

Ans ② Given, $\bar{w} = \begin{pmatrix} 1 \\ \epsilon \end{pmatrix} \in \mathbb{R}^2$

So,

$$\|w\|_1 = 1 + \epsilon \longrightarrow L_1 \text{ Norm}$$

$$\|w\|_2 = \sqrt{1 + \epsilon^2} \longrightarrow L_2 \text{ Norm}$$

Now, comparing the results obtained by reducing \bar{w} by a small value $\begin{pmatrix} \alpha \\ 0 \end{pmatrix}$ where $\alpha < \epsilon$

$$\left. \begin{aligned} \left\| \begin{pmatrix} 1 \\ \epsilon \end{pmatrix} - \begin{pmatrix} \alpha \\ 0 \end{pmatrix} \right\|_1 &= 1 - \alpha + \epsilon \\ \left\| \begin{pmatrix} 1 \\ \epsilon \end{pmatrix} - \begin{pmatrix} 0 \\ \alpha \end{pmatrix} \right\|_1 &= 1 - \alpha + \epsilon \end{aligned} \right\} L_1 \text{ Norms}$$

$$\left. \begin{aligned} \left\| \begin{pmatrix} 1 \\ \epsilon \end{pmatrix} - \begin{pmatrix} \alpha \\ 0 \end{pmatrix} \right\|_2 &= \sqrt{1 - 2\alpha + \alpha^2 + \epsilon^2} \\ \left\| \begin{pmatrix} 1 \\ \epsilon \end{pmatrix} - \begin{pmatrix} 0 \\ \alpha \end{pmatrix} \right\|_2 &= \sqrt{1 - 2\epsilon\alpha + \alpha^2 + \epsilon^2} \end{aligned} \right\} L_2 \text{ Norms}$$

We can see,

for L_2 norm, regularizing the larger term results in larger reduction in norm output when compared to smaller one.

Whereas for L_1 norm, reduction is independent of quantity being penalized and is always equal to α .

Hence, L_2 norm discourages sparsity.

Ans ① Given, training set is $(\bar{x}_{1:N}, t_{1:N})$ using Least Squares approach, estimated model parameter is:-

$$\bar{w}^{(N)} = \left(\Phi^T(\bar{x}) \Phi(\bar{x}) \right)^{-1} \Phi^T(\bar{x}) t$$

\Rightarrow

Now, estimated target values for given additional M input points $(x_{N+1:N+M})$ can be regressed by:—

$$\hat{t} = y(\bar{x}, \bar{w}) = \bar{w}^{(N)T} \phi(\bar{x}_{N+1:N+M})$$

So, modified train set is $:= (\bar{x}_{1:N+M}, \bar{t}_{1:N+M})$ and final error with new train set:—

$$J(\bar{w}) = \frac{1}{2} \sum_{n=1}^M (t_n - w^T \phi(x_n))^2$$

$$J(\bar{w}) = \frac{1}{2} \sum_{n=1}^N (t_n - w^T \phi(x))^2 + \frac{1}{2} \sum_{n=N+1}^{N+M} (\hat{t}_n - w^T \phi(x_n))^2$$

$$\nabla J(\bar{w}) = \underbrace{-\phi^T(x)(t - w^T \phi(x))}_{x=1 \text{ to } N} - \underbrace{\phi^T(x)(w^{(N)T} \phi(x) - w^T \phi(x))}_{x=N+1 \text{ to } N+M}$$

$$= 0$$

$$\Rightarrow \phi^T(x) \phi(x) w^{N+M} = \phi^T(x) t + \phi^T(x) \phi(x) w^N$$

$$w^{N+M} = (\phi^T(x) \phi(x))^{-1} \phi^T(x) t + (\phi^T(x) \phi(x))^{-1} \phi^T(x) \phi(x) w^N$$

$$w^{N+M} = w^N + (\phi^T(x) \phi(x))^{-1} \phi^T(x) t$$

Hence, w^{N+M} performs better than w^N .

Ans (4) $\bar{x} = [0 \ 1]^T$

$$\bar{t} = \left[\begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} -1 \\ -2 \end{pmatrix}, \begin{pmatrix} -2 \\ -1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \end{pmatrix} \right]$$

$$\phi(0) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \phi(1) = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\{w = (\phi^T(\bar{x}) \phi(\bar{x}))^{-1} \phi^T(x) t\}$$

$$\phi(\bar{x}) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = I_{2 \times 2} \quad \phi^T(x) \phi(x) = I$$

Hence, $\boxed{\bar{w} = \bar{t}}$

Now, given $p(\bar{t}/\bar{x}, w) = \prod_{k=1}^K \mathcal{N}(t_k / w_k^T \phi_k(x) \beta_k^{-1})$

$$\log p(\bar{t}/\bar{x}, w) = -\frac{\beta}{2} \sum_{k=1}^K (t_k - w_k^T \phi_k(x))^2 - \frac{K}{2} \log \beta - \frac{K}{2} \log 2\pi$$

$$\max \log(p(\bar{t}/\bar{x}, w)) = \min \frac{1}{2} \sum_{k=1}^K (t_k - w_k^T \phi_k(x))^2$$

$$\Rightarrow w_{ML}^{(k)} = (\phi_k^T(x) \phi_k(x))^{-1} \phi_k(x) t_k$$

$$\beta_{ML}^{(k)} = \frac{1}{K} \sum_{k=1}^K (t_k - w_{ML}^T \phi_k(x))^2$$

$$w_{ML}(0) = \left[(1 \ 0) \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right]^{-1} \begin{pmatrix} 1 \\ 0 \end{pmatrix} (-1 \ -1 \ -2 \ 1 \ 1 \ 2)$$

$$\therefore w_{ML}(0) = \begin{bmatrix} -1 & -1 & -2 & 1 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\& w_{ML}(1) = \left[(0 \ 1) \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right]^{-1} \begin{pmatrix} 0 \\ 1 \end{pmatrix} (-1 \ -2 \ -1 \ 1 \ 2 \ 1)$$

$$w_{ML}(1) = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ -1 & -2 & -1 & 1 & 2 & 1 \end{bmatrix}$$

Ans (3) A/C, errors follow Laplacian distribution

$$\therefore p(t_n / \bar{x}_n, \bar{w}, \beta) = e_n \sim \text{Laplace}(0, b)$$

$$= \frac{1}{2b} \exp\left(-\frac{e_n}{b}\right)$$

$$\therefore \text{mean} = b, \text{ variance} = b^2$$

$$(a) J_L(\bar{w}) = \max \cdot -\frac{\beta}{2} \sum_{n=1}^N (t_n - \bar{w}^T \phi(x_n))^2$$

$$(b) \cancel{w_{MAP}} = (\cancel{\phi^T \phi})^{-1} \cancel{\phi^T t} \quad w_{MAP} = (\phi^T \phi + \lambda I)^{-1} \phi^T t$$

where $\lambda = \frac{\alpha}{\beta}$ corresponding to L_1 regularized regularization term is $\frac{\alpha}{\beta} (w, 1) = \lambda (w, 1)$