

Delegation and Strategic Silence

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Decision Processes in Organizational Economics

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- ▶ Organizations with **choice and execution**:
 - ▶ Choice: **what is intended to be done** (Mintzberg, 1979)
 - ▶ e.g. projects.
 - ▶ A subordinate **executes** what is chosen.
- ▶ Who makes a decision on choice?
 - ▶ Choice in a top-down manner is a feature of hierarchical organizations.
 - ▶ Delegation to the executor may influence performances in the organization.

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Two Contrasted Successes during the Financial Crisis

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- ▶ Nintendo (Inoue, 2010):
 - ▶ Satoru Iwata (President) motivated the engineers through 'directing a "non-tech" way'.
 - ▶ Nintendo Wii regained top market share in the seventh generation.
- ▶ HCL Technologies (Nayar, 2010):
 - ▶ 'Inverting the pyramid' to capture imagination at the bottom.
 - ▶ Vineet Nayar (CEO) needed to convince (passive) employees that they understand business better than CEO.

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- ▶ Why did both Nintendo and HCLT successfully motivate workers by different decision processes?
 - ▶ Iwata's direction (**centralization** in Nintendo).
 - ▶ Inverting the pyramid (**delegation** in HCLT).
- ▶ Why did HCLT need to persuade employees in the process of investing pyramid?

Introduction

Purpose of This Paper

- ▶ We investigate an organization (P-A model) with **choice (project)** and **execution (effort)**.
 - ▶ Each has imperfect information on the project.
 - ▶ Successful execution of the project requires the agent's effort.
 - ▶ Incomplete contracting: no incentive contract.
- ▶ The allocation of authority is specified formally:
 - ▶ **centralization**: the principal chooses a project.
 - ▶ **delegation**: the agent chooses a project.
- ▶ Later, formal delegation is infeasible:
 - ▶ informal delegation (**empowerment**): the principal chooses a project **based on the agent's report**.

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Results

- ▶ The allocation of authority influences
 - ▶ the probability to choose the promising project (direct effect); and
 - ▶ the agent's **motivation** to **execute the project** (indirect effect).
- ▶ It may be optimal to allocate authority to the **party with less precise information**.
- ▶ Empowerment might be prevented even **without conflict of interest** over projects.
 - ▶ benefit of **being passive**: the agent may deny to report his proposal.

Related Literature

Related Works

- ▶ The allocation of authority: Aghion and Tirole (1997); Bolton and Dewatripont (2013); Gibbons et al. (2013); Mookherjee (2013)
- ▶ Choice and execution:
 - ▶ Blanes i Vidal and Möller (2007, 2016a,b), Landier et al. (2009), Itoh and Morita (2018)
 - ▶ Zábojník (2002):
 - ▶ formal incentives are available.
 - ▶ Other setup with allocation of authority: Bester and Krähmer (2008), Hirata (2017), Ishihara (2020)

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Related Literature

Related Works

- ▶ Informal delegation in relational contracting: Baker et al. (1999), Alonso and Matouschek (2007), Li et al. (2017). Lipnowski and Ramos (2020)
 - ▶ Non-credible informal delegation due to conflict of interest over projects: the principal has incentives to overturn the agent's proposal.
 - ▶ We demonstrate non-credible informal delegation even **without conflict of interest**.

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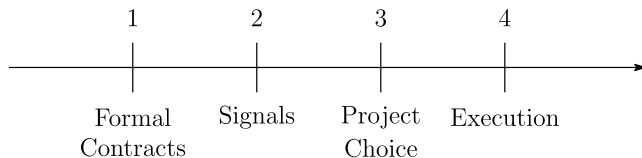
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- ▶ Players: Principal (P) and Agent (A), both risk neutral.
- ▶ Timing in period t :



- ▶ Stage 1: P offers a **formal contract** that specifies the party with authority $\alpha \in \{P, A\}$:
 - ▶ **centralization**: $\alpha = P$;
 - ▶ **delegation**: $\alpha = A$.

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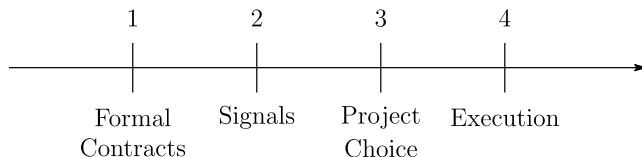
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- ▶ There are **two** alternative projects: $\{1, -1\}$
- ▶ Stage 2:
 - ▶ (Unknown) state variable $s \in \{1, -1\}$ indicates the **promising project**.
 - ▶ Prior $Prob(s = 1) = Prob(s = -1) = 1/2$
 - ▶ Each $i \in \{P, A\}$ receives **signal** $\theta_i \in \{1, -1\}$ such that $Prob(\theta_i = s \mid s) \equiv q_i \in (1/2, 1)$.
 - ▶ $Prob(s = \theta_i \mid \theta_i) = q_i$: precision of the signal

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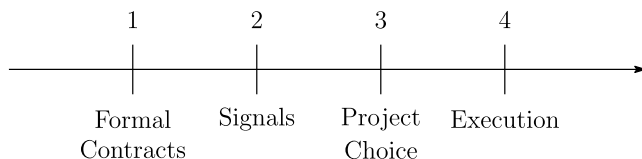
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- ▶ Stage 3: party α chooses a **project** $d \in \{1, -1\}$.
- ▶ Stage 4: A chooses execution **effort** $e \in \{1, 0\}$ with effort cost ce , where $c > 0$.
- ▶ The project results in either
 - ▶ $x = 1$ (success) $\iff d = s$ and $e = 1$; or
 - ▶ $x = 0$ (failure) $\iff d \neq s$ or $e = 0$.

Static Setup

Assumptions

- ▶ P and A receive benefit x_B and x_b , respectively, where $B > 0$ and $b > 0$.
- ▶ Payoffs given e and x :
 - ▶ P : x_B ;
 - ▶ A : $x_b - ce$.
- ▶ Informational assumptions
 - ▶ **verifiable** variables: authority (who decides d)
 - ▶ **observable** but **nonverifiable** variables: d and x
 - ▶ **private information**: θ_i and e
 - ▶ **unobservable variables**: s

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- ▶ P 's optimal perfect Bayesian equilibria in which Bayes rule applies as much as possible
 - ▶ Fudenberg and Tirole (1991, Ch. 8).
- ▶ Equilibrium actions: $(\alpha, d^\alpha(\theta_\alpha), e^\alpha(\theta_A, d))$
 - ▶ Centralization ($\alpha = P$) or delegation ($\alpha = A$)?

Formal Allocation of Authority

Equilibrium Conditions

- ▶ Given $\alpha \in \{P, A\}$, let
 - ▶ π^α be P 's optimal expected payoff;
 - ▶ u^α be A 's associated payoff.
- ▶ Constraints:
 - ▶ (PIC): α chooses $d^\alpha(\theta_\alpha)$.
 - ▶ (EIC): A chooses $e^\alpha(\theta_A, d)$.

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Project Choice (PIC)

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Lemma

$$d^\alpha(\theta_\alpha) = \theta_\alpha.$$

- ▶ The project is chosen based on the **decision maker's information**.
- ▶ The party with a **more precise signal** (i.e., higher q_i) is more likely to choose the promising project.

Formal Allocation of Authority

Effort Choice (EIC)

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- ▶ $e^\alpha(\theta_A, d) = 1$ if and only if

$$\begin{aligned} & \text{Prob}(s = d \mid \theta_A, d, \alpha)b - c \geq 0 \\ \iff v \equiv \frac{b}{c} & \geq \frac{1}{\text{Prob}(s = d \mid \theta_A, d, \alpha)}. \end{aligned}$$

- ▶ v : A 's **intrinsic incentive**
- ▶ $\text{Prob}(s = d \mid \theta_A, d, \alpha)$: A 's **confidence**
 - ▶ Posterior belief of the chosen project to be promising given A 's signal θ_A
 - ▶ A exerts more effort **as he believes project d to be promising more likely**.

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- ▶ For $\alpha = A$, since $d = \theta_A$, A 's confidence is

$$\text{Prob}(s = d \mid d = \theta_A, \alpha = A) = q_A.$$

- ▶ A exerts effort (for all d and θ_A)

$$\Longleftrightarrow v \underbrace{\geq}_{(\text{EIC})} v^D \equiv \frac{1}{q_A}.$$

- ▶ P 's payoff: $\pi^A = q_A B$
- ▶ Otherwise, A exerts no effort (for all d and θ_A).
 - ▶ P 's payoff: $\pi^A = 0$

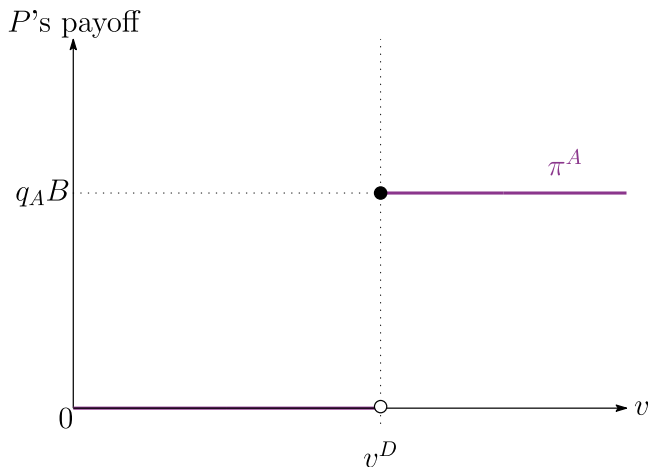
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► Illustration of π^A :



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Centralization

- ▶ For $\alpha = P$, A learns θ_P through P 's choice $d = \theta_P$.
- ▶ By Bayesian updating,

$$\begin{aligned} & \text{Prob}(s = d \mid \theta_A, d = \theta_P, \alpha = P) \\ &= \begin{cases} \frac{q_P q_A}{q_P q_A + (1 - q_P)(1 - q_A)} & \text{if } \theta_P = \theta_A, \\ \frac{q_P(1 - q_A)}{q_P(1 - q_A) + (1 - q_P)q_A} & \text{if } \theta_P \neq \theta_A. \end{cases} \end{aligned}$$

- ▶ A 's confidence is (ex ante) uncertain:

$$\begin{aligned} & \text{Prob}(s = d \mid \theta_A = d = \theta_P, \alpha = P) \\ & > \text{Prob}(s = d \mid \theta_A \neq d = \theta_P, \alpha = P) \end{aligned}$$

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- ▶ (Full execution): A exerts effort for all d and θ_A

$$\iff v \underbrace{\geq}_{\text{(EIC) for } d \neq \theta_A} v_1^C \equiv 1 + \frac{(1 - q_P)q_A}{q_P(1 - q_A)},$$

- ▶ P 's payoff: $\pi^P = q_P B$

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- ▶ (Partial execution): even for $v < v_1^C$, A may exert effort **only when** A is **more confident** ($d = \theta_A$):

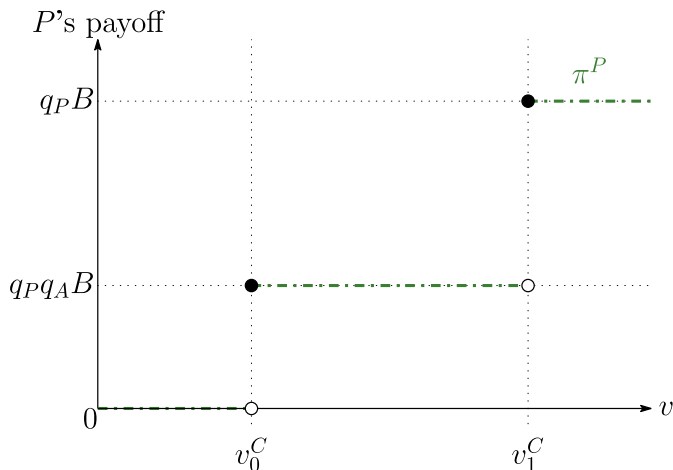
$$\iff v \underbrace{\geq}_{\text{(EIC) for } d=\theta_A} v_0^C \equiv 1 + \frac{(1 - q_P)(1 - q_A)}{q_P q_A}.$$

- ▶ P 's payoff: $\pi^P = q_P q_A B$

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► Illustration of π^P :



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- ▶ Let $\bar{q}_A \equiv q_A^2 / [q_A^2 + (1 - q_A)^2] (> q_A)$.

Definition

P is

- ▶ *strongly (informationally) superior* if $q_P \geq \bar{q}_A$.
- ▶ *weakly (informationally) superior* if $q_P \in (q_A, \bar{q}_A)$.
- ▶ *(informationally) inferior (or A is superior)* if $q_P \leq q_A$.

- ▶ When $q_P \geq \bar{q}_A$, P always holds authority.

Formal Allocation of Authority

Uncertainty of Confidence

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- ▶ If $q_P < \bar{q}_A$, A 's confidence satisfies:

$$\underbrace{\text{Prob}(s = d \mid d = \theta_A)}_{\text{Centralization with } d=\theta_A} > \underbrace{\text{Prob}(s = d \mid \theta_A)}_{\text{Delegation}} \\ > \underbrace{\text{Prob}(s = d \mid d \neq \theta_A)}_{\text{Centralization with } d \neq \theta_A}.$$

- ▶ **Uncertainty of A 's confidence under centralization:**
 - ▶ **misalignment** of the signals ($d \neq \theta_A$) **demotivates** A to exert effort;
 - ▶ **alignment** of the signals ($d = \theta_A$) **motivates** A to exert effort.

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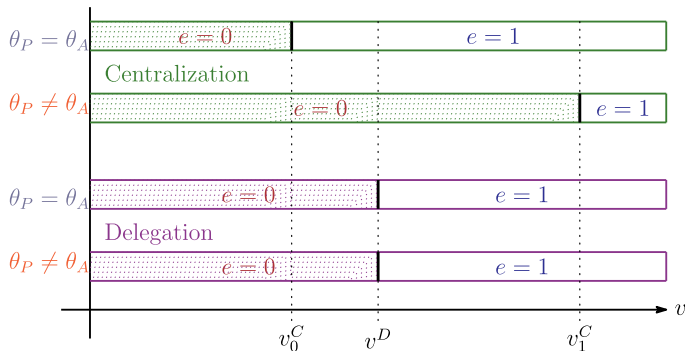
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► Effort decision when $q_P < \bar{q}^A$



► For $v \in [v^D, v_1^C)$, only **delegation** can induce **full execution**.

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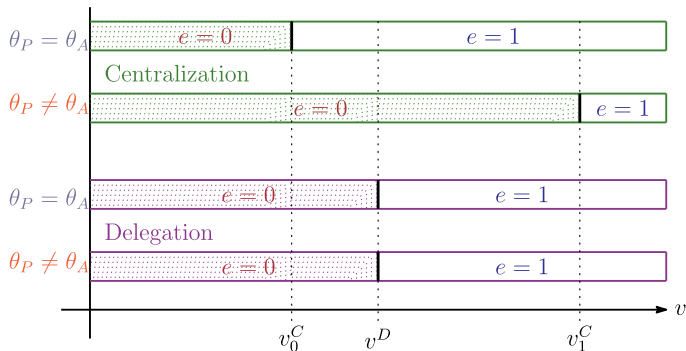
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► Effort decision when $q_P < \bar{q}^A$



► For $v \in [v_0^C, v^D)$, only **centralization** may induce effort.

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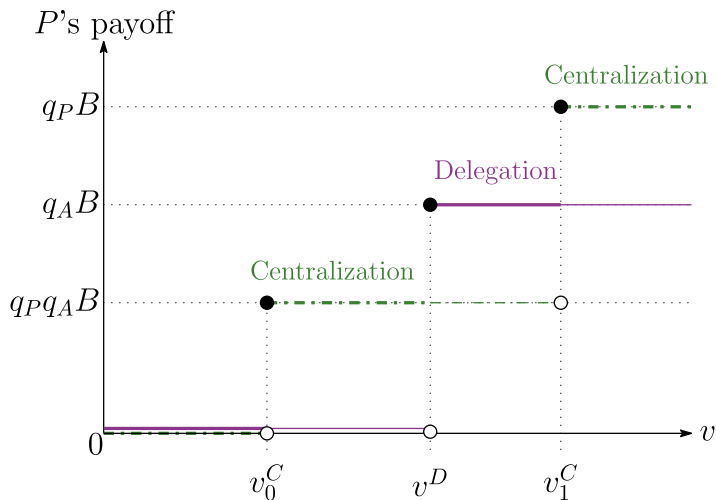
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P Is Weakly Informationally Superior

- Even if $q_P \in (q_A, \bar{q}_A)$, A may hold authority.



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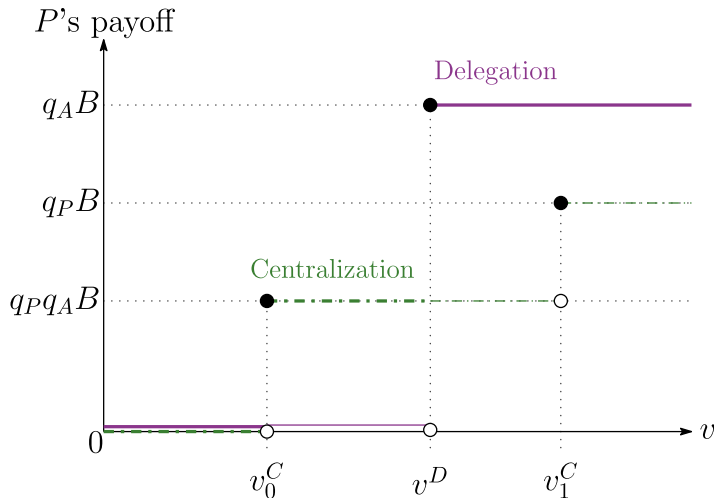
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A Is Informationally Superior

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- Even if $q_P \leq q_A$, P may hold authority.



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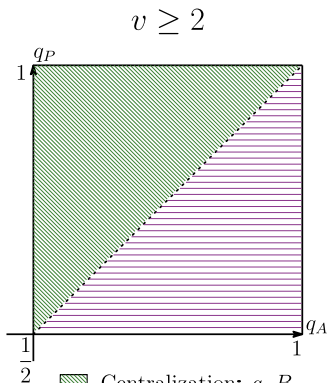
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
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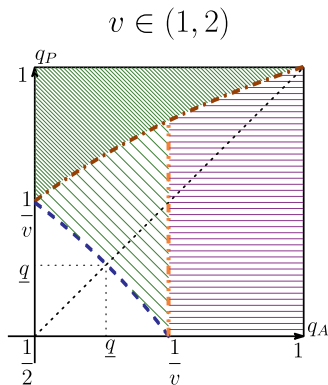
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-  Centralization: $q_P B$
-  Delegation: $q_A B$
-  Centralization: $q_P q_A B$
-  Indifferent: 0



-  $v_0^C = v$
-  $v_1^C = v$
-  $v^D = v$

$$\underline{q} \equiv \frac{1 - \sqrt{v-1}}{2-v}$$

Formal Allocation of Authority

Case Studies: Nintendo

- ▶ **High uncertainty** to develop hit products in the video game industry.
 - ▶ Low q_P and q_A
 - ▶ Centralized decision making
 - ▶ is a desirable way to motivate employees; but
 - ▶ induces environments to be more uncertain due to the motivation problem.

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- ▶ Necessary for customers satisfactory to learn what customers need (Nayar, 2010)
 - ▶ High q_A : employees directly interact with customers and would have better information.

Empowerment

Informal Delegation

- ▶ HCLT initially struggled through inverting the pyramid.
 - ▶ Employees were initially passive in decision making.
 - ▶ Could the passive attitude be prevent delegation?
- ▶ It is often argued that all formal decision rights must **reside at the top**.
 - ▶ Control rights are **not contractible**.
- ▶ **Empowerment**: informal delegation as a form of report and ratification.
- ▶ Can the equilibrium outcome of delegation be implemented through A 's **report** on his signal?
 - ▶ P chooses d based on A 's report.

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- ▶ Timing modified:
 - 1. Formal contracting to specify α .
 - 1. s , θ_P , and θ_A .
 - 2. A reports $m \in \{\theta_A, \phi\}$.
 - 3. P chooses d .
 - 4. A chooses e .
- ▶ Signal θ_A is **concealable**, but **not fabricatable** (disclosure games by Milgrom (1981)).
- ▶ Let $m(\theta_A)$ be A 's message.

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Requirement 1

1. *(Symmetric Messages) either*
 - 1.1 $m(\theta_A) = \theta_A$ for any θ_A ; or
 - 1.2 $m(\theta_A) = \phi$ for any θ_A .
2. *(Symmetric Beliefs) If $m = \phi$ is off the equilibrium path, $\text{Prob}(\theta_A \mid \theta_P, m = \phi) = \text{Prob}(\theta_A \mid \theta_P)$.*
3. *(Continuation Optimality) After the communication stage, the parties' play an optimal equilibrium for the principal.*

Empowerment

Modified Setup

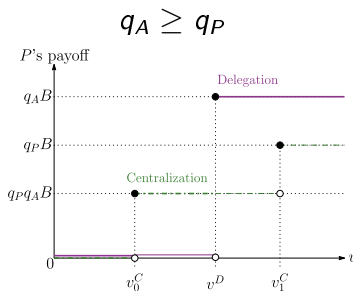
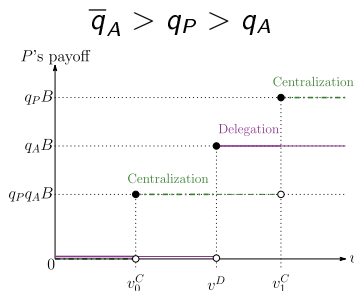
- ▶ P behaves as if she has **no additional information** after observing $m = \phi$.
- ▶ Neologism-proof (Farrell, 1993) by Requirement 1.
 - ▶ “Even when neologisms are naively believed, A does not prefer to use such neologisms.”
- ▶ The strategy constitutes **empowerment** if
 - ▶ $m^l(\theta_A) = \theta_A$ for all θ_A ;
 - ▶ $d^l(\theta_P, m) = m$ for all θ_P , and $m \in \{1, -1\}$; and
 - ▶ $e^l(\theta_A, m, d) = 1$ for some (θ_A, m, d) such that $d = m$.

Empowerment

Delegation versus Empowerment

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- ▶ Recall: delegation is strictly preferred to centralization \iff
 - ▶ $q_P \in (q_A, \bar{q}_A)$ and $v^D \leq v < v_1^C$; or
 - ▶ $q_A \geq q_P$ and $v \geq v^D$.
- ▶ Under these parameters, can empowerment be implemented?

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Proposition

There exists an equilibrium that constitutes empowerment and satisfies Requirement 1 if and only if

1. $v \geq v^E \equiv 1 + q_P(1 - q_A)/[(1 - q_P)q_A]$; and
2. $q_P \leq q_A$.

- ▶ Empowerment is implemented **only when A is informationally superior**.
- ▶ For $q_P \in (q_A, \bar{q}_A)$ and $v^D \leq v < v_1^C$,
 - ▶ **formal** delegation is strictly preferred; but
 - ▶ it **cannot** be implemented **informally**.

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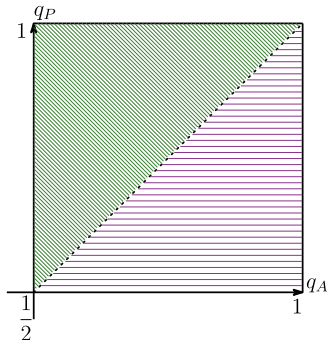
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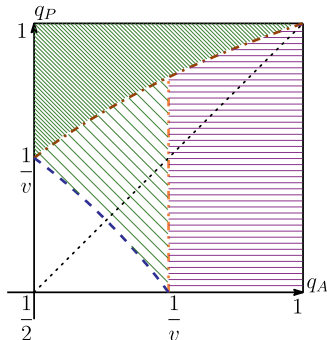
References




$$v \geq 2$$



-  Centralization: $q_P B$
-  Delegation: $q_A B$
-  Centralization: $q_P q_A B$
-  Indifferent: 0

$$v \in (1, 2)$$



-  $v_0^C = v$
-  $v_1^C = v$
-  $v^D = v$

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Centralization and Empowerment

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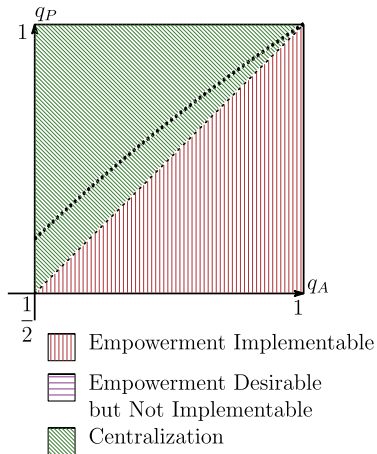
D vs. E

Interpretation

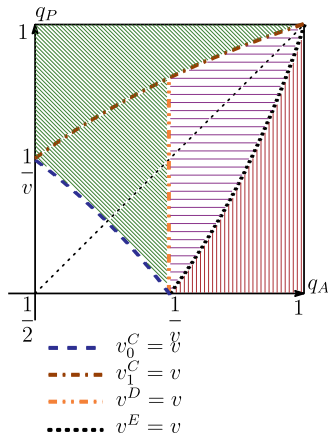
Conclusion

References

$$v \geq 2$$



$$v \in (1, 2)$$



Empowerment

Interpretation

- ▶ Informationally inferior A **conceals his information**.
 - ▶ If A conceals θ_A ,
 - ▶ P chooses $d = \theta_P$;
 - ▶ A knows θ_P when he decides e .
- ▶ Intuition: benefit of being 'passive' worker
 - ▶ Strategic silence yields **additional information**.
 - ▶ Executed projects become **more selective**.
 - ▶ **A saves execution costs** for the project with less confidence.
- ▶ Nayar tried to convince employees that
 - ▶ they understand business better than CEO;
 - ▶ the CEO was not able to answer all the employee's questions ($q_P \downarrow$).

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- ▶ The previous literature: non-credibility of empowerment due to the **ratification process**.
 - ▶ **Conflict of interest** over projects matters.
- ▶ Empowerment might be impossible even if the parties have **no conflict of interest over projects**.
 - ▶ Another factor necessary for empowerment: subordinates' **information transmission**.

- ▶ Incomplete contracting models of allocation of authority.
- ▶ Motivational advantage and disadvantage:
 - ▶ Delegation shuts down the boss's signal
⇒ certain confidence.
 - ▶ Centralization provides an additional signal
⇒ uncertain confidence.
- ▶ Gap between delegation and empowerment.
 - ▶ Preventing informal delegation due to information concealment.

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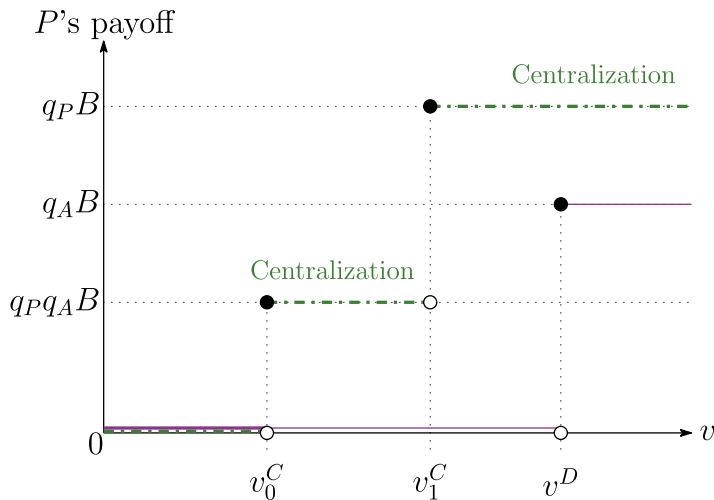
Formal Allocation of Authority

P Is Strongly Informationally Superior

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- ▶ When $q_P \geq \bar{q}_A$, P always holds authority.



Appendix

Rev vs. Conc

Appendix: Analysis

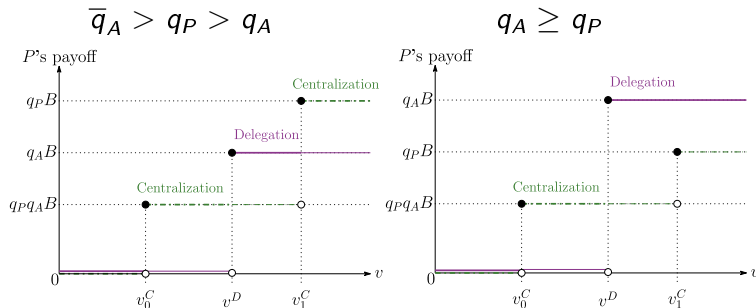
Interpretation: Large v

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Rev vs. Conc



- ▶ $v \geq v_1^C$: effort is easily induced.
- ▶ The superior party should have authority.

Appendix: Analysis

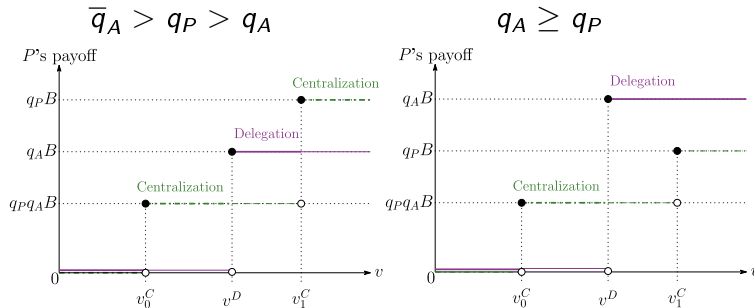
Interpretation: Intermediate v

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- ▶ $v \in [v^D, v_1^C)$: **advantage of delegation**
 - ▶ Centralization prevents A from exerting effort **after** observing $d \neq \theta_A$.
 - ▶ **Delegation is optimal even when $q_A < q_P$** since A's confidence is not reduced.

Appendix: Analysis

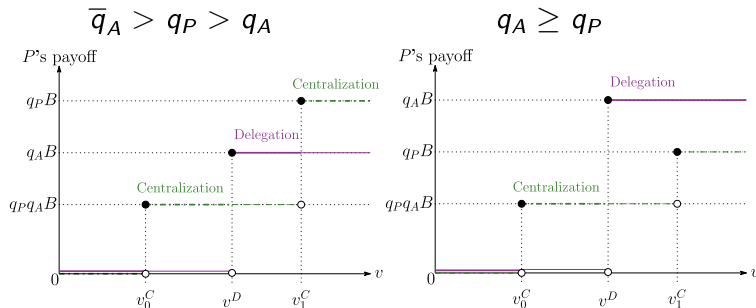
Interpretation: Small v

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- ▶ $v \in [v_0^C, v^D)$: **advantage of centralization**
 - ▶ Delegation induces A to exert **no** effort.
 - ▶ **Centralization is optimal even when $q_P < q_A$** since A's confidence is increased by observing $d = \theta_A$.

Appendix: Analysis

Relation to Zábojník (2002)

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- ▶ Zábojník (2002):
 - ▶ Incentive contracts are available.
 - ▶ No motivational advantage of centralization: centralization is optimal *only when* $q_P \geq q_A$.
 - ▶ Uncertainty of beliefs is costly for P .
- ▶ In our setup, centralization may be *motivationally advantageous*.
 - ▶ No incentive contracts.
 - ▶ When v is small,
 - ▶ centralization may induce effort; while
 - ▶ delegation does not induce effort at all.

Appendix: Analysis

Relation to Zábojník (2002)

- ▶ Zábojník (2002): **incentive contracts** are available.
- ▶ When Δ is incentive payment for $x = 1$, (EIC) is

$$\begin{aligned} & \text{Prob}(s = d \mid \theta_A, d)(b + \Delta) - c \geq 0 \\ \iff & \frac{1}{\text{Prob}(s = d \mid \theta_A, d)} \leq \frac{b + \Delta}{c} \equiv \hat{v}(\Delta) \end{aligned}$$

- ▶ Effort can always induced by sufficiently high Δ .
- ▶ Under centralization, **uncertainty of A's belief** may yield A's **rent** if limited liability is imposed.
- ▶ In our setup, no incentive contracts $\implies \Delta = 0$.

Empowerment

Revelation versus Concealment

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Rev vs. Conc

- ▶ Informationally inferior A **conceals his information**.
- ▶ Suppose $q_A \leq q_P$ and $v^D \leq v < v_1^C$.
 - ▶ If A reports θ_A and P chooses $d = \theta_A$, then his payoff is $q_A b - c$.
 - ▶ If A conceals θ_A and P chooses $d = \theta_P$, then the project is executed only when $d = \theta_A$: his payoff is

$$\underbrace{q_A q_P}_{\text{Prob}(s=\theta_A=\theta_P)} b - \underbrace{[q_A q_P + (1 - q_A)(1 - q_P)]}_{\text{Prob}(\theta_A=\theta_P)} c$$

- ▶ The difference: $q_A(1 - q_P)b - [q_A + q_P - 2q_A q_P]c$
 - ▶ negative for $q_A \leq q_P$.