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Chapter 1

First Weight Estimation

1.1 Introduction

To develop UDAAN - a lightweight, energy efficient, inflatable drone capable of vertical Take off, Stand By and Landing, which can deliver payloads and is self rechargeable. Drones allows for a wide variety of missions, however with the weight of the sensors increasing, the drones able to carry such payloads are cumbersome and difficult to transport. That is why we are trying to develop India's first inflatable drone. The drone has inflatable structure, is at the same time will be easy to transport and rugged because of the flexible structure. Moreover, the drone would be waterproof and can land and take-off on water surface because of compressed Helium gas used in the inflatable structure.

1.2 Novelty Features

1.2.1 Fast

The UDAAN will unfold in a few seconds and can be operated by a single person.

1.2.2 Compact

The UDAAN will be easily transportable thanks to its compact and foldable inflatable structure

1.2.3 Amphibious

The UDAAN is waterproof, therefore deployable under heavy rain or even on water.

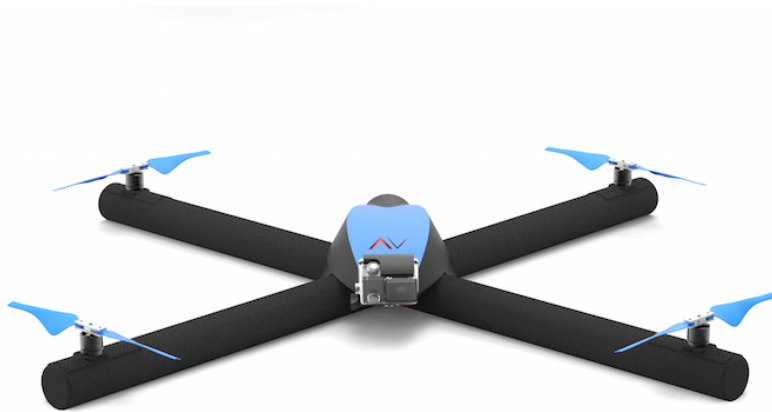


Figure 1.1: Inflatable drone

1.2.4 Payload and Surveillance

UDAAN is capable of carrying a Payload and hence can be utilised for delivery of items via e-commerce channel.

1.2.5 Self Rechargeable

UDAAN would be equipped with self rechargeable capabilities. We are trying to develop and incorporate a mechanism to recharge the battery using renewable energy sources.

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1.3 Mission Profile

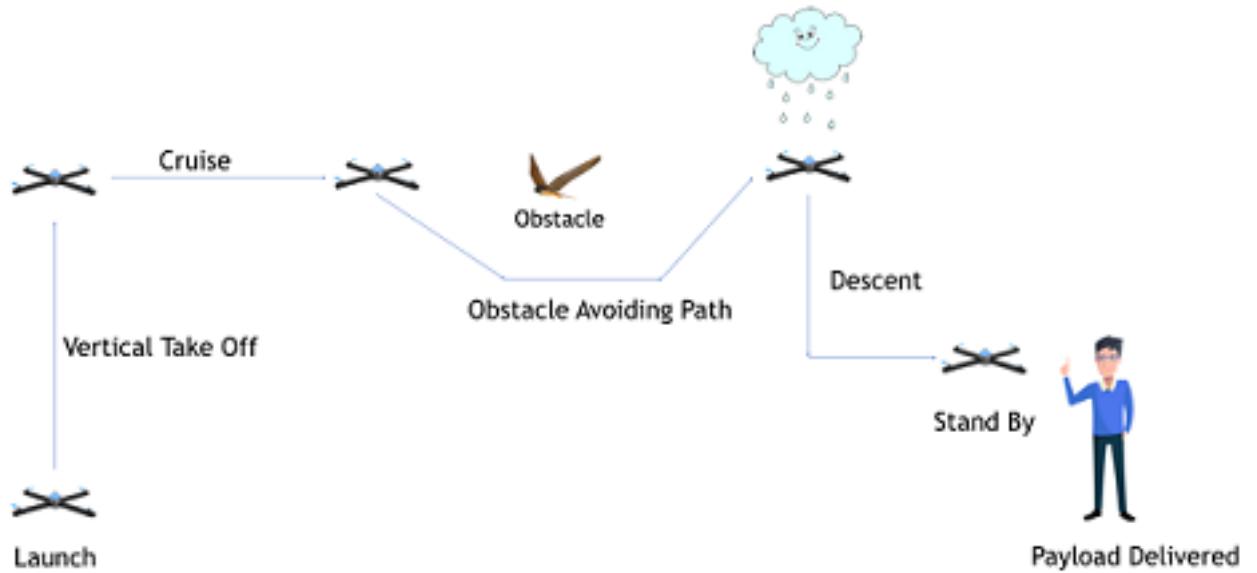


Figure 1.2: Mission Profile

1.4 Estimated Data

1.4.1 Dimensions

Available Payload : Camera, Parcel

Folded : 300x300x150 mm

Unfolded : 800x800x150 mm

Endurance : up to 60 min

1.4.2 Common Characteristics

Waterproof

Wind resistance : 37 kmph

Unfolding time : 60s

Folding time : 60s

1.4.3 Weight Estimate

The approximated weight of the UDAAN will be 300-500gm, which will be depend upon material used and the battery required.

Chapter 2

Second Weight Estimation

2.1 Weight Estimate

- Propeller = 30 grams
- Motor = $4 * 23 = 92$ grams
- Flight Control Board = 60 grams
- Electronic speed controller = $4 * 100 = 400$ grams
- Base weight = 200 grams
- Bolts = 20 grams
- Locking nuts = 20 grams
- Wires = 30 grams
- Camera weight = 100 grams
- Battery = 160 grams (2200mah)
- Total weight = 1112 grams

2.2 Thrust Calculation

- Estimated Weight of drone = 1112 grams
- Thrust/Weight = 2
- Headspace given for thrust = 20 %

- Net thrust required = $2.4 * 1112 \text{ grams} = 2669 \text{ grams}$
- Net thrust required per motor = 670 grams
- Specification of propeller:
 1. Diameter = 8 inches
 2. pitch = 4 inches

2.2.1 Motor Specification

Motor: Avionic M2226/18 KV2570 MICRO brushless motor

KV (rpm/v): 2570

Power: 80W

Winds: 18

Resistance: 327 mOhm

Idle current: 0.8 A

Weight: 23 gms

2.2.2 Formula used for thrust calculation

Figure 2.1: fig.thrust v/s graph

2.2.3 Battery Specification

Minimum Capacity: 2200mAh

Configuration: 3S1P / 11.1v / 3Cell

Constant Discharge: 25C

Peak Discharge (10sec): 35C

2.3 Procedure

- Decide appropriate dimension of propeller.

- Choose suitable RPM of motor.
- Get the required static thrust from the table.
- Iterate the dimensions until you get the required thrust which is 672 g of thrust.
- After fixing the dimension and RPM of motor, find suitable LiPo battery
- $\text{RPM} = \text{KV} * \text{Battery voltage}$ $\text{RPM} = 2570 * 11.1 = 28500$
- This is the RPM of motor without propeller. After using propeller RPM reduces by 2.5 times approximately.
- Net RPM = 11410 (estimated)
- After finalizing the battery, fix the Electronic speed controller.

2.4 Conclusion

The weight of the inflatable drone is estimated to be around 1112g. The estimated static thrust produced is 6.636 N. In the next phase, after performing successive iterations we will finalize the weight of the drone and perform dynamic thrust calculations.

2.5 References

1. <http://www.rcbazaar.com/product.aspx?productid=2400>
2. <http://www.3drcparts.com/zippy-2200mah-11-1v-3s-25-35c-light-weight-lipo-battery/>
3. <https://www.flitetest.com/articles/propeller-static-dynamic-thrust-calculation>