### Yuanzhi Liang

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EDUCATION

Xi'an Jiaotong University, Xi'an, China

M.S., Software Engineer, Jun. 2020Advisors: Xueming Qian and Zhu Li

• GPA: 88.89 / 100

Lanzhou University, Lanzhou, China

• B.S., Electronic Engineering, Jul 2017

• GPA: 4.43 / 5

Honors

- First place in iMat Product Competition @ CVPR 2019 FGVC6 workshop
- First place in Fieldguide Challenge: Moths & Butterflies @ CVPR 2019 FGVC6 workshop
- Second place in iFood Competition @ CVPR 2019 FGVC6 workshop
- First Prize Scholarship (2013 in LZU)
- Second Prize Scholarship (2015 in LZU)
- Third Prize Scholarship (2014 in LZU)
- First Prize Scholarship (2017 in XJTU)
- Meritorious Winner in Interdisciplinary Contest in Modeling (ICM) 2016
- National Third Prize in National Undergraduate Internet Innovation and Application Design Contest 2016
- **Provincial Second Prize** in National Undergraduate Electronic Design Contest 2015

Publications

1. **Yuanzhi Liang**, Yalong Bai, Wei Zhang, Xueming Qian, Li Zhu and Tao Mei. "VrR-VG: Refocusing Visually-Relevant Relationships".

Accepted to ICCV 2019.

Dataset website: http://vrr-vg.com

2. **Yuanzhi Liang**, Zhu Li, and Xueming Qian. "Counting Passengers in Railway Compartment Surveillance Video".

Submitted to TOMCCAP.

3. Yuanzhi Liang, Rong Ma and Yide Ma. "A Size Self-adaptive Method For RBCs Counting From Different Blood Smears Based On PCNN And Image Quality".

Accepted by BIBM 2016.

Research Interests Visual Relationships Detection and Scene Graph Generation; Fine-grained Classification; Face Recognition; Crowd Counting

Engineering Capability Programming Language: Python, Matlab, C/C++, Java

Framework: pytorch, tensorflow, mxnet

RESEARCH EXPERIENCE

### JD AI Research, Image Understanding, Beijing, China

Research Intern

Aug. 2018 – Jun. 2019

(Advised by Yalong Bai and Wei Zhang)

- Visual Relationships: Representation and Applications in Cognitive Tasks
  - \* Constructed Visually-relevant Relationships Dataset (VrR-VG) to reduce the predictability of visual relationships by data bias and prior knowledge, and boosted performances of cognitive tasks by providing more valuable interaction knowledge of instances in the scene. A novel method was proposed to distinguish the visually-relevant relationships for VrR-VG.
  - \* Explored image representation learning with visual relationships. Both of the categorical knowledge including locations, attributes of single objects and the inter-action relationships among multiple objects in the images are considered for learning representations.
  - \* Studied visual relationships applications in **cognitive tasks** like visual question answering and image captioning. With visual related applications, boosted the ability of features in expressing inter-instance interaction of scenes, which perform better in cognitive tasks.
  - \* Studied scene graph generation and evaluated state-of-the-art methods. Working on a novel method to avoided quadratic time complexity in relation representation, which also adapted to various detection backbones.
- Fine-grained image recognition research.
  - \* Refactored and improved DCL method (Destruction and Construction Learning for Fine-grained Image Recognition, CVPR 2019) to work on competitions in CVPR 2019 FGVC6 workshop. Improved 0.2% 0.6% top3 accuracy of baseline methods in iMat product, Moths & Butterfly and iFood datasets
  - \* Maintaining open source code of DCL in https://github.com/JDAI-CV/DCL

# XJTU, Key Laboratory for Intelligent Network and Network Security, Xi'an, China

Sep.2017 - Jul.2018

(Advised by Xueming Qian)

- Passenger Analysis in Highway Compartment Surveillance Video.
  - \* The project was supported by CRRC Corporation Limited. The research topic is about **semi-supervised passengers detection and counting**. With surveillance videos in highway compartment, designed annotation methods and plans at minimum cost. Proposed a semi-supervised method with the CNN encoder and the post-processing module including Hebb learning module and Kalman filter. Adjusted annotations and methods to get better performances.
- Face detection and recognition.
  - \* Targeting at solving **occluded face** in surveillance video, researched related methods and validated performances ( data from China Graduate Contest on Smart-city Technology and Creative Design ). Explored and designed a system with face detection ( SFD, FAN ), face recognition ( SphereFace, CosFace, ArcFace ), face alignment ( dlib and opency API ), occluded face segmentation ( Watershed Algorithm, FCN based model ) and occluded face completion ( CycleGAN ).

## LZU, Laboratory for Electronics and Communications Engineering, Lanzhou, China

Sep.2015 - Aug.2017

(Advised by Yide Ma and Kun Zhan)

- Pulse Coupled Neural Network (PCNN) based Red Blood Cells (RBCs) Counting.
  - \* Worked on **RBCs counting** via microscope images. Extracted the contours of RBCs based on the pixel quality of a binary mask from PCNN. The Circular Hough Transform (CHT) for different amplifications was used for self-adapting multiple scales of RBCs.
- PCNN based Image Representation and Classification.
  - \* Studied **image classification** (datasets: Caltech 101, CIFAR-100) by encoding the distributions of PCNN masks. Applied the PCNN outputs in different time series to extract image features, and utilized the PCNN in image representation.

#### Others

- Bachelor's Period: Explored time series prediction in traffic flow (Wavelet Neural Network (WNN)). Created color ring resistors recognition system based on image processing (PCNN, SIFT).
- Participated in the Sales Forecasting of Supply Chain Project in JD. ( sales forecasting with LSTM )
- As a director, completed one National Innovation and Entrepreneurship Training Program in 2016. The project was about prediction and control system of traffic flow in urban road networks.
- As a director, completed one LZU Innovation and Entrepreneurship Training Program in LZU in 2014. The project was about traffic navigation system.
- As a member, completed National Innovation and Entrepreneurship Training Program in 2016 about Through-the-Wall Radar Imaging. Completed another LZU Innovation and Entrepreneurship Training Program in 2015 about the control system in robotic grasping.