

Entanglement Filtering in 3D Tensor-Network Renormalization Group

XL and Kawashima, arXiv:2311.05891

XL and Kawashima, arXiv:2412.13758

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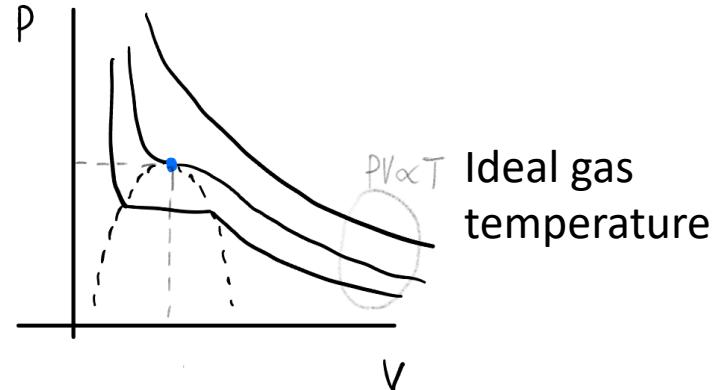


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Universality, Criticality, and RG



G
Einstein's GR

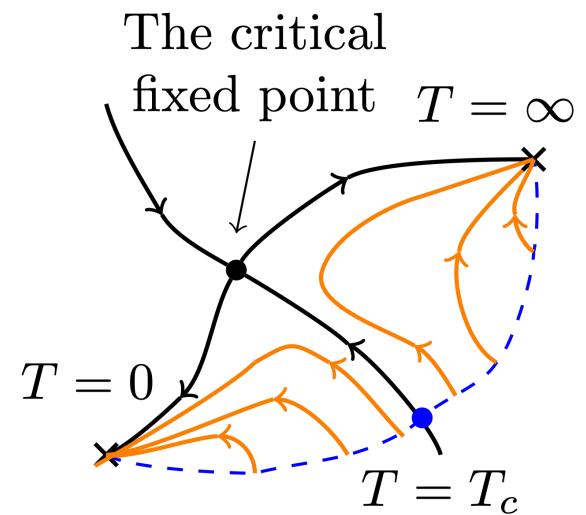


When liquid-gas transition kicks in, P_c, V_c depends on gas molecules.

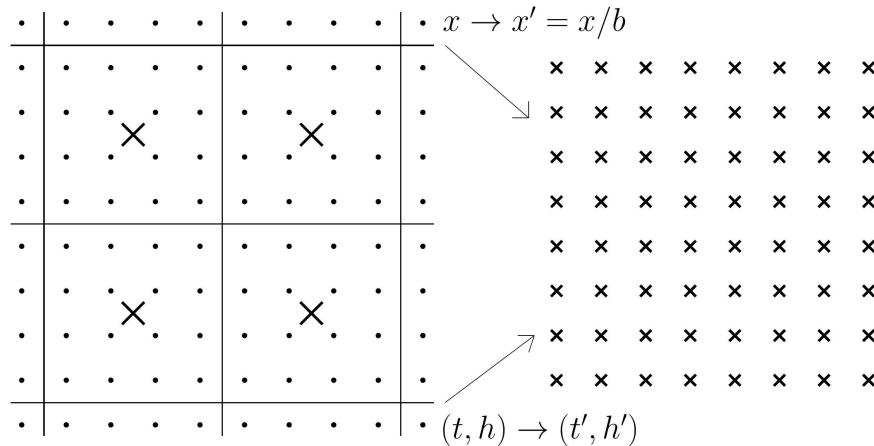
$(P - P_c) \propto (T - T_c)^\delta \rightarrow$ Critical exponents are universal

Due to interaction, theoretically predicting δ is challenging.

In 1960s and 70s, people like Kadanoff, Wilson, Fisher developed an idea called renormalization group (RG) to calculate these exponents.



Block-spin: prototype of real-space RG



Wilson (1975) implemented a numerical 3x3 block-spin map by keeping 217 couplings of 2D Ising:

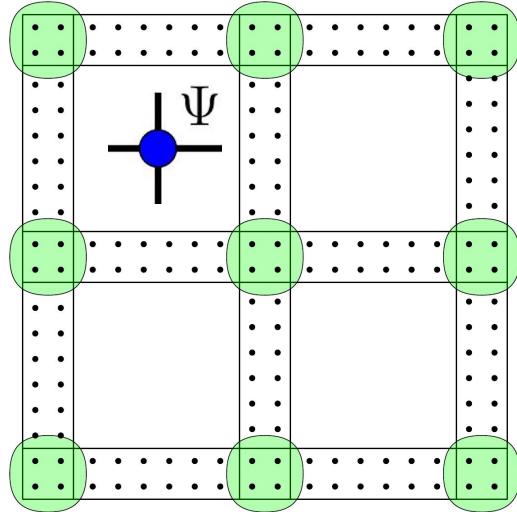
- High accuracy—1% or even 0.1% for first two exponents

“Difficult for 3D Ising... since 3x3x3 block contains about 30 spins, corresponding to 10^9 configurations”

Migdal-Kadanoff bond moving (1976) gives $\chi_\epsilon = 2.1$ (best-known value is 1.41) for 3D Ising; the relative error is about 50%...

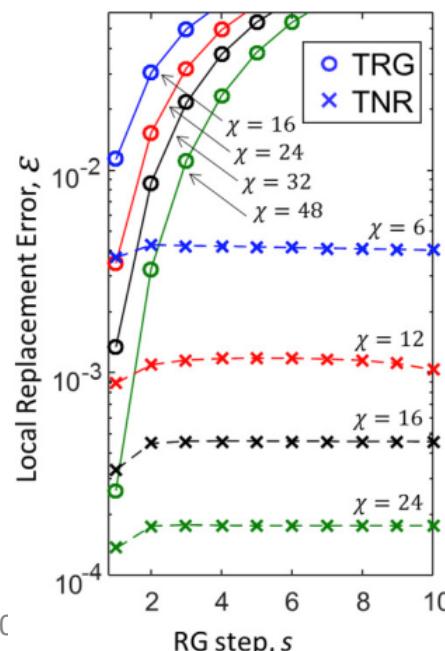
- Uncontrolled approximation
- One-shot approximation

Tensor-network reformulation



2D classical \rightarrow 1D quantum chain (radial quantization)
 \rightarrow Entanglement-entropy area law: $S(L) \sim S_0$ [due to Levin and Nave, *PRL* **99**, 120601 (2007)]

Constant S_0 can justify the practice of keeping constant number of couplings!



Systematically improvable 2D real-space RG!

exact	TNR(6)	TNR(16)	TNR(24)
0.125	0.125679	0.124941	0.124997
1	1.001499	1.000071	1.000009
1.125	1.125552	1.125011	1.124991
1.125	1.127024	1.125201	1.125027
max err.	0.83%	0.046%	0.0069%

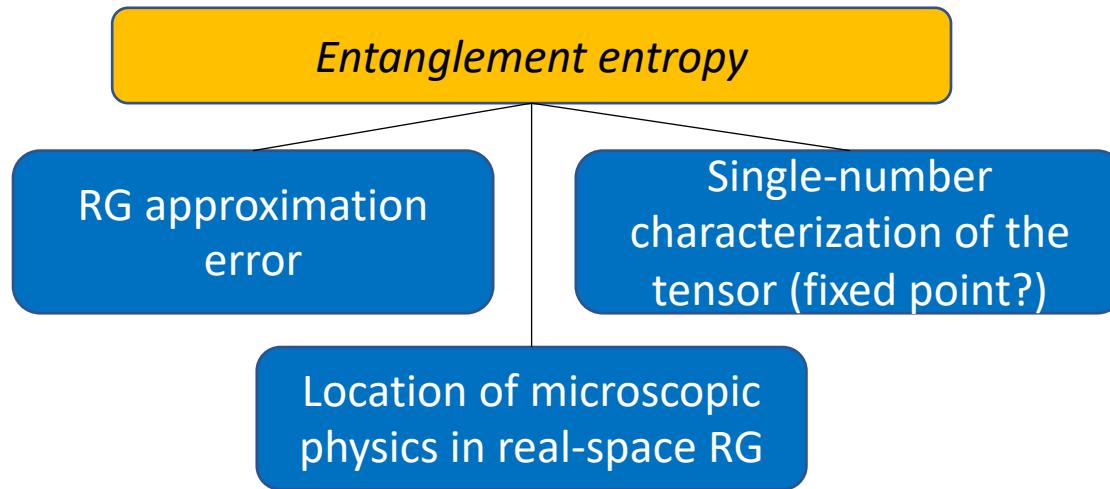
Evenly and Vidal, *PRL* **115**, 180405 (2015)

EE and Tensor-Network RG

Real-space RG methods often *work better in low dimensions, but struggle more in higher dimensions*:

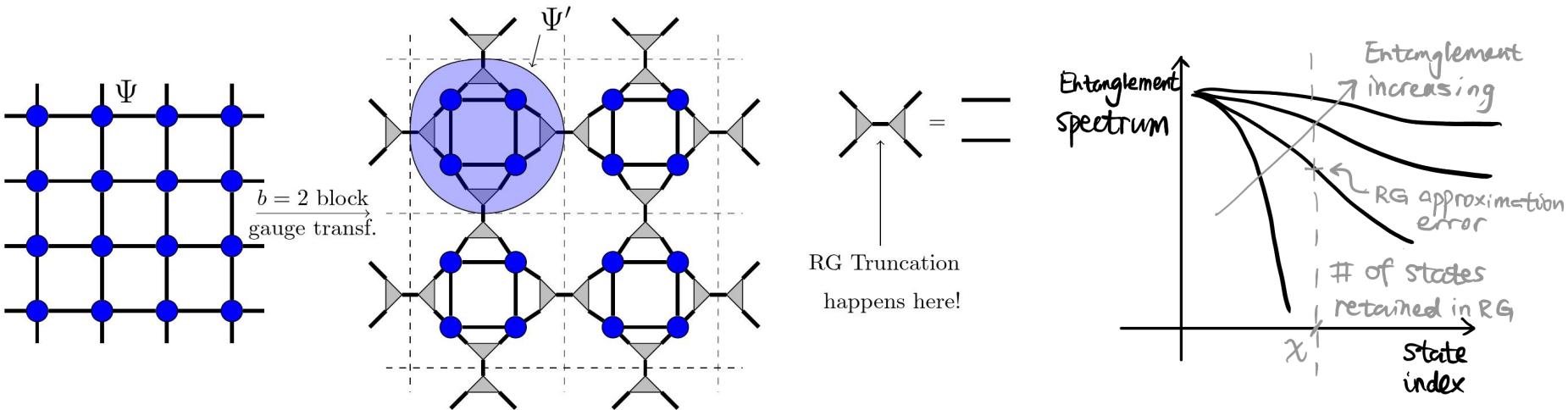
- Migdal-Kadanoff bond moving can be intuitively seen as a perturbative approach starting from d_L
- Computationally, dimensionality of coupling constant space grows faster

For Tensor-Network RG, entanglement entropy is a tool for understanding



EE and TNRG: block-tensor map

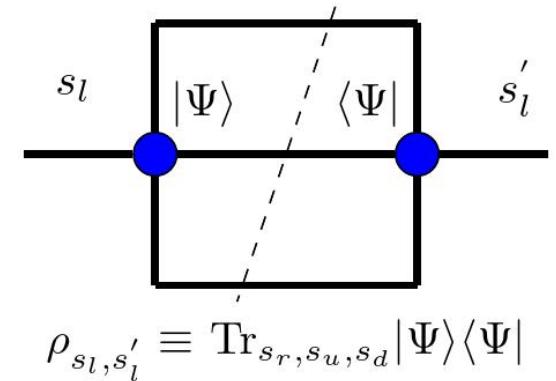
Block idea in tensor-network language: *block-tensor transformation*



An RG flow in tensor space: $\Psi^{(0)} \rightarrow \Psi^{(1)} \rightarrow \Psi^{(2)} \rightarrow \dots$

Takeaways:

- Entanglement entropy \nearrow indicates RG error \nearrow
- Changing entanglement entropy indicates your tensor isn't fixed (but we *wish* to have a fixed-point tensor).



EE and TNRG: block-tensor in 3D

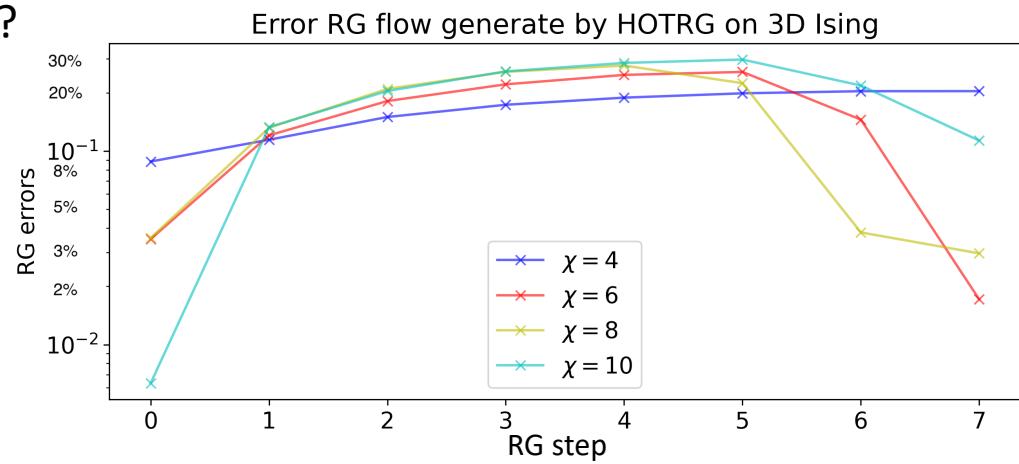
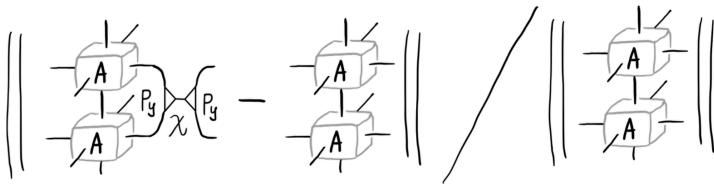
UV physics Universal physics

$$S(L) = \alpha L - F$$

Linear growth of S marks a *qualitative* difference between 3D and 2D for block-tensor RG!

Consequences on the numerical side?

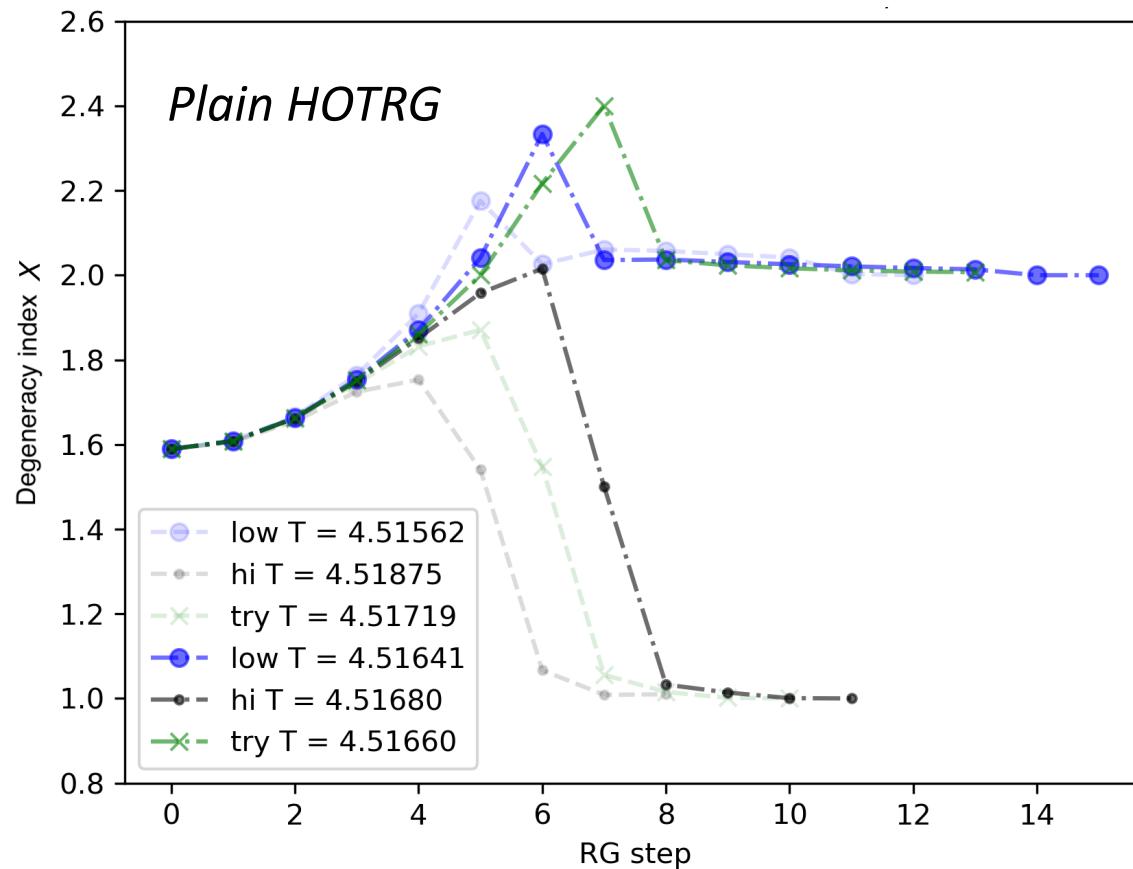
- Large RG truncation errors
- Increase states doesn't help



Block-tensor transformation in 3D

We perform a thorough analysis for bond dimensions up to 20

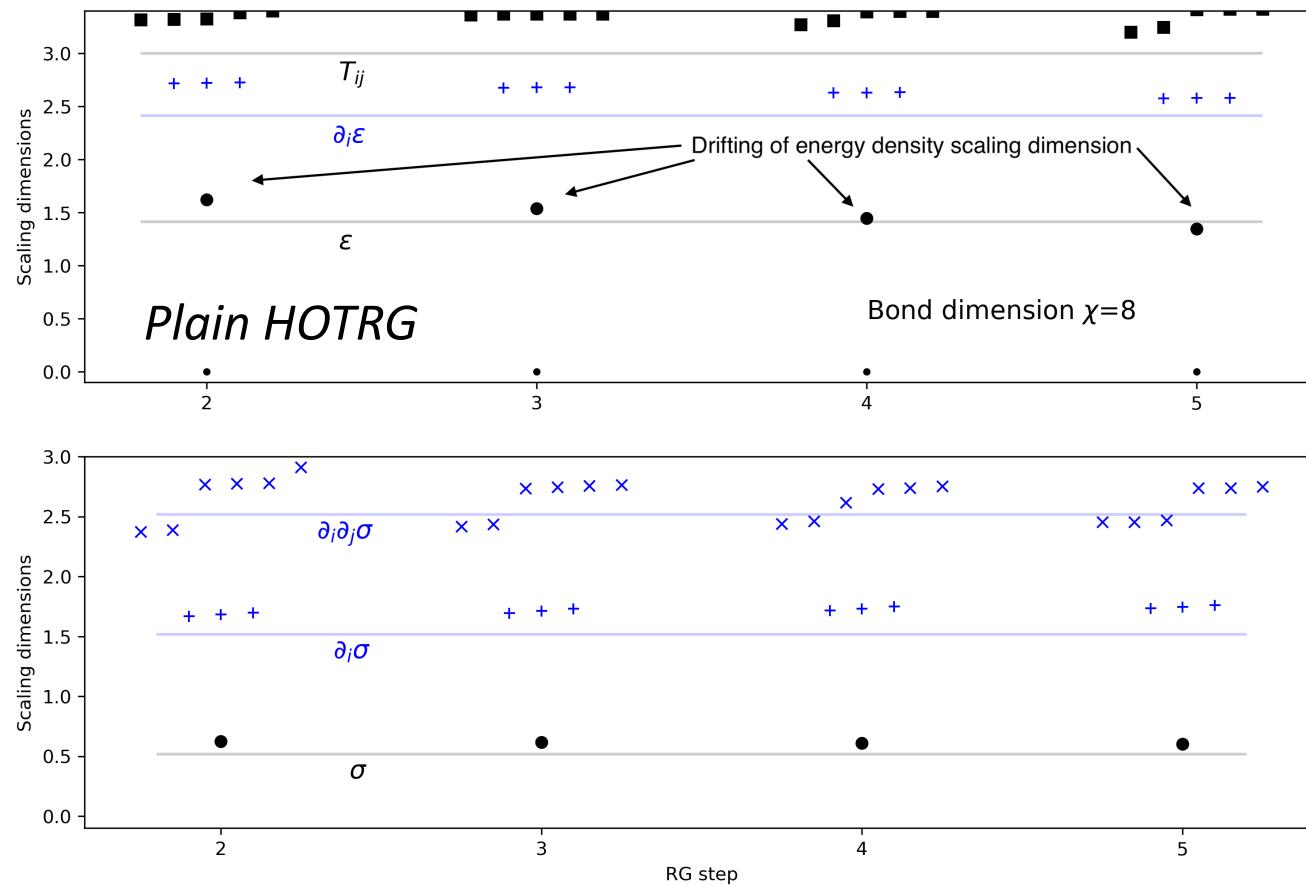
Estimates fail to convergence w.r.t RG step!



Block-tensor transformation in 3D

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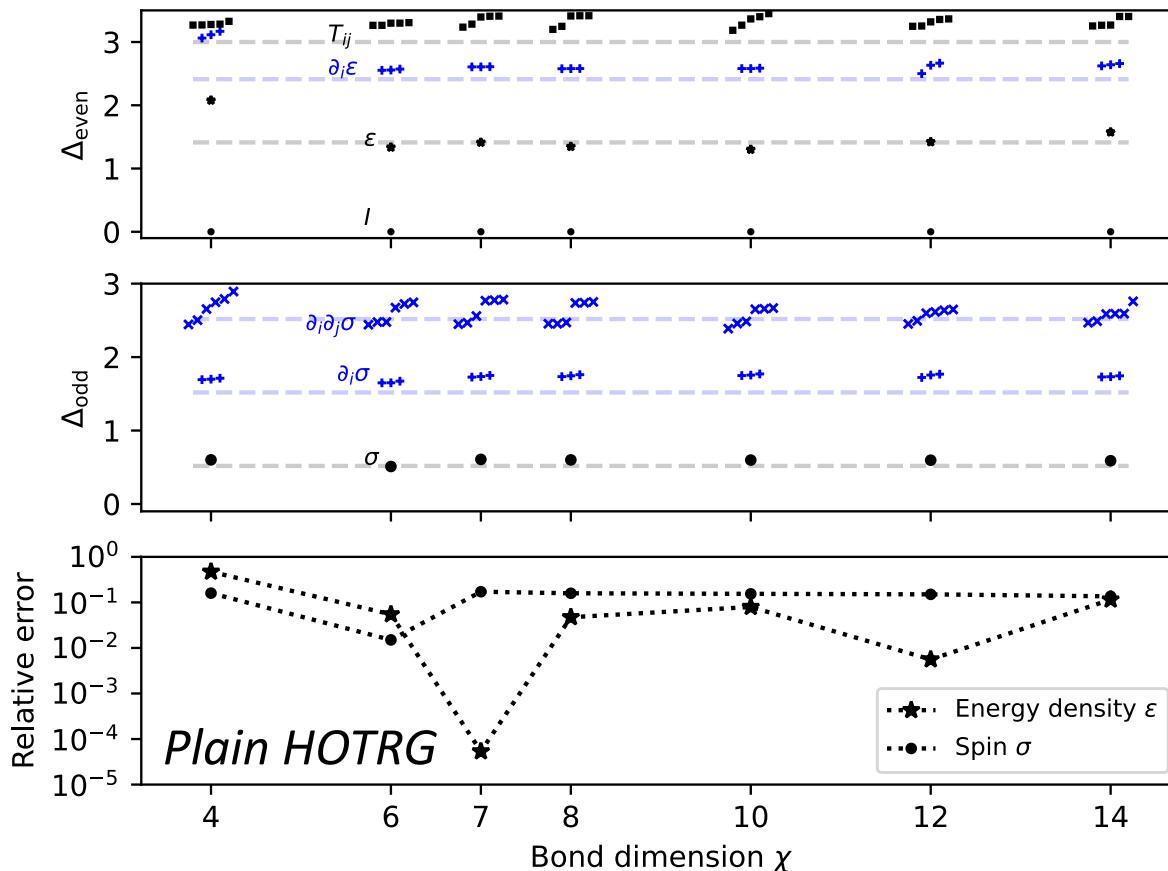
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Block-tensor transformation in 3D

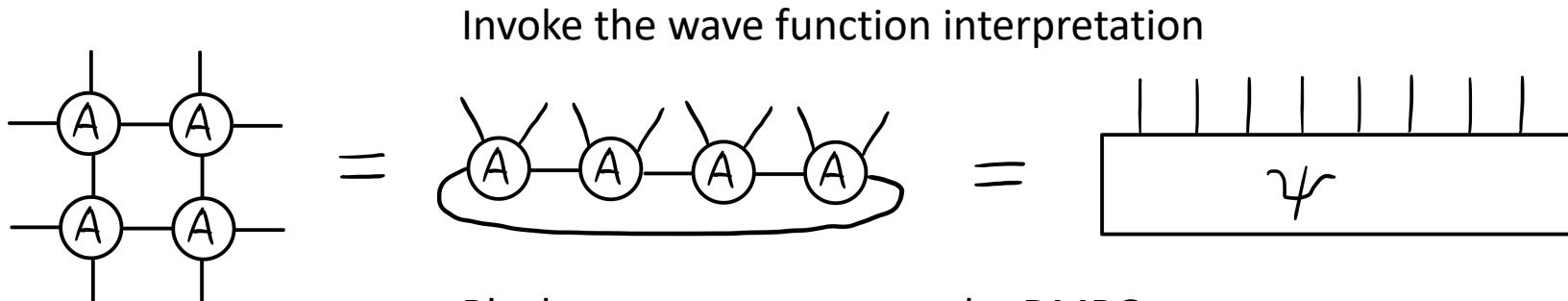
- Estimated scaling dimensions Δ versus the bond dimension χ

(Choose the estimates that are closest to the known value)

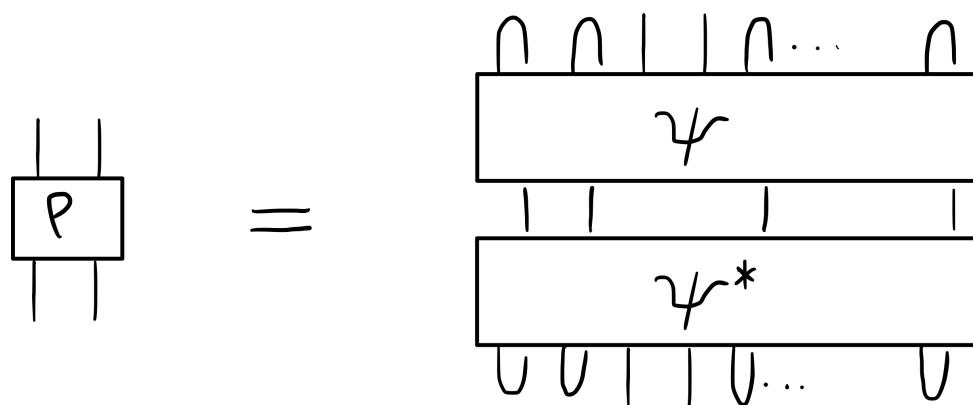
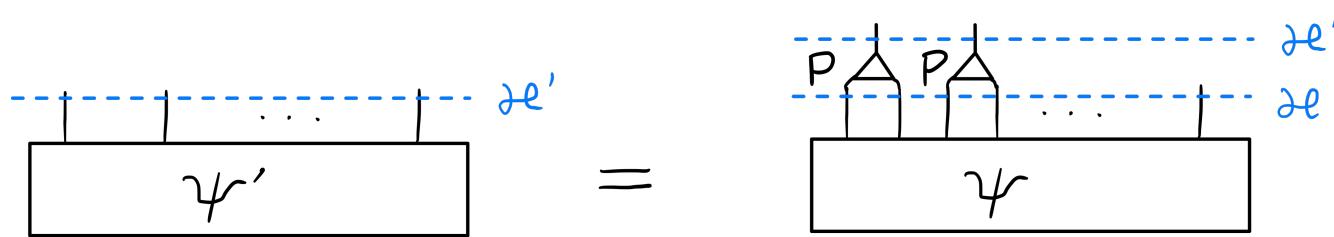


Entanglement filtering: basic idea

Area law can be circumvented in coarse-grained description if the boundary of the block is "dissolved"

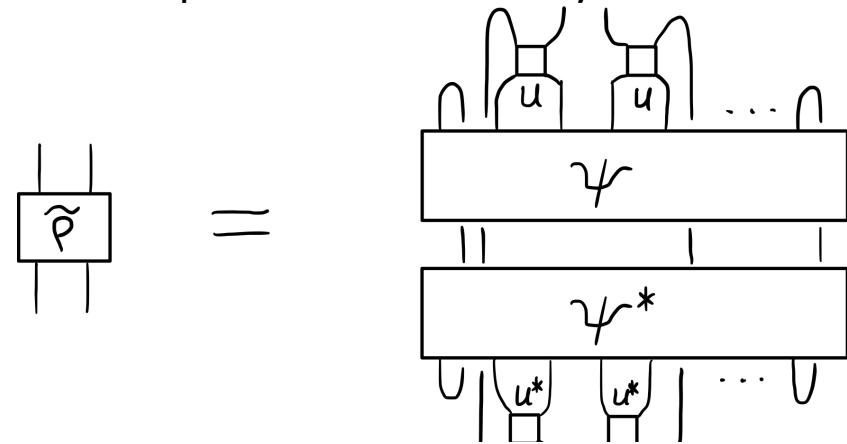
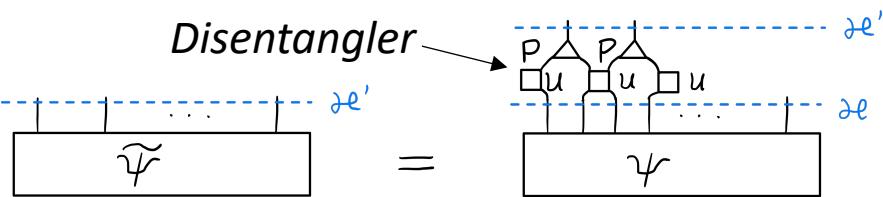


Block-tensor map seen as the DMRG

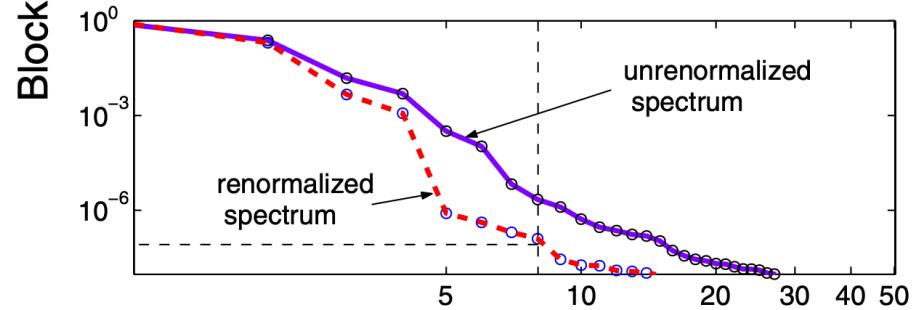
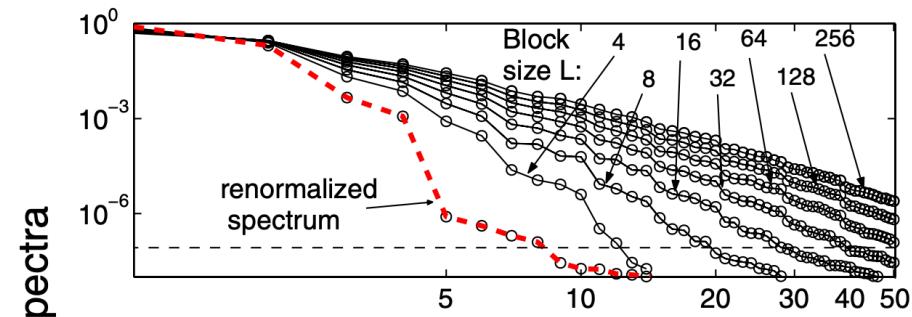
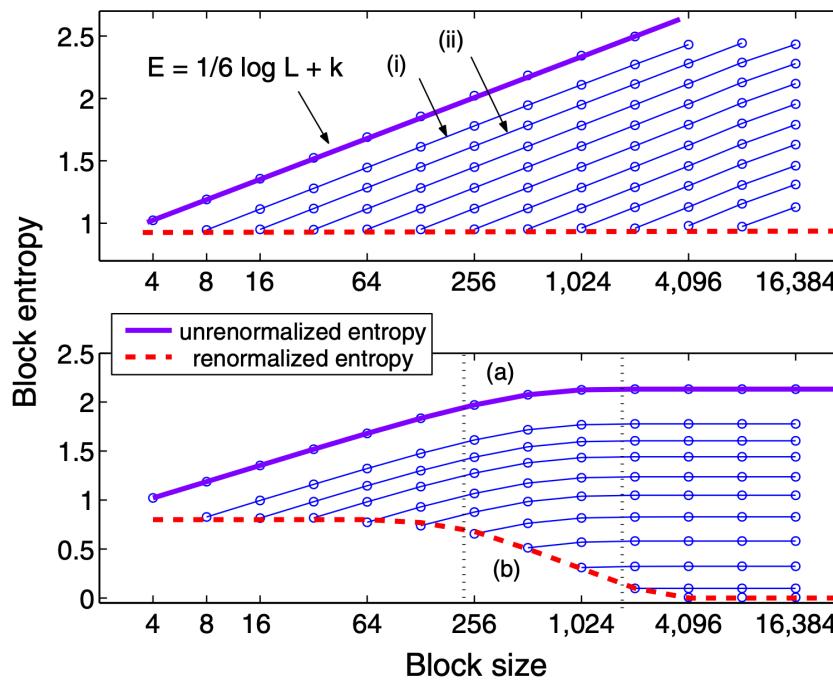


Entanglement filtering: basic idea

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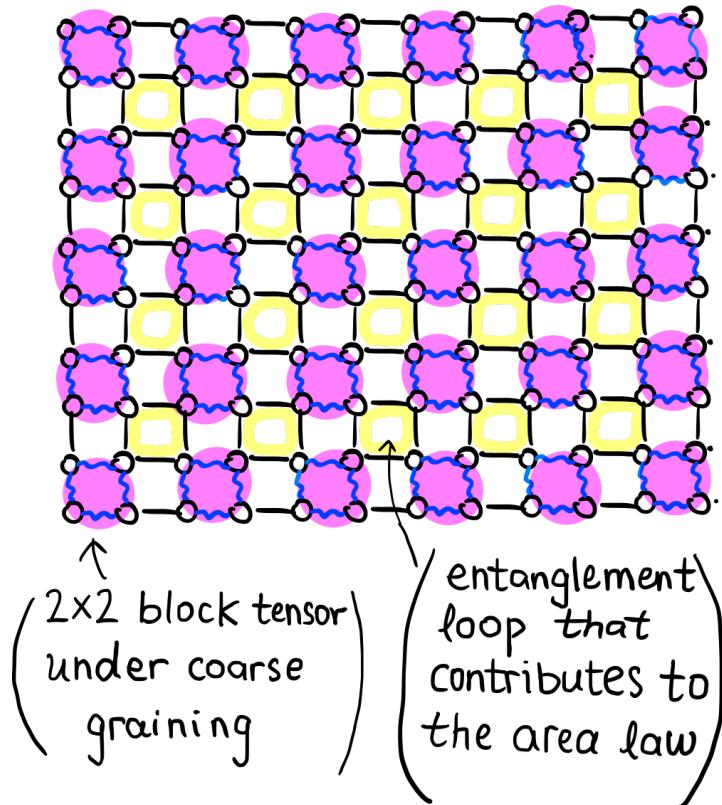


Vidal, *PRL* 99, 220405 (2007)

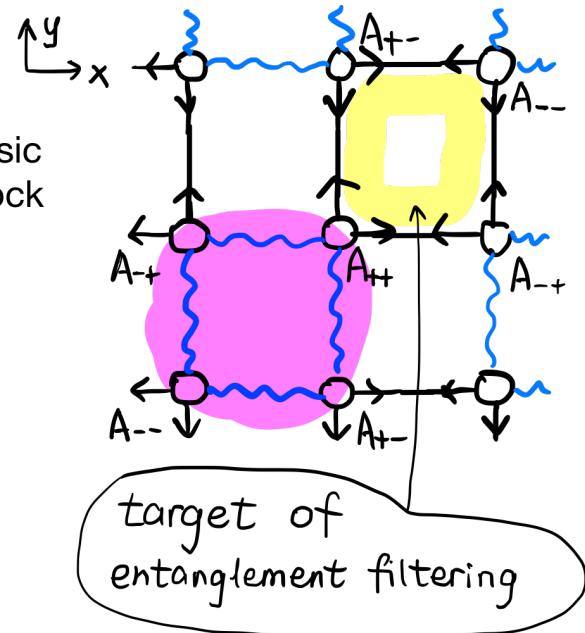


Proposed filtering scheme

Demonstrated in the 2D square lattice, here is how to *integrate Entanglement Filtering into a block-tensor transformation*:



with the basic building block patch as

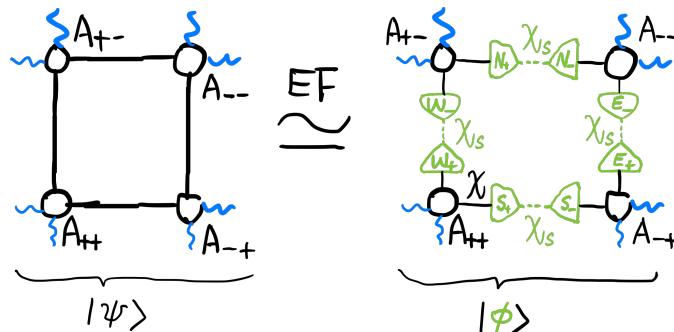


Proposed filtering scheme

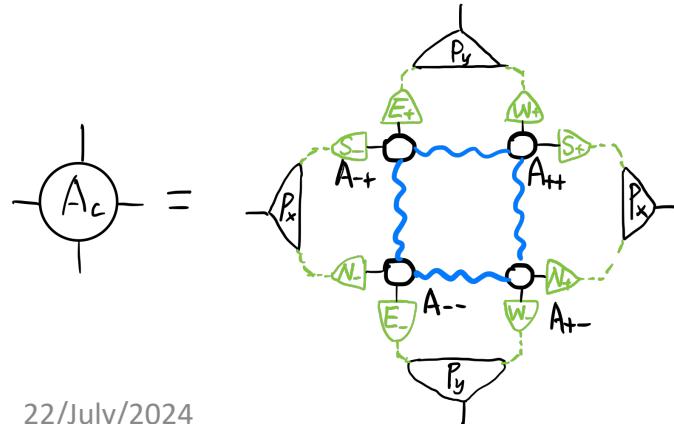
We adopt the graph-independence idea in GILT
+

Use another way to find the filtering matrix: full environment truncation

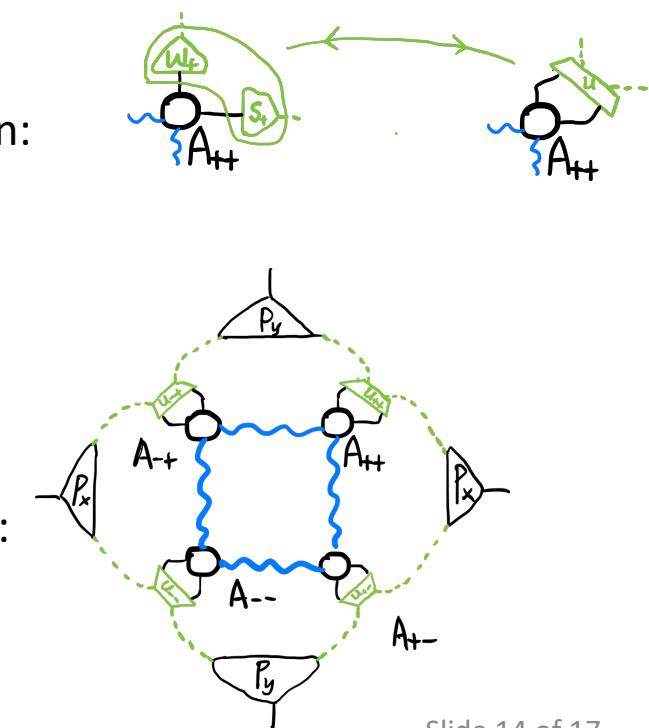
Demonstrated in the 2D square lattice, we propose:



Disentangler interpretation:



Disentangler interpretation:



Hauru, Delcamp, and Mizera,
PRB **97**, 045111 (2018)

Evenbly, *PRB* **98**,
085155 (2018)

XL and Kawashima,
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Entanglement filtering in 3D

Entanglement entropy grows in 3D:

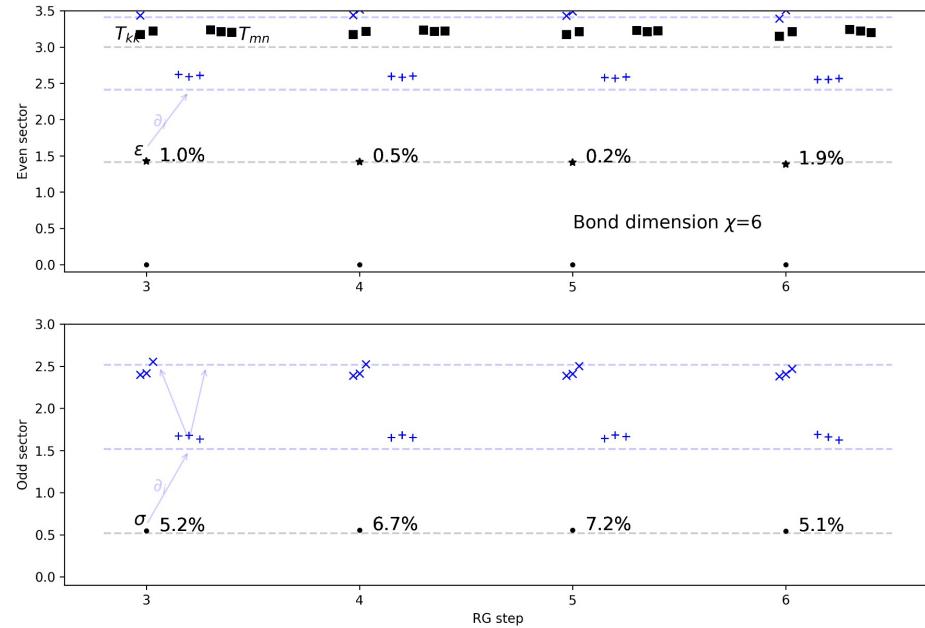
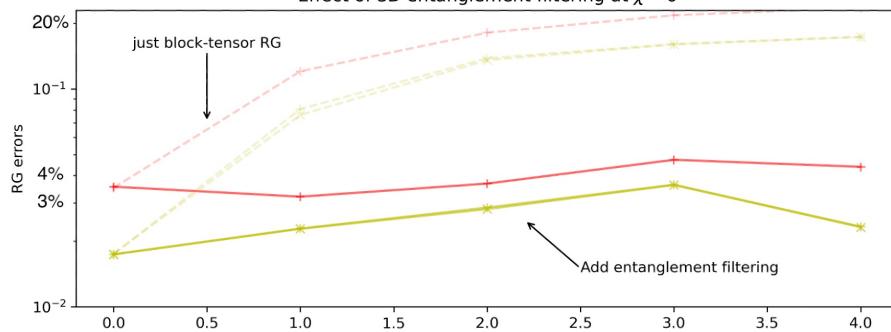
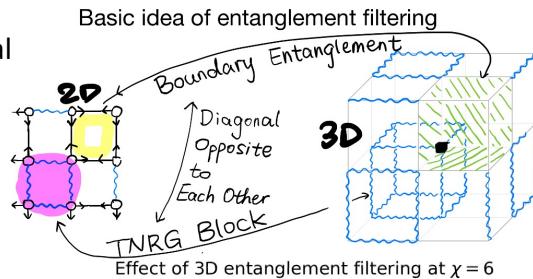
$$S = \alpha L - F$$

Fixed # of couplings:

Filtering out the boundary entanglement is essential in 3D!

2D filtering:

Evenly and Vidal
Hauru et al.

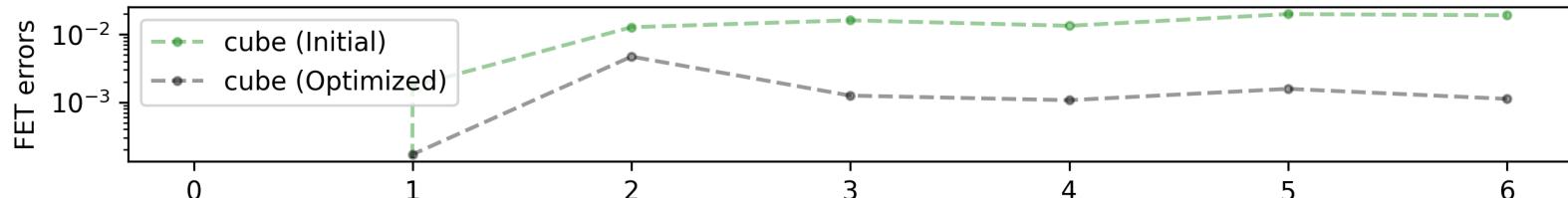
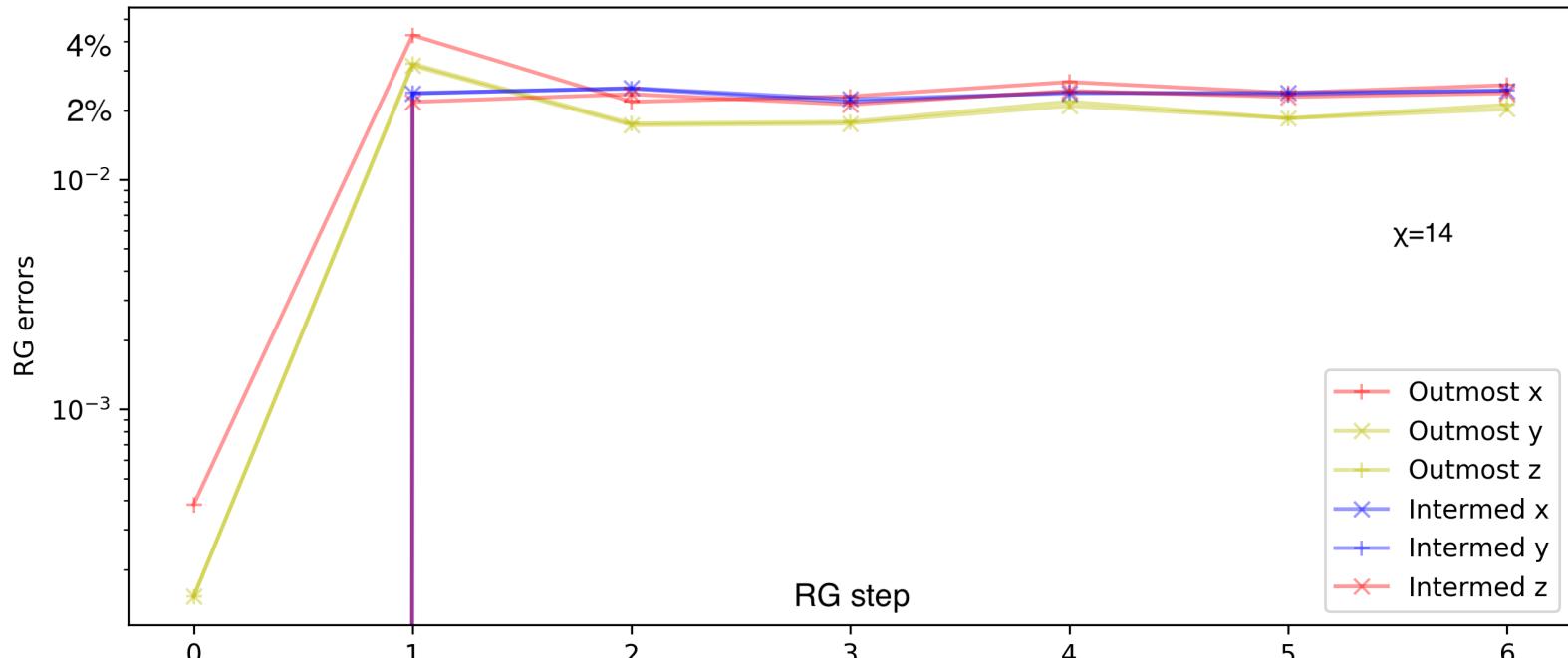


Note: the accuracy of exponents x_ϵ, x_σ ranges from 1% to 0.01% for the majority of well-developed methods

Entanglement filtering in 3D

RG truncation errors versus the bond dimension χ

χ	6	8	11	14
RG error	6%	7%	4%	2%



Entanglement filtering in 3D

Scaling dimensions versus the bond dimension χ

χ	6	8	11	14
min error	5%	4%	3%	0.4%
max error	8%	6%	6%	0.5%

Table 8.1: Estimation errors for x_σ versus bond dimension

χ	6	8	11	14
min error	0.1%	4%	1%	2%
max error	1%	5%	6%	4%

Table 8.2: Estimation errors for x_ϵ versus bond dimension

For spin field x_σ

- ✓ Mild decay of error with increasing bond dimension
- ✓ The magic bond dimension is $\chi = 14$

For energy density field x_ϵ

- ✓ Decay of error isn't clear; but there is no apparent increase either.
- ✓ The magic bond dimension is $\chi = 6$

Remark: in 2D TNR, the systematical improvement is demonstrated by increasing the bond dimension $\chi = 6 \rightarrow 16 \rightarrow 24$

Summary

XL and Kawashima, arXiv:2311.05891
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- The Kadanoff's block idea has been upgraded to become a *reliable* 3D real space RG
- In its best scenario, the error of x_σ is 0.4% and that of x_ϵ is 0.1%

$$x_\sigma, x_\epsilon$$

$$m \sim (\lambda - \lambda_c)^\beta$$

TN Methods	Proposed	HOTRG	2D MERA	iPEPS
Smallest error	0.1%, 0.4%	0.9%	1.0%	1.7%
Computational cost	$\chi^{12.5}$	χ^{11}	χ^{16}	$D^{10 \sim 14}$

- The *conformal tower structure* is unique among all well-established numerical techniques
- It is a solid step towards a systematically improvable numerical RG