view_frames Result

Recorded at time: 1742040679.279

base_link

Broadcaster: /my_gen3/robot_state_publisher
Average rate: 40.204 Hz
Most recent transform: 1742040679.264 (0.014 sec old)
Buffer length: 4.975 sec

shoulder_link

Broadcaster: /my_gen3/robot_state_publisher
Average rate: 40.204 Hz
Most recent transform: 1742040679.264 (0.014 sec old)
Buffer length: 4.975 sec

half_arm_1_link

Broadcaster: /my_gen3/robot_state_publisher
Average rate: 40.204 Hz
Most recent transform: 1742040679.264 (0.014 sec old)
Buffer length: 4.975 sec

half_arm_2_link

Broadcaster: /my_gen3/robot_state_publisher
Average rate: 40.204 Hz
Most recent transform: 1742040679.264 (0.014 sec old)
Buffer length: 4.975 sec

forearm_link

Broadcaster: /my_gen3/robot_state_publisher
Average rate: 40.204 Hz
Most recent transform: 1742040679.264 (0.014 sec old)
Buffer length: 4.975 sec

spherical_wrist_1_link

Broadcaster: /my_gen3/robot_state_publisher
Average rate: 40.204 Hz
Most recent transform: 1742040679.264 (0.014 sec old)
Buffer length: 4.975 sec

spherical_wrist_2_link

Broadcaster: /my_gen3/robot_state_publisher
Average rate: 40.204 Hz
Most recent transform: 1742040679.264 (0.014 sec old)
Buffer length: 4.975 sec

bracelet_link

Broadcaster: /my_gen3/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1742040679.279 sec old)
Buffer length: 0.000 sec

end_effector_link

Broadcaster: /my_gen3/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1742040679.279 sec old)
Buffer length: 0.000 sec

Broadcaster: /my_gen3/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1742040679.279 sec old)
Buffer length: 0.000 sec

Broadcaster: /my_gen3/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1742040679.279 sec old)
Buffer length: 0.000 sec

camera_link

robotiq_arg2f_base_link

tool_frame

Broadcaster: /camera/camera_color_tf_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1742040679.279 sec old)
Buffer length: 0.000 sec

Broadcaster: /camera/camera_depth_tf_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1742040679.279 sec old)
Buffer length: 0.000 sec

Broadcaster: /my_gen3/robot_state_publisher
Average rate: 40.204 Hz
Most recent transform: 1742040679.264 (0.014 sec old)
Buffer length: 4.975 sec

Broadcaster: /my_gen3/robot_state_publisher
Average rate: 40.204 Hz
Most recent transform: 1742040679.264 (0.014 sec old)
Buffer length: 4.975 sec

Broadcaster: /my_gen3/robot_state_publisher
Average rate: 40.204 Hz
Most recent transform: 1742040679.264 (0.014 sec old)
Buffer length: 4.975 sec

Broadcaster: /my_gen3/robot_state_publisher
Average rate: 40.204 Hz
Most recent transform: 1742040679.264 (0.014 sec old)
Buffer length: 4.975 sec

camera_color_frame

camera_depth_frame

left_outer_knuckle

right_outer_knuckle

left_inner_knuckle

right_inner_knuckle

Broadcaster: /my_gen3/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1742040679.279 sec old)
Buffer length: 0.000 sec

Broadcaster: /my_gen3/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1742040679.279 sec old)
Buffer length: 0.000 sec

left_outer_finger

right_outer_finger

Broadcaster: /my_gen3/robot_state_publisher
Average rate: 40.204 Hz
Most recent transform: 1742040679.264 (0.014 sec old)
Buffer length: 4.975 sec

Broadcaster: /my_gen3/robot_state_publisher
Average rate: 40.204 Hz
Most recent transform: 1742040679.264 (0.014 sec old)
Buffer length: 4.975 sec

left_inner_finger

right_inner_finger

Broadcaster: /my_gen3/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1742040679.279 sec old)
Buffer length: 0.000 sec

Broadcaster: /my_gen3/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1742040679.279 sec old)
Buffer length: 0.000 sec

left_inner_finger_pad

right_inner_finger_pad