



Baumer



User's Guide LXG cameras (Gigabit Ethernet)

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1. General Information

Thanks for purchasing a camera of the Baumer family. This User's Guide describes how to connect, set up and use the camera.



Read this manual carefully and observe the notes and safety instructions!

Target group for this User's Guide

This User's Guide is aimed at experienced users, which want to integrate camera(s) into a vision system.

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Classification of the safety instructions

In the User's Guide, the safety instructions are classified as follows:

Notice

Gives helpful notes on operation or other general recommendations.



Caution



Indicates a possibly dangerous situation. If the situation is not avoided, slight or minor injury could result or the device may be damaged.

2. General safety instructions

Observe the the following safety instruction when using the camera to avoid any damage or injuries.

⚠ Caution

Provide adequate dissipation of heat, to ensure that the temperature does not exceed +50 °C (+122 °F).



The surface of the camera may be hot during operation and immediately after use. Be careful when handling the camera and avoid contact over a longer period.

3. Intended Use

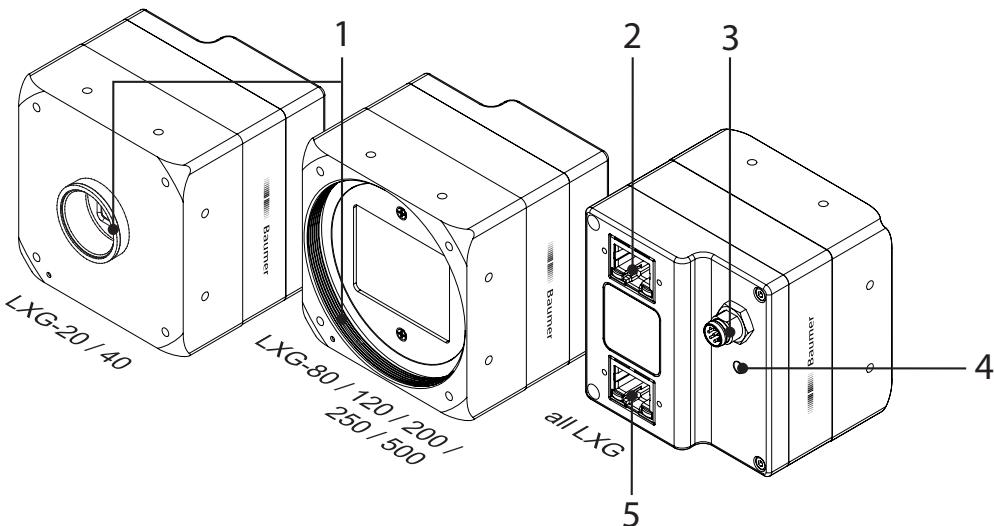
The camera is used to capture images that can be transferred over two GigE interfaces to a PC.

Notice

Use the camera only for its intended purpose!

For any use that is not described in the technical documentation poses dangers and will void the warranty. The risk has to be borne solely by the unit's owner.

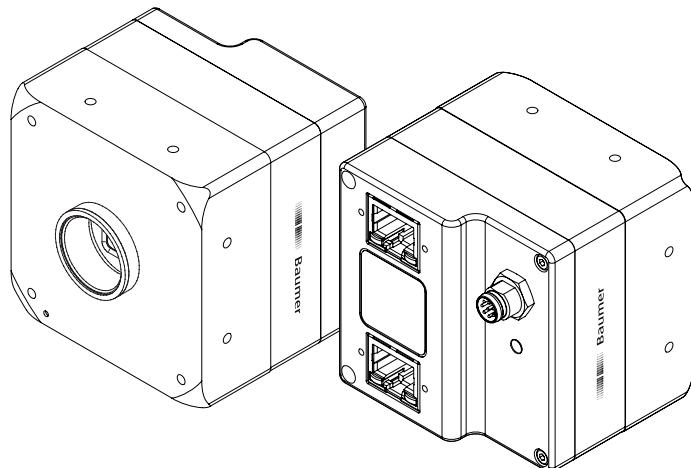
4. General Description



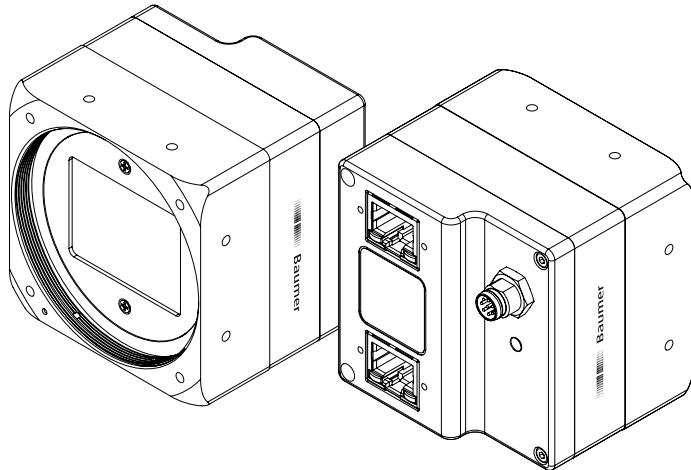
No.	Description	No.	Description
1	LXG-20 / 40 lens mount (C-Mount)	4	Signalizing LED
2	Data Port 1 (PoE)	5	Data Port 2
3	Power Supply / Digital-IO		

5. Camera Models

5.1 LXG – Camera



LXG-20M / C / NIR
LXG-40M / C / NIR

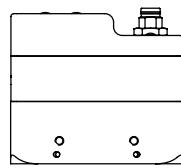


LXG-80M / C
LXG-120M / C
LXG-200M / C
LXG-250M / C
LXG-500M / C

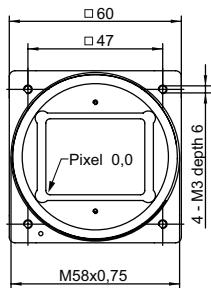
Camera Type	Sensor Size	Resolution	Full Frames [max. fps]
Monochrome / Color			
LXG-20M / C / NIR	2/3"	2048 x 1088	111
LXG-40M / C / NIR	1"	2048 x 2048	59
LXG-80M / C	4/3"	3360 x 2496	29
LXG-120M / C	APS-C	4096 x 3072	19
LXG-200M / C	35 mm	5120 x 3840	12
LXG-250M / C	APS-H	5120 x 5120	9
LXG-500M / C	35 mm	7920 x 6004	5

Dimensions

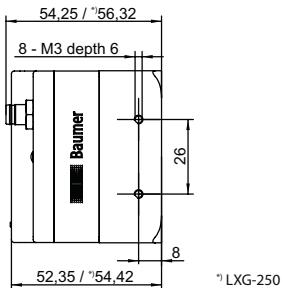
Bottom View



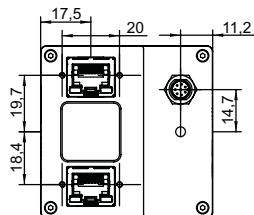
Front View



Side View



Back View



^a LXG-250

LXG-80M / C

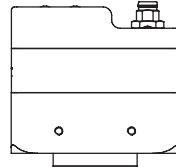
LXG-120M / C

LXG-200M / C

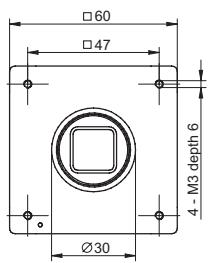
LXG-250M / C

LXG-500M / C

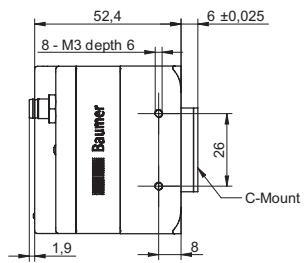
Bottom View



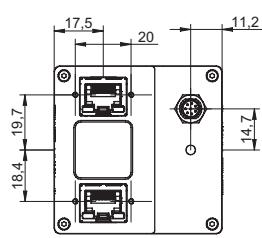
Front View



Side View



Back View



LXG-20M / C / NIR

LXG-40M / C / NIR

◀ Figure 1

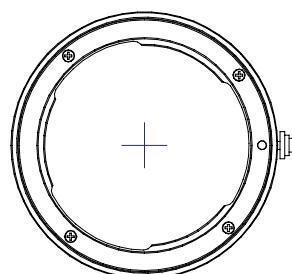
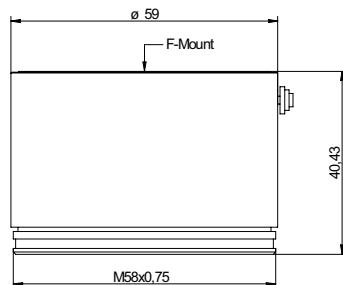
Dimensions of the Baumer LXG cameras

5.2 Lens Mount Adapter

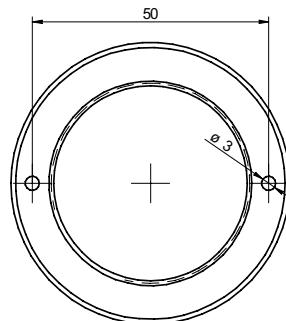
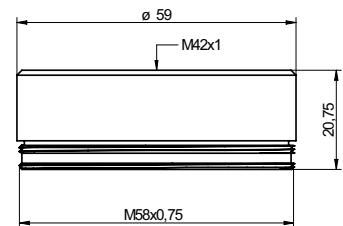
Notice

LXG-20 and LXG-40 have a C-Mount interface only.

Adapter M58 / F-Mount (Art. No.: 11117852)



Adapter M58 / M42x1-Mount (26.8mm) (Art. No.: 11127232)

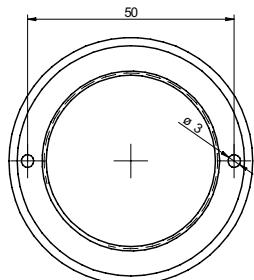
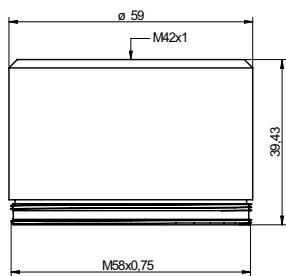


Notes:

flange focal distance: 27 mm, ±0,25 mm

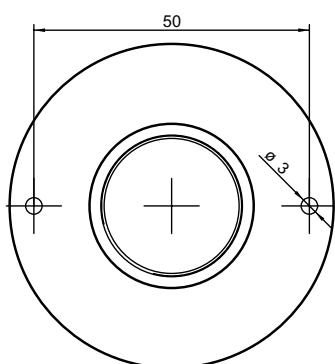
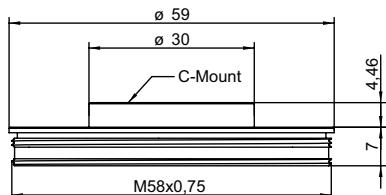
suitable for Zeiss M42 lenses (e.g. Biogon T* 2,8/21 Z-M42-I, Biogon T* 2/35 Z-M42-I, C Sonnar T* 1,5/50 Z-M42-I)

Adapter M58 / M42x1-MOUNT (45.5 mm) (Art. No: 11137781)

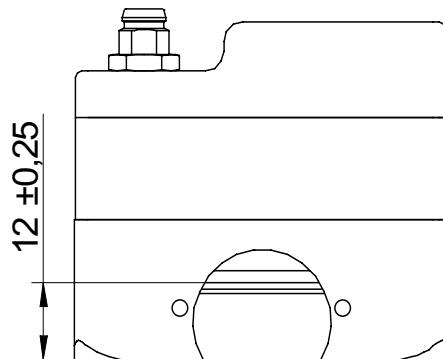


Notice: suitable for Zeiss (e.g. Distagon T* 2/25 Z-M42-I, Planar T* 1.4/50 Z-M42-I, Makro-Planar T* 2/50 Z-M42-I) and KOWA M42 lenses (e.g. LM28LF P-Mount, LM35LF P-Mount)

Adapter M58 / C-Mount (Art. No: 11115198)



5.3 Flange Focal Distance



6. Installation

Lens mounting

Notice

Avoid contamination of the sensor and the lens by dust and airborne particles when mounting the support or the lens to the device!

Therefore the following points are very important:

- Install the camera in an environment that is as dust free as possible!
- Keep the dust cover (foil) on camera as long as possible!
- Hold the print with the sensor downwards with unprotected sensor.
- Avoid contact with any optical surface of the camera!

6.1 Environmental Requirements

Temperature	
Storage temperature	-10 °C ... +70 °C (+14 °F ... +158 °F)
Operating temperature*	see Heat Transmission

* If the environmental temperature exceeds the values listed in the table below, the camera must be cooled. (see Heat Transmission)

Humidity	
Storage and Operating Humidity	10 % ... 90 % Non-condensing

6.2 Heat Transmission

⚠ Caution

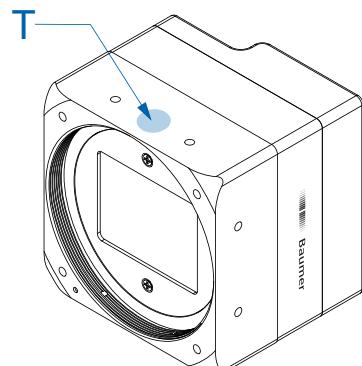
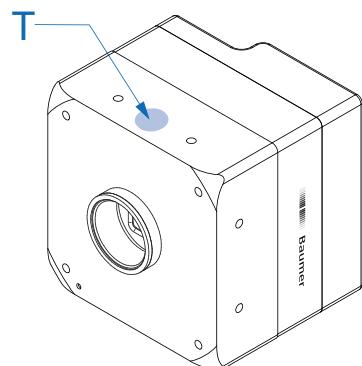
Provide adequate dissipation of heat, to ensure that the temperature does not exceed +50 °C (+122 °F) at temperature measurement point T.

The surface of the camera may be hot during operation and immediately after use. Be careful when handling the camera and avoid contact over a longer period.



As there are numerous possibilities for installation, Baumer do not specify a specific method for proper heat dissipation, but suggest the following principles:

- operate the cameras only in mounted condition
- mounting in combination with forced convection may provide proper heat dissipation



◀ Figure 2

Temperature measurement points of Baumer LXG cameras.

Measure Point	Maximal Temperature
T	60°C (140°F)

For remote temperature monitoring of the camera a temperature sensor is integrated. The temperature sensor is able to deliver values of 0°C (32°F) to +85°C (185°F)

Take care that the temperature of the camera does not exceed the specified case temperature +60°C (+140°F).

6.2.1 Emergency shutdown at Overtemperature

Notice

Feature only available on the LXG-250, LXG-500.

To prevent damage on the hardware due to high temperatures, the camera is equipped with an emergency shutdown. The *DeviceTemperatureStatusTransitionSelector* (Category: *Device Control*) feature allows you to select different thresholds for temperatures:

NormalToHigh: freely programmable value

HighToExceeded: fixed value (camera shutdown if exceeded)

ExceededToNormal: freely programmable value, temperature for error-free reactivation of the camera.

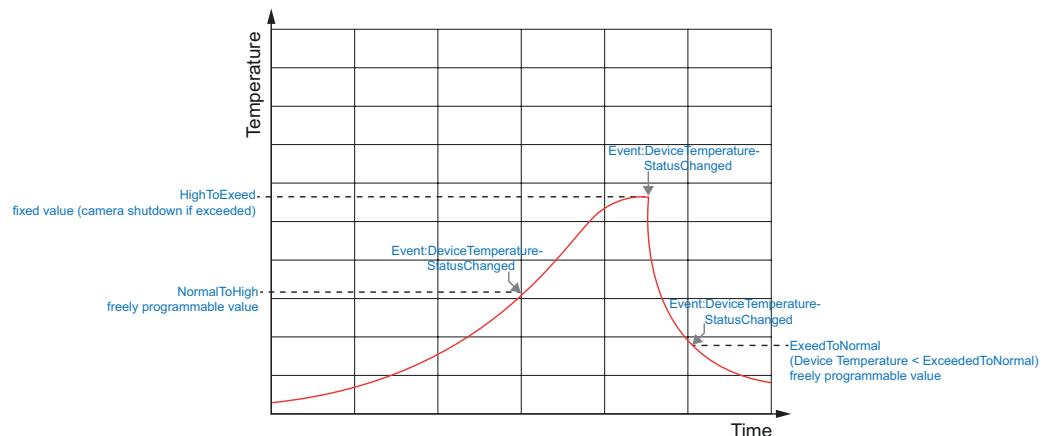
In the *DeviceTemperatureStatusTransition* feature, the temperatures for the programmable temperature transitions are set.

The *Event DeviceTemperatureStatusChanged* is always generated when *DeviceTemperatureStatus* changes.

If the temperature rises above the value set at *HighToExceeded*, the *DeviceTemperatureExceeded* feature is set to *True*, the image recording is stopped, and the LED is set to red.

For further use, the camera must disconnected from the power supply after cooling down or a device reset should be carried out.

The sufficient coolingis recognizable when the event *EvenDeviceTemperatureStatusChanged* (*Device Temperature < ExceededToNormal*) is output.



6.3 Mechanical Tests

Tested with C-Mount adapter adapter and lens dummy.

Environmental Testing	Standard	Parameter	
Vibration, sinussodial	IEC 60068-2-6	Search for Resonance	10-2000 Hz
		Amplitude underneath cross-over frequencies	0,75 mm
	IEC 60068-2-64	Acceleration	1 g
		Test duration	15 min (axis) 45 min (total)
Vibration, broad band	IEC 60068-2-64	Frequency range	10-1000 Hz
		Acceleration	10 g
		Test duration	300 min (axis) 15 h (total)
Shock	IEC 60068-2-27	Puls time	11 ms / 6 ms
		Acceleration	50 g / 100 g
Bump	IEC 60068-2-29	Pulse Time	2 ms
		Acceleration	100 g

7. Process- and Data Interface

7.1 Pin-Assignment Interface

Notice

Only Port 1 (at the top) supports Power over Ethernet (36 VDC .. 57 VDC).

For the data transfer, the ports are equal. For Single GigE connect one Port and for Dual GigE connect the second Port additionally. The order does not matter.

Data / Control 1000 Base-T (Port 1)				Data / Control 1000 Base-T (Port 2)			
1 MX1+ (green/white) (negative/positive V_{port})	5 MX3- (blue/white)	1 MX1+ (green/white) (negative/positive V_{port})	5 MX3- (blue/white)	2 MX1- (green) (negative/positive V_{port})	6 MX2- (orange) (positive/negative V_{port})	2 MX1- (green) (negative/positive V_{port})	6 MX2- (orange) (positive/negative V_{port})
3 MX2+ (orange/white) (positive/negative V_{port})	7 MX4+ (brown/white)	3 MX2+ (orange/white) (positive/negative V_{port})	7 MX4+ (brown/white)	4 MX3+ (blue)	8 MX4- (brown)	4 MX3+ (blue)	8 MX4- (brown)

7.2 Pin-Assignment Power Supply and Digital-IOs

Power Supply / Digital-IOs M8 / 8 pins		
1	(white)	OUT 3
2	(brown)	Power VCC +
3	(green)	IN 1
4	(yellow)	IO GND
5	(grey)	IO Power VCC
6	(pink)	OUT 1
7	(blue)	Power GND
8	(red)	OUT 2

Power Supply	
Power VCC	12 VDC ... 24 VDC

7.3 Power saving Mechanisms

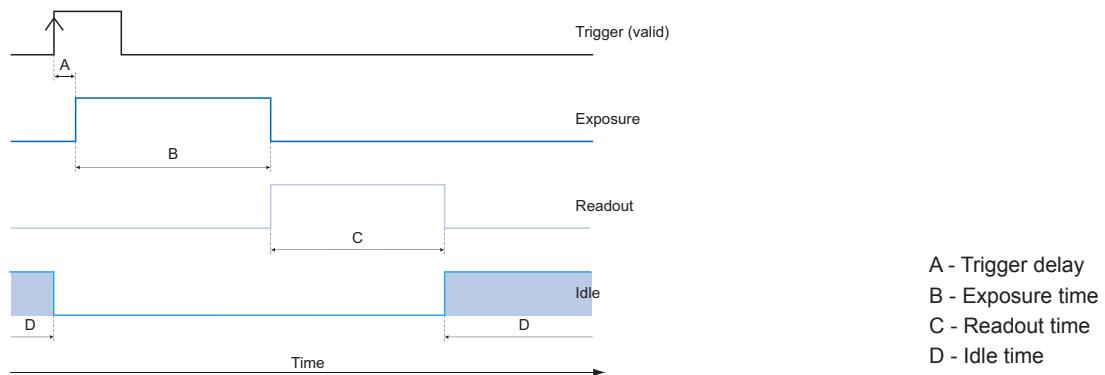
The camera is equipped with various power saving mechanisms to reduce the power consumption and to prevent excessive heating.

1. Set the sensor into idle state (LXG-250 only)

If no frame is requested for a specific time (idle time), the sensor is set into idle state. This reduces the power consumption of the camera.

The sensor is not set into idle state:

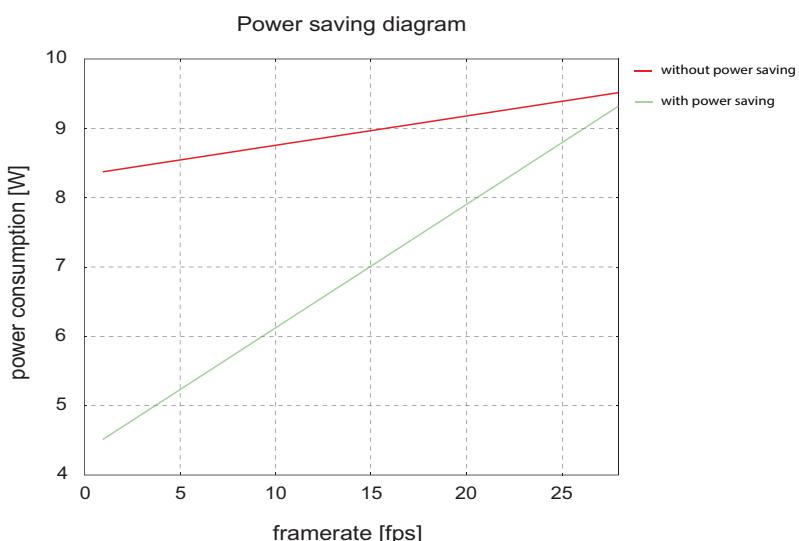
- in Sequencer Mode
- in Burst Mode
- at set Acquisition Frame Rate



2. Dynamic adjustment of the framerate (all models)

The frame rate is dynamically adjusted to the current situation. This means that only so many frames are recorded, as can be transferred via the interface with the current settings (resolution, binning, pixel format).

This dynamic adjustment only works when the feature *Acquisition Frame Rate* is deactivated, so the camera takes pictures at FreeRunning Mode.



Notice

The diagram applies for a low exposure time. As the exposure time increases, the power consumption of the camera increases even with small framerate.

7.4 LED Signaling

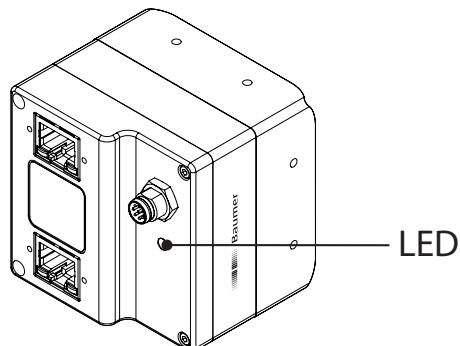


Figure 3 ▶

LED positions on Baumer LXG cameras.

	Signal	Meaning
LED	green on	Power on, link good
	green blinking	Power on, no link
	red on	Error / Overtemperature
	red blinking	Warning (update in progress, don't switch off)
	yellow	Readout active

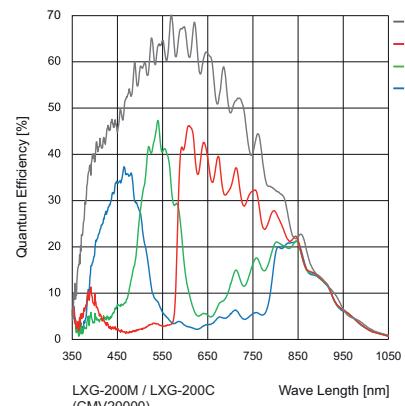
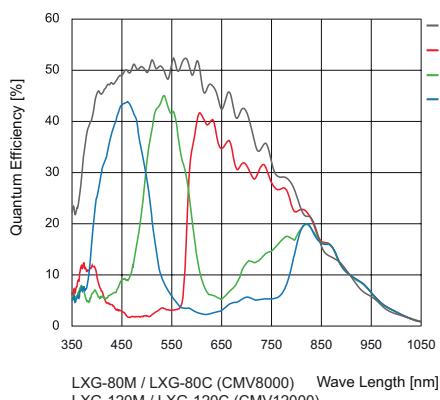
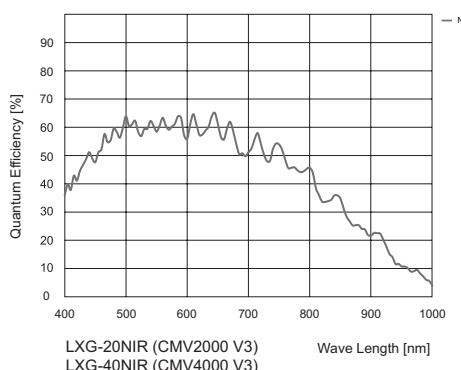
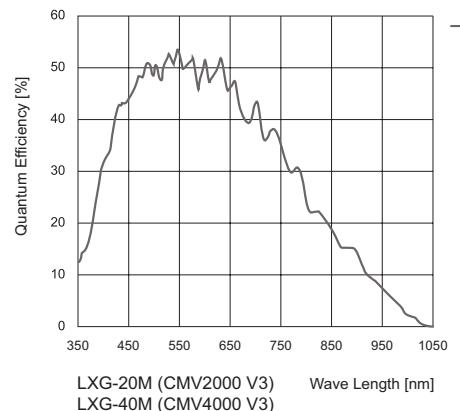
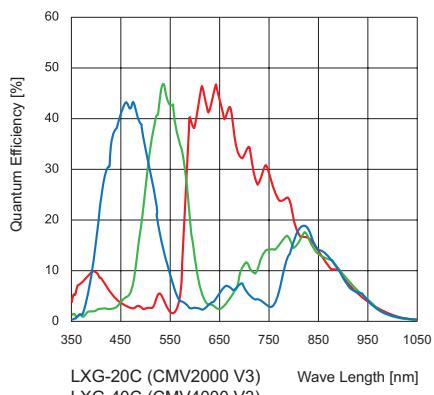
8. Product Specifications

8.1 Sensor Specifications

8.1.1 Quantum Efficiency for Baumer LXG Cameras

The quantum efficiency characteristics of monochrome and color matrix sensors for Baumer LXG cameras are displayed in the following graphs. The characteristic curves for the sensors do not take the characteristics of lenses and light sources without filters into consideration, but are measured with an AR coated cover glass.

Values relating to the respective technical data sheets of the sensors manufacturer.



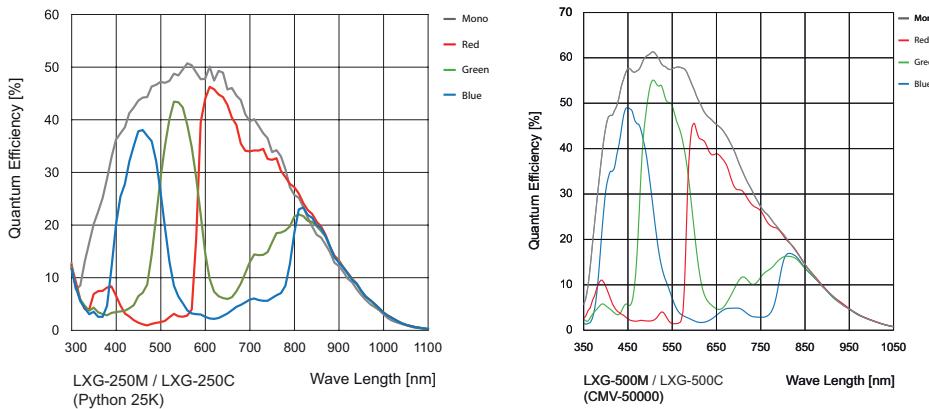


Figure 4 ▶

Quantum efficiency for Baumer LXG cameras.

8.1.2 Shutter

All cameras of the LXG series are equipped with a global shutter.

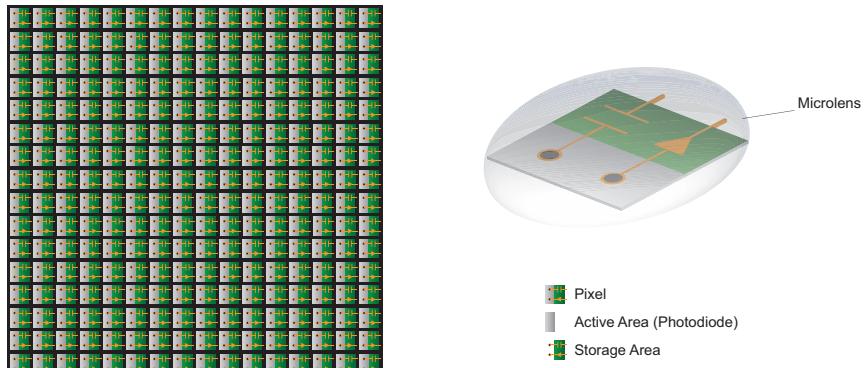


Figure 5 ▶

Structure of an imaging sensor with global shutter

Global shutter means that all pixels of the sensor are reset and afterwards exposed for a specified interval (t_{exposure}).

For each pixel an adjacent storage circuit exists. Once the exposure time elapsed, the information of a pixel is transferred immediately to its circuit and read out from there.

Due to the fact that photosensitive area gets "lost" by the implementation of the circuit area, the pixels are equipped with microlenses, which focus the light on the pixel.

8.1.3 Digitization Taps

The CMOSIS sensors, employed in Baumer LXG cameras are read out with 16 (LXG-500: 11) channels in parallel.

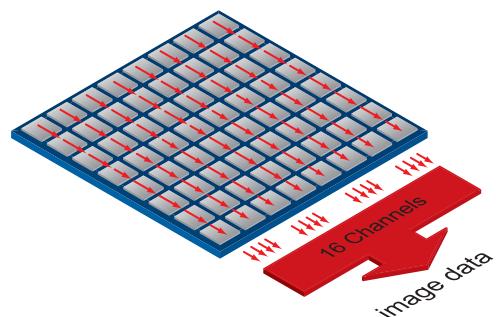
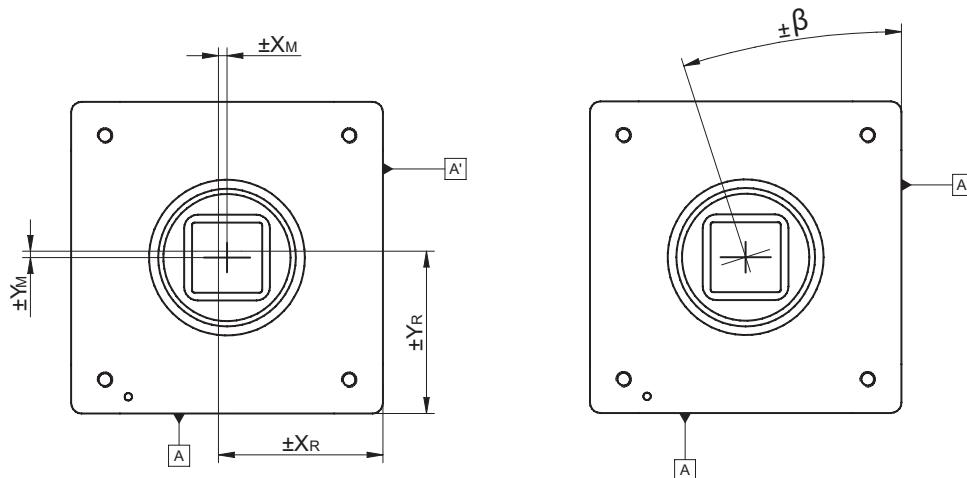


Figure 6 ▶

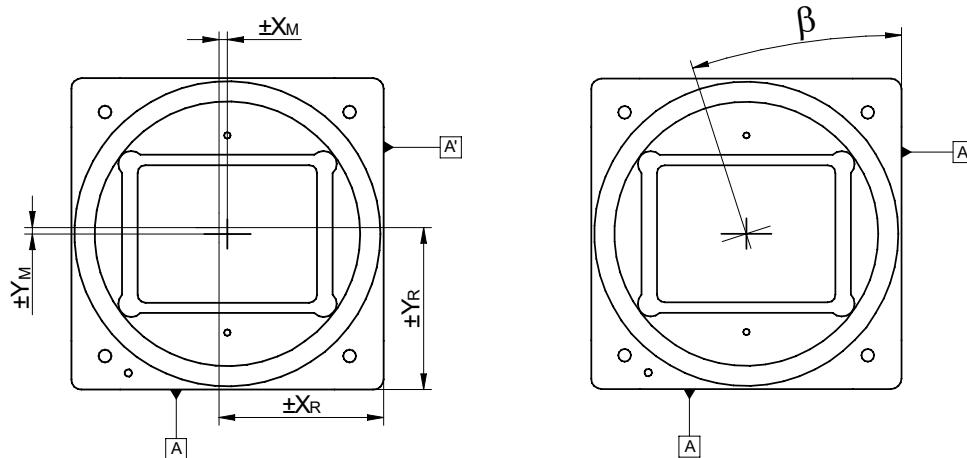
Digitization Tap of the Baumer LXG cameras
Readout with 16 channels

8.1.4 Field of View Position

The typical accuracy by assumption of the root mean square value is displayed in the figures and the table below:



LXG-20, LXG-40



LXG-80, LXG-120, LXG-200, LXG-250, LXG-500

Figure 7
Sensor accuracy of
Baumer LXG cameras.

Camera Type	$\pm X_{M,\text{typ}}$ [mm]	$\pm Y_{M,\text{typ}}$ [mm]	$\pm X_{R,\text{typ}}$ [mm]	$\pm Y_{R,\text{typ}}$ [mm]	$\pm \beta_{\text{typ}}$ [°]
LXG-20	0.09	0.09	0.1	0.1	0.4
LXG-40	0.09	0.09	0.1	0.1	0.4
LXG-80	0.07	0.06	0.08	0.07	0.26
LXG-120	0.07	0.06	0.08	0.07	0.26
LXG-200	0.08	0.08	0.09	0.08	0.27
LXG-250	0.07	0.06	0.08	0.07	0.47
LXG-500	0.1	0.09	0.1	0.09	0.31

8.2 Timings

Notice

Overlapped mode can be switched off with setting the readout mode to *sequential shutter* instead of *overlapped shutter*.

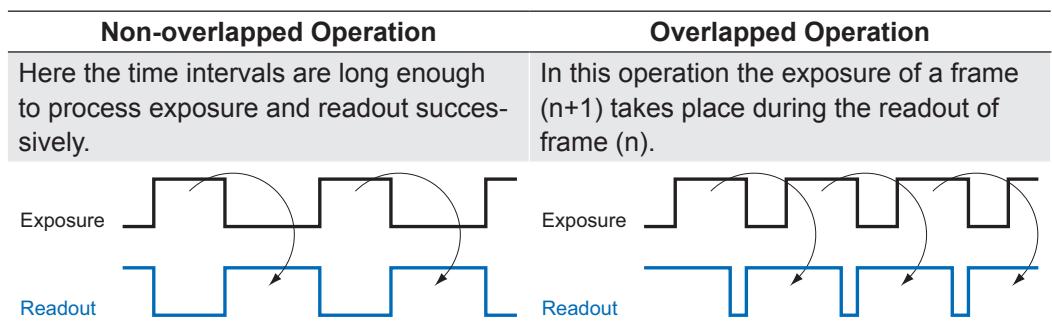
The image acquisition consists of two separate, successively processed components.

Exposing the pixels on the photosensitive surface of the sensor is only the first part of the image acquisition. After completion of the first step, the pixels are read out.

Thereby the exposure time (t_{exposure}) can be adjusted by the user, however, the time needed for the readout (t_{readout}) is given by the particular sensor and image format.

Baumer cameras can be operated with two modes, the Free Running Mode and the Trigger Mode.

The cameras can be operated non-overlapped¹⁾ or overlapped. Depending on the mode used, and the combination of exposure and readout time:

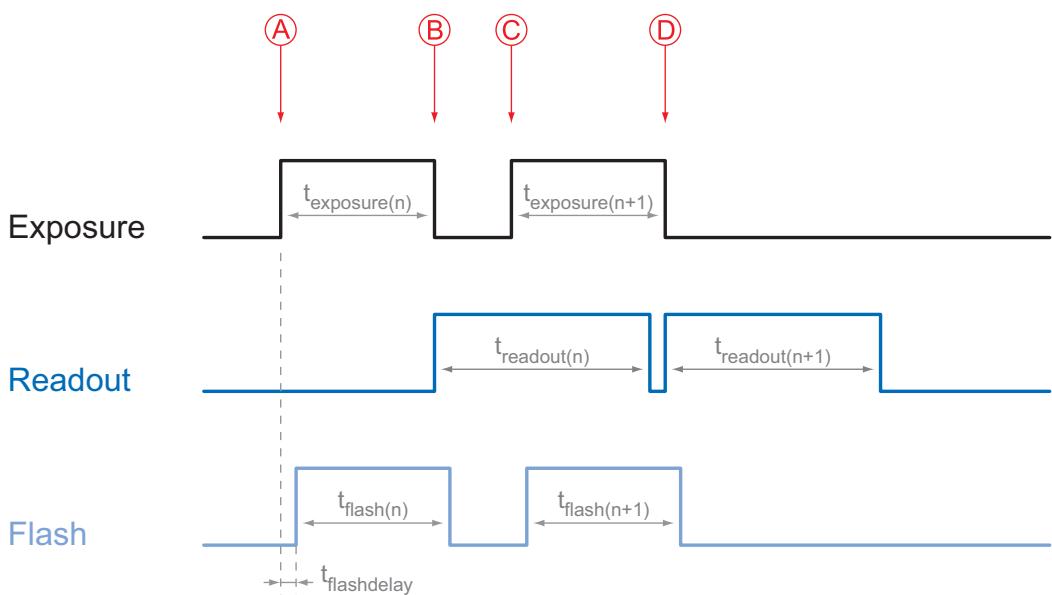


8.2.1 Free Running Mode

In the "Free Running" mode the camera records images permanently and sends them to the PC. In order to achieve an optimal (with regard to the adjusted exposure time t_{exposure} and image format) the camera is operated overlapped.

In case of exposure times equal to / less than the readout time ($t_{\text{exposure}} \leq t_{\text{readout}}$), the maximum frame rate is provided for the image format used. For longer exposure times the frame rate of the camera is reduced.

Timings:	
A - exposure time	frame (n) effective
frame (n) effective	
B - image parameters	frame (n) effective
frame (n) effective	
C - exposure time	frame (n+1) effective
frame (n+1) effective	
D - image parameters	frame (n+1) effective
frame (n+1) effective	



$$t_{\text{flash}} = t_{\text{exposure}}$$

1) Non-overlapped means the same as sequential.

8.2.2 Trigger Mode

After a specified external event (trigger) has occurred, image acquisition is started. Depending on the interval of triggers used, the camera operates non-overlapped or overlapped in this mode.

With regard to timings in the trigger mode, the following basic formulas need to be taken into consideration:

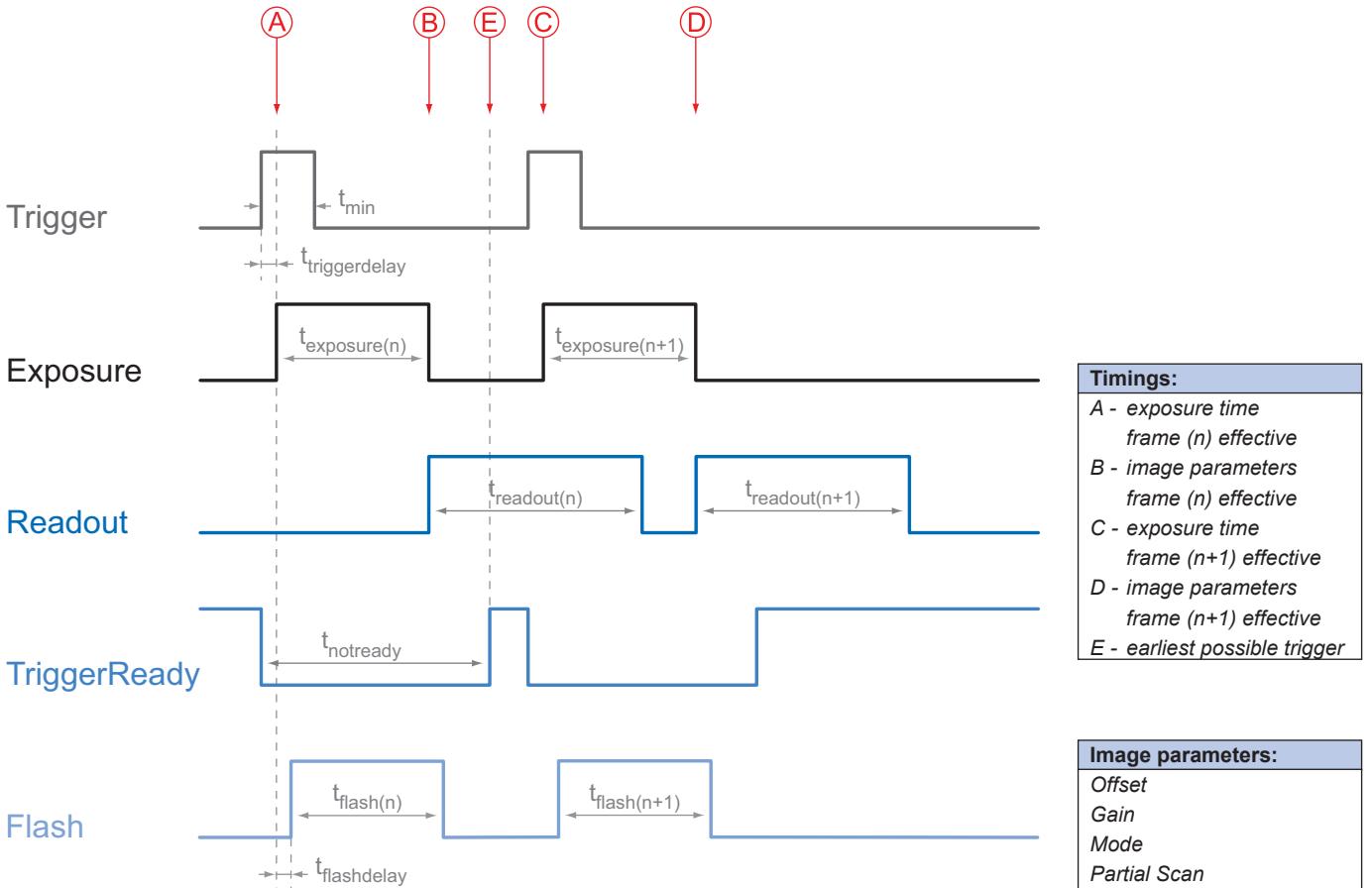
Case	Formula	
$t_{exposure} < t_{readout}$	(1)	$t_{earliestpossibletrigger(n+1)} = t_{readout(n)} - t_{exposure(n+1)}$
	(2)	$t_{notready(n+1)} = t_{exposure(n)} + t_{readout(n)} - t_{exposure(n+1)}$
$t_{exposure} > t_{readout}$	(3)	$t_{earliestpossibletrigger(n+1)} = t_{exposure(n)}$
	(4)	$t_{notready(n+1)} = t_{exposure(n)}$

8.2.2.1 Overlapped Operation: $t_{exposure(n+2)} = t_{exposure(n+1)}$

In overlapped operation attention should be paid to the time interval where the camera is unable to process occurring trigger signals ($t_{notready}$). This interval is situated between two exposures. When this process time $t_{notready}$ has elapsed, the camera is able to react to external events again.

After $t_{notready}$ has elapsed, the timing of (E) depends on the readout time of the current image ($t_{readout(n)}$) and exposure time of the next image ($t_{exposure(n+1)}$). It can be determined by the formulas mentioned above (no. 1 or 3, as is the case).

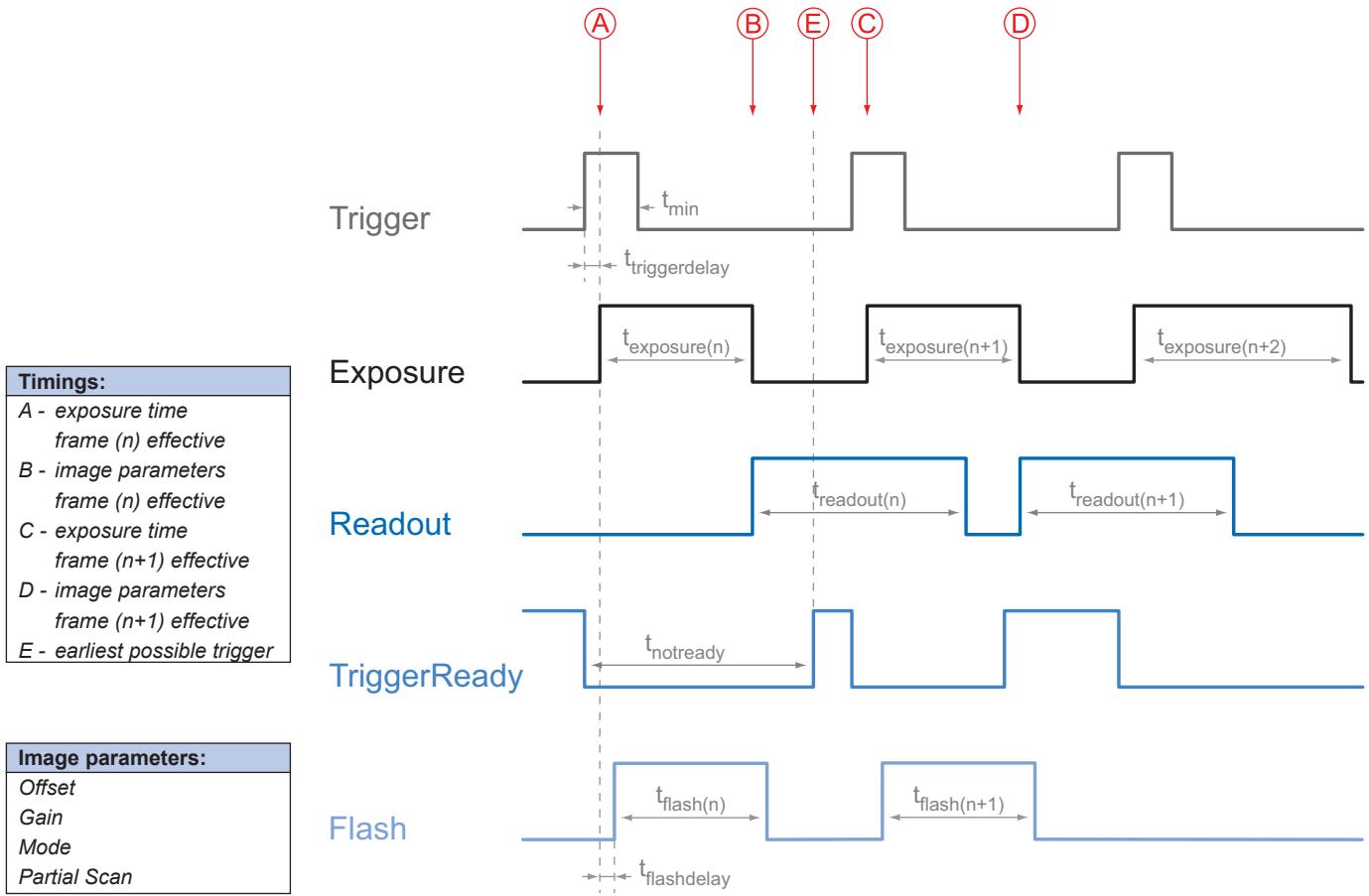
In case of identical exposure times, $t_{notready}$ remains the same from acquisition to acquisition.



8.2.2.2 Overlapped Operation: $t_{\text{exposure}(n+2)} > t_{\text{exposure}(n+1)}$

If the exposure time (t_{exposure}) is increased from the current acquisition to the next acquisition, the time the camera is unable to process occurring trigger signals (t_{notready}) is scaled down.

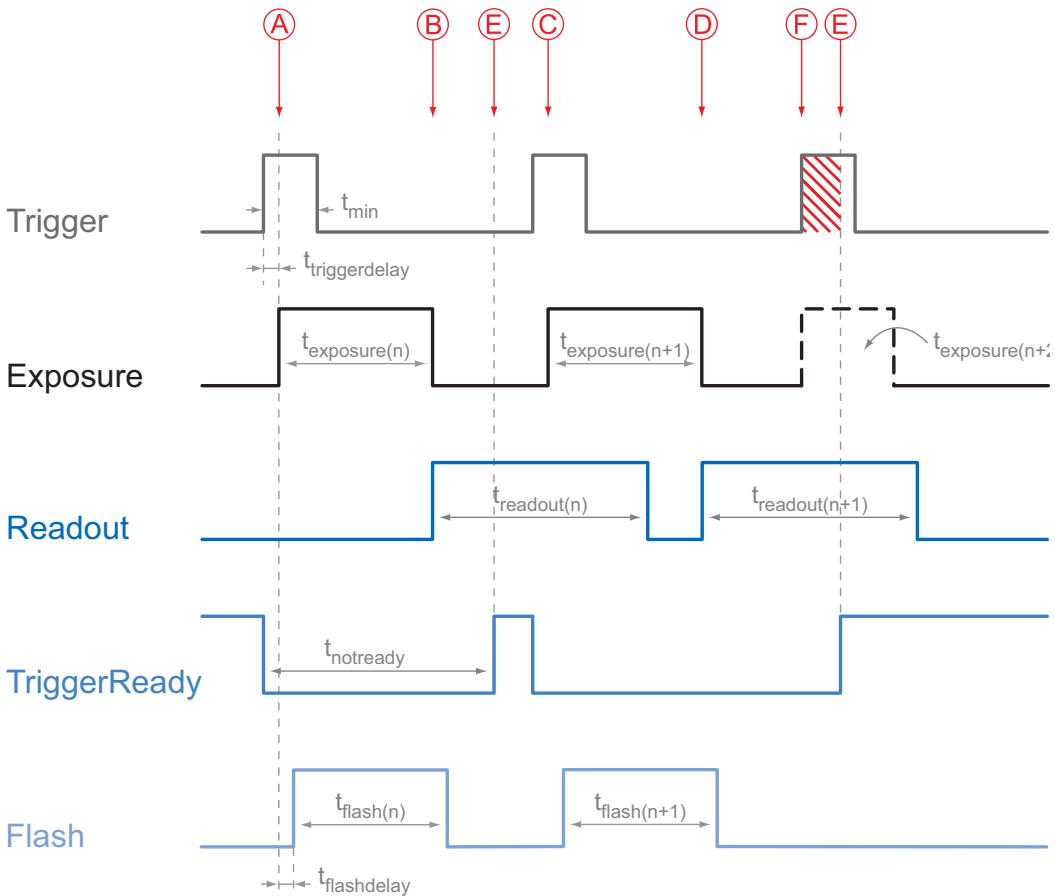
This can be simulated with the formulas mentioned above (no. 2 or 4, as is the case).



8.2.2.3 Overlapped Operation: $t_{\text{exposure}(n+2)} < t_{\text{exposure}(n+1)}$

If the exposure time (t_{exposure}) is decreased from the current acquisition to the next acquisition, the time the camera is unable to process occurring trigger signals (t_{notready}) is scaled up.

When decreasing the t_{exposure} such, that t_{notready} exceeds the pause between two incoming trigger signals, the camera is unable to process this trigger and the acquisition of the image will not start (the trigger will be skipped).



Timings:
A - exposure time frame (n) effective
B - image parameters frame (n) effective
C - exposure time frame (n+1) effective
D - image parameters frame (n+1) effective
E - earliest possible trigger
F - frame not started / trigger skipped

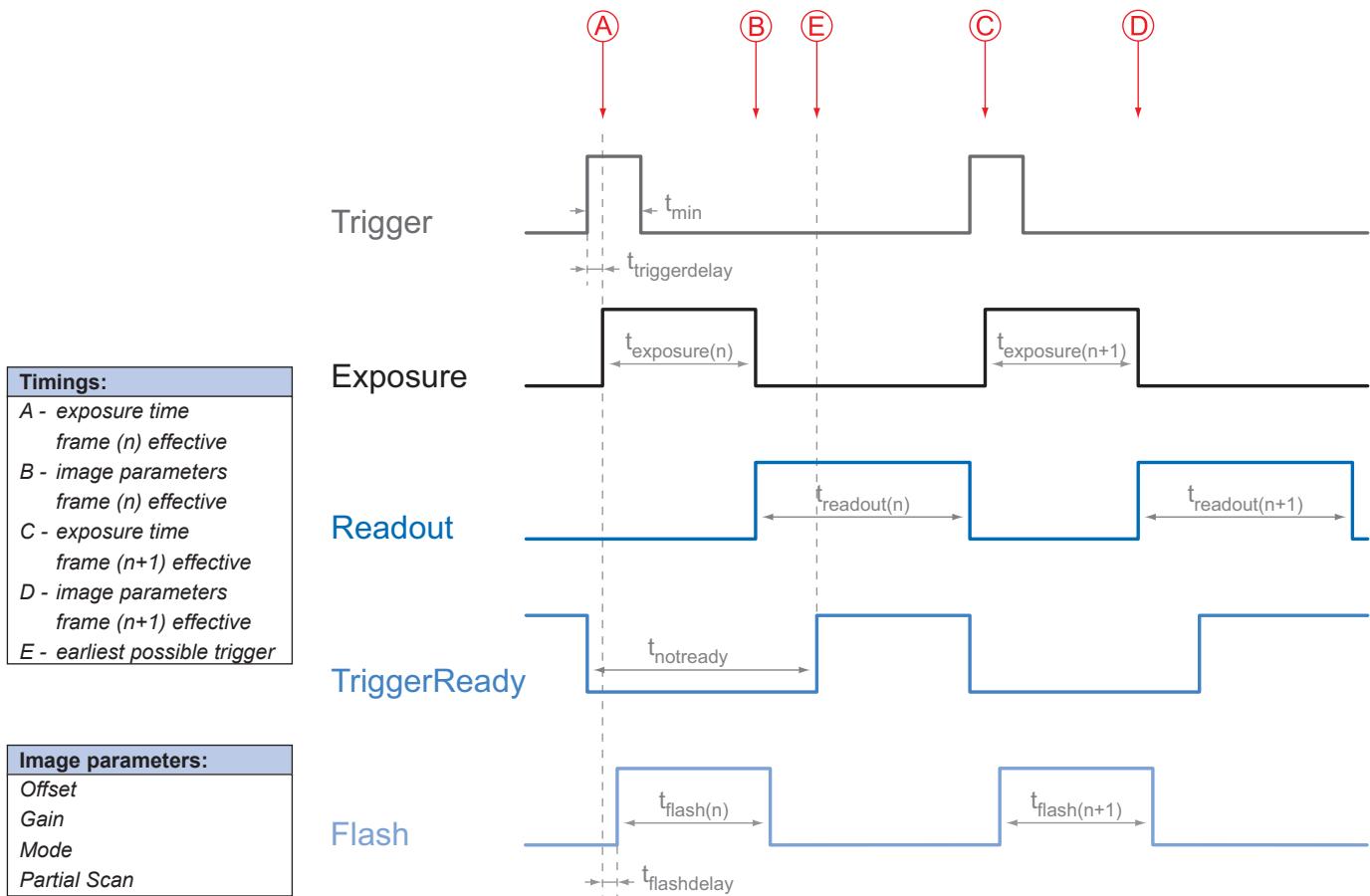
Image parameters:
Offset
Gain
Mode
Partial Scan

Notice

From a certain frequency of the trigger signal, skipping triggers is unavoidable. In general, this frequency depends on the combination of exposure and readout times.

8.2.2.4 Non-overlapped Operation

If the frequency of the trigger signal is selected for long enough, so that the image acquisitions ($t_{\text{exposure}} + t_{\text{readout}}$) run successively, the camera operates non-overlapped.



9. Software

9.1 Baumer GAPI

Baumer GAPI stands for **Baumer “Generic Application Programming Interface”**. With this API Baumer provides an interface for optimal integration and control of Baumer cameras. This software interface allows changing to other camera models.

It provides interfaces to several programming languages, such as C, C++ and the .NET™ Framework on Windows®, as well as Mono on Linux® operating systems, which offers the use of other languages, such as e.g. C# or VB.NET.

For LXG cameras Baumer GAPI v 2.3 SP1 and higher is required.

More information can be found at: <https://www.baumer.com/vision/software>

9.2 3rd Party Software

Strict compliance with the GenICam™ standard allows Baumer to offer the use of 3rd Party Software for operation with cameras.

You can find a current listing of 3rd Party Software, which was tested successfully in combination with Baumer cameras, at <https://www.baumer.com/c/14180>

10. Camera Functionalities

10.1 Image Acquisition

10.1.1 Live Mode / Buffered Mode

A distinction is made between the image capture modes *Live* and *Buffered*.

In the mode *Live*, the images are sent immediately to the PC. If images cannot be sent to the PC, they will be lost.

In the mode *Buffered* the images will be buffered in the camera in image buffers. The number of available buffer is dependent on the camera type (see table below).

Recorded images will not be lost until these image buffers are full, the images could not be sent to the PC and further images are taken.

Notice

If the buffers are full and further image recordings to be triggered by a trigger, the event *Trigger skipped* is issued.

Camera Type	Number of Buffers
Monochrome / Color	
LXG-20M / C / NIR	16
LXG-40M / C / NIR	16
LXG-80M / C	14
LXG-120M / C	14
LXG-200M / C	9
LXG-250M / C	9
LXG-500M / C	9

10.1.2 Image Format

A digital camera usually delivers image data in at least one format - the native resolution of the sensor. Baumer cameras are able to provide several image formats (depending on the type of camera).

Compared with standard cameras, the image format on Baumer cameras not only includes resolution, but a set of predefined parameter.

These parameters are:

- Resolution (horizontal and vertical dimensions in pixels)
- Binning Mode
- Decimation

Camera Type	Full frame	Binning 2x2	Binning 1x2	Binning 2x1	Decimation 2x2	Decimation 1x2	Decimation 2x1
Mono							
LXG-20M / NIR	■	■	■	■	■	■	■
LXG-40M / NIR	■	■	■	■	■	■	■
LXG-80M	■	■	■	■	■	■	■
LXG-120M	■	■	■	■	■	■	■
LXG-200M	■	■	■	■	■	■	■
LXG-250M	■	■	■	■	■	■	■
LXG-500M	■	■	■	■	■	■	■
Color							
LXG-20C	■	□	□	□	■	■	■
LXG-40C	■	□	□	□	■	■	■
LXG-80C	■	□	□	□	■	■	■
LXG-120C	■	□	□	□	■	■	■
LXG-200C	■	□	□	□	■	■	■
LXG-250C	■	□	□	□	■	■	■
LXG-500C	■	□	□	□	■	■	■

10.1.3 Pixel Format

On Baumer digital cameras the pixel format depends on the selected image format.

10.1.3.1 Pixel Formats on Baumer LXG Cameras

Camera Type	Mono8	Mono10	Mono10Packed	Mono12	Mono12Packed	BayerGB8	BayerRG8	BayerBG8	BayerGB10	BayerGB10Packed	BayerBG12	BayerRG12	BayerBG12Packed	BayerGB12Packed	BayerRG12Packed
Mono															
LXG-20M / NIR	■	■	■	□	□	□	□	□	□	□	□	□	□	□	□
LXG-40M / NIR	■	■	■	□	□	□	□	□	□	□	□	□	□	□	□
LXG-80M	■	□	□	■	■	□	□	□	□	□	□	□	□	□	□
LXG-120M	■	□	□	■	■	□	□	□	□	□	□	□	□	□	□
LXG-200M	■	□	□	■	■	□	□	□	□	□	□	□	□	□	□
LXG-250M	■	■	■	□	□	□	□	□	□	□	□	□	□	□	□
LXG-500M	□	□	□	■	■	□	□	□	□	□	□	□	□	□	□
Color															
LXG-20C	□	□	□	□	□	■	□	□	■	■	□	□	□	□	□
LXG-40C	□	□	□	□	□	□	■	□	□	■	■	□	□	□	□
LXG-80C	□	□	□	□	□	□	■	□	□	□	□	■	□	□	□
LXG-120C	□	□	□	□	□	□	■	□	□	□	□	□	■	□	□
LXG-200C	□	□	□	□	□	□	□	■	□	□	□	□	■	□	□
LXG-250C	□	□	□	□	□	□	■	□	□	■	■	□	□	□	□
LXG-500C	□	□	□	□	□	□	□	■	□	□	■	□	□	■	□

10.1.3.2 Definitions

Notice

Below is a general description of pixel formats. The table above shows, which camera support which formats.

Bayer: Raw data format of color sensors.

Color filters are placed on these sensors in a checkerboard pattern, generally in a 50% green, 25% red and 25% blue array.

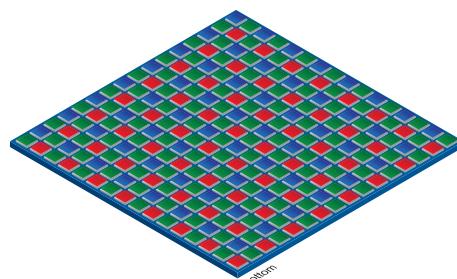
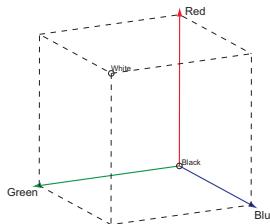


Figure 8 ▶

Sensor with Bayer Pattern.

Mono: Monochrome. The color range of mono images consists of shades of a single color. In general, shades of gray or black-and-white are synonyms for monochrome.

RGB: Color model, in which all detectable colors are defined by three coordinates, Red, Green and Blue.



◀ **Figure 9**
RGB color space displayed as color tube.

The three coordinates are displayed within the buffer in the order R, G, B.

BGR: Here the color alignment mirrors RGB.

YUV: Color model, which is used in the PAL TV standard and in image compression.

In YUV, a high bandwidth luminance signal (Y: luma information) is transmitted together with two color difference signals with low bandwidth (U and V: chroma information). Thereby U represents the difference between blue and luminance ($U = B - Y$), V is the difference between red and luminance ($V = R - Y$). The third color, green, does not need to be transmitted, its value can be calculated from the other three values.

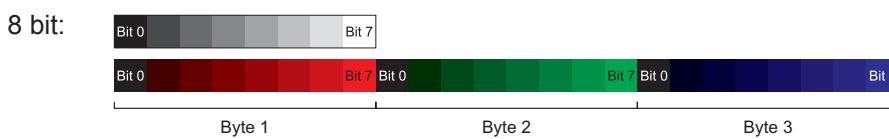
YUV 4:4:4 Here each of the three components has the same sample rate. Therefore there is no subsampling here.

YUV 4:2:2 The chroma components are sampled at half the sample rate. This reduces the necessary bandwidth to two-thirds (in relation to 4:4:4) and causes no, or low visual differences.

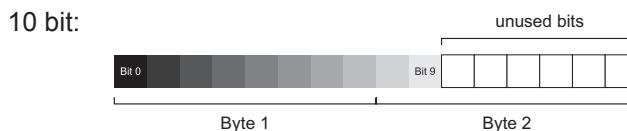
YUV 4:1:1 Here the chroma components are sampled at a quarter of the sample rate. This decreases the necessary bandwidth by half (in relation to 4:4:4).

Pixel depth: In general, pixel depth defines the number of possible different values for each color channel. Mostly this will be 8 bit, which means 2^8 different "colors".

For RGB or BGR these 8 bits per channel equal 24 bits overall.



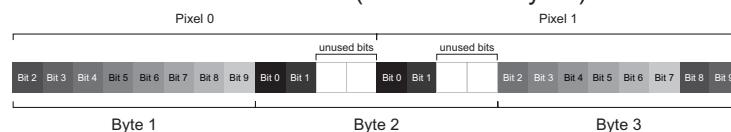
◀ **Figure 10**
Bit string of Mono 8 bit and RGB 8 bit.



◀ **Figure 11**
Spreading of Mono 10 bit over two bytes.

10 bit This pixel format defines a 10-bit monochrome, unsigned, GigE Packed Vision-specific packed format.

With this GigE Vision packing style, two 10-bit pixels are packed into 24 bits as illustrated below (little-endian layout).



◀ **Figure 12**
Spreading of Mono 12 bit over two bytes.

10.1.4 Exposure Time

On exposure of the sensor, the inclination of photons produces a charge separation on the semiconductors of the pixels. This results in a voltage difference, which is used for signal extraction.

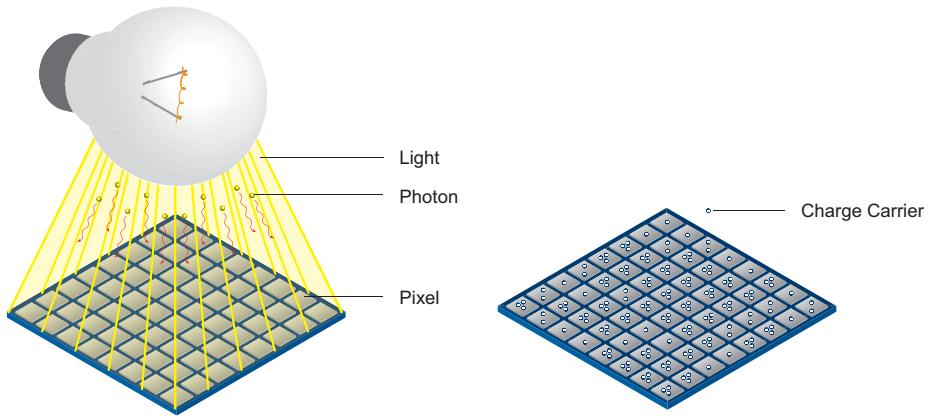


Figure 13 ▶

Incidence of light causes charge separation on the semiconductors of the sensor.

The signal strength is influenced by the incoming amount of photons. It can be increased by increasing the exposure time (t_{exposure}).

On Baumer LXG cameras, the exposure time can be set within the following ranges (step size 1 μ sec):

Camera Type	$t_{\text{exposure min}}$	$t_{\text{exposure max}}$
LXG-20M / C / NIR	30 μ sec	1 sec
LXG-40M / C / NIR	30 μ sec	1 sec
LXG-80M / C	44 μ sec	1 sec
LXG-120M / C	44 μ sec	1 sec
LXG-200M / C	190 μ sec	1 sec
LXG-250M / C	27 μ sec	1 sec
LXG-500M / C	95 μ sec	1 sec

Notice

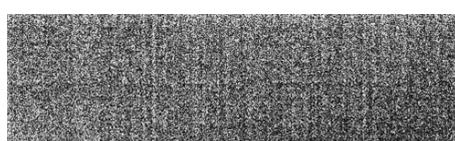
The exposure time can be programmed or controlled via trigger width.

However, the sensor needs additional time for the sampling operation during which the sensor is still light sensitive. As a consequence the real minimum exposure time is the respective $t_{\text{exposure min}}$ longer (except LXG-500).

10.1.5 PRNU / DSNU Correction (FPN - Fixed Pattern Noise)

CMOS sensors exhibit nonuniformities that are often called fixed pattern noise (FPN). However it is no noise but a fixed variation from pixel to pixel that can be corrected. The advantage of using this correction is a more homogeneous picture which may simplify the image analysis. Variations from pixel to pixel of the dark signal are called dark signal non-uniformity (DSNU) whereas photo response nonuniformity (PRNU) describes variations of the sensitivity. DSNU is corrected via an offset while PRNU is corrected by a factor.

The correction is based on columns. It is important that the correction values are computed for the used sensor readout configuration. During camera production this is derived for the factory defaults. If other settings are used (e.g. different number of readout channels) using this correction with the default data set may degrade the image quality. In this case the user may derive a specific data set for the used setup.



PRNU / DSNU Correction Off



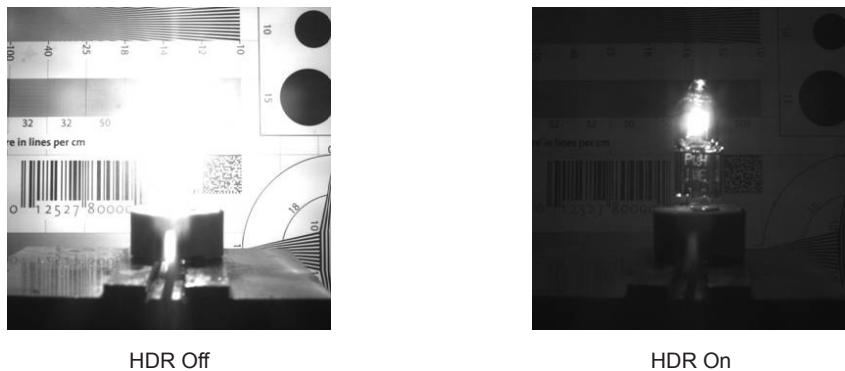
PRNU / DSNU Correction On

10.1.6 HDR (except LXG-250 / LXG-500)

Beside the standard linear response the sensor supports a special high dynamic range mode (HDR) called piecewise linear response. With this mode illuminated pixels that reach a certain programmable voltage level will be clipped. Darker pixels that do not reach this threshold remain unchanged. The clipping can be adjusted two times within a single exposure by configuring the respective time slices and clipping voltage levels. See the figure below for details.

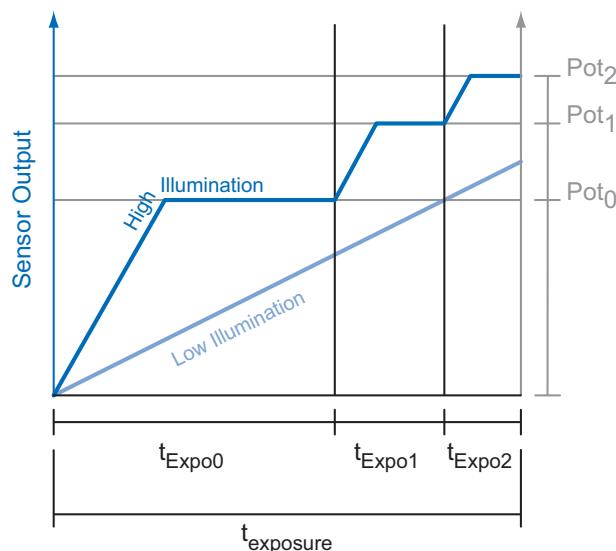
In this mode, the values for t_{Expo0} , t_{Expo1} , Pot_0 and Pot_1 can be edited.

The value for t_{Expo2} will be calculated automatically in the camera. ($t_{\text{Expo2}} = t_{\text{exposure}} - t_{\text{Expo0}} - t_{\text{Expo1}}$)



HDR Off

HDR On

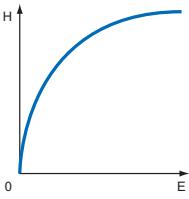


10.1.7 Look-Up-Table

The Look-Up-Table (LUT) is employed on Baumer monochrome cameras. It contains 2^{12} (4096) values for the available levels of gray. These values can be adjusted by the user.

Notice

The LUT always calculates with 12 bit input and 12 bit output. In 8/10 bit mode, the lower bits of the input values are equal zero but can be spread to full 12 bit because of digital gain. Therefore, all values of the LUT have to be filled in.



▲ Figure 14

Non-linear perception of the human eye.
H - Perception of brightness
E - Energy of light

10.1.8 Gamma Correction

With this feature, Baumer LXG cameras offer the possibility of compensating nonlinearity in the perception of light by the human eye.

For this correction, the corrected pixel intensity (Y') is calculated from the original intensity of the sensor's pixel (Y_{original}) and correction factor γ using the following formula (in oversimplified version):

$$Y' = Y_{\text{original}}^{\gamma}$$

10.1.9 Region of Interest (ROI) and Multi ROI

With this functions it is possible to predefine a so-called Region of Interest (ROI) or Partial Scan. The ROI is an area of pixels of the sensor. After image acquisition, only the information of these pixels is sent to the PC.

This functions is turned on, when only a region of the field of view is of interest. It is coupled to a reduction in resolution and increases the frame rate.

The ROI is specified by following values:

- Region Selector Region 0 / Multi-ROI horizontal 1-8, Multi-ROI vertical 1-8
- Region Mode On/Off
- Offset X - x-coordinate of the first relevant pixel
- Offset Y - y-coordinate of the first relevant pixel
- Width - horizontal size of the ROI
- Height - vertical size of the ROI

Notice

The value (Inc) of the Offset X must be a multiple of 8.

The value (Inc) of the Offset Y must be a multiple of 2 (LXG 80/120 = 4).

The value (Inc) of the Width must be a multiple of 8.

The value (Inc) of the Height must be a multiple of 2.

Notice

If defect pixels should exist in the first (mono cameras) or in the first two (color cameras) rows or columns of a ROI, these cannot be corrected with the defect pixel correction. In this case you need to move or increase the ROI by a few pixels.

The coordinates of defect pixels can be read out with the Camera Explorer (Category: Control LUT).

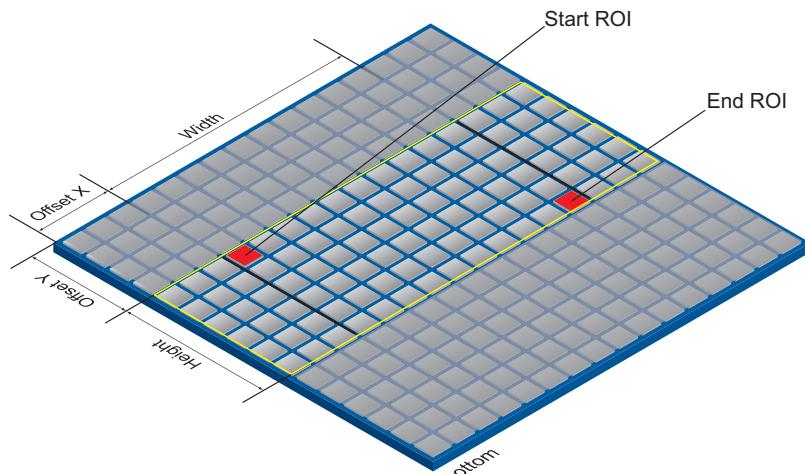


Figure 15 ▶

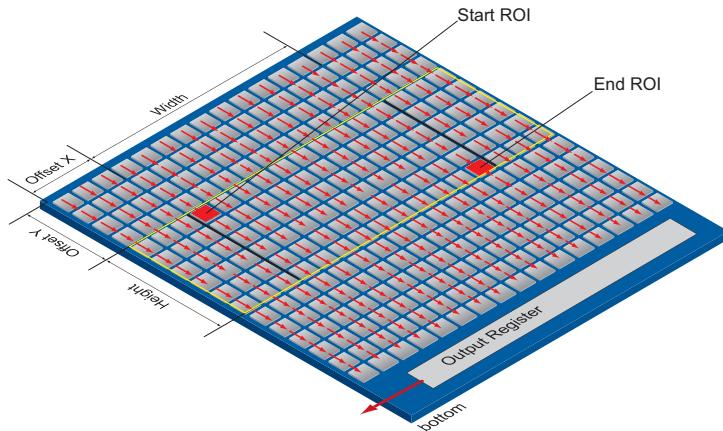
Parameters of the ROI.

10.1.9.1 Normal- ROI Readout (Region 0)

For the sensor readout time of the ROI, the horizontal subdivision of the sensor is unimportant – only the vertical subdivision is of importance.

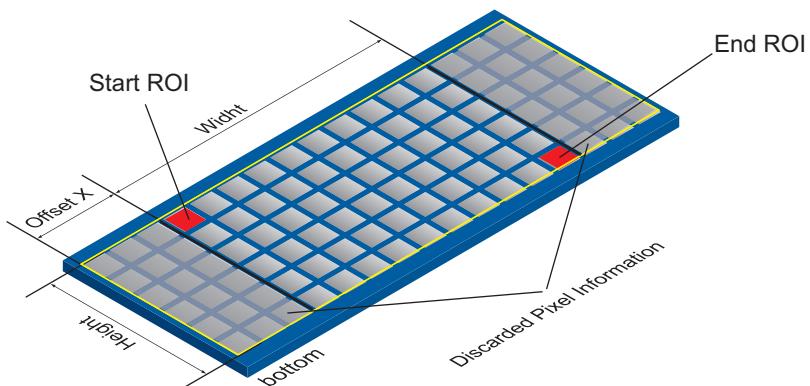
Notice

The activation of ROI turns off all Multi-ROIs.



◀ Figure 16
ROI: Readout

The readout is line based, which means always a complete line of pixels needs to be read out and afterwards the irrelevant information is discarded.



◀ Figure 17
ROI:
Discarded Information

10.1.10 Multi-ROI

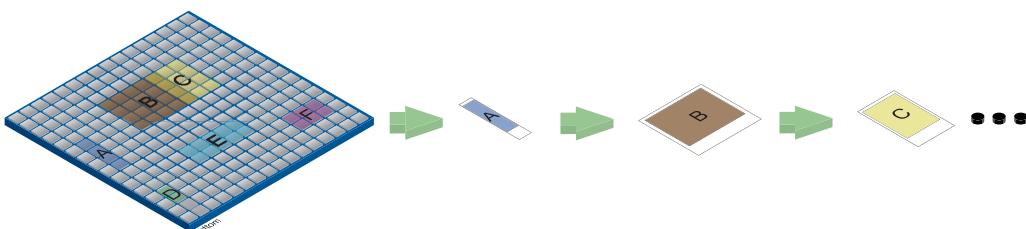
With Multi-ROI it is possible to predefine several Region of Interests (ROIs). It can be specified up to 8 ROIs. Overlapped Multi-ROIs (in the figure ROI B and C) are possible.

The camera only reads out sensor parts that are within one of the active Multi Regions. Each defined ROI is sequentially transferred in a separate frame.

The activation of Multi-ROI turns off ROI.

Notice

Multi-ROI can not be used simultaneously with Binning.



◀ Figure 18
Result frames generated by using Multi-ROI's

10.1.11 Binning

On digital cameras, you can find several operations for progressing sensitivity. One of them is the so-called "Binning". Here, the charge carriers of neighboring pixels are aggregated. Thus, the progression is greatly increased by the amount of binned pixels. By using this operation, the progression in sensitivity is coupled to a reduction in resolution.

Baumer cameras support three types of Binning – vertical, horizontal and bidirectional.

In unidirectional binning, vertically or horizontally neighboring pixels are aggregated and reported to the software as one single "superpixel".

In bidirectional binning, a square of neighboring pixels is aggregated.

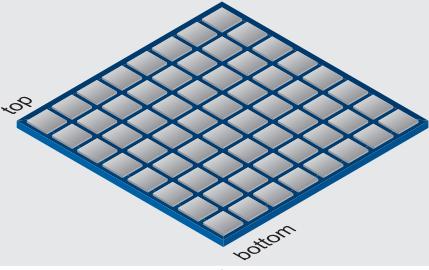
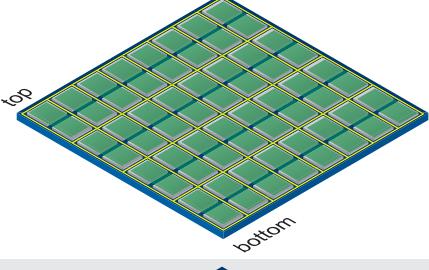
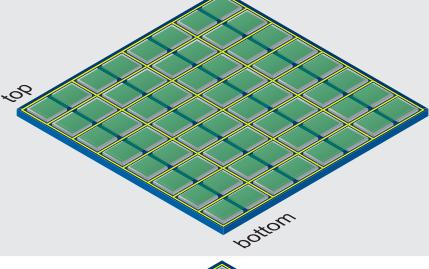
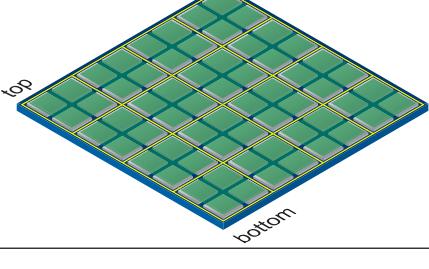
Binning	Illustration	Example
without		
1x2		
2x1		
2x2		

Figure 19 ▶

Full frame image, no binning of pixels.

Figure 20 ▶

Vertical binning causes a vertically compressed image with doubled brightness.

Figure 21 ▶

Horizontal binning causes a horizontally compressed image with doubled brightness.

Figure 22 ▶

Bidirectional binning causes both a horizontally and vertically compressed image with quadruple brightness.

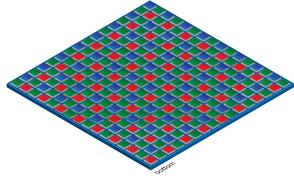
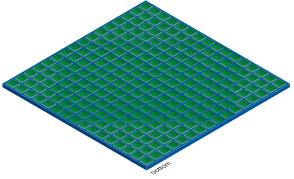
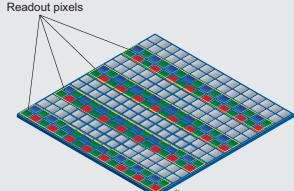
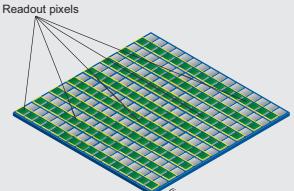
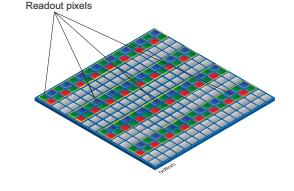
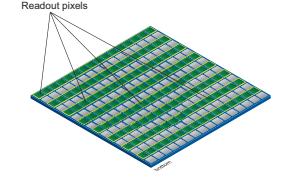
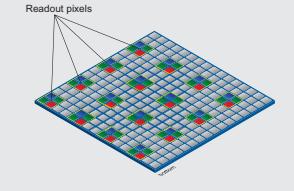
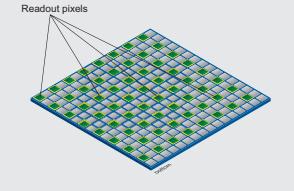
10.1.12 Decimation (sub-sampling)

In this mode, the sensor is read out partially. Thus the frame rate is increased and the amount of data transferred is reduced.

It is available for mono and color cameras. With color cameras, a color correct readout of the pixels takes place.

Notice

The camera must be stopped before decimation can be set.

Decimation	Illustration	Example	
	color	mono	
without			
1x2			
2x1			
2x2			

◀ Figure 23

Full frame image, no decimation of pixels.

◀ Figure 24

Vertical decimation causes a vertically compressed image.

◀ Figure 25

Horizontal decimation causes a horizontally compressed.

◀ Figure 26

Bidirectional decimation causes both a horizontally and vertically compressed image.

10.1.13 Brightness Correction (Binning Correction)

The summation of pixel values may cause an overload. To prevent this, binning correction was introduced.

Binninig	Realization
1x2	1x2 binning is performed within the sensor, binning correction also takes place here. A possible overload is prevented by halving the exposure time.
2x1	2x1 binning takes place within the FPGA of the camera. The binning correction is realized by aggregating the charge quantities, and then halving this sum.
2x2	2x2 binning is a combination of the above versions.

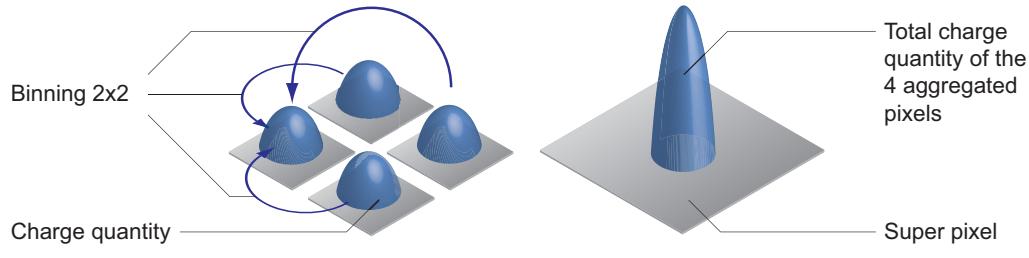


Figure 27 ▶

Aggregation of charge carriers from four pixels in bidirectional binning.

10.2 Color Adjustment – White Balance

This feature is available on all color Baumer LXG cameras and takes place within the Bayer processor.

White balance means independent adjustment of the three color channels, red, green and blue by employing of a correction factor for each channel.

10.2.1 User-specific Color Adjustment

The user-specific color adjustment in Baumer color cameras facilitates adjustment of the correction factors for each color gain. This way, the user is able to adjust the amplification of each color channel exactly to his needs. The correction factors for the color gains range from 1 to 4.

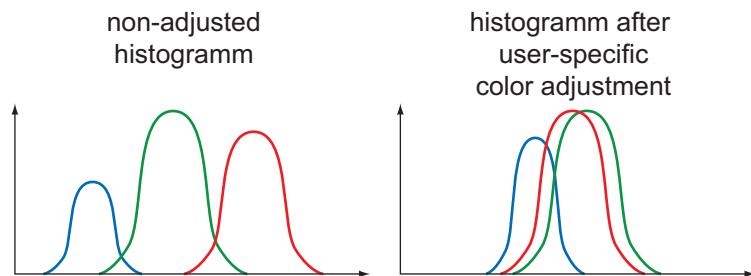


Figure 28 ▶

Examples of histograms for a non-adjusted image and for an image after user-specific white balance..

10.2.2 One Push White Balance

Notice

Due to the internal processing of the camera, One Push White Balance refers to the current ROI but always considers the entire row.

Here, the three color spectrums are balanced to a single white point. The correction factors of the color gains are determined by the camera (one time).

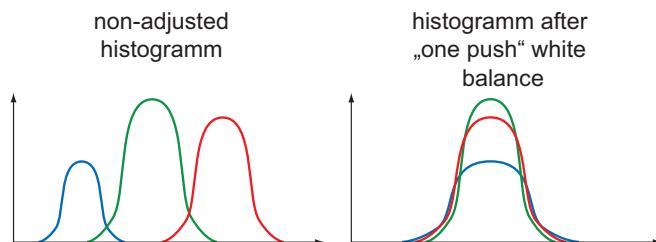


Figure 29 ▶

Examples of histograms for a non-adjusted image and for an image after "one push" white balance.

10.3 Analog Controls

10.3.1 Offset / Black Level

On Baumer LXG cameras the offset (or black level) is adjustable.

Camera Type	Values
Monochrome	
LXG-20M	0 ... 63 LSB 10 bit
LXG-20NIR	0 ... 63 LSB 10 bit
LXG-40M	0 ... 63 LSB 10 bit
LXG-40NIR	0 ... 63 LSB 10 bit
LXG-80M	0 .. 255 LSB 12 Bit
LXG-120M	0 .. 255 LSB 12 Bit
LXG-200M	0 .. 255 LSB 12 Bit
LXG-250M	0 ... 63 LSB 10 bit
LXG-500M	0 .. 255 LSB 12 Bit
Color	
LXG-20C	0 ... 63 LSB 10 bit
LXG-40C	0 ... 63 LSB 10 bit
LXG-80C	0 .. 255 LSB 12 Bit
LXG-120C	0 .. 255 LSB 12 Bit
LXG-200C	0 .. 255 LSB 12 Bit
LXG-250C	0 ... 63 LSB 10 bit
LXG-500C	0 .. 255 LSB 12 Bit

10.3.2 Gain

In industrial environments motion blur is unacceptable. Due to this fact exposure times are limited. However, this causes low output signals from the camera and results in dark images. To solve this issue, the signals can be amplified by user within the camera. This gain is adjustable from 0 to 12 db.

Notice

Increasing the gain factor causes an increase of image noise and leads to missing codes at Mono12, if the gain factor > 1.0.

10.4 Pixel Correction

Notice

If defect pixels should exist in the first (mono cameras) or in the first two (color cameras) rows or columns of a ROI, these cannot be corrected with the defect pixel correction. In this case you need to move or increase the ROI by a few pixels.

The coordinates of defect pixels can be read out and edit with the Camera Explorer (Category: *Control LUT*).

Notice

LXG-500 only

Pixels that are more than the value specified by *Pixel Correction Threshold* from the environment are dynamically corrected. If the value for *Pixel Correction Threshold* is greater than the value of the value from the environment, no correction is performed.

10.4.1 General information

A certain probability for abnormal pixels - the so-called defect pixels - applies to the sensors of all manufacturers. The charge quantity on these pixels is not linear-dependent on the exposure time.

The occurrence of these defect pixels is unavoidable and intrinsic to the manufacturing and aging process of the sensors.

The operation of the camera is not affected by these pixels. They only appear as brighter (warm pixel) or darker (cold pixel) spot in the recorded image.

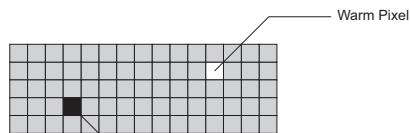


Figure 30 ▶

Distinction of "hot" and "cold" pixels within the recorded image.

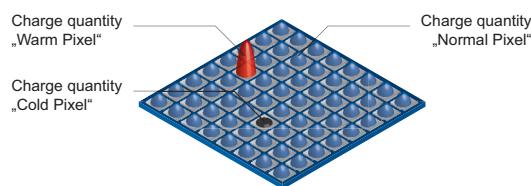


Figure 31 ▶

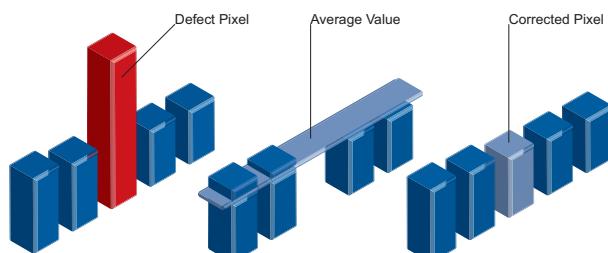
Charge quantity of "hot" and "cold" pixels compared with "normal" pixels.

10.4.2 Correction Algorithm

On Baumer LXG cameras the problem of defect pixels is solved as follows:

- Possible defect pixels are identified during the production process of the camera.
 - The coordinates of these pixels are stored in the factory settings of the camera.
- Once the sensor readout is completed, correction takes place:
- Before any other processing, the values of the neighboring pixels with the same color on the left and the right side of the defect pixel, will be read out
 - Then the average value of these pixels is determined
 - Finally, the value of the defect pixel is substituted by the previously determined average value

This works horizontally and vertically. With this approach whole defect rows and defect columns can be corrected.



10.4.3 Add Defect Pixel / Defect Columns / Defect Rows to Defect pixel list

As stated previously, this list is determined within the production process of Baumer cameras and stored in the factory settings. This list is editable.

Additional hot pixels, cold pixels, defect columns or defect rows can develop during the lifecycle of a camera. In this case Baumer offers the possibility of adding their coordinates to the defect pixel list.

The user can determine the coordinates¹⁾ of the affected pixels, columns and rows and add them to the list. Once the defect pixel list is stored in a user set, pixel correction is executed for all coordinates on the defect pixel list.

Notice

There are defect pixels, defect columns or defect rows, which occur only under certain environmental parameters. These include temperatures or exposure settings.

Complete defect pixels, defect columns or defect rows that occur in your application.

Procedure

1. Start the *Camera Explorer*. Connect to the camera. Select the profile *Gen/Cam Expert*.
2. Open the category *LUT Control*.
3. Select the to be corrected defect at *Defect Pixel List Selector* (Pixel, Column, Row).
4. Locate an empty *Defect Pixel List Index*.

An empty *Defect Pixel List Index* can be recognized by the fact that no entries are present at *Defect Pixel List Entry PosX* and *Defect Pixel List Entry PosY*.

Avoid using existing entries!

5. Determine the coordinates of the defect pixels, defect column or defect row. Keep the mouse pointer over the defect. The coordinates are displayed in the status bar.

For simplification, you can enlarge the image.

6. Enter the determined values of the defect.

Pixel

Enter the determined coordinates for X (*Defect Pixel List Entry PosX*).

Enter the determined coordinates for Y (*Defect Pixel List Entry PosY*).

Column

Enter the determined column (*Defect Pixel List Entry PosX*).

Row

Enter the determined row (*Defect Pixel List Entry PosY*).

7. Activate the registered *Defect Pixel List Index* (*Defect Pixel List Entry Active = True*).

8. Stop the camera and start them again to take over the updated entries.

1) Position in relation to Full Frame Format (Raw Data Format / No flipping).

10.5 Sequencer

10.5.1 General Information

A sequencer is used for the automated control of series of images using different sets of parameters.

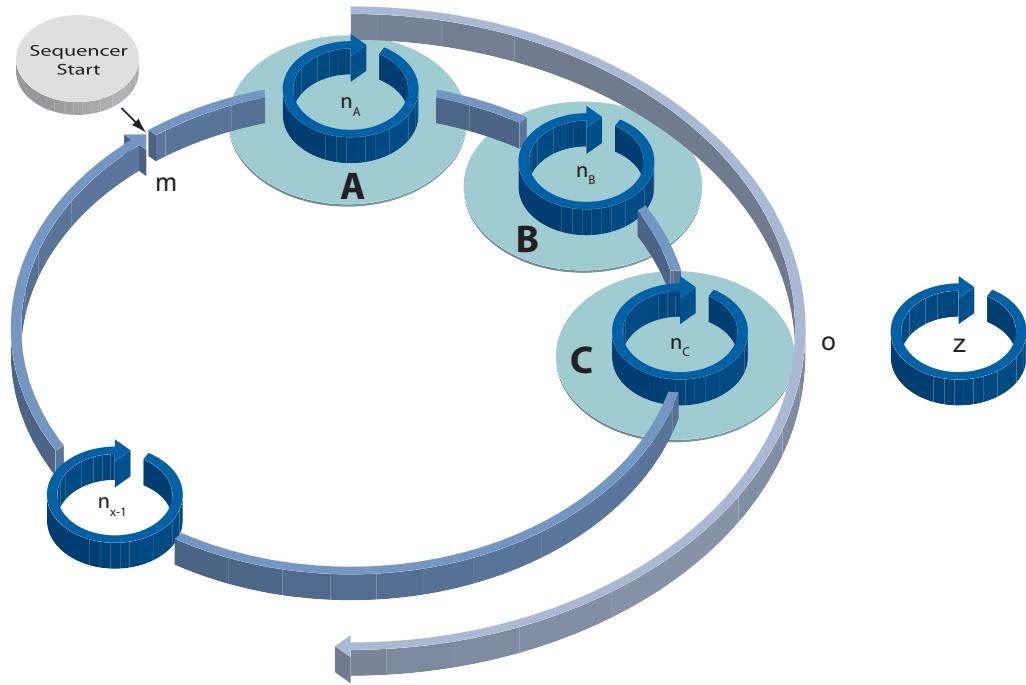


Figure 33 ▶

Flow chart of sequencer.

m - number of loop passes

n - number of set repetitions

o - number of sets of parameters

z - number of frames per trigger

Sequencer Parameter:

The mentioned sets of parameter include the following:

- Exposure time
- Gain factor
- Output line value
- Origin of ROI (Offset X, Y)

The figure above displays the fundamental structure of the sequencer module.

The loop counter (m) represents the number of sequence repetitions.

The repeat counter (n) is used to control the amount of images taken with the respective sets of parameters. For each set there is a separate n.

The start of the sequencer can be realized directly (free running) or via an external event (trigger). The source of the external event (trigger source) must be determined before.

The additional frame counter (z) is used to create a half-automated sequencer. It is absolutely independent from the other three counters, and used to determine the number of frames per external trigger event.

The following timeline displays the temporal course of a sequence with:

- $n_1 = 5$ repetitions of parameters for set 1
- $n_2 = 3$ repetitions of parameters for set 2
- $n_3 = 2$ repetitions of parameters for set 3
- $o = 3$ sets of parameters (A,B and C)
- $m = 1$ sequence and
- $z = 2$ frames per trigger

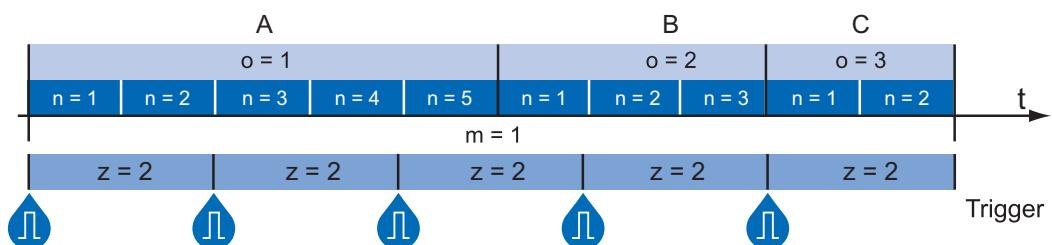


Figure 34 ▶

Timeline for a single sequence

10.5.2 Baumer Optronic Sequencer in Camera xml-file

The Baumer Optronic sequencer is described in the category "BOSequencer" by the following features:

Static Sequencer Features

These values are valid for all sets.

BoSequencerEnable	Enable / Disable
BoSequencerFramesPerTrigger	Number of frames per trigger (z)
BoSequencerIsRunning	Check whether the sequencer is running
BoSequencerLoops	Number of sequences (m)
BoSequencerMode	Running mode of Sequencer
BoSequencerSetNumberOfSets	Number of sets - 1
BoSequencerStart	Start / Stop
BoSequencerSetActive	Returns the index of the active set of the running sequencer.

Set-specific Features

These values can be set individually for each set.

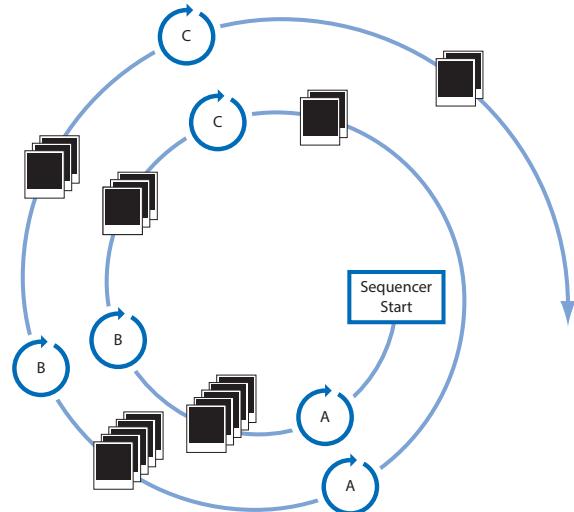
BoSequencerExposure	Parameter exposure
BoSequencerGain	Parameter gain
BoSequencerOffsetX	ROI Offset X
BoSequencerOffsetY	ROI Offset Y
BoSequencerIOSelector	Selected output lines
BoSequencerIOSTatus	Status of all Sequencer outputs
BoSequencerSetRepeats	Number of repetitions (n)
BoSequencerSetSelector	Configure set of parameters

Sequencer Running Modes

Mode	Description
SingleStepTrigger	On each trigger, the sequencer goes acquires Z images.Z is the count of freerunning images to take on one trigger event. When the end of the cycle is reached, the sequencer will restart automatically.
SingleStep-TriggerOnce	On each trigger, the sequencer goes acquires Z images. Z is the count of freerunning frames to take on one trigger event. When the end of the cycle is reached, the sequencer will not restart automatically.
FreeRunning (continuous)	The sequencer will not wait for an incoming event but starts immediately taking freerunning frames. When the end of the cycle is reached, the sequencer will restart automatically.
FreeRunningOnce	The sequencer will not wait for an incoming event but starts immediately taking freerunning frames. When the end of the cycle is reached, the sequencer will not restart automatically.
FreeRunningInit-Trigger	On the first incoming event, the sequencer will start with freerunning a full cycle. After completion, it will restart on the next incoming event automatically.
FreeRunningInit-TriggerOnce	On the first incoming event, the sequencer will start with freerunning a full cycle. After completion, it will not restart automatically.

10.5.3 Examples

10.5.3.1 Sequencer without Machine Cycle



◀ **Figure 35**

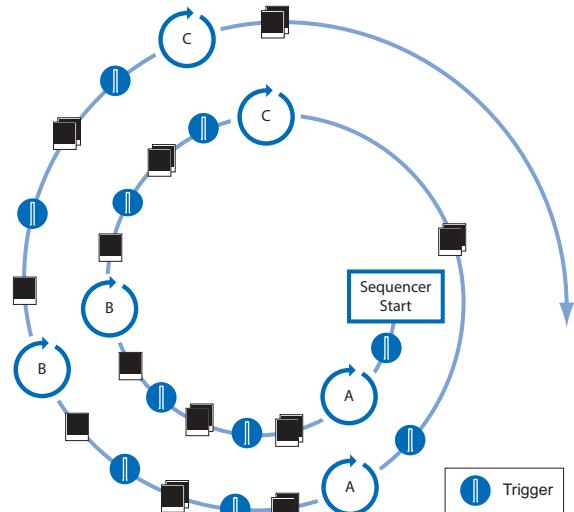
Example for a fully automated sequencer.

The figure above shows an example for a fully automated sequencer with three sets of parameters (A, B and C). Here the repeat counter (n) is set for (A=5), (B=3), (C=2) and the loop counter (m) has a value of 2.

When the sequencer is started, with or without an external event, the camera will record the pictures using the sets of parameters A, B and C (which constitutes a sequence).

After that, the sequence is started once again, followed by a stop of the sequencer - in this case the parameters are maintained.

10.5.3.2 Sequencer Controlled by Machine Steps (trigger)



▶ **Figure 36**

Example for a half-automated sequencer.

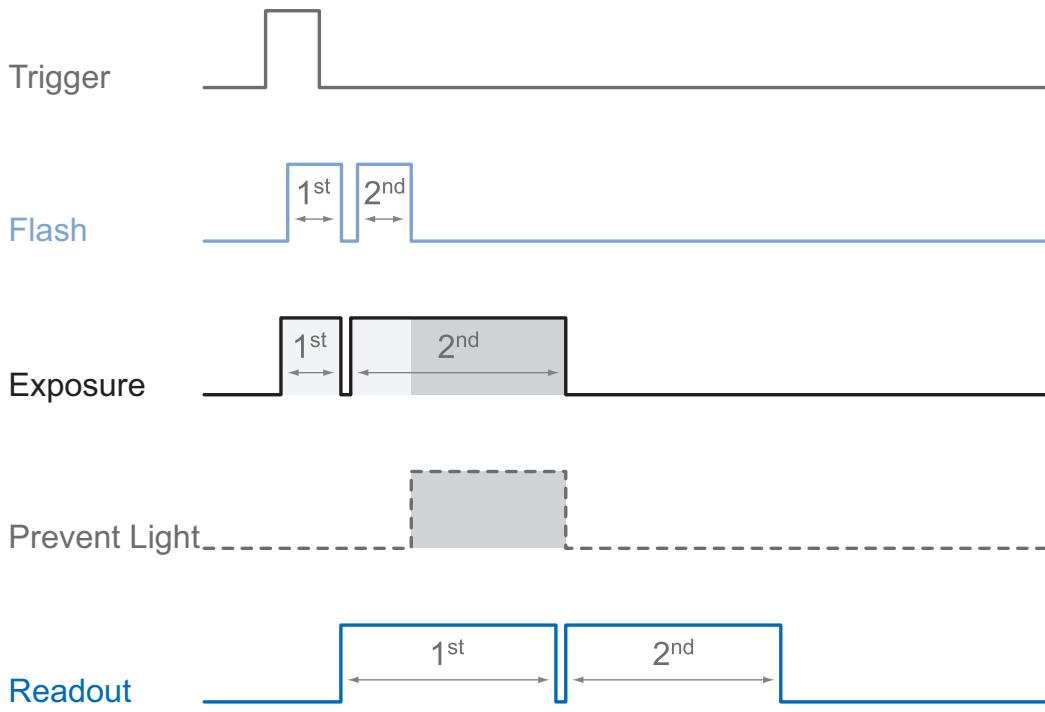
The figure above shows an example for a half-automated sequencer with three sets of parameters (A,B and C) from the previous example. The frame counter (z) is set to 2. This means the camera records two pictures after an incoming trigger signal.

10.5.4 Capability Characteristics of Baumer GAPI Sequencer Module

- up to 128 sets of parameters
- up to 2 billion loop passes
- up to 2 billion repetitions of sets of parameters
- up to 2 billion images per trigger event
- free running mode without initial trigger

10.5.5 Double Shutter

This feature offers the possibility of capturing two images in a very short interval. Depending on the application, this is performed in conjunction with a flash unit. Thereby the first exposure time (t_{exposure}) is arbitrary and accompanied by the first flash. The second exposure time must be equal to, or longer than the readout time (t_{readout}) of the sensor. Thus the pixels of the sensor are receptive again shortly after the first exposure. In order to realize the second short exposure time without an overrun of the sensor, a second short flash must be employed, and any subsequent extraneous light prevented.



◀ Figure 37
Example of a double shutter.

In order to generate this sequence, the sequencer can be configured, for example, as follows:

Parameter	Setting
Readout Mode	Overlapped
Sequencer Run Mode	SingleStepTrigger
Sets of parameters (o)	2
Loops (m)	1
Repeats (n)	1
Frames Per Trigger (z)	2

10.6 Process Interface

10.6.1 Digital I/O

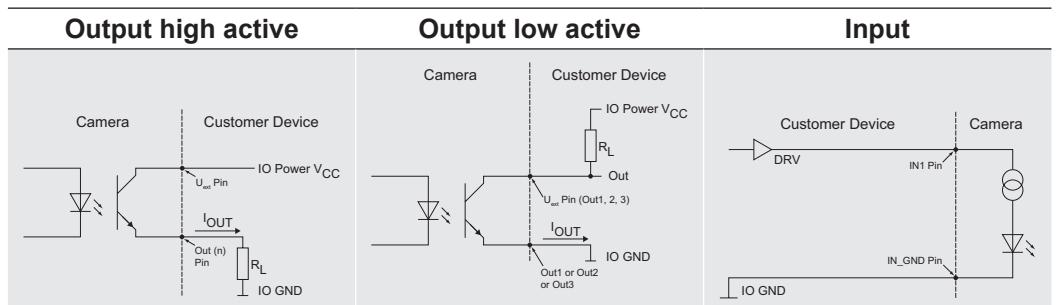
All Baumer LXG cameras are equipped with one input line and three output lines.

10.6.1.1 I/O Circuits

Notice

Low Active: At this wiring, only one consumer can be connected. When all Output pins (1, 2, 3) connected to I/O_GND, then current flows through the resistor as soon as one Output is switched. If only one output connected to I/O_GND, then this one is only usable.

The other two Outputs are not usable and may not be connected (e.g. I/O Power V_{CC})!



10.6.1.2 User Definable Inputs

The wiring of the input connector is left to the user.

Sole exception is the compliance with predetermined high and low levels (0 .. 4,5V low, 11 .. 30V high).

The defined signals will have no direct effect, but can be analyzed and processed on the software side and used for controlling the camera.

The employment of a so called "IO matrix" offers the possibility of selecting the signal and the state to be processed.

On the software side the input signals are named "Line0".

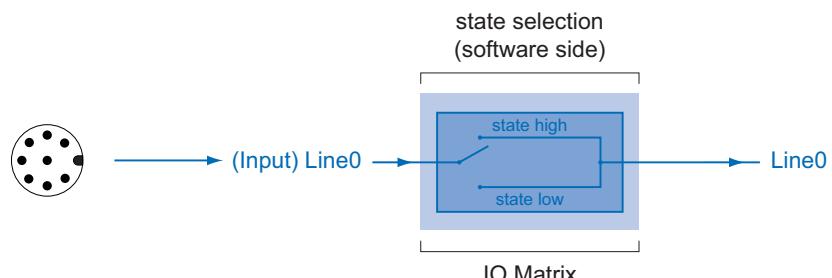


Figure 38 ▶

IO matrix of the
Baumer LXG on input
side.

10.6.1.3 Configurable Outputs

With this feature, Baumer offers the possibility of wiring the output connectors to internal signals, which are controlled on the software side.

Hereby on Baumer LXG cameras 17 signal sources – subdivided into three categories – can be applied to the output connectors.

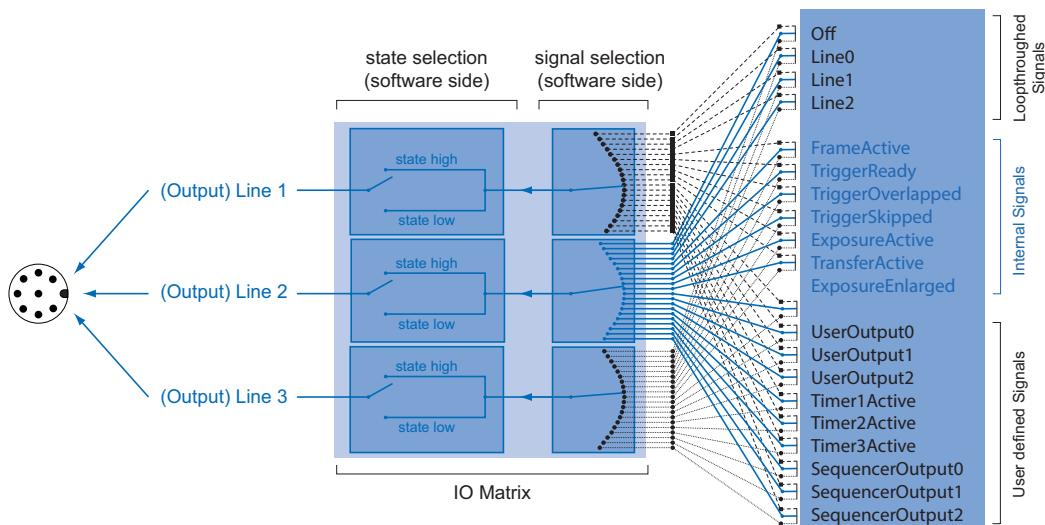
The first category of output signals represents a loop through of signals on the input side, such as:

Signal Name	Explanation
Line0	Signal of input "Line0" is loopthroughed to this output
Line1	Signal of input "Line1" is loopthroughed to this output
Line2	Signal of input "Line2" is loopthroughed to this output

Within the second category you will find signals that are created on camera side:

Signal Name	Explanation
FrameActive	The camera processes a Frame consisting of exposure and readout
TriggerReady	Camera is able to process an incoming trigger signal
TriggerOverlapped	The camera operates in overlapped mode
TriggerSkipped	Camera rejected an incoming trigger signal
ExposureActive	Sensor exposure in progress
TransferActive	Image transfer via hardware interface in progress
ExposureEnlarged	This output marks the period of enlarged exposure time

Beside the 10 signals mentioned above, each output can be wired to a user-defined signal ("UserOutput0", "UserOutput1", "UserOutput2", "SequencerOut 0...2" or disabled ("OFF").



◀ Figure 39
IO matrix of the
Baumer LXG on output
side.

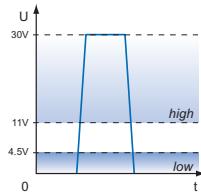


Figure 40 ▲

Trigger signal, valid for Baumer cameras.

10.7 Trigger Input / Trigger Delay

Trigger signals are used to synchronize the camera exposure and a machine cycle or, in case of a software trigger, to take images at predefined time intervals.

Different trigger sources can be used here:

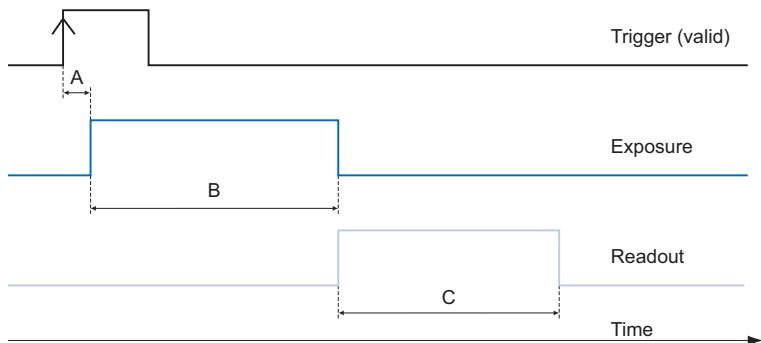
Line0	Actioncommand
Line1	Off
Line2	
SW-Trigger	

Possible settings of the Trigger Delay: :

Delay	0-2 sec
Number of tracked Triggers	512
Step	1 μ sec

There are three types of modes. The timing diagrams for the three types you can see below.

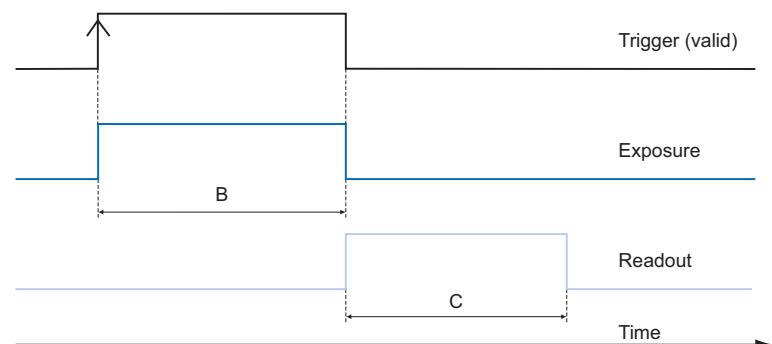
Normal Trigger with adjusted Exposure



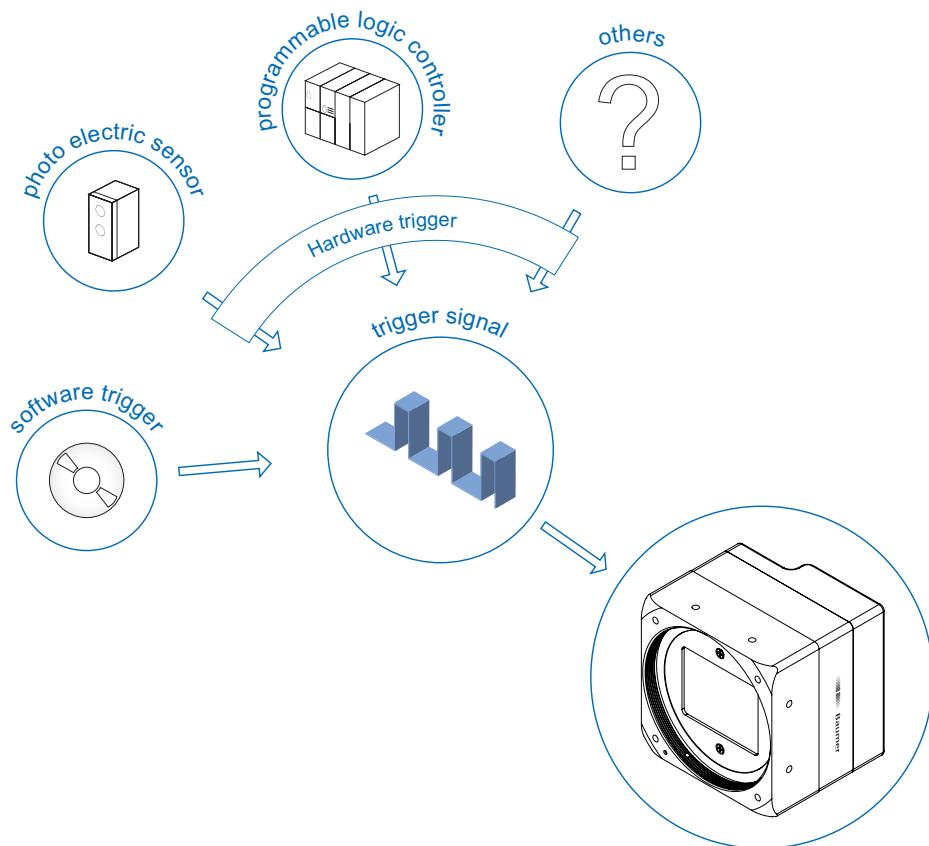
Camera in trigger mode:
A - Trigger delay
B - Exposure time
C - Readout time

A - Trigger delay
B - Exposure time
C - Readout time

Pulse Width controlled Exposure



10.7.1 Trigger Source



◀ Figure 41

Examples of possible trigger sources.

Each trigger source has to be activated separately. When the trigger mode is activated, the hardware trigger is activated by default.

10.7.2 Debouncer

The basic idea behind this feature was to separate interfering signals (short peaks) from valid square wave signals, which can be important in industrial environments. Debouncing means that invalid signals are filtered out, and signals lasting longer than a user-defined testing time $t_{\text{DebounceHigh}}$ will be recognized, and routed to the camera to induce a trigger.

In order to detect the end of a valid signal and filter out possible jitters within the signal, a second testing time $t_{\text{DebounceLow}}$ was introduced. This timing is also adjustable by the user. If the signal value falls to state low and does not rise within $t_{\text{DebounceLow}}$, this is recognized as end of the signal.

The debouncing times $t_{\text{DebounceHigh}}$ and $t_{\text{DebounceLow}}$ are adjustable from 0 to 5 msec in steps of 1 μ sec.

This feature is disabled by default.

Debouncer:
<i>Please note that the edges of valid trigger signals are shifted by $t_{\text{DebounceHigh}}$ and $t_{\text{DebounceLow}}$! Depending on these two timings, the trigger signal might be temporally stretched or compressed.</i>

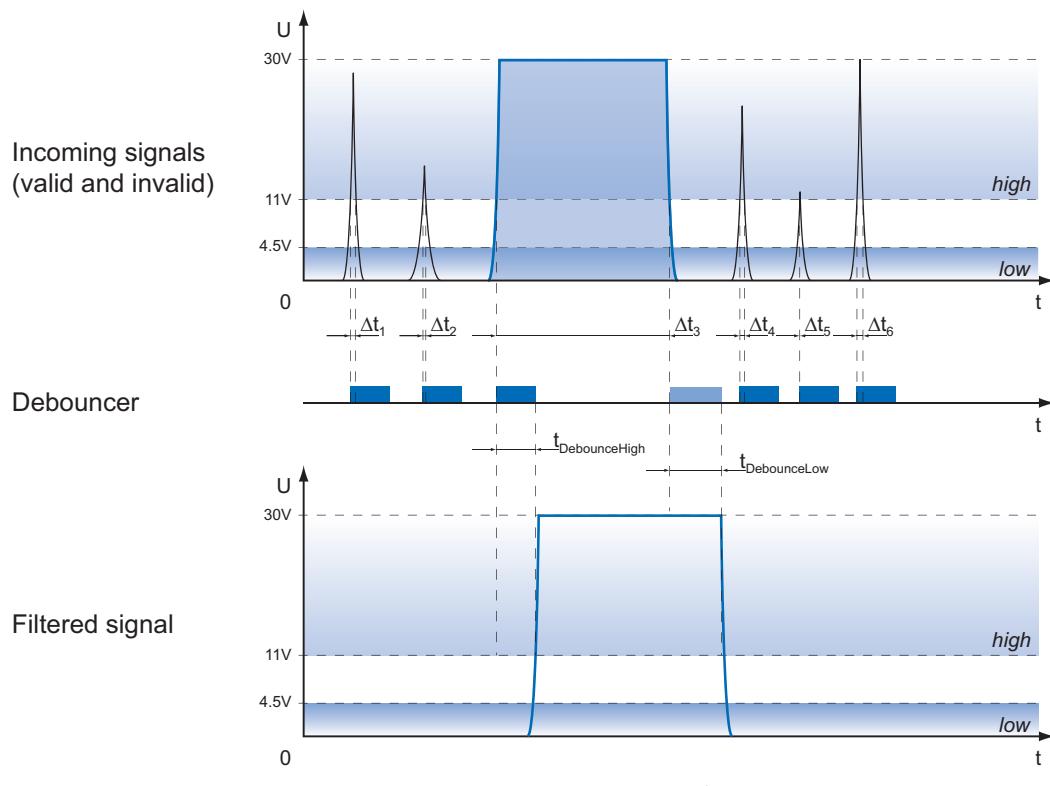


Figure 42 ▶

Principle of the Baumer debouncer.

10.7.3 Flash Signal

On Baumer cameras, this feature is realized by the internal signal "ExposureActive", which can be wired to one of the digital outputs.

Δt_x - high time of the signal
 $t_{\text{DebounceHigh}}$ - user-defined debouncer delay for state high
 $t_{\text{DebounceLow}}$ - user-defined debouncer delay for state low

10.7.4 Timer

Timers were introduced for advanced control of internal camera signals.

On Baumer LXG cameras the timer configuration includes four components:

Setting	Description
Timeselector	There are three timers. Own settings for each timer can be made. (Timer1, Timer2, Timer3)
TimerTriggerSource	This feature provides a source selection for each timer.
TimerTriggerActivation	This feature selects that part of the trigger signal (edges or states) that activates the timer.
TimerDelay	This feature represents the interval between incoming trigger signal and the start of the timer. (0 µsec .. 2 sec, step: 1 µsec)
TimerDuration	By this feature the activation time of the timer is adjustable. (10 µsec .. 2 sec, step: 1 µsec)

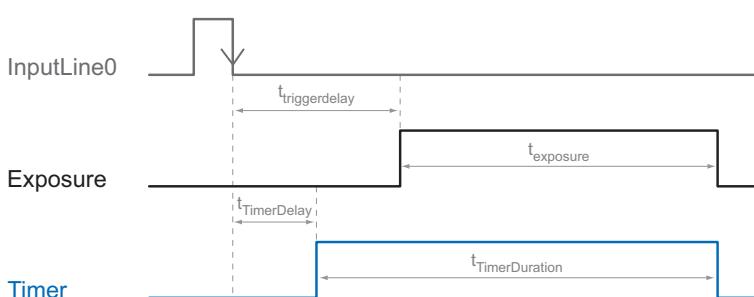
Different Timer sources can be used:

Input Line0	Frame Start
SW-Trigger	Frame End
ActionCommandTrigger	TriggerSkipped
Exposure Start	
Exposure End	

For example the using of a timer allows you to control the flash signal in that way, that the illumination does not start synchronized to the sensor exposure but a predefined interval earlier.

For this example you must set the following conditions:

Setting	Value
TriggerSource	InputLine0
TimerTriggerSource	InputLine0
Outputline1 (Source)	Timer1Active
TimerTriggerActivation	Falling Edge
Trigger Polarity	Falling Edge



10.8 User Sets

Three user sets (1-3) are available for the Baumer LXG cameras. The user sets can contain the following information:

Parameter	
Binning Mode	Mirroring Control
Defectpixellist	Partial Scan
Digital I/O Settings	PixelFormat
Exposure Time	Readout Mode
Gain Factor	Testpattern
Look-Up-Table	Trigger Settings
Sequencer	Action Command Parameter
Events	Counter
Timer	Frame Delay
Fixed Frame Rate	Offset
Gamma	HDR Control
Sensor Speed	

These user sets are stored within the camera and cannot be saved outside the device.

By employing a so-called "user set default selector", one of the three possible user sets can be selected as default, which means, the camera starts up with these adjusted parameters.

10.9 Factory Settings

The factory settings are stored in an additional parametrization set which is used by default. These settings are not editable.

11. Interface Functionalities

11.1 Link Aggregation Group Configuration

Link Aggregation (LAG) allows grouping the two links of the LXG camera to form a “virtual” link, enabling the camera to treat the LAG as if it was a single link. This is done in a transparent way from the application perspective.

It is important to note that LAG does not define the distribution algorithm to be used at the transmission end of a link aggregation group. Since LAG shows a single MAC/IP, then switches cannot figure out how to distribute the image traffic: the traffic might end-up on one outgoing port of the switch.

Characteristic	Static LAG
Number of network interfaces	2
Number of IP address	1
Number of stream channels	1
Load balancing	Round-robin distribution algorithm
Physical link down recovery	Packets redistributed on remaining physical link
Grouping configuration	All links are automatically grouped on the device. Manual grouping must be performed on the PC (often called teaming)

Notice

The installation of LAG is described in the *Installation Guide for Baumer GAPI SDK Gigabit Ethernet*.

11.1.1 Camera Control

The communication for the camera control is always sent on the same physical link of the LAG.

11.1.2 Image data stream

A round-robin distribution algorithm allows for a uniform distribution of the bandwidth associated to the image data since all image packets have the same size. So it adequately balances the bandwidth across the two available links. A suitable packet size must be selected to ensure all physical links can handle it.

Because of this loose definition of conversation and the selected distribution algorithm, it is necessary for the receiver of the image data to be tolerant to out-of-order packets and accommodate longer timeouts than seen with Single Link configuration.

Special provision must be taken for the inter packet gap: it represents the delay between packets of the image data stream travelling on a given physical link.

11.2 Device Information

This Gigabit Ethernet-specific information on the device is part of the Discovery-Acknowledge of the camera.

Included information:

- MAC address
- Current IP configuration (persistent IP / DHCP / LLA)
- Current IP parameters (IP address, subnet mask, gateway)
- Manufacturer's name
- Manufacturer-specific information
- Device version
- Serial number
- User-defined name (user programmable string)

Single GigE

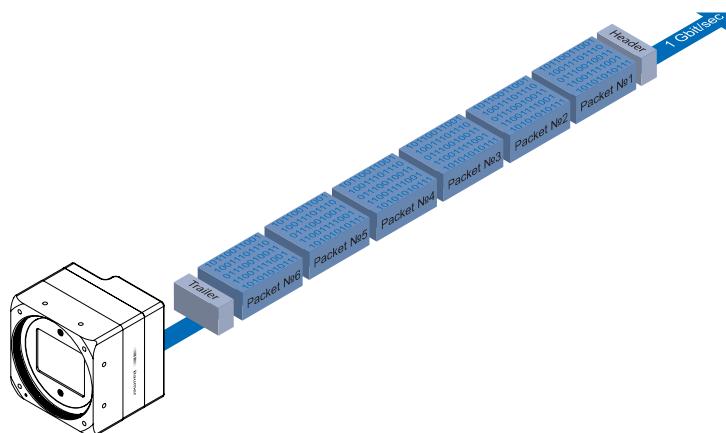


Figure 43 ▶

Transmission of data packets with single GigE

By using Single GigE all data packets are sequentially transmitted over one cable. At the beginning of a frame will be transmitted a Leader and at the end will be transmitted a Trailer.

Dual GigE

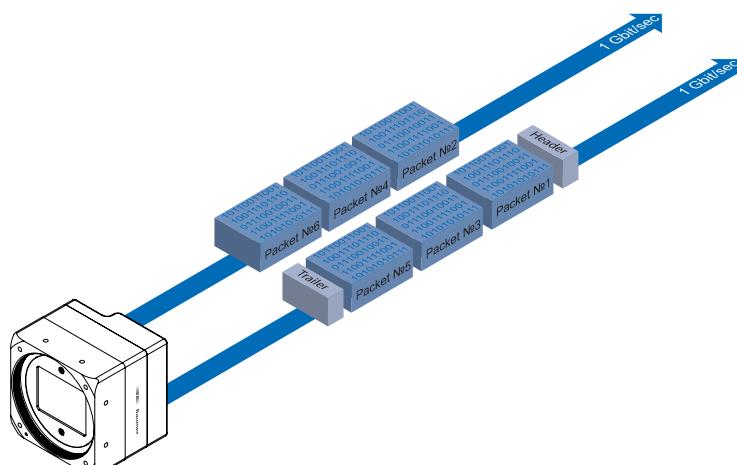


Figure 44 ▶

Transmission of data packets with Dual GigE

By using Dual GigE the data packets are alternately distributed over both cables. The Leader and the Trailer are always transmitted over the same cable.

11.3 Baumer Image Info Header (Chunk Data)

The Baumer Chunk are data, which are generated by the camera.

These data include different settings for the respective image. Baumer GAPI can read this settings. Third Party Software, which supports the Chunk mode, can read the settings in the table below.

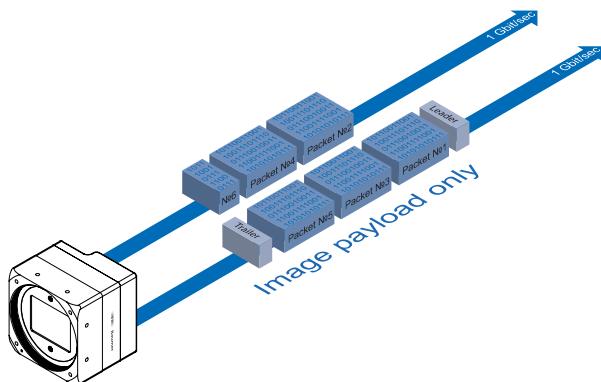
This settings may be for example (not completely):

Feature	Description
ChunkOffsetX	Horizontal offset from the origin to the area of interest (in pixels).
ChunkOffsetY	Vertical offset from the origin to the area of interest (in pixels).
ChunkWidth	Returns the Width of the image included in the payload.
ChunkHeight	Returns the Height of the image included in the payload.
ChunkPixelFormat	Returns the PixelFormat of the image included in the payload.
ChunkExposureTime	Returns the exposure time used to capture the image.
ChunkBlackLevelSelector	Selects which Black Level to retrieve data from.
ChunkBlackLevel	Returns the black level used to capture the image included in the payload.
ChunkFrameID	Returns the unique Identifier of the frame (or image) included in the payload.

There are three Chunk modes:

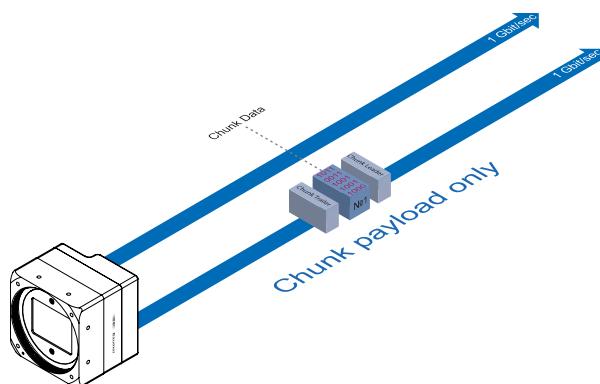
Image Data

Only the image data are transferred, no Chunk data.



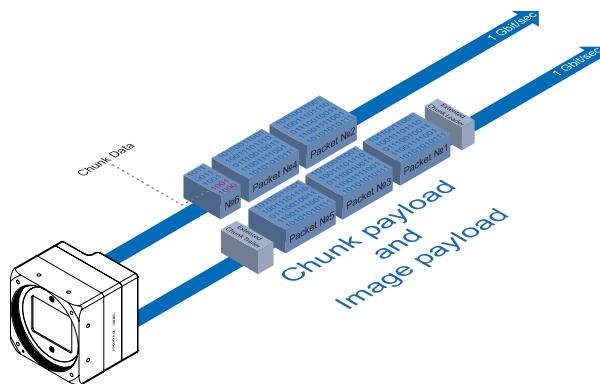
Chunk Data

Only the chunk is transferred, no image data.



Extented Chunk Data

Chunk data and image data are transferred. The Chunk Data are included in the last data packet.



11.4 Packet Size and Maximum Transmission Unit (MTU)

Network packets can be of different sizes. The size depends on the network components employed. When using GigE Vision®- compliant devices, it is generally recommended to use larger packets. On the one hand the overhead per packet is smaller, on the other hand larger packets cause less CPU load.

The packet size of UDP packets can differ from 576 Bytes up to the MTU.

The MTU describes the maximal packet size which can be handled by all network components involved.

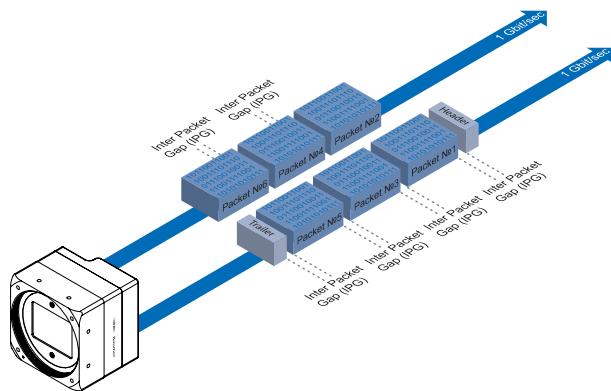
In principle modern network hardware supports a packet size of 1518 Byte, which is specified in the network standard. However, so-called "Jumbo frames" are on the advance as Gigabit Ethernet continues to spread. "Jumbo frames" merely characterizes a packet size exceeding 1500 Bytes.

Baumer LXG cameras can handle a MTU of up to 16384 Bytes.

11.5 "Inter Packet Gap" (IPG)

To achieve optimal results in image transfer, several Ethernet-specific factors need to be considered when using Baumer LXG cameras.

Upon starting the image transfer of a camera, the data packets are transferred at maximum transfer speed (1 Gbit/sec). In accordance with the network standard, Baumer employs a minimal separation of 12 Bytes between two packets. This separation is called "Inter Packet Gap" (IPG). In addition to the minimal PD, the GigE Vision® standard stipulates that the PD be scalable (user-defined).

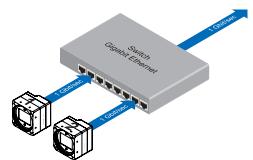


◀ **Figure 45**
Packet Delay (PD) between the packets

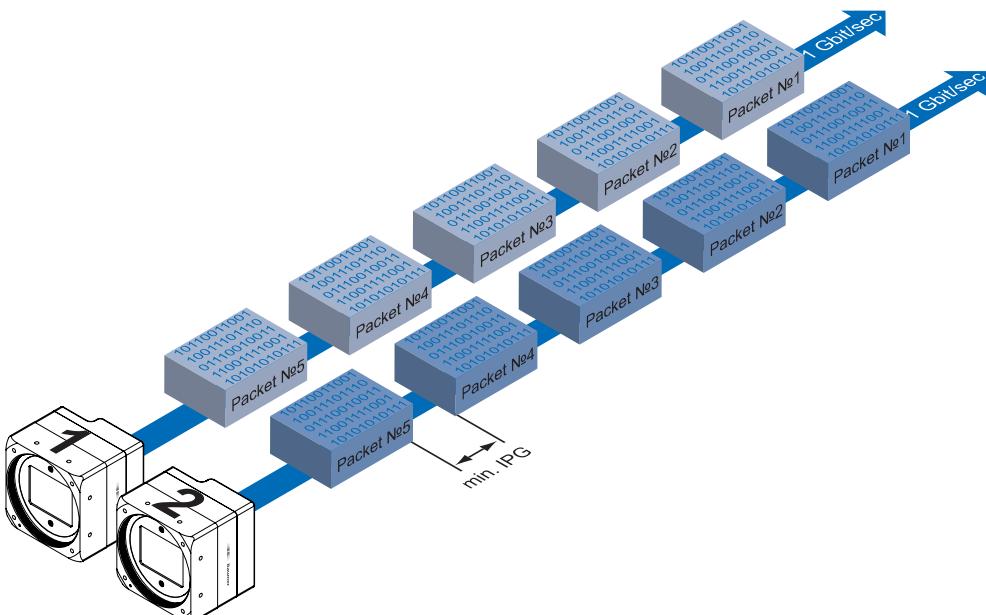
11.5.1 Example 1: Multi Camera Operation – Minimal IPG

Setting the IPG to minimum means every image is transferred at maximum speed. Even by using a frame rate of 1 fps this results in full load on the network. Such "bursts" can lead to an overload of several network components and a loss of packets. This can occur, especially when using several cameras.

In the case of two cameras sending images at the same time, this would theoretically occur at a transfer rate of 2 Gbits/sec. The switch has to buffer this data and transfer it at a speed of 1 Gbit/sec afterwards. Depending on the internal buffer of the switch, this operates without any problems up to n cameras ($n \geq 1$). More cameras would lead to a loss of packets. These lost packets can however be saved by employing an appropriate resend mechanism, but this leads to additional load on the network components.



▲ **Figure 45**
Operation of two cameras employing a Gigabit Ethernet switch.
Data processing within the switch is displayed in the next two figures.



◀ **Figure 46**
Operation of two cameras employing a minimal inter packet gap (IPG).

11.5.2 Example 2: Multi Camera Operation – Optimal IPG

A better method is to increase the IPG to a size of

$$\text{optimal IPG} = \text{packet size} + 2 \times \text{minimal IPG}$$

In this way both data packets can be transferred successively (zipper principle), and the switch does not need to buffer the packets.

Max. IPG:
On the Gigabit Ethernet the max. IPG and the data packet must not exceed 1 Gbit. Otherwise data packets can be lost.

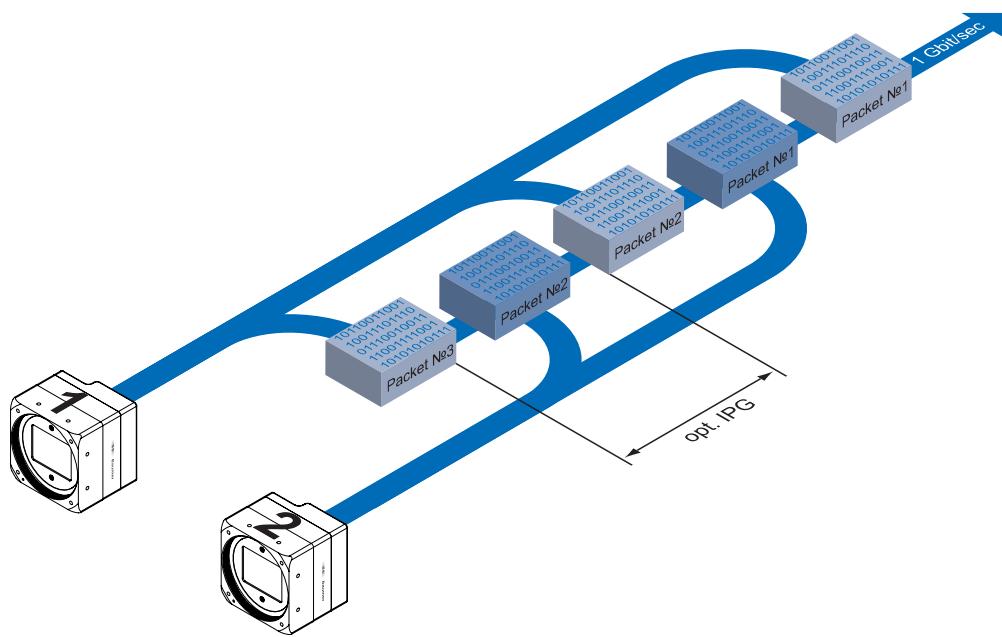


Figure 47 ▶

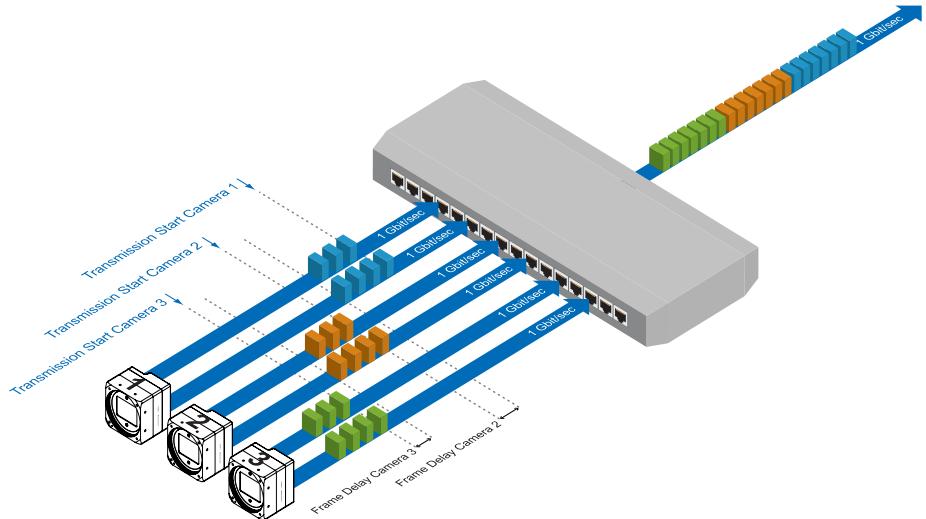
Operation of two cameras as employing an optimal inter packet gap (IPG).

11.6 Frame Delay

Another approach for packet sorting in multi-camera operation is the so-called Frame Delay, which was introduced to Baumer Gigabit Ethernet cameras in hardware release 2.1.

Due to the fact, that the currently recorded image is stored within the camera and its transmission starts with a predefined delay, complete images can be transmitted to the PC at once.

The following figure should serve as an example:

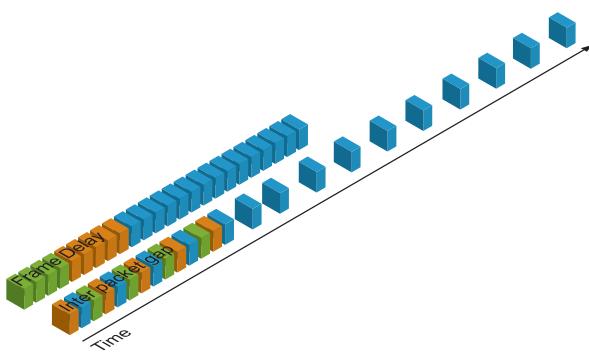


◀ **Figure 48**
Principle of the Frame delay.

Due to process-related circumstances, the image acquisitions of all cameras end at the same time. Now the cameras are not trying to transmit their images simultaneously, but – according to the specified transmission delays – subsequently. Thereby the first camera starts the transmission immediately – with a transmission delay "0".

11.6.1 Time Saving in Multi-Camera Operation

As previously stated, the Frame delay feature was especially designed for multi-camera operation with employment of different camera models. Just here an significant acceleration of the image transmission can be achieved:



◀ **Figure 49**
Comparison of frame delay and inter packet gap, employed for a multi-camera system with different camera models.

For the above mentioned example, the employment of the transmission delay feature results in a time saving – compared to the approach of using the inter paket gap – of approx. 45% (applied to the transmission of all three images).

11.6.2 Configuration Example

For the three used cameras the following data are known:

Camera Model	Sensor Resolution	Pixel Format (Pixel Depth)	Data Volume	Readout Time	Exposure Time	Transfer Time (Dual-GigE)
	[Pixel]	[bit]	[bit]	[msec]	[msec]	[msec]
LXG-200	5120 x 3840	8	157286400	30.768	6	≈ 73.24
LXG-200	5120 x 3840	8	157286400	30.768	6	≈ 73.24
LXG-200	5120 x 3840	8	157286400	30.768	6	≈ 73.24

- The sensor resolution and the readout time ($t_{readout}$) can be found in the respective Technical Data Sheet (TDS). For the example a full frame resolution is used.
- The exposure time ($t_{exposure}$) is manually set to 6 msec.

- The resulting data volume is calculated as follows:

$$\text{Resulting Data Volume} = \text{horizontal Pixels} \times \text{vertical Pixels} \times \text{Pixel Depth}$$

- The transfer time ($t_{transferGigE}$) for full Dual-GigE transfer rate is calculated as follows:

$$\text{Transfer Time (Dual-GigE)} = \text{Resulting Data Volume} / 1024^3 \times 500 \text{ [msec]}$$

All the cameras are triggered simultaneously.

The transmission delay is realized as a counter, that is started immediately after the sensor readout is started.

Timings:
A - exposure start for all cameras
B - all cameras ready for transmission
C - transmission start camera 2
D - transmission start camera 3

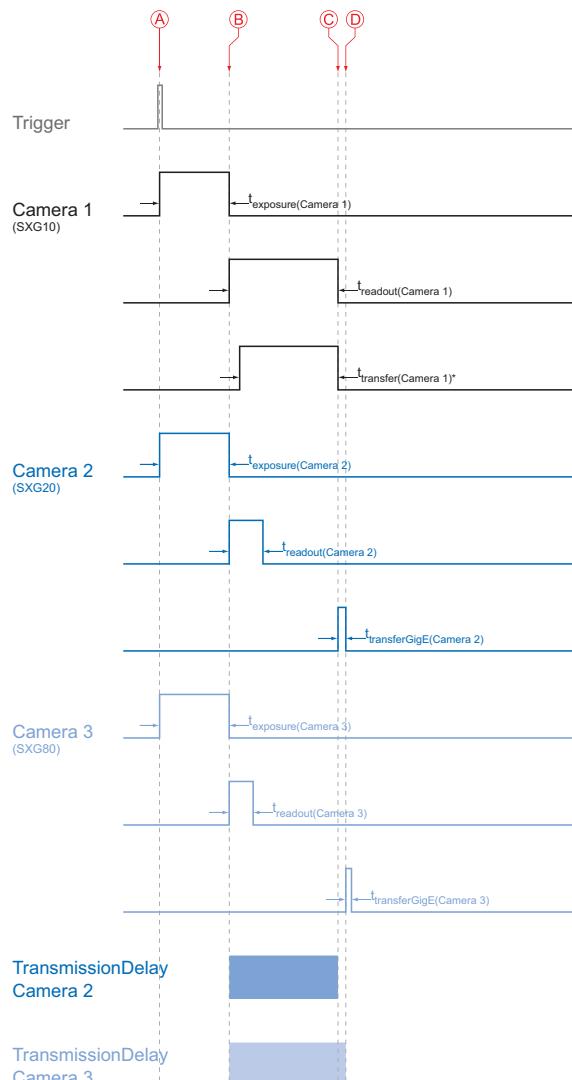


Figure 50 ▶

Timing diagram for the transmission delay of the three employed cameras, using even exposure times.

In general, the transmission delay is calculated as:

$$t_{TransmissionDelay(Camera\ n)} = t_{exposure(Camera\ 1)} + t_{readout(Camera\ 1)} - t_{exposure(Camera\ n)} + \sum_{n \geq 3}^n t_{transferGigE(Camera\ n-1)}$$

Therewith for the example, the transmission delays of camera 2 and 3 are calculated as follows:

$$\begin{aligned}t_{TransmissionDelay(Camera\ 2)} &= t_{exposure(Camera\ 1)} + t_{readout(Camera\ 1)} - t_{exposure(Camera\ 2)} \\t_{TransmissionDelay(Camera\ 3)} &= t_{exposure(Camera\ 1)} + t_{readout(Camera\ 1)} - t_{exposure(Camera\ 3)} + t_{transferGige(Camera\ 2)}\end{aligned}$$

Solving this equations leads to:

$$\begin{aligned}t_{TransmissionDelay(Camera\ 2)} &= 6\ msec + 30.768\ msec - 6\ msec \\&= 30.768\ msec \\&= 30768000\ ticks\end{aligned}$$

$$\begin{aligned}t_{TransmissionDelay(Camera\ 3)} &= 6\ msec + 30.768\ msec - 6\ msec + 73.27\ msec \\&= 104.038\ msec \\&= 10403800\ ticks\end{aligned}$$

Notice

In Baumer GAPI the delay is specified in ticks. How do convert microseconds into ticks?

$$1\ tick = 1\ ns$$

$$1\ msec = 1000000\ ns$$

$$1\ tick = 0.000001\ msec$$

$$\text{ticks} = t_{TransmissionDelay}[msec] / 0.000001 = t_{TransmissionDelay}[ticks]$$

11.7 Multicast

Multicasting offers the possibility to send data packets to more than one destination address – without multiplying bandwidth between camera and Multicast device (e.g. Router or Switch).

The data is sent out to an intelligent network node, an IGMP (Internet Group Management Protocol) capable Switch or Router and distributed to the receiver group with the specific address range.

In the example on the figure below, multicast is used to process image and message data separately on two different PC's.

Multicast Addresses:
For multicasting Baumer suggests an address range from 232.0.1.0 to 232.255.255.255.

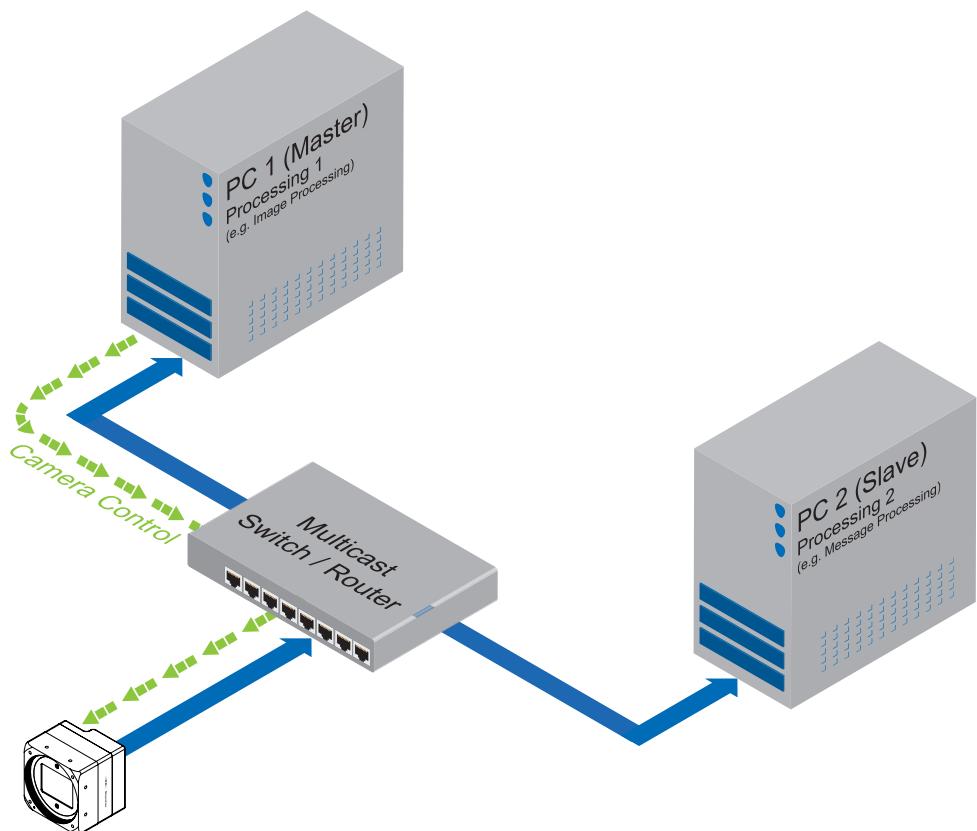


Figure 51 ►

Principle of Multicast

11.8 IP Configuration

11.8.1 Persistent IP

A persistent IP address is assigned permanently. Its validity is unlimited.

Internet Protocol:

On Baumer cameras IP v4 is employed.

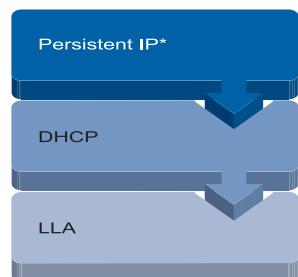


Figure 52 ▲

Connection pathway for Baumer Gigabit Ethernet cameras:
The device connects step by step via the three described mechanisms.

Notice

Please ensure a valid combination of IP address and subnet mask.

IP range:	Subnet mask:
0.0.0.0 – 127.255.255.255	255.0.0.0
128.0.0.0 – 191.255.255.255	255.255.0.0
192.0.0.0 – 223.255.255.255	255.255.255.0

These combinations are not checked by Baumer GAPI, Baumer GAPI Viewer or camera on the fly. This check is performed when restarting the camera, in case of an invalid IP - subnet combination the camera will start in LLA mode.

* This feature is disabled by default.

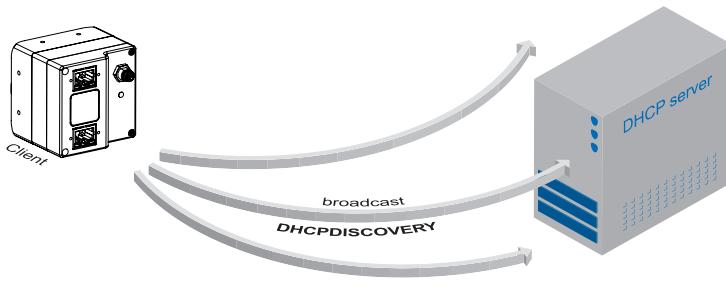
11.8.2 DHCP (Dynamic Host Configuration Protocol)

The DHCP automates the assignment of network parameters such as IP addresses, subnet masks and gateways. This process takes up to 12 sec.

Once the device (client) is connected to a DHCP-enabled network, four steps are processed:

▪ DHCP Discovery

In order to find a DHCP server, the client sends a so called DHCPDISCOVER broadcast to the network.



DHCP:

Please pay attention to the DHCP Lease Time.

◀ Figure 53

DHCP Discovery (broadcast)

▪ DHCP Offer

After reception of this broadcast, the DHCP server will answer the request by a unicast, known as DHCPOFFER. This message contains several items of information, such as:

Information for the client	MAC address offered IP address
Information on server	IP address subnet mask duration of the lease



◀ Figure 53

DHCP offer (unicast)

- **DHCP Request**

Once the client has received this DHCPOFFER, the transaction needs to be confirmed. For this purpose the client sends a so called DHCPREQUEST broadcast to the network. This message contains the IP address of the offering DHCP server and informs all other possible DHCP servers that the client has obtained all the necessary information, and there is therefore no need to issue IP information to the client.



Figure 54 ▶

DHCP Request
(broadcast)

- **DHCP Acknowledgement**

Once the DHCP server obtains the DHCPREQUEST, a unicast containing all necessary information is sent to the client. This message is called DHCPACK.

According to this information, the client will configure its IP parameters and the process is complete.

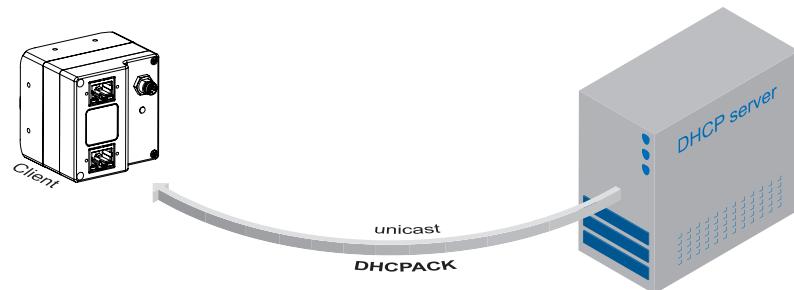


Figure 55 ▶

DHCP Acknowledgement (unicast)

11.8.3 LLA

LLA (Link-Local Address) refers to a local IP range from 169.254.0.1 to 169.254.254.254 and is used for the automated assignment of an IP address to a device when no other method for IP assignment is available.

The IP address is determined by the host, using a pseudo-random number generator, which operates in the IP range mentioned above.

Once an address is chosen, this is sent together with an ARP (Address Resolution Protocol) query to the network to check if it already exists. Depending on the response, the IP address will be assigned to the device (if not existing) or the process is repeated. This method may take some time - the GigE Vision® standard stipulates that establishing connection in the LLA should not take longer than 40 seconds, in the worst case it can take up to several minutes.

11.8.4 Force IP¹⁾

Inadvertent faulty operation may result in connection errors between the PC and the camera. In this case "Force IP" may be the last resort. The Force IP mechanism sends an IP address and a subnet mask to the MAC address of the camera. These settings are sent without verification and are adapted immediately by the client. They remain valid until the camera is de-energized.

1) In the GigE Vision® standard, this feature is defined as "Static IP".

11.9 Packet Resend

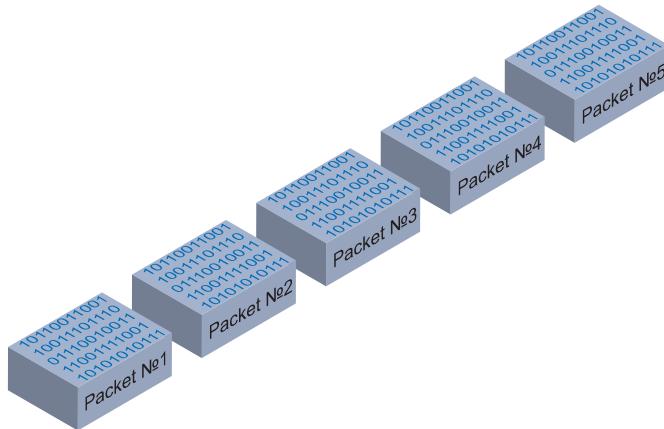
Due to the fact, that the GigE Vision® standard stipulates using a UDP – a stateless user datagram protocol – for data transfer, a mechanism for saving the "lost" data needs to be employed.

Here, a resend request is initiated if one or more packets are damaged during transfer and – due to an incorrect checksum – rejected afterwards.

On this topic one must distinguish between three cases:

11.9.1 Normal Case

In the case of unproblematic data transfer, all packets are transferred in their correct order from the camera to the PC. The probability of this happening is more than 99%.

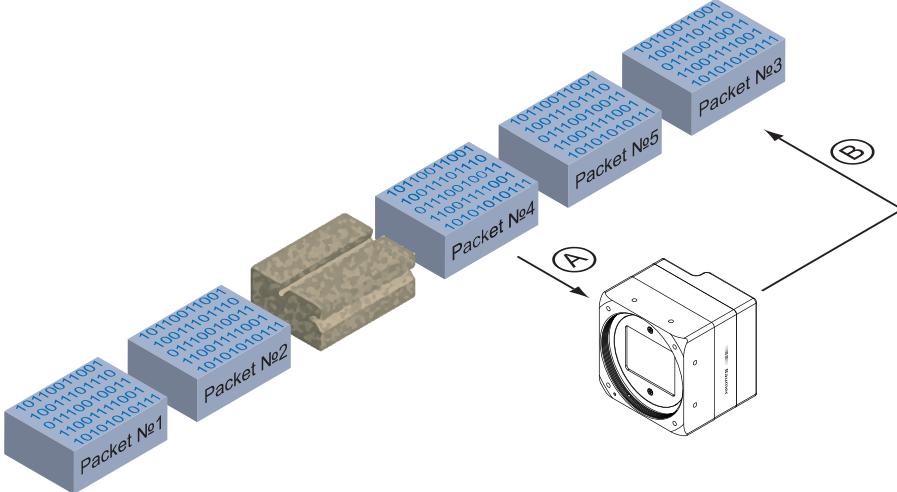


◀ Figure 56

Data stream without damaged or lost packets.

11.9.2 Fault 1: Lost Packet within Data Stream

If one or more packets are lost within the data stream, this is detected by the fact, that packet number n is not followed by packet number (n+1). In this case the application sends a resend request (A). Following this request, the camera sends the next packet and then resends (B) the lost packet.



◀ Figure 57

Resending lost packets within the data stream.

In our example packet no. 3 is lost. This fault is detected on packet no. 4, and the resend request triggered. Then the camera sends packet no. 5, followed by resending packet no. 3.

11.9.3 Fault 2: Lost Packet at the End of the Data Stream

In case of a fault at the end of the data stream, the application will wait for incoming packets for a predefined time. When this time has elapsed, the resend request is triggered and the "lost" packets will be resent.

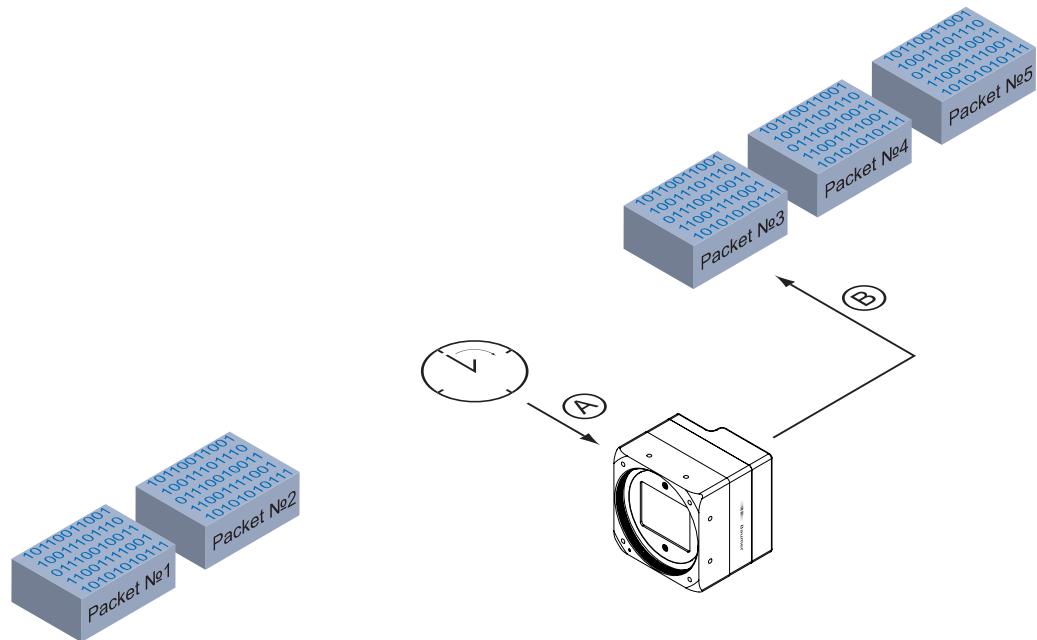


Figure 58 ▶

Resending of lost packets at the end of the data stream.

In our example, packets from no. 3 to no. 5 are lost. This fault is detected after the predefined time has elapsed and the resend request (A) is triggered. The camera then resends packets no. 3 to no. 5 (B) to complete the image transfer.

11.9.4 Termination Conditions

The resend mechanism will continue until:

- all packets have reached the pc
- the maximum of resend repetitions is reached
- the resend timeout has occurred or
- the camera returns an error.

11.10 Message Channel

The asynchronous message channel is described in the GigE Vision® standard and offers the possibility of event signaling. There is a timestamp (64 bits) for each announced event, which contains the accurate time the event occurred. Each event can be activated and deactivated separately.

Bit	Edge	Event-ID	XML-Event	Description
	rising	0x0007	PrimaryApplication-Switch	A primary application switchover has been granted.
0	rising	0x9000	Line0RisingEdge	Rising Edge is detected on the Line 0.
1	falling	0x9001	Line0FallingEdge	Falling Edge is detected on the Line 0.
2	rising	0x9002	Line1RisingEdge	Rising Edge is detected on the Line 1.
3	falling	0x9003	Line1FallingEdge	Falling Edge is detected on the Line 1.
4	rising	0x9004	Line2RisingEdge	Rising Edge is detected on the Line 2.
5	falling	0x9005	Line2FallingEdge	Falling Edge is detected on the Line 2.
6	rising	0x9006	Line3RisingEdge	Rising Edge is detected on the Line 3.
7	falling	0x9007	Line3FallingEdge	Falling Edge is detected on the Line 3.
12	rising	0x900C	ExposureStart	Exposure started.
13	rising	0x900D	ExposureEnd	Exposure ended.
14	rising	0x900E	FrameStart	Device just started the capture of one Frame.
15	rising	0x900F	FrameEnd	Device just completed the capture of one Frame.
16	rising	0x9010	TriggerReady	Camera is able to process incoming trigger.
17	rising	0x9011	TriggerOverlapped	Trigger Overlapped.
18	rising	0x9012	TriggerSkipped	Camera reject an incoming trigger signal.
20	rising	0x9014	Action	Action command has triggered an image in the camera.
22	rising	0x9016	PhysicalConnection0Up	Physical Connection 0 Up Event.
23	falling	0x9017	PhysicalConnection0Down	Physical Connection 0 Down Event.
24	rising	0x9018	PhysicalConnection1Up	Physical Connection 1 Up Event.
25	falling	0x9019	PhysicalConnection1Down	Physical Connection 1 Down Event
26	rising	0x901A	Timer1 End	Timer 1 ends counting.
27	rising	0x901B	Timer2 End	Timer 2 ends counting.
28	rising	0x901C	Timer3 End	Timer 3 ends counting.
31	rising	0x901F	LinkSpeedChanged	The link speed has changed.
32	rising	0x9020	GigEVisionError	Device just detected an error.
33	rising	0x9021	EventLost	Event was lost in the camera.
34	rising	0x9022	EventDiscarded	Event discarded.
35	rising	0x9023	GigEVisionHeartbeatTimeOut	Device runs in heartbeat timeout.
48	rising	0x9030	DeviceTemperatureStatusChanged	Device temperature status in the camera changed.

11.11 Action Commands

The basic idea behind this feature was to achieve a simultaneous trigger for multiple cameras.

Action Command	Description
Action Command Trigger	used to send a trigger to all connected cameras.

Therefore a broadcast ethernet packet was implemented. This packet can be used to induce a trigger as well as other actions.

Due to the fact that different network components feature different latencies and jitters, the trigger over the Ethernet is not as synchronous as a hardware trigger. Nevertheless, applications can deal with these jitters in switched networks, and therefore this is a comfortable method for synchronizing cameras with software additions.

The action command is sent as a broadcast. In addition it is possible to group cameras, so that not all attached cameras respond to a broadcast action command.

Such an action command contains:

- a Device Key - for authorization of the action on this device
- a Group Key - for triggering actions on separated groups of devices
- a Group Mask - for extension of the range of separate device groups

11.11.1 Action Command Trigger

The figure below displays three cameras, which are triggered synchronously by a software application.

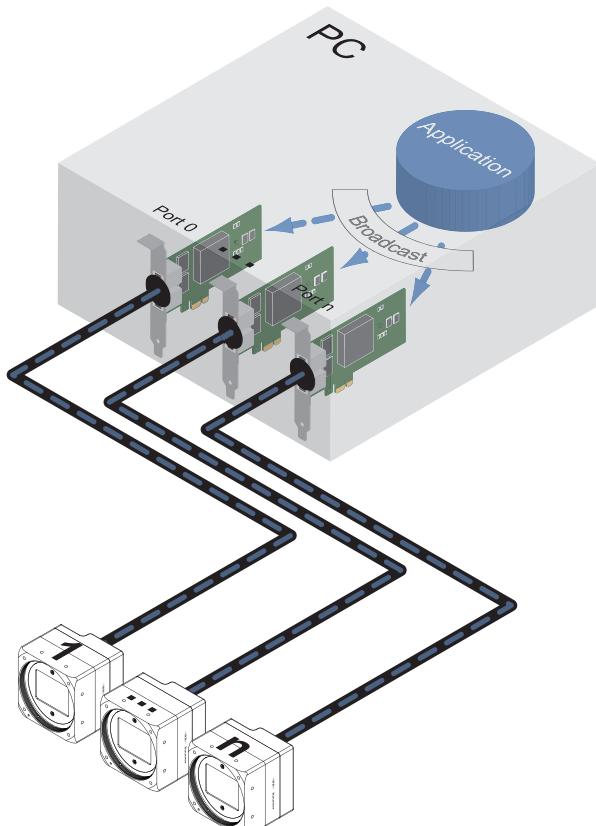


Figure 59 ▶

Triggering of multiple cameras via trigger over Ethernet (ToE).

Another application of action command is that a secondary application or PC or one of the attached cameras can actuate the trigger.

12. Start-Stop-Behaviour

12.1 Start / Stop Acquisition (Camera)

Once the image acquisition is started, three steps are processed within the camera:

- Determination of the current set of image parameters
- Exposure of the sensor
- Readout of the sensor.

Afterwards a repetition of this process takes place until the camera is stopped.

Stopping the acquisition means that the process mentioned above is aborted. If the stop signal occurs within a readout, the current readout will be finished before stopping the camera. If the stop signal arrives within an exposure, this will be aborted.

Special Case: Asynchronous Reset

The asynchronous reset represents a special case of stopping the current acquisition. Thereby exposure is aborted immediately. Thus the current image is not read out and the image is upcasted.

Asynchronous Reset:
For further information on the timings of this feature, please see the respective data sheets.

This feature was introduced to accelerate the changing of image parameters.

12.2 Start / Stop Interface

Without starting the interface, transmission of image data from the camera to the PC will not proceed. If the image acquisition is started before the interface is activated, the recorded images are lost.

If the interface is stopped during a transmission, this is aborted immediately.

12.3 Pause / Resume Interface

Pausing while the interface is operational, results in an interim storage of the recorded images within the internal buffer of the camera.

After resuming the interface, the buffered image data will be transferred to the PC.

12.4 Acquisition Modes

In general, three acquisition modes are available for the cameras in the Baumer LXG series.

12.4.1 Free Running

Free running means the camera records images continuously without external events.

12.4.2 Trigger

The basic idea behind the trigger mode is the synchronization of cameras with machine cycles. Trigger mode means that image recording is not continuous, but triggered by external events.

12.4.3 Sequencer

A sequencer is used for the automated control of series of images, using different settings for exposure time and gain.

13. Cleaning

Avoid cleaning if possible. To prevent dust, follow the instructions under *Installation*.

Notice

Perform the cleaning in a dust-free room with clean tools. Use localized ionized air flow on to the glass during cleaning.

13.1 Sensor

Recommended Equipment

- Miroscope
- Air gun
- Single drop bottle with pure alcohol
- Swab
- Phillips screwdriver

Procedure

1. Make sure that the contamination is not on the sensor glass (except LXG-20M, LXG-40M) or the installed lens.
2. Uninstall the lens mount adapter (except LXG-20M, LXG-40M). Uninstall the sensor glass (except LXG-20M, LXG-40M) using the phillips screw driver.
3. Blow away mobile contamination using the air gun.
4. Place the sensor under the microscope to determine the location of any remaining contamination.
5. Clean the contamination on the sensor using one drop pure alcohol on a swab. Wipe the swab from left to right (or conversely, but only in one direction). Do this in an overlapping pattern, turning the swab after the first wipe and with each subsequent wipe. Avoid swiping back and forth with the same swab in order to ensure that particles are removed and not transferred to a new location on the sensor. Use several swabs for this procedure.

13.2 Cover glass

If you must clean it, use compressed air or a soft, lint free cloth dampened with a small quantity of pure alcohol.

13.3 Housing



Caution!



Volatile solvents for cleaning.

Volatile solvents damage the surface of the camera.

Never use volatile solvents (benzine, thinner) for cleaning!

To clean the surface of the camera housing, use a soft, dry cloth. To remove persistent stains, use a soft cloth dampened with a small quantity of neutral detergent, then wipe dry.

14. Transport / Storage

Notice

Transport the camera only in the original packaging. When the camera is not installed, then storage the camera in the original packaging.

Storage Environment

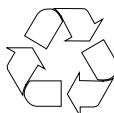
Storage temperature	-10°C ... +70°C (+14°F ... +158°F)
Storage Humidity	10% ... 90% non condensing

15. Disposal



Dispose of outdated products with electrical or electronic circuits, not in the normal domestic waste, but rather according to your national law and the directives 2002/96/EC and 2006/66/EC for recycling within the competent collectors.

Through the proper disposal of obsolete equipment will help to save valuable resources and prevent possible adverse effects on human health and the environment.



The return of the packaging to the material cycle helps conserve raw materials and reduces the production of waste. When no longer required, dispose of the packaging materials in accordance with the local regulations in force.

Keep the original packaging during the warranty period in order to be able to pack the device in the event of a warranty claim.

16. Warranty Information

Notice

There are no adjustable parts inside the camera!

In order to avoid the loss of warranty do not open the housing!

Notice

If it is obvious that the device is / was dismantled, reworked or repaired by other than Baumer technicians, Baumer will not take any responsibility for the subsequent performance and quality of the device!

17. Conformity



Baumer LXG cameras comply with:

- CE
- RoHS
- KC (several models)

17.1 CE

We declare, under our sole responsibility, that the previously described Baumer LXG cameras conform with the directives of the CE (electromagnetic compatibility (EMC) 2004/108EC).

17.1.1 RoHS

All LXG cameras comply with the recommendation of the European Union concerning RoHS Rules.

17.2 Korean Conformity

Registration of Broadcasting and Communication Equipments

Several of the described Baumer LXG cameras conform with the directives of the Korean Conformity.

Product	Article No.	Registration No.	Date of Registration
LXG-200M	11117848	MSIP-REI-BkR-LXG-200M	2017-08-09
LXG-200C	11117849	MSIP-REI-BkR-LXG-200M	2017-08-09

18. Support

If you have any problems with the camera, then feel free to contact our support.

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