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A lead compensator used for a closed loop controller has the following transfer function

$$G(s)=k \frac{1 + \frac{s}{a}}{1 + \frac{s}{b}}$$

For such a lead compensator

✔ ☐ a < b.

☒ b < a.

☐ a < kb.

☐ a > kb.

Incorrect

Zero at transfer function = - a, Pole at transfer function = - b.

For a lead compensator, the zero is nearer to the origin as compared to the pole.

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