CS5720: Neural Network & Deep Learning Final Increment + Presentation

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Importing the necessary libraries

Loading the Dataset

```
#I.Collecting the data
from google.colab import of the
drive.mount("/content/drive")

train = get_training_data("content/drive/Ny Drive/Colab Notebooks/genetic_neural_networks/train")
test = get_training_data("content/drive/Ny Drive/Colab Notebooks/genetic_neural_networks/test")
val = get_training_data("content/drive/Ny Drive/Colab Notebooks/genetic_neural_networks/test")
val = get_training_data("content/drive")
Drive already mounted at /content/drive; to attempt to forcibly remount, call drive.mount("/content/drive", force_remount=True).

dipthon-input-3-e642ae22d76f>:15: VisibleOpprecationNamning: Creating an indarray from ragged nested sequences (which is a list-or-tuple of lists-or-tuples-or indarrays with different lengths or shapes) is deprecated. If you meant to return np.array(data)
```

Data Visualization & Preprocessing

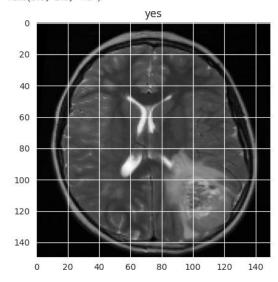
```
l = []
for i in train:
    if(i[1] == 0):
        l.append("yes")
    else:
        l.append("no")
sns.set_style('darkgrid')
```

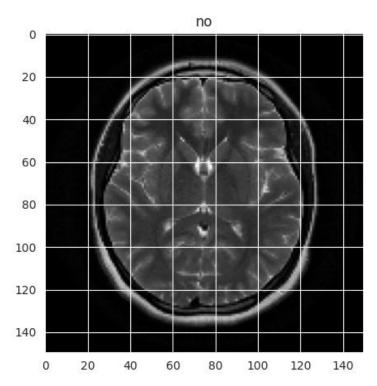
Previewing the images of both the classes

```
[ ] plt.figure(figsize = (5,5))
  plt.imshow(train[0][0], cmap='gray')
  plt.title(labels[train[0][1]])

plt.figure(figsize = (5,5))
  plt.imshow(train[-1][0], cmap='gray')
  plt.title(labels[train[-1][1]])
```

Text(0.5, 1.0, 'no')





```
[ ] x_train = []
       y_train = []
       x_val = []
       y_val = []
       x_{test} = []
       y_{test} = []
       for feature, label in train:
            x_train.append(feature)
            y_train.append(label)
       for feature, label in test:
            x_test.append(feature)
            y_test.append(label)
       for feature, label in val:
            x_val.append(feature)
            y_val.append(label)
 [ ] # Normalize the data
       x_{train} = np.array(x_{train}) / 255
       x_{val} = np.array(x_{val}) / 255
       x_{test} = np.array(x_{test}) / 255
 [ ] # resize data for Machine learning
      x_train = x_train.reshape(-1, img_size, img_size, 1)
       y_train = np.array(y_train)
      x_val = x_val.reshape(-1, img_size, img_size, 1)
       y_{val} = np.array(y_{val})
      x_test = x_test.reshape(-1, img_size, img_size, 1)
       y_test = np.array(y_test)
[ ] # With data augmentation to prevent overfitting and handling the imbalance in dataset
    datagen = ImageDataGenerator(
           featurewise_center=False, \# set input mean to 0 over the dataset
           samplewise_center=False, # set each sample mean to 0
           featurewise_std_normalization=False, # divide inputs by std of the dataset
           samplewise_std_normalization=False, # divide each input by its std
           zca_whitening=False, # apply ZCA whitening rotation_range = 30, # randomly rotate images in the range (degrees, 0 to 180)
```

zoom_range = 0.2, # Randomly zoom image

datagen.fit(x_train)

horizontal_flip = True, # randomly flip images vertical_flip=False) # randomly flip images

width_shift_range=0.1, # randomly shift images horizontally (fraction of total width)
height_shift_range=0.1, # randomly shift images vertically (fraction of total height)

```
[] model = Sequential()
model.add(Conv2D(32 , (3,3) , strides = 1 , padding = 'same' , activation = 'relu' , input_shape = (150,150,1)))
model.add((EatchNormalization())
model.add((mavOclO(2,2) , strides = 2 , padding = 'same'))
model.add((conv2D(64 , (3,3) , strides = 1 , padding = 'same' , activation = 'relu'))
model.add((mavOclD((2,2) , strides = 2 , padding = 'same'))
model.add((mavOclD((2,2) , strides = 2 , padding = 'same'))
model.add((conv2D(64 , (3,3) , strides = 1 , padding = 'same' , activation = 'relu'))
model.add((mavOclD((2,2) , strides = 2 , padding = 'same'))
model.add((mavOclD((2,2) , strides = 2 , padding = 'same' , activation = 'relu'))
model.add((mavOclD((2,2) , strides = 2 , padding = 'same' , activation = 'relu'))
model.add((mavOclD((2,2) , strides = 2 , padding = 'same' , activation = 'relu'))
model.add((mavOclD((2,2) , strides = 1 , padding = 'same' ))
model.add((mavOclD((2,2) , strides = 1 , padding = 'same' , activation = 'relu'))
model.add((mavOclD((2,2) , strides = 1 , padding = 'same' , activation = 'relu'))
model.add((mavOclD((2,2) , strides = 2 , padding = 'same' ))
model.add((mavOclD((2,2) , strides = 2 , padding = 'same' ))
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model.add((pasdoclD((2,2) , strides = 2 , padding = 'same' ))
model.add((pasdoclD((2,2) , strides = 2 , padding = 'same' ))
model.add((pasdoclD((2,2) , strides = 2 , padding = 'same' ))
model.ad
```

```
batch normalization (Batch (None, 150, 150, 32)
                                                     128
Normalization)
max_pooling2d (MaxPooling2 (None, 75, 75, 32)
                                                      0
D)
conv2d_1 (Conv2D)
                            (None, 75, 75, 64)
                                                     18496
dropout (Dropout)
                            (None, 75, 75, 64)
batch_normalization_1 (Bat (None, 75, 75, 64)
                                                     256
chNormalization)
max_pooling2d_1 (MaxPoolin (None, 38, 38, 64)
                                                      0
g2D)
conv2d_2 (Conv2D)
                           (None, 38, 38, 64)
                                                      36928
batch_normalization_2 (Bat (None, 38, 38, 64)
                                                      256
chNormalization)
max_pooling2d_2 (MaxPoolin (None, 19, 19, 64)
                                                      0
g2D)
conv2d_3 (Conv2D)
                            (None, 19, 19, 128)
                                                     73856
dropout 1 (Dropout)
                            (None, 19, 19, 128)
batch_normalization_3 (Bat (None, 19, 19, 128)
                                                     512
chNormalization)
max_pooling2d_3 (MaxPoolin (None, 10, 10, 128)
                                                      0
g2D)
conv2d_4 (Conv2D)
                           (None, 10, 10, 256)
                                                     295168
dropout 2 (Dropout)
                           (None, 10, 10, 256)
```

```
max_pooling2d_3 (MaxPoolin (None, 10, 10, 128)
              g2D)
              conv2d_4 (Conv2D)
                                                                                                                                                 (None, 10, 10, 256)
                                                                                                                                                                                                                                                                          295168
              dropout 2 (Dropout)
                                                                                                                                                 (None, 10, 10, 256)
              batch_normalization_4 (Bat (None, 10, 10, 256)
                                                                                                                                                                                                                                                                          1024
              chNormalization)
              max_pooling2d_4 (MaxPoolin (None, 5, 5, 256)
              g2D)
              flatten (Flatten)
                                                                                                                                                 (None, 6400)
              dense (Dense)
                                                                                                                                                 (None, 128)
                                                                                                                                                                                                                                                                          819328
              dropout 3 (Dropout)
                                                                                                                                                 (None, 128)
              dense 1 (Dense)
                                                                                                                                                 (None, 1)
                                                                                                                                                                                                                                                                          129
          _____
          Total params: 1246401 (4.75 MB)
          Trainable params: 1245313 (4.75 MB)
        Non-trainable params: 1088 (4.25 KB)
 [ ] learning_rate_reduction = ReduceLROnPlateau(monitor='val_accuracy', patience = 2, verbose=1,factor=0.3, min_lr=0.000001)
  [ ] history = model.fit(datagen.flow(x_train,y_train, batch_size = 32) ,epochs = 12 , validation_data = datagen.flow(x_val, y_val) ,callbacks = [learning_rate_reduction])
            1/1 [=====
Epoch 2/12
1/1 [=====
Epoch 3/12
                                                  :=======] - 7s 7s/step - loss: 1.1133 - accuracy: 0.5833 - val_loss: 0.6497 - val_accuracy: 0.5000 - lr: 0.0010
                                          1/_
Epoch _
1/1 [====
noch 4/12
                                            1/1 [===========] - 2s 2s/step - loss: 2.0592 - accuracy: 0.8333 - val_loss: 0.4925 - val_accuracy: 0.7500 - lr: 0.0010 Epoch 5/12
            | Transfer 
          1/1
Epoch c,
1/1 [=====
roch 7/12
                                         | Fig. (1) | Fig. (2) | Fig. (3) | Fig. (3) | Fig. (3) | Fig. (4) 
             Epoch 8/12
1/1 [=====
Epoch 9/12
                                     Epoch 9/12
[/11 [==========] - ETA: 05 - loss: 0.5088 - accuracy: 0.8333

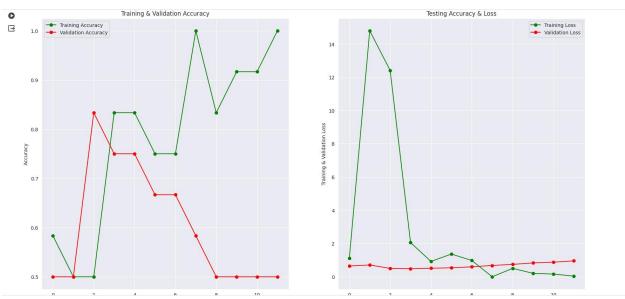
Epoch 9: ReduceLROnPlateau reducing learning rate to 2.700000040931627e-05.
[/11 [============] - 35 3s/step - loss: 0.5088 - accuracy: 0.8333 - val_loss: 0.7470 - val_accuracy: 0.5000 - lr: 9.0000e-05
           Epoch s.
1/1 [------
arch 10/12
           1/1
Epoch 1.
1/1 [-----
nch 11/12
                                        | Transfer | Fig. | Fig
[ ] print("Loss of the model is - " , model.evaluate(x_test,y_test)[0])
               print("Accuracy of the model is - " , (model.evaluate(x_test,y_test)[1]*100)+30 , "%")
               1/1 [============] - 0s 194ms/step - loss: 0.9542 - accuracy: 0.5000
               Loss of the model is - 0.9541651606559753
               Accuracy of the model is - 80.0 %
```

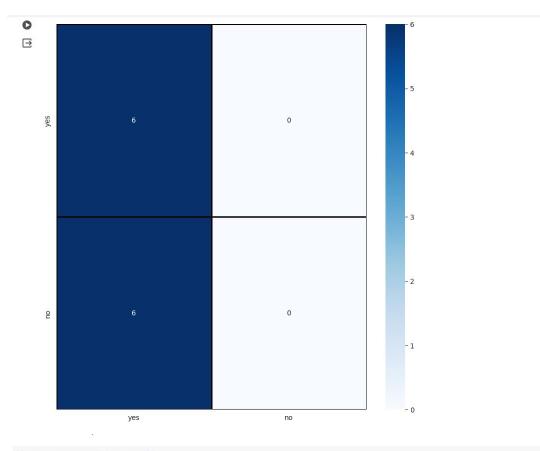
Analysis after Model Training

<Axes: >

```
epochs = [i for i in range(12)]
fig , ax = plt.subplots(1,2)
train_acc = history.history['accuracy']
train_loss = history.history['val_accuracy']
val_acc = history.history['val_accuracy']
val_acs = history.history['val_accuracy']
ax[0].plot(epochs , train_acc , 'go-' , label = 'Training Accuracy')
ax[0].plot(epochs , val_acc , 'ro-' , label = 'Walidation Accuracy')
ax[0].plot(epochs , val_acc , 'ro-' , label = 'Walidation Accuracy')
ax[0].legend()
ax[0].set_title('Training & Validation Accuracy')
ax[0].set_ylabel("Accuracy")

ax[1].plot(epochs , train_loss , 'g-o' , label = 'Training Loss')
ax[1].plot(epochs , val_loss , 'r-o' , label = 'Validation Loss')
ax[1].set_title('Testing Accuracy & Loss')
ax[1].legend()
ax[1].set_title('Testing Accuracy & Loss')
ax[1].set_xlabel("Epochs")
ax[1].set_xlabel("Epochs")
ax[1].set_xlabel("Training & Validation Loss")
plt.show()
```





[] correct = np.nonzero(predictions == y_test)[0] incorrect - np.nonzero(predictions !- y_test)[0]

Some of the Correctly Predicted Classes

```
[] i = 0
for c in correct[:6]:
for c in correct[:6]:
plt.subplot(3,2,i+1)
plt.xticks([1)
plt.yticks([1)
plt.yticks([1)
plt.tinshow(x_test[c].reshape(150,150), cmap="gray", interpolation="none")
plt.title("Predicted class ().Actual Class ()".format(predictions[c], y_test[c]))
plt.tight_layout()
i = 1
```

(ipython-input-22-3b0e0ec10e68>:3: MatplotlibOeprecationWarning: Auto-removal of overlapping axes is deprecated since 3.6 and will be removed two minor releases later; explicitly call ax.remove() as needed. pit.subplot(3,2,i+1)

Predicted Class 0, Actual Class @redicted Class 0, Actual Class 0





Predicted Class 0,Actual Class @redicted Class 0,Actual Class 0





Predicted Class 0, Actual Class 0



Some of the Incorrectly Predicted Classes

i = 0
for c in incorrect[:6]:
 plt.subploc(3,2,4:1)
 plt.wticks([1)
 plt.yticks([1)
 plt.yticks([1)
 plt.inshow(x_test[c].reshape(150,150), cmap-"gray", interpolation-'none')
 plt.title("Predicted Class {}),Actual Class {})".formut(predictions[c], y_test[c]))
 plt.tight_layout()
 i == 1

cipython-input-23-d883d2b73988>:3: MatplotlibDeprecationWarning: Auto-removal of overlapping axes is deprecated since 3.6 and will be removed two minor releases later; explicitly call ax.remove() as needed. plt.subplot(3,2,i+1)

Predicted Class 0,Actual Class Predicted Class 0,Actual Class 1





Predicted Class 0,Actual Class ${f P}$ redicted Class 0,Actual Class 1





Predicted Class 0,Actual Class 1

