## Numerical Analysis – Lecture 8

## 6.3 The error of polynomial interpolation

Let [a, b] be a closed interval of  $\mathbb{R}$ . We denote by C[a, b] the space of all continuous functions from [a, b] to  $\mathbb{R}$  and let  $C^s[a, b]$ , where s is a positive integer, stand for the linear space of all functions in C[a, b] that possess s continuous derivatives.

**Theorem** Given  $f \in C^{n+1}[a,b]$ , let  $p \in \mathbb{P}_n[x]$  interpolate the values  $f(x_i)$ ,  $i = 0, 1, \ldots, n$ , where  $x_0, \ldots, x_n \in [a,b]$  are pairwise distinct. Then for every  $x \in [a,b]$  there exists  $\xi \in [a,b]$  such that

$$f(x) - p(x) = \frac{1}{(n+1)!} f^{(n+1)}(\xi) \prod_{i=0}^{n} (x - x_i).$$
(6.1)

**Proof.** The formula (6.1) is true when  $x = x_j$  for  $j \in \{0, 1, ..., n\}$ , since both sides of the equation vanish. Let  $x \in [a, b]$  be any other point and define

$$\phi(t) := [f(t) - p(t)] \prod_{i=0}^{n} (x - x_i) - [f(x) - p(x)] \prod_{i=0}^{n} (t - x_i), \qquad t \in [a, b].$$

[Note: The variable in  $\phi$  is t, whereas x is a fixed parameter.] Note that  $\phi(x_j)=0, j=0,1,\ldots,n,$  and  $\phi(x)=0$ . Hence,  $\phi$  has at least n+2 distinct zeros in [a,b]. Moreover,  $\phi\in C^{n+1}[a,b]$ . We now apply the Rolle theorem: if the function  $g\in C^1[a,b]$  vanishes at two distinct points in [a,b] then its derivative vanishes at an intermediate point. We deduce that  $\phi'$  vanishes at (at least) n+1 distinct points in [a,b]. Next, applying Rolle to  $\phi'$ , we conclude that  $\phi''$  vanishes at n points in [a,b]. In general, we prove by induction that  $\phi^{(s)}$  vanishes at n+2-s distinct points of [a,b] for  $s=0,1,\ldots,n+1$ . Letting s=n+1, we have  $\phi^{(n+1)}(\xi)=0$  for some  $\xi\in [a,b]$ . But  $p^{(n+1)}\equiv 0$ ,  $d^{n+1}\prod_{i=0}^n (t-x_i)/dt^{n+1}\equiv (n+1)!$ , and we obtain (6.1).

**Runge's example** We interpolate  $f(x) = 1/(1+x^2)$ ,  $x \in [-5, 5]$ , at the equally-spaced points  $x_j = -5 + 10\frac{j}{n}$ ,  $j = 0, 1, \ldots, n$ . Some of the errors for n = 20 are

x	f(x) - p(x)	$\prod_{i=0}^{n} (x - x_i)$
0.75	$3.2 \times 10^{-3}$	$-2.5 \times 10^{6}$
1.75	$7.7 \times 10^{-3}$	$-6.6 \times 10^{6}$
2.75	$3.6 \times 10^{-2}$	$-4.1 \times 10^{7}$
3.75	$5.1 \times 10^{-1}$	$-7.6 \times 10^{8}$
4.75	$4.0 \times 10^{+2}$	$-7.3 \times 10^{10}$

The growth in the error is explained by the product term in (6.1) (the rightmost column of the table). Adding more interpolation points makes the largest error even worse. A remedy to this state of affairs is to cluster points toward the end of the range.

A considerably smaller error is attained for  $x_j = 5\cos\frac{(n-j)\pi}{n}$ , j = 0, 1, ..., n (so-called *Chebyshev points*). It is possible to prove that this choice of points minimizes the magnitude of  $\max_{x \in [-5,5]} |\prod_{i=0}^n (x-x_i)|$ .

## 6.4 Divided differences: a definition

Given pairwise-distinct points  $x_0, x_1, \ldots, x_n \in [a, b]$ , we let  $p \in \mathbb{P}_n[x]$  interpolate  $f \in C[a, b]$  there. The coefficient of  $x^n$  in p is called the *divided difference* and denoted by  $f[x_0, x_1, \ldots, x_n]$ . We say

that this divided difference is of degree n.

We can derive  $f[x_0, \ldots, x_n]$  from the Lagrange formula,

$$f[x_0, x_1, \dots, x_n] = \sum_{k=0}^n f(x_k) \prod_{\substack{\ell=0\\\ell\neq k}}^n \frac{1}{x_k - x_\ell}.$$
 (6.2)

**Theorem** Let  $[\bar{a}, \bar{b}]$  be the shortest interval that contains  $x_0, x_1, \ldots, x_n$  and let  $f \in C^n[\bar{a}, \bar{b}]$ . Then there exists  $\xi \in [\bar{a}, \bar{b}]$  such that

$$f[x_0, x_1, \dots, x_n] = \frac{1}{n!} f^{(n)}(\xi).$$
 (6.3)

**Proof.** Let p be the interpolating polynomial. The error function f-p has at least n+1 zeros in  $[\bar{a}, \bar{b}]$  and, applying Rolle's theorem n times, it follows that  $f^{(n)} - p^{(n)}$  vanishes at some  $\xi \in [\bar{a}, \bar{b}]$ . But  $p(x) = \frac{1}{n!}p^{(n)}(\xi)x^n$  + lower order terms (for any  $\xi \in \mathbb{R}$ ), and we deduce (6.3).

**Application** It is a consequence of the theorem that divided differences can be used to approximate derivatives.

## 6.5 Recurrence relations for divided differences

Our next topic is a useful way to calculate divided differences (and, ultimately, to deduce yet another means to construct an interpolating polynomial). We commence with the remark that  $f[x_i]$  is the coefficient of  $x^0$  in the polynomial of degree 0 (i.e., a constant) that interpolates  $f(x_i)$ , hence  $f[x_i] = f(x_i)$ .

**Theorem** Suppose that  $x_0, x_1, \ldots, x_{k+1}$  are pairwise distinct, where  $k \geq 0$ . Then

$$f[x_0, x_1, \dots, x_{k+1}] = \frac{f[x_1, x_2, \dots, x_{k+1}] - f[x_0, x_1, \dots, x_k]}{x_{k+1} - x_0}.$$
(6.4)

**Proof.** Let  $p, q \in \mathbb{P}_k[x]$  be the polynomials that interpolate f at

$$\{x_0, x_1, \dots, x_k\}$$
 and  $\{x_1, x_2, \dots, x_{k+1}\}$ 

respectively and define

$$r(x) := \frac{(x - x_0)q(x) + (x_{k+1} - x)p(x)}{x_{k+1} - x_0} \in \mathbb{P}_{k+1}[x].$$

We readily verify that  $r(x_i) = f(x_i)$ , i = 0, 1, ..., k+1. Hence r is the (k+1)-degree interpolating polynomial and  $f[x_0, ..., x_{k+1}]$  is the coefficient of  $x^{k+1}$  therein. The recurrence (6.4) follows from the definition of divided differences.