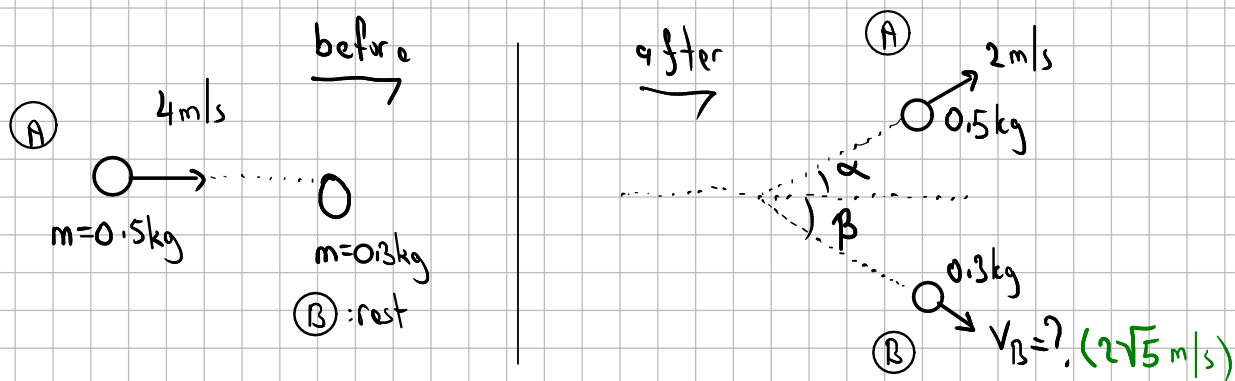


## Elastic Coll. | 2D example



\* Given that the collision is "elastic":

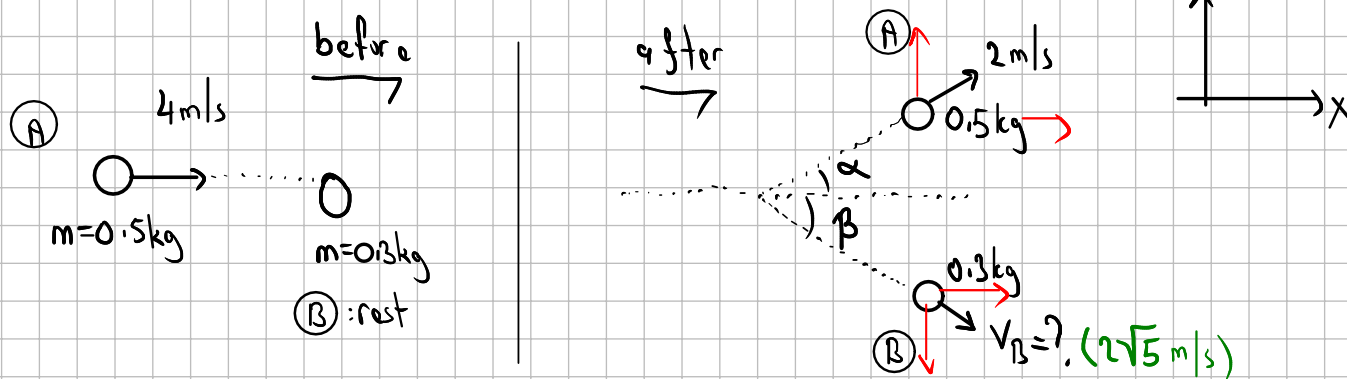
$\Rightarrow$  Find  $V_B = ?$  and angles  $\alpha, \beta$

○ Using conservation of energy:

$$K = \frac{1}{2}(0.5) \cdot (4^2) + 0 = \frac{1}{2}(0.5)(2^2) + \frac{1}{2}(0.3)V_B^2$$

$$4 = \frac{1}{4} \cdot 4 + \frac{1}{2} \cdot \frac{3}{10} \cdot V_B^2 \rightarrow \cancel{4} = \frac{1}{4} \cdot \cancel{4} + \frac{1}{2} \cdot \frac{3}{10} \cdot V_B^2 \rightarrow V_B^2 = 20$$

$$V_B = \sqrt{20} = 2\sqrt{5} \text{ m/s}$$



\* Conservation of momentum:

$$p_x: (0.5)(4) + 0 = (0.5)(2)\cos\alpha + (0.3)(2\sqrt{5})\cos\beta$$

$$2 = \cos\alpha + \frac{3}{10} \cdot 2\sqrt{5} \cos\beta \rightarrow \boxed{2 = \cos\alpha + \frac{3}{\sqrt{5}} \cos\beta} \quad (1)$$



\* Cons. of momentum:

$$p_y: 0 = (0.5)(2) \sin \alpha - (0.3)(2\sqrt{5}) \sin \beta$$

$$\Rightarrow \sin \alpha = \frac{3}{5} \sin \beta \Rightarrow \boxed{\sin \alpha = \frac{3}{5} \sin \beta} \quad (2)$$

$$\boxed{2 = \cos \alpha + \frac{3}{\sqrt{5}} \cos \beta} \quad (1)$$

$$\boxed{\sin \alpha = \frac{3}{5} \sin \beta} \quad (2)$$

$$\rightarrow \left( \frac{(2 - \cos \alpha) \sqrt{5}}{3} = \cos \beta \right)^2$$

$$\rightarrow \boxed{\cos^2 \beta = \frac{5}{9} [4 + \cos^2 \alpha - 4 \cos \alpha]} \quad (2)^2$$

$$\sin^2 x + \cos^2 x = 1$$

$$\sin^2 \beta = 1 - \cos^2 \beta$$

$$\cos^2 \beta = 1 - \sin^2 \beta$$

$$\sin^2 \alpha = \frac{9}{5} \sin^2 \beta \Rightarrow \boxed{\frac{5 \sin^2 \alpha}{9} = \sin^2 \beta} \quad (1)^2$$

$$1 - \sin^2 \beta = \cos^2 \beta = 1 - \frac{5}{9} \sin^2 \alpha = \frac{5}{9} [4 + \cos^2 \alpha - 4 \cos \alpha]$$

$$9 - 5 \sin^2 \alpha = 20 + 5 \cos^2 \alpha - 20 \cos \alpha$$



$$9 - 5 \sin^2 \alpha - 20 - 5 \cos^2 \alpha + 20 \cos \alpha = 0$$

$$-11 - 5(\underbrace{\sin^2 \alpha + \cos^2 \alpha}_1) + 20 \cos \alpha = 0$$

$$-16 + 20 \cos \alpha = 0 \Rightarrow \boxed{\cos \alpha = \frac{4}{5}}$$

$$\sin \alpha = \sqrt{1 - \cos^2 \alpha}$$

$$\sin \alpha = \sqrt{1 - \frac{16}{25}}$$

$$\sin \alpha = \frac{3}{5}$$

$$\boxed{\sin \alpha = \frac{3}{\sqrt{5}} \sin \beta}$$

$$\frac{3}{5} = \frac{3}{\sqrt{5}} \sin \beta$$

$$\boxed{\frac{1}{\sqrt{5}} = \sin \beta}$$

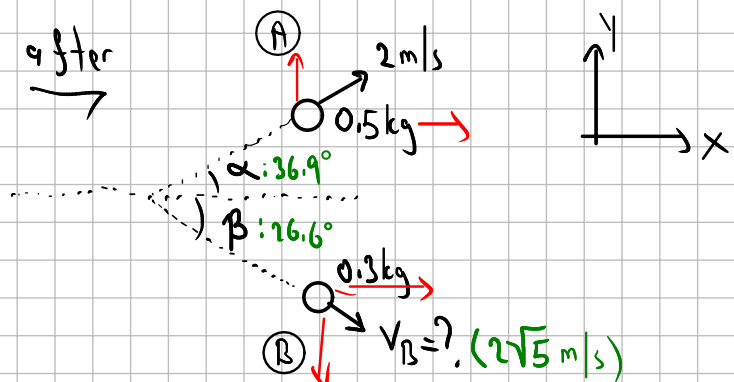
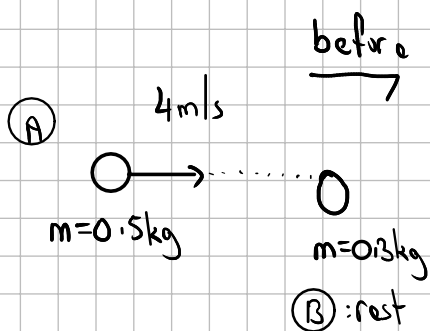
$$\alpha = \cos^{-1}\left(\frac{4}{5}\right)$$

$$\alpha \approx 36.9^\circ$$

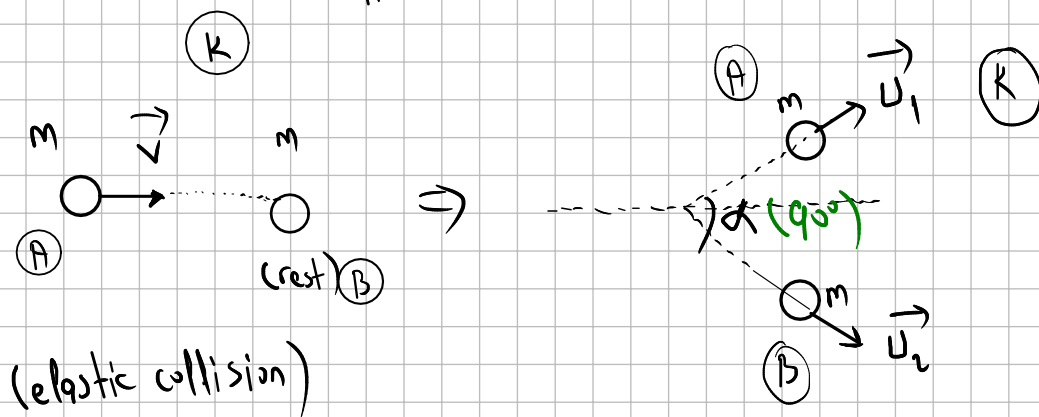
$$\beta = \sin^{-1}\left(1/\sqrt{5}\right)$$

$$\beta \approx 26.6^\circ$$

$$\boxed{\alpha + \beta \approx 63.5^\circ}$$



Special case:  $m_A = m_B = m$  (one of them is at rest)



\* Conservation of energy:

$$K = \cancel{\frac{1}{2} m v^2} = \cancel{\frac{1}{2} m u_1^2} + \cancel{\frac{1}{2} m u_2^2} \Rightarrow \boxed{v^2 = u_1^2 + u_2^2}$$

$$\vec{p} = \cancel{m \vec{v}} + 0 = \cancel{m \vec{u}_1} + \cancel{m \vec{u}_2} \Rightarrow \boxed{\vec{v} = \vec{u}_1 + \vec{u}_2}$$

$$v^2 = \vec{v} \cdot \vec{v} = (\vec{u}_1 + \vec{u}_2) \cdot (\vec{u}_1 + \vec{u}_2)$$

$$v^2 = u_1^2 + \vec{u}_1 \cdot \vec{u}_2 + \vec{u}_2 \cdot \vec{u}_1 + u_2^2$$

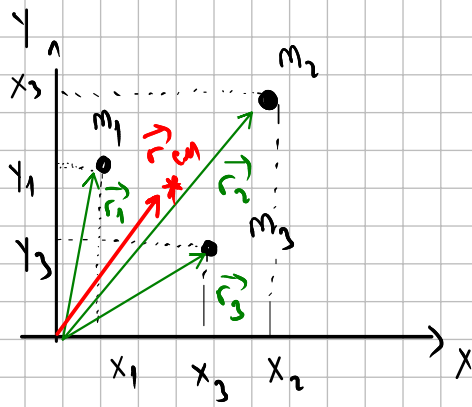
$$v^2 = u_1^2 + u_2^2 + 2\vec{u}_1 \cdot \vec{u}_2$$

$$\cancel{u_1^2} + \cancel{u_2^2} = \cancel{u_1^2} + \cancel{u_2^2} + 2\vec{u}_1 \cdot \vec{u}_2 \rightarrow \vec{u}_1 \cdot \vec{u}_2 = 0$$

$$\hookrightarrow u_1 u_2 \cos \alpha = 0$$

$$\cos \alpha = 0 \Rightarrow \alpha = 90^\circ$$

## Center of Mass



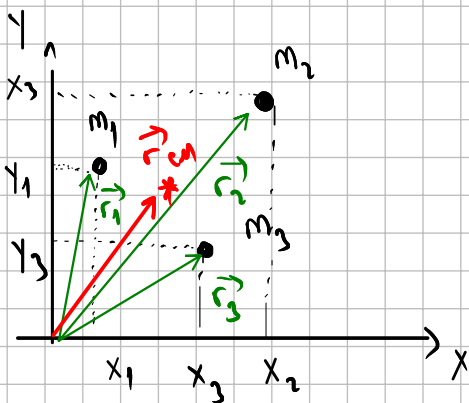
$m_1, m_2, m_3, \dots$  : masses

$\vec{r}_1, \vec{r}_2, \vec{r}_3, \dots$  : position vectors.

define the center of mass: (C.M)

$\Rightarrow$  C.M is a point as if all the mass ( $m_1 + m_2 + m_3 + \dots$ ) is concentrated at.

$\hookrightarrow$  C.M is the weighted average of positions (weighted by mass values)



$$\vec{r}_{cm} = \frac{m_1 \vec{r}_1 + m_2 \vec{r}_2 + m_3 \vec{r}_3 + \dots}{m_1 + m_2 + m_3 + \dots}$$

$m_1 + m_2 + \dots = M$  (total mass)

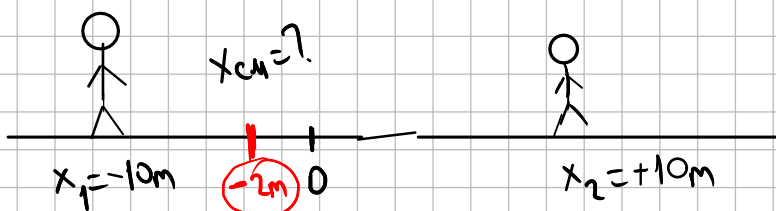
Coordinates of the centre of Mass:

$$x_{cm} = \frac{m_1 x_1 + m_2 x_2 + m_3 x_3 + \dots}{M}$$

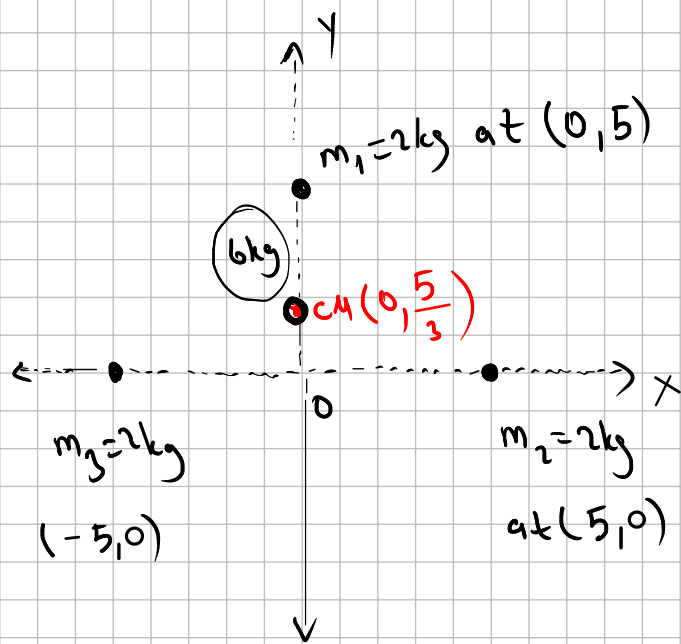
$$y_{cm} = \frac{m_1 y_1 + m_2 y_2 + m_3 y_3 + \dots}{M}$$

$m_1 = 90 \text{ kg}$

$m_2 = 60 \text{ kg}$



$$x_{cm} = \frac{(90)(-10) + (60)(10)}{150} = \frac{-900 + 600}{150} \Rightarrow x_{cm} = -2 \text{ m}$$



$x_{cm}, y_{cm}$  in  $x_{cm}, y_{cm}$

$$x_1 = 0 \quad y_1 = 5$$

$$x_2 = 5 \quad y_2 = 0$$

$$x_3 = -5 \quad y_3 = 0$$

$$M = 6 \text{ kg}$$

$$x_{cm} = \frac{m_1 x_1 + m_2 x_2 + m_3 x_3}{M} = \frac{2 \cdot 0 + 2 \cdot 5 + 2 \cdot (-5)}{6} = 0$$

$$y_{cm} = \frac{m_1 y_1 + m_2 y_2 + m_3 y_3}{M} = \frac{2(5) + 2(0) + 2(0)}{6} = \frac{10}{6} = \frac{5}{3}$$

Center of Mass Motion:

$$\vec{r}_{cm} = \frac{m_1 \vec{r}_1 + m_2 \vec{r}_2 + m_3 \vec{r}_3 + \dots}{M} \quad (M = m_1 + m_2 + \dots)$$

$$M \vec{r}_{cm} = (m_1 \vec{r}_1 + m_2 \vec{r}_2 + m_3 \vec{r}_3 + \dots)$$

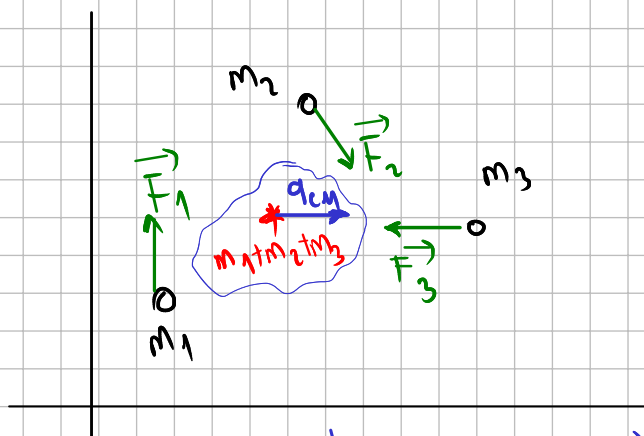
$$M \vec{v}_{cm} = (m_1 \vec{v}_1 + m_2 \vec{v}_2 + m_3 \vec{v}_3 + \dots)$$

$$M \vec{a}_{cm} = (m_1 \vec{a}_1 + m_2 \vec{a}_2 + m_3 \vec{a}_3 + \dots)$$

$$\left\{ \vec{F} = m \cdot \vec{a} \right\}$$

$$\vec{a} = \frac{d\vec{v}}{dt} = \frac{d^2 \vec{r}}{dt^2}$$

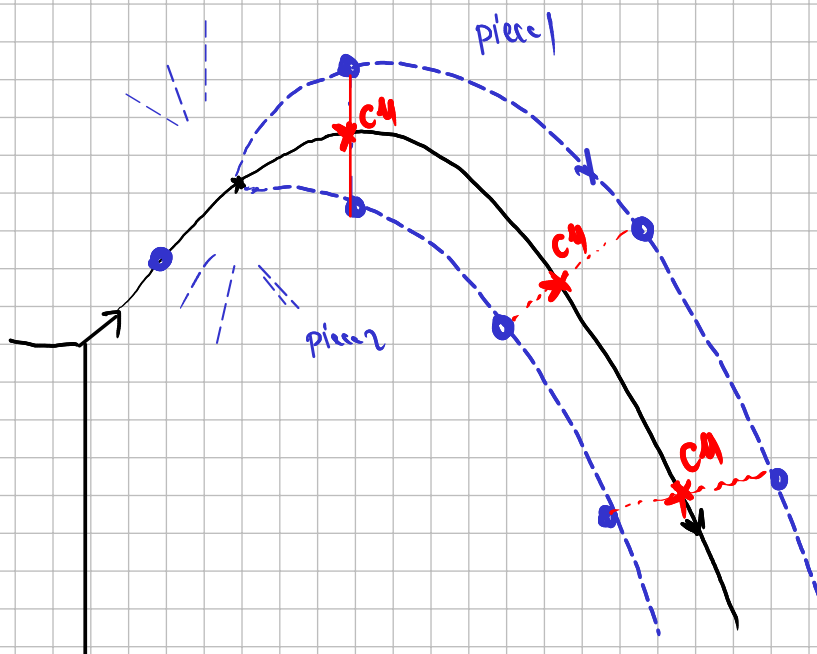
$$\vec{v} = \frac{d\vec{r}}{dt}$$



$$M\vec{a}_{cm} = \vec{F}_1 + \vec{F}_2 + \vec{F}_3 + \dots$$

$$M\vec{a}_{cm} = \vec{F}_{NET}$$

\* Center of mass behaves like a single object with a total mass ( $m_1 + m_2 + \dots$ ) with a net acceleration of  $a_{cm}$



$$M\vec{v}_{cm} = (m_1\vec{v}_1 + m_2\vec{v}_2 + m_3\vec{v}_3 + \dots)$$