

INSTRUCTION DIVISION FIRST/ SECOND SEMESTER 2015-2016

Course Handout Part II

Date: 03-08-2016

In addition to part-I (General Handout for all courses appended to the time table) this portion gives further specific details regarding the course.

Course No. : MF F311

Course Title : MECHATRONICS AND AUTOMATION

Instructor-in-Charge : Dr. ARSHAD JAVED

Scope and Objective of the Course: This course is intended to a comprehensive knowledge of the technology related to Mechatronics and Automation. The necessity of integrating and embedding electronics and microprocessor into mechanical systems have been long felt, due to rapid progress in microprocessor computer based technology, in domestic products to manufacturing systems. Mechatronics is a recently defined engineering field that builds on the traditional mechanical engineering studies, combines it with technologies from the electrical, electronics, computer and control fields, using techniques such as simultaneous engineering to provide solutions in manufacturing applications. Also, mechatronics has been applied to manufacturing and other industrial automation: robotic automation found in car automated production lines, such as welding, and assembly line in computer integrated manufacture etc. This course will develop overall background of the student in interdisciplinary mechatronic technology and a broad introduction to the issues encountered and techniques required in developing mechatronic products and automation systems.

Textbooks:

- 1. W. Bolton, *Mechatronics*, 3rd Ed., Pearson, 2004. [1]
- 2. A. Smaili and F. Mrad, Applied Mechatronics, Oxford University Press, 2008. [2]

Reference books

- 1. M.P. Groover, "Automation, Production systems, and Computer-Integrated Manufacturing", PHI, 2008. [3]
- 2. W. Stadler, Analytical Robotics and Mechatronics, McGraw Hill, 1995. [4]
- 3. Tai-Ran Hsu, MEMS and Microsystems: Design and Manufacture, John Wiley & Sons. 2008. [5]

Course Plan:

Lecture No.	Learning objectives	Topics to be covered	Chapter in the Text Book
1	Understand mechatronics and the development of automation system through mechatronics	Introduction, Mechatronic systems – Examples	[1]-1
2		Introduction to automation, Key issues, Approach to Mechatronics and automation	class notes, [1]-4, [2]-14
3-5	Understanding working principles and applications of sensors	Sensors and Instrumentation: Sensor functions, Characteristics,	[1]-2, 3 [2]-11



		Applications, Specifications & Selection	
6-8	Understanding the	Actuation Systems: Pneumatic and hydraulic actuation systems	[1]-5
9	working principles and applications of different	Mechanical actuation and systems	[1]-6, class notes
10-12	actuation and transmission systems used for	Electrical Actuators	[1]-7, [2]-12, class notes
13-14	automation	Torque estimation, Performance & Selection of actuation system	[2]-12, class notes
15-17	Understanding basic control concepts	[1]-13, class notes	
18-19	Understanding the application and	Digital electronics, Digital logic, Microprocessors	[1]-14, 15
20-21	implementation of automatic control for small and large automation systems	Programmable and selection of PLC's (Programmable Logic Controller)	[1]-19, 21 class notes
22-24	Understanding the application of Industrial manipulator	Introduction, specification, selection and programming of industrial manipulator (robot).	class notes
25-26	Understanding the challenges in real time Mechatronics and Automation system	Case-Studies	[2]-14, [4], class notes
27-28	Understanding the basics of MEMS	Introduction to MEMS, Modeling and simulation of MEMS	[5]-1,2

Evaluation Scheme:

Component	Duration	Weightage (%)	Date & Time	Nature of Component
Test I	60 min	20		Close Book
Test II	60 min	20		Open Book
Tutorial		10		Open book and open discussion based assignments
Laboratory		10		
Comprehensive- Examination	3 Hrs	40		Partially Close & Open Book

Chamber Consultation Hour: To be decided based on Timetable.

Notices: All notices will be put up on CMS only.

Make-up Policy: Make-up will be given with prior concern and genuine reasons only.

INSTRUCTOR-IN-CHARGE

