「ガウス過程と機械学習」

P28. 線形回帰モデル

```
In [1]:
         using Plots
In [2]:
         data = [
             2.7613622 0.7812694
             -2.5020371 0.5784024
             -0.6534198 -0.8364839
             -0.5093708 -1.0659939
             1.0698123 -0.5053178
             1.2444854 0.0656932
             -0.1583863 -1.7132896
             -1.8188962 0.1539270
             -3.6129367 1.0440645
             -2.8263055 0.7741641
             -1.0204458 -0.8304516
             0.2611304 - 1.3202885
             -0.9667795 -1.0839772
             0.4701717 - 0.0456008
             -0.7279929 -0.0369160
             0.3050133 - 1.1703207
             0.3901433 -0.7787978
             3.0430492 1.2799983
             -1.6307559 -0.2210154
             -3.5160842 0.5724240
             -6.4898371 -0.4126926
             1.8201852 0.9120053
             -0.7767629 -0.8371592
             -3.4106994 0.6317732
             -0.9195992 -1.2476601
             -1.1248267 -0.4371627
             -1.5116412 -0.7774516
             1.8203302 1.2516907
             -1.1185539 -1.6227401
             0.0985207 -0.0693066
         X = data[:, 1]
         y = data[:, 2]
         scatter(X, y, label="Observed data")
Out[2]:
                                                                Observed data
```

```
1.0 Observed data

0.5

-0.5

-1.0

-6

-4

-2

0

2
```

特徴ベクトルの計算

関数を、 $\hat{y}=w_0+w_1x+w_2x^2+w_3\sin x$ とした場合について考える。

1.0 -2.50204 6.26019 -0.596839 1.0 -0.65342 0.426957 -0.607905 1.0 -0.509371 0.259459 -0.487628 1.0 1.06981 1.1445 0.87711

scatter!(X, y, label="Observed data")

線形モデルの解

Out[5]:

1.0

Nonlinear Regression Observed data

-0.5

-1.0

-1.5

-6

-4

-2

0

2

関数に \cos 項を加えた $\hat{y}=w_0+w_1x+w_2x^2+w_3\sin x+w_4\cos x$ の場合についても考える。

```
In [6]: 

\phi = zeros(N, 5)
\phi[:, 1] .= 1.0
\phi[:, 2] = X
\phi[:, 3] = [X[n] * X[n] \text{ for n in } 1:N]
\phi[:, 4] = sin.(X)
\phi[:, 5] = cos.(X)
w = inv(\phi' * \phi) * \phi' * y
f(x) = w[1] + w[2] * x + w[3] * x^2 + w[4] * sin(x) + w[5] * cos(x)
xs = minimum(X): 0.5: maximum(X)
ys = f.(xs)
plot(xs, ys, label="Nonlinear Regression")
scatter!(X, y, label="Observed data")
```

