

**BIRLA INSTITUTE OF TECHNOLOGY AND SCIENCE, PILANI,
HYDERABAD CAMPUS
INSTRUCTION DIVISION
FIRST SEMESTER 2016-2017
Course Handout (Part II)**

Date: 01.08.2016

In addition to part I (General Handout for all courses appended to the time table) this portion gives further specific details regarding the course.

Course No. : ME F432
Course Title : Computer Aided Manufacturing
Instructor-in-charge : Kurra Suresh

1. Scope and objective of the Course:

To increase the productivity, industry has tried to apply more computerized automation in manufacturing. This has led to an increased number of computer-controlled machine tools, an appearance of industrial robots in the production lines. This trend towards computerized manufacturing is leading to a demand for appropriately trained engineers to design and maintain these systems. The course aims to provide an introduction to the theory and applications of control in the manufacturing area. It presents concepts of computer control as applied to stand-alone manufacturing systems (such as Machine tools and industrial robots) computer aided process planning, production control, inspection & quality control and provides a useful approach to their implementation. Projects using CAD/CAM software (PRO-E, CATIA) and CNC machines demonstrations are highlights of the course.

2. Text Book:

1. Yoram Koren., "Computer Control of Manufacturing Systems", McGraw-Hill International edition, 1985.

Reference Books:

1. P.N. Rao, "CAD/CAM", Tata McGraw-Hill, New Delhi, 2003
2. Ibrahim Zeid, "Mastering CAD/CAM", Tata McGraw-Hill, New Delhi
3. P.N. Rao, N.K. Tewari, and T.K. Kundra., "Computer Aided Manufacturing", Tata McGraw-Hill, New Delhi.

3. Course Plan:

Lec. No.	Objective	Topics	Chap. (T/R)
1-2	Introduction	<ul style="list-style-type: none">• Basic concepts of manufacturing• Fundamentals, advantages• Classifications of NC systems	T1-1
3	To introduce features of NC machine tools	<ul style="list-style-type: none">• Design considerations of machine tools• Methods of improving accuracy• Increasing productivity with NC machines• Machining Centres, MCU functions	T1- 2
4	To equip students with NC Part Programming skills	<ul style="list-style-type: none">• Introduction• Manual Programming	R1
5-7		<ul style="list-style-type: none">• Manual Programming - Lathe	R1

8-9		• Manual Programming - Milling	R1
10-11	To introduce other part programming techniques	<ul style="list-style-type: none"> • Computer Aided Programming • APT programming • Other programming Systems 	R1
12-13	Introduction to CAD	<ul style="list-style-type: none"> • Curves and surfaces • Geometric transformations 	R2
14-16	Machining of freeform surfaces	<ul style="list-style-type: none"> • Toolpath generation • 5 and 4 axis machining 	Class notes
17-19	Pro/Manufacturing	<ul style="list-style-type: none"> • Toolpath generation using CAD/CAM packages 	Class notes
20-21	Master CAM	<ul style="list-style-type: none"> • Tool path generation using CAM packages 	
22-23	To introduce various CAM system devices	<ul style="list-style-type: none"> • Drives • Feedback devices • Counting devices, • Digital to Analog converters • Hydraulic Systems 	T1-4
24-25	To make familiar students with Interpolators	<ul style="list-style-type: none"> • DDA integrator • DDA Hardware interpolator • CNC software interpolators • Software DDA interpolators 	T1-5
26	To explain control loops of NC system	<ul style="list-style-type: none"> • Control of point to point systems • Control loops in contouring systems 	T1-6
27	CNC Tooling	<ul style="list-style-type: none"> • Cutting tools • Work holding devices • Cutting process parameter selection 	R1-11
28-29	To introduce Adaptive Controls	<ul style="list-style-type: none"> • Introduction • Adaptive Control with optimization • Adaptive control with constraints 	T1-8
30	To make students to grasp Industrial Robots fundamentals	<ul style="list-style-type: none"> • Basic concepts in Robotics • The manipulator • The control and drives 	
31	To introduce robot programming and economic aspects	<ul style="list-style-type: none"> • Robot programming • Intelligent robots • Economics • Applications of robots 	R3
32-33	To explain use of computers in process planning	<ul style="list-style-type: none"> • What is process planning • Computer Aided Process Planning (CAPP) • Group Technology • Application programs 	R3
34-35	To introduce Rapid Prototyping	<ul style="list-style-type: none"> • Introduction to free form fabrication • RP Techniques 	Class Notes

36-37	To explain use of computers in inspection and quality control	<ul style="list-style-type: none"> • Quality assurance & quality control • SQC • Coordinate measuring machine, Non-contact inspection 	R3
38	To make students familiar with CIM architecture	<ul style="list-style-type: none"> • Hierarchical computer control • DNC systems • The Manufacturing Cell • Flexible Manufacturing Systems • The factory of the future 	T1-10

4. Evaluation Scheme:

Component	Duration	Weightage (%)	Date & Time	Venue	Remarks
Test I	50 mts.	15	13/9, 10.00--11 AM		OB
Test II	50 mts.	15	21/10 10.00--11 AM		CB
Compre. Exam.	3 hrs.	35	14/12 AN		CB
Seminar/Computer Project		35			OB

5. Chamber Consultation Hours: To be announced in the class.

6. Notices:

Notices, if any, concerning the course will be displayed on the CMS only.

Instructor-in-charge
ET C422/ME

C432