arm_x
gyros_arm_y
gyros_arm_z
accel_arm_x
accel_arm_y
accel_arm_z
magnet_arm_x
magnet_arm_y
magnet_arm_z
roll_dumbbell
pitch_dumbbell
yaw_dumbbell
total_accel_dumbbell
gyros_dumbbell_x
gyros_dumbbell_y
gyros_dumbbell_z
accel_dumbbell_x
accel_dumbbell_y
accel_dumbbell_z
magnet_dumbbell_x
magnet_dumbbell_y
magnet_dumbbell_z
roll_forearm
pitch_forearm
yaw_forearm
total_accel_forearm
gyros_forearm_x
gyros_forearm_y
gyros_forearm_z
accel_forearm_x
accel_forearm_y
accel_forearm_z
magnet_forearm_x
magnet_forearm_y
magnet_forearm_z
1
0.8
0.6
0.4
0.2
0
−0.2
−0.4
−0.6
−0.8
−1