

# LED ring for meeting room information and timer

## Hardware Components:

1. Tiva C Series TM4C123GH6PM Microcontroller
2. Main processing unit for the project, responsible for controlling the WS2812B LEDs based on room status, 16-bit WS2812B 5050 RGB LED Ring Circular development board.

The LED ring is controlled via UART commands to indicate the status of the meeting room. Here are some sample commands:

## Key Functions

1. **To reserve a room (Orange LED):**
  - The "O" button indicates that the room is occupied (orange LED).
  - Make sure reservations are only made when the room is Green, or available.
2. **The meeting will begin (blue LED):**
  - The "B" button initiates the meeting.
  - To show the passing of time, set a timer (for example, 16 minutes), during which the LEDs will turn off one after the other.
3. **Yellow LEDs for the Meeting End Indicator:**
  - All of the LEDs turn yellow for five minutes at the end of the timer, signifying that the meeting is over.
4. **Green LED Room Availability:**
  - The room is once again usable when all of the LEDs turn green after five minutes of yellow.

## Variable Timing:

Receive time input through UART and set a timer for the LED status to change after the given duration.

Time Data Format:

A standard format, like HH:MM, can be used to send the time since the meeting began.

WS2812B Board to Microcontroller Connection:

- **DIN (Data In)** of the WS2812B LEDs should be connected to a GPIO pin on the microcontroller capable of outputting a data signal with the timing required by the WS2812B protocol.
- **VCC** and **GND** should be connected to a 5V power supply and ground, respectively.

Tiva C Microcontroller Pin Connections:

- **Data Line (DIN)**: Connect to a GPIO pin, e.g., **Pin PA2**.
- **Power (VCC)**: Connect to a 5V pin.
- **Ground (GND)**: Connect to a ground (GND) pin.

## Microcontroller programming

Code which glows led

```
#include <stdint.h>
#include "tm4c123gh6pm.h" // Make sure this is correctly included
#define LED_PIN 0x08 // PortA, Pin 3
#define SYS_CLOCK 16000000 // Default 16 MHz

// Function prototypes
void delayMs(uint32_t ms);
void sendBit(uint8_t bit);
void sendByte(uint8_t byte);
void sendColor(uint8_t green, uint8_t red, uint8_t blue);
void initGPIO(void);
void initSysTick(void);
void SysTickDelay(uint32_t ticks);

int main(void) {
    int i; // Ensure 'i' is properly declared
    initGPIO();
    initSysTick();

    while (1) {
        // Glow green, red, and blue sequentially for all LEDs
```

```

        for (i = 0; i < 16; i++) { // Correctly declared loop
            variable 'i'
            sendColor(0xFF, 0x00, 0x00); // Green
        }
        delayMs(500); // Delay for 500ms

        for (i = 0; i < 16; i++) { // Correctly declared loop
            variable 'i'
            sendColor(0x00, 0xFF, 0x00); // Red
        }
        delayMs(500); // Delay for 500ms

        for (i = 0; i < 16; i++) { // Correctly declared loop
            variable 'i'
            sendColor(0x00, 0x00, 0xFF); // Blue
        }
        delayMs(500); // Delay for 500ms
    }

    void initGPIO(void) {
        SYSTCTL_RCGCGPIO_R |= 0x01; // Enable PortA clock
        while ((SYSTCTL_PRGPIO_R & 0x01) == 0) {} // Wait for GPIOA to be
            ready
        GPIO_PORTA_DIR_R |= LED_PIN; // Set PA3 as output
        GPIO_PORTA_DEN_R |= LED_PIN; // Enable PA3 digital functionality
    }

    void initSysTick(void) {
        NVIC_ST_CTRL_R = 0; // Disable SysTick during setup
        NVIC_ST_RELOAD_R = 0xFFFFFFFF; // Set maximum reload value
        NVIC_ST_CURRENT_R = 0; // Clear current value
        NVIC_ST_CTRL_R = 0x05; // Enable SysTick with system
            clock
    }

    void SysTickDelay(uint32_t ticks) {
        NVIC_ST_RELOAD_R = ticks - 1; // Set reload value
        NVIC_ST_CURRENT_R = 0; // Clear current value
        while ((NVIC_ST_CTRL_R & 0x10000) == 0) {} // Wait for COUNT flag
    }

    void delayMs(uint32_t ms) {
        uint32_t ticks = (SYS_CLOCK / 1000) * ms;
        SysTickDelay(ticks);
    }

```

```

    }

    void sendBit(uint8_t bit) {
        if (bit) {
            GPIO_PORTA_DATA_R |= LED_PIN; // HIGH
            SysTickDelay(13); // Approx. 800ns
            GPIO_PORTA_DATA_R &= ~LED_PIN; // LOW
            SysTickDelay(7); // Approx. 450ns
        } else {
            GPIO_PORTA_DATA_R |= LED_PIN; // HIGH
            SysTickDelay(6); // Approx. 400ns
            GPIO_PORTA_DATA_R &= ~LED_PIN; // LOW
            SysTickDelay(13); // Approx. 850ns
        }
    }

    void sendByte(uint8_t byte) {
        int i; // Declare the loop variable 'i' here
        for (i = 7; i >= 0; i--) { // Send 8 bits, MSB first
            sendBit((byte >> i) & 0x01);
        }
    }

void sendColor(uint8_t green, uint8_t red, uint8_t blue) {
    sendByte(green); // Send Green byte
    sendByte(red); // Send Red byte
    sendByte(blue); // Send Blue byte
}

```

## New code:

Here is an example code to control the WS2812B RGB LEDs using the inbuilt UART of the Tiva C TM4C123GH6PM microcontroller. This code is written for Code Composer Studio and assumes you have the appropriate WS2812B protocol implemented using GPIO and UART for data input.

```

#include <stdint.h>
#include <stdbool.h>
#include "tm4c123gh6pm.h"

// UART and SysTick initialization
void UART_Init(void);
void SysTick_Init(void);
void SysTick_DelayUs(uint32_t delay);
void WS2812B_SendColor(uint8_t red, uint8_t green, uint8_t blue);
void WS2812B_SendReset(void);

// WS2812B Parameters
#define NUM_LEDS 16
#define LED_PIN (1U << 2) // Assuming PF2 is connected to the data
                             pin of WS2812B

// LED Color Buffer
uint8_t ledBuffer[NUM_LEDS][3]; // Format: [Green, Red, Blue]

// GPIO Initialization for WS2812B
void GPIO_Init(void) {
    SYSTCTL_RCGCGPIO_R |= SYSTCTL_RCGCGPIO_R5; // Enable clock for
    GPIOF
    while ((SYSTCTL_PRGPIO_R & SYSTCTL_PRGPIO_R5) == 0);
    GPIO_PORTF_DIR_R |= LED_PIN; // Set PF2 as output
    GPIO_PORTF_DEN_R |= LED_PIN; // Enable PF2 digital functionality
    GPIO_PORTF_DATA_R &= ~LED_PIN; // Initialize pin to low
}

int main(void) {
    char input;
    uint8_t red = 0, green = 0, blue = 0;

    UART_Init();
    SysTick_Init();
    GPIO_Init();

    while (1) {
        // Wait for data from UART
        input = UART0_DR_R; // Read received character

        // Example: Change colors based on keyboard input
        if (input == 'R') { red = 255; green = 0; blue = 0; } // Red
        if (input == 'G') { red = 0; green = 255; blue = 0; } //
            Green
        if (input == 'B') { red = 0; green = 0; blue = 255; } // Blue

        // Update all LEDs with the new color
        for (int i = 0; i < NUM_LEDS; i++) {
            ledBuffer[i][0] = green;

```

```

        ledBuffer[i][1] = red;
        ledBuffer[i][2] = blue;
    }

    // Send colors to WS2812B
    for (int i = 0; i < NUM_LEDS; i++) {
        WS2812B_SendColor(ledBuffer[i][1], ledBuffer[i][0],
            ledBuffer[i][2]);
    }
    WS2812B_SendReset();
}

// Function to initialize UART0
void UART_Init(void) {
    SYSCTL_RCGCUART_R |= SYSCTL_RCGCUART_R0; // Enable UART0
    SYSCTL_RCGCGPIO_R |= SYSCTL_RCGCGPIO_R0; // Enable PORTA clock
    UART0_CTL_R &= ~UART_CTL_UARTEN; // Disable UART0
    UART0_IBRD_R = 104; // Set baud rate to 9600
    UART0_FBRD_R = 11;
    UART0_LCRH_R = UART_LCRH_WLEN_8; // 8-bit, no parity, 1
    stop bit
    UART0_CTL_R |= UART_CTL_UARTEN; // Enable UART0
    GPIO_PORTA_AFSEL_R |= 0x03; // Enable PA0, PA1
    alternate functions
    GPIO_PORTA_DEN_R |= 0x03; // Enable PA0, PA1
    digital functions
    GPIO_PORTA_PCTL_R |= 0x11; // Set PA0, PA1 for UART
}

// Function to initialize SysTick
void SysTick_Init(void) {
    NVIC_ST_CTRL_R = 0; // Disable SysTick
    NVIC_ST_RELOAD_R = 0xFFFFF; // Max reload value
    NVIC_ST_CURRENT_R = 0; // Clear current value
    NVIC_ST_CTRL_R = 5; // Enable SysTick with processor
    clock
}

// Microsecond delay using SysTick
void SysTick_DelayUs(uint32_t delay) {
    NVIC_ST_RELOAD_R = (delay * 16) - 1; // For 16 MHz clock
    NVIC_ST_CURRENT_R = 0;
    while ((NVIC_ST_CTRL_R & 0x10000) == 0); // Wait for COUNT flag
}

// Function to send color data to WS2812B
void WS2812B_SendColor(uint8_t red, uint8_t green, uint8_t blue) {
    uint8_t color[3] = {green, red, blue};
    for (int j = 0; j < 3; j++) {
        for (int i = 7; i >= 0; i--) {
            if (color[j] & (1 << i)) {

```

```

        GPIO_PORTF_DATA_R |= LED_PIN; // High for '1'
        SysTick_DelayUs(0.9);          // ~900 ns
        GPIO_PORTF_DATA_R &= ~LED_PIN; // Low
        SysTick_DelayUs(0.35);          // ~350 ns
    } else {
        GPIO_PORTF_DATA_R |= LED_PIN; // High for '0'
        SysTick_DelayUs(0.35);          // ~350 ns
        GPIO_PORTF_DATA_R &= ~LED_PIN; // Low
        SysTick_DelayUs(0.9);           // ~900 ns
    }
}

}

}

// Function to send reset signal
void WS2812B_SendReset(void) {
    GPIO_PORTF_DATA_R &= ~LED_PIN;
    SysTick_DelayUs(80); // >50us reset pulse
}

```