# Akhilesh Kumar

http://branded.me/akhilesh\_k akhilesh\_k@outlook.com | +91-9829754634 14-H 45-D Azad Bhawan, JUIT Waknaghat, Himachal Pradesh-173234

## **EDUCATION**

## TION TECHNOLOGY WAKNAGHAT

**B.Tech Electronics and COMMUNICATION ENGINEERING FRESHMEN** Expected June 2020 CGPA: 6.6/10.0

#### C.G. SCHOOL, BHABUA

HIGH SCHOOL Grad. April 2015 | Bhabua, India Percentage: 72.4%

#### D.A.V. PUBLIC SCHOOL

**CERTIFICATE OF MERIT** Grad. April 2013 | Sasaram, India CGPA: 10.0/10.0

## LINKS

Github://akhilesh k LinkedIn://akhilesh\_k

## COURSEWORK

Programming & Data Structures Discrete Mathematics Basic Electronics Devices & Circuit Advanced Calculus Artificial Intelligence (EdX) The Arduino Platform and C Prog. (Coursera) Introduction to MATLAB (EdX) Control of Mobile Robots (Coursera) Machine Learning (EdX)

## TECHNICAL EXPERTISE

#### HARDWARE

ATmega • Arduino • Raspberry Pi • TI Development Boards

#### **SOFTWARE**

Pspice • LabView • SolidWorks • Proteus •Visual Studio •Gazebo

## LANGUAGES

C • Python • C++ • LATEX • MATLAB • BASH

• PHP • Embedded C

#### **Systems**

Git • OpenCV • Internet of Things

## **EXTRA-CURRICULARS**

Flocution • Dramatics • Basket Ball

## RESEARCH EXPERIENCE/ PROJECTS

## JAYPEE UNIVERSITY OF INFORMA- UNDER WATER GLIDER FOR REAL TIME MAPPING WITH SENSORTAG IOT SYSTEM | ACM-ELECTRONICS TEAM |

December 2016 - January 2017

- Accomplished automated movement of the glider controlled with a ballast system. Developed obstacle-avoiding feature and algorithm for mapping of environment using MATLAB.
- Used Sensor Tag TI CC2650 to pair it with Raspberry Pi device and retrieve data in real time on web interface.
- Glider was balanced using accelerometer.

### IOT BASED POLLUTION MONITORING AND WASTE MANAGEMENT FOR SMART CITIES | ACM ELECTRONICS

TEAM | March 2017 - Present

- Accomplished communication between Dustbins acreoss the city and server on web platfrom.
- Interfaced Xbee modules with Raspberry Pi for dustbins localization.
- Conceptualized model of routes optimization for waste pickups using Google Maps API.

## MOTION IMITATING AND PATH REPLICATING ROBOT **ENABLED WITH MAPPING | PROJECT LEADER | March**

2017-Present

- Bot based on Arduino and interfaced with Raspberry Pi
- Bot uses a Pi cam as input to handle control & object recognition using
- Real time video streaming with python client on Raspberry Pi.

#### INTELLIGENT ALARM SYSTEM WITH ANDROID **INTERFACE** | PROJECT MEMBER | October 2016-December 2016

• Pattern recognizing alarm based on Arduino which can set on from an android UI.

#### **INCOMING MAIL NOTIFICATION SYSTEM | FEBRUARY** 2016-PRESENT

• Built on Pyton Tkinter and serverside on Flask

## POSITIONS OF RESPONSIBILITY

## MEMBER OF ORGANIZING COMMITTEE | TECHNICAL TEAM | February 2016

• As part of the university's official Annual Techfest- Murious XI

#### **ORGANIZING MEMBER | IPR CELL- JUIT**

Organized Workshop on Patent filing

## CO-CURRICULAR ACCOLADES

Mar, 2017 Participated in National Level Dramatics Competetion-Mantha 2<sup>nd</sup> in University's Dramatics Competition- Hallla Bol Feb. 2017

Oct. 2013 National Level Chess- CBSE