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Knowledge Checks

Question 1

1/1 point (graded)

Which three statements characterize the difference between supervised learning, unsupervised learning and reinforcement learning?

- Supervised learning uses marked or known cases to train an algorithm to predict these cases correctly.
- Unsupervised learning attempts to find structure or relationships between cases in a data set without the need for marked cases.
- A reinforcement learning agent learns by measuring the error between predictions and known correct results in data cases.
- A reinforcement learning agent learns to interact with an environment and attempts to optimize its actions to maximize rewards received.
- Reinforcement learning seeks to reduce the dimensionality of the state information by averaging the error between the original state data and the encoding of that data.



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You have used 1 of 2 attempts

✓ Correct (1/1 point)

Question 2

1/1 point (graded)

Which of the following examples is NOT a suitable reward function for reinforcement learning?

- A robot must pick up a component and place it in the correct position on a circuit board and receives a reward of 1 if this task is done correctly and -10 if the part is placed incorrectly, or if the robot strikes any of the other components on the circuit board.
- A tic-tac-to player receives a receives a reward of 1 for winning the game, and no reward for a tie or lost game.
- An agent is trained to drive a car using rules derived from the correct behavior of human drivers.



An agent must pick assets for a pension fund which must pay its benefits over time. The agent receives positive rewards for assets that appreciate more than a target return level and negative rewards for assets which do not achieve this performance.

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Question 3

1/1 point (graded)

Which three features are absolutely required for a reinforcement learning agent?

■ A method to mark the time of interactions with the environment.

■ A way for the agent to sense the state of its environment.
A reward function the agent can use to judge success in the task.
Correctly marked cases to train the agent.
A model of the environment the agent will interact with.
A way for the agent to take actions in the environment.
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✓ Correct (1/1 point)
Question 4
1/1 point (graded)
Which of the following is NOT a component of a reinforcement learning problem?
The environment sends the information of reward to the agent.
The agent decides to act based on certain policy.
 The agent determines which reward it should get based on its action.
The environment sends the information of state to the agent.
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✓ Correct (1/1 point)

Question 5

1/1 point (graded)

Which two of the following are good applications for reinforcement learning?

- An agent that discovers structure in data to reduce the dimensionality.
- Steering a self-driving car, where the reward is positive for arriving at a destination and negative for coming too close to obstacles, other vehicles, edges of driving lanes, or failure to obey traffic rules.
- A robot which sells refreshments to people waiting for an airplane flight a reward function that is positive for each person who buys a refreshment and negative for each passenger who does not buy anything.
- An inventory management agent that places orders for products that is trained using the history of demand for the products.



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✓ Correct (1/1 point)

Question 6

1/1 point (graded)

Which of the following are differences between episodic tasks and continuing tasks?

• An episodic tasks run for a fixed number of time steps, whereas continuing tasks proceed for an infinite number of tasks.

 An episodic task has a terminal state, whereas the continuing task has no terminal state.
An episodic task can only run once, whereas a continuing task runs indefinitely.
An episodic task receives rewards at the end of each episode, whereas a continuous task can receives rewards at any time.
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✓ Correct (1/1 point)
Question 7
1/1 point (graded)
Which of the following are episodic tasks?
Playing a game of chess.
An agent for a self-driving car which determines the route for each trip.
A robot that places parts on assemblies in a factory.
All of the above.
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✓ Correct (1/1 point)

Question 8

1/1 point (graded)

Which two of the following definitions of value functions are correct?

- A state value function maps the value of a particular action given the state.
- ☑ A state value function maps the state to the value of being in that state.
- A value-state function (action-state function) maps taking a particular action from a state to the value of that action from the state.
- A value-state function (action-state function) maps the value of a series of states.



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