# Advanced Electromagnetics

Chapter 1 – Maxwell's Equations

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#### **Outline**

- 1.1 Formulation of Maxwell's Equations
- 1.2 Constitutive Relations
- **1.3 Boundary Conditions**
- **1.4 Wave Equations**
- 1.5 Energy Flow
- 1.6 Time Harmonic Form
- 1.7 Complex Poynting Theorem

#### Faraday's law

$$\vec{\nabla} \times \vec{E} = -\partial_t \vec{B} - \vec{M} \tag{1.1.1}$$

Maxwell-Ampere's Law

$$\vec{\nabla} \times \vec{H} = \partial_t \vec{D} + \vec{J} \tag{1.1.2}$$

Continuity relation

$$\vec{\nabla} \cdot \vec{J} = -\partial_t \rho, \quad \vec{\nabla} \cdot \vec{M} = -\partial_t \varrho \tag{1.1.3}$$

\*Lorentz equation of force

$$\vec{F} = q(\vec{E} + \vec{v} \times \vec{B}) \tag{1.1.4}$$

- $\vec{E}$ : electric field intensity (V/m)
- $\vec{H}$ : magnetic field intensity (A/m)
- $\overrightarrow{D}$ : electric flux density (C/m<sup>2</sup>)
- $\vec{B}$ : magnetic flux density (T)
- $\vec{J}$ : volumetric electric current density (A/m<sup>2</sup>)
- $\rho$ : electric charge density (C/m<sup>3</sup>)
- $\overline{M}$ : volumetric magnetic current density (V/m<sup>2</sup>)
- $\varrho$ : magnetic charge density (Wb/m<sup>3</sup>)

Taking divergence of (1.1.2)

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{H}) = \partial_t \vec{\nabla} \cdot \vec{D} + \vec{\nabla} \cdot \vec{J} \equiv 0 \tag{1.1.5}$$

And from (1.1.3) we get

$$\partial_t (\vec{\nabla} \cdot \vec{D} - \rho) \equiv 0 \tag{1.1.6}$$

This implies that

$$\vec{\nabla} \cdot \vec{D} - \rho = C(x, y, z) \tag{1.1.7}$$

similarly

$$\vec{\nabla} \cdot \vec{B} - \varrho = C'(x, y, z) \tag{1.1.8}$$

In (1.1.7), if  $C \neq 0$ , it can be absorbed into  $\rho$ . The case is similar to (1.1.8). Thus, we can set C = C' = 0.

We get the Gauss's law

$$\vec{\nabla} \cdot \vec{D} = \rho \tag{1.1.10}$$

$$\vec{\nabla} \cdot \vec{B} = \varrho \tag{1.1.11}$$

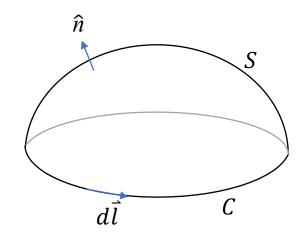
Note that (1.1.10) and (1.1.11) are not independent of (1.1.1)-(1.1.3).

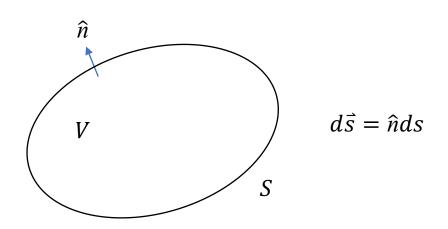
#### Stokes' theorem

$$\int_{S} \vec{\nabla} \times \vec{\Psi} \cdot d\vec{s} = \oint_{C} \vec{\Psi} \cdot d\vec{l}$$
 (1.1.12)

#### Divergence theorem

$$\int_{V} \overrightarrow{\nabla} \cdot \overrightarrow{\Psi} \, dv = \oint_{S} \overrightarrow{\Psi} \cdot d\overrightarrow{s} \tag{1.1.13}$$





Applying (1.1.12) to (1.1.1) and (1.1.2), we get

$$\oint_C \vec{E} \cdot d\vec{l} = -\int_S (\partial_t \vec{B} + \vec{M}) \cdot d\vec{s}$$
 (1.1.14)

$$\oint_C \vec{H} \cdot d\vec{l} = \int_S (\partial_t \vec{D} + \vec{J}) \cdot d\vec{s}$$
 (1.1.15)

Applying (1.1.13) to (1.1.3), (1.1.10) and (1.1.11), we get

$$\oint_{S} \vec{J} \cdot d\vec{s} = -\partial_{t} \int_{V} \rho \, dv \tag{1.1.16}$$

$$\oint_{S} \vec{D} \cdot d\vec{s} = \int_{V} \rho \, dV \tag{1.1.17}$$

$$\oint_{S} \vec{B} \cdot d\vec{s} = \int_{V} \varrho \, dv \tag{1.1.18}$$

Another theorem for the curl operator

$$\int_{V} \overrightarrow{\nabla} \times \overrightarrow{\Psi} \, dv = \oint_{S} (\widehat{n} \times \overrightarrow{\Psi}) \cdot d\overrightarrow{s} \tag{1.1.19}$$

Applying (1.1.19) to (1.1.1) and (1.1.2), we get

$$\oint_{S} \hat{n} \times \vec{E} \cdot d\vec{s} = -\int_{V} (\partial_{t} \vec{B} + \vec{M}) dv \qquad (1.1.20)$$

$$\oint_{S} \hat{n} \times \vec{H} \cdot d\vec{s} = \int_{V} (\partial_{t} \vec{D} + \vec{J}) dv \qquad (1.1.21)$$

Excluding  $\overline{M}$  and  $\varrho$  (non-physical), there are 5 vectors and 1 scalar, resulting in 16 unknowns.

From (1.1.1)-(1.1.3), there are 7 scalar equations, which means extra 9 equations are needed to make the system determinate.

The constitutive relations relates  $\vec{D}$ ,  $\vec{B}$ ,  $\vec{J}$  with  $\vec{E}$ ,  $\vec{H}$  by

$$\begin{cases}
\overrightarrow{D} = \overline{\overline{C}}_{1}(\overrightarrow{E}, \partial_{t} \overrightarrow{E}, \partial_{t}^{2} \overrightarrow{E}, ... \overrightarrow{H}, \partial_{t} \overrightarrow{H}, \partial_{t}^{2} \overrightarrow{H}, ...) \\
\overrightarrow{H} = \overline{\overline{C}}_{2}(\overrightarrow{E}, \partial_{t} \overrightarrow{E}, \partial_{t}^{2} \overrightarrow{E}, ... \overrightarrow{H}, \partial_{t} \overrightarrow{H}, \partial_{t}^{2} \overrightarrow{H}, ...) \\
\overrightarrow{J} = \overline{\overline{C}}_{3}(\overrightarrow{E}, \partial_{t} \overrightarrow{E}, \partial_{t}^{2} \overrightarrow{E}, ... \overrightarrow{H}, \partial_{t} \overrightarrow{H}, \partial_{t}^{2} \overrightarrow{H}, ...)
\end{cases} (1.2.1)$$

In general,  $\bar{\bar{C}}_j$  (j=1,2,3) are tensor functions of time.

We confine our exposition on the material properties by the following restrictions:

- Stationary:  $ar{ar{C}}_i$  are not functions of time
- Non-chiral:  $\bar{\bar{C}}_1$ ,  $\bar{\bar{C}}_3$  are related to  $\bar{E}$  and  $\bar{\bar{C}}_2$  is related to  $\bar{H}$
- Linear:  $\bar{C}_i$  are related to  $\vec{E}$  and  $\vec{H}$  only (no higher derivatives)

#### Often simplifications can be made if the medium is

- Isotropic:  $\bar{C}_j$  are scalars, i.e.,  $C_j$  (otherwise they are called anisotropic)
- Homogeneous:  $ar{ar{C}}_j$  are not functions of space
- In this note, we call a medium simple if it is linear, isotropic and homogeneous.

When a linear dielectric medium is perturbed by an electric field, the constitutive relation for  $\overrightarrow{D}$  and  $\overrightarrow{E}$  is

$$\vec{D} = \varepsilon_0 \vec{E} + \vec{\mathcal{P}} \tag{1.2.2}$$

 $\varepsilon_0$  is the electric permittivity of the vacuum (8.854×10<sup>-12</sup> F/m), and  $\vec{\mathcal{P}}$  is the electric polarization defined as

$$\vec{\mathcal{P}} = \bar{\bar{\chi}}_e \varepsilon_0 \vec{E} \tag{1.2.3}$$

 $\bar{\chi}_e$  is the electric susceptibility tensor. If the medium is isotropic, then  $\bar{\chi}_e$  becomes a scalar, and  $\vec{\mathcal{P}}$  is parallel to  $\vec{E}$ . We can define

$$\overrightarrow{D} = \overline{\varepsilon} \overrightarrow{E}$$
 (1.2.4)

$$\overline{\overline{\varepsilon}} = \varepsilon_0 (\overline{\overline{I}} + \overline{\overline{\chi}}_e) \tag{1.2.5}$$

Similarly in magnetic medium, we have

$$\vec{B} = \mu_0 \vec{H} + \vec{\mathcal{M}} \tag{1.2.6}$$

 $\mu_0$  is the magnetic permeability of the vacuum ( $4\pi \times 10^{-7}$  H/m), and  $\overrightarrow{\mathcal{M}}$  is the magnetic polarization defined as

$$\overrightarrow{\mathcal{M}} = \overline{\bar{\chi}}_m \mu_0 \overrightarrow{H} \tag{1.2.7}$$

 $ar{\chi}_m$  is the magnetic susceptibility tensor. We can define

$$\vec{B} = \overline{\overline{\mu}} \, \vec{H} \tag{1.2.8}$$

$$\overline{\overline{\mu}} = \mu_0(\overline{\overline{I}} + \overline{\overline{\chi}}_m) \tag{1.2.9}$$

The constitutive relation between  $\overrightarrow{J}$  and  $\overrightarrow{E}$  is

$$\vec{J} = \overline{\overline{\sigma}}\,\vec{E} \tag{1.2.10}$$

 $\overline{\overline{\sigma}}$  is the conductivity of the medium. The conductivity in vacuum is 0 (S/m).

For a simple medium, we can simplify the tensors  $\overline{\varepsilon}$ ,  $\overline{\mu}$  and  $\overline{\sigma}$  to  $\varepsilon$ ,  $\mu$  and  $\sigma$ , respectively. (1.1.1) and (1.1.2) can be rewritten as

$$\vec{\nabla} \times \vec{E} = -\mu \partial_t \vec{H} \tag{1.2.11}$$

$$\vec{\nabla} \times \vec{H} = (\sigma + \varepsilon \partial_t) \vec{E} \tag{1.2.12}$$

To derive boundary conditions, integral form of Maxwell's equations are needed.

Applying (1.1.20) to the pillbox

$$\hat{n} \times (\vec{E}_1 - \vec{E}_2)\Delta S + \int_{side} \hat{t} \times \vec{E} \cdot d\vec{s} = -\Delta S \int_{-h/2}^{h/2} (\partial_t \vec{B} + \vec{M}) d\zeta$$
 (1.3.1)

when  $h \to 0$ , we define the surface magnetic current density (V/m) as

$$\vec{M}_{S} = \lim_{h \to 0} \int_{-h/2}^{h/2} \vec{M} d\zeta \qquad (1.3.2)$$

we get

$$\hat{n} \times (\vec{E}_1 - \vec{E}_2) = -\vec{M}_s \tag{1.3.3}$$

Similarly, applying (1.1.21) to the pillbox, when  $h \to 0$ , we define the surface electric current density (A/m) as

$$\vec{J}_S = \lim_{h \to 0} \int_{-h/2}^{h/2} \vec{J} d\zeta \tag{1.3.4}$$

we get

$$\hat{n} \times (\vec{H}_1 - \vec{H}_2) = \vec{J}_s \tag{1.3.5}$$

Note that  $\overline{J}_S$  exists only when one of the medium's  $\sigma \to \infty$ .

Applying (1.1.17) to the pillbox

$$\hat{n} \cdot (\vec{D}_1 - \vec{D}_2) \Delta S + \int_{side} \hat{t} \cdot \vec{D} \, ds = \Delta S \int_{-h/2}^{h/2} \rho \, d\zeta \tag{1.3.6}$$

when  $h \to 0$ , we define the surface charge density (C/m<sup>2</sup>) as

$$\rho_{S} = \lim_{h \to 0} \int_{-h/2}^{h/2} \rho d\zeta \tag{1.3.7}$$

we get

$$\hat{n} \cdot (\vec{D}_1 - \vec{D}_2) = \rho_s \tag{1.3.8}$$

Similarly, from (1.1.18) we get

$$\hat{n} \cdot (\vec{B}_1 - \vec{B}_2) = \varrho_s \tag{1.3.9}$$

Lastly, applying (1.1.16) to the pillbox

$$\hat{n} \cdot (\vec{J}_1 - \vec{J}_2) \Delta S + \int_{side} \hat{t} \cdot \vec{J} \, ds = -\Delta S \int_{-h/2}^{h/2} \partial_t \rho d\zeta \qquad (1.3.10)$$

when  $h \to 0$ , we can express the side integral as

$$\oint_{C'} \lim_{h \to 0} \int_{-h/2}^{h/2} \overrightarrow{J} d\zeta \cdot \hat{t} dl = \oint_{C'} \overrightarrow{J}_S \cdot \hat{t} dl = \int_{S'} \overrightarrow{\nabla}_S \cdot \overrightarrow{J}_S dS \qquad (1.3.11)$$

we get

$$(\vec{J}_1 - \vec{J}_2) + \vec{\nabla}_S \cdot \vec{J}_S = -\partial_t \rho_S \tag{1.3.12}$$

Similarly

$$\left(\vec{M}_1 - \vec{M}_2\right) + \vec{\nabla}_S \cdot \vec{M}_S = -\partial_t \rho_S \tag{1.3.13}$$

# 1.4 Wave Equations

### 1.4 Wave Equations

Consider a lossless simple medium, taking the curl of (1.1.1)

$$\vec{\nabla} \times \vec{\nabla} \times \vec{E} = \vec{\nabla} (\vec{\nabla} \cdot \vec{E}) - \nabla^2 \vec{E} = -\partial_t (\vec{\nabla} \times \mu \vec{H}) \qquad (1.4.1)$$

$$\nabla^2 \vec{E} - \mu \varepsilon \partial_t^2 \vec{E} = \mu \partial_t \vec{J} + \vec{\nabla} (\rho/\varepsilon) + \vec{\nabla} \times \vec{M}$$
 (1.4.2)

Similarly, for the magnetic field, we have

$$\nabla^2 \vec{H} - \mu \varepsilon \partial_t^2 \vec{H} = -\vec{\nabla} \times \vec{J} + \vec{\nabla} (\varrho/\mu) + \varepsilon \partial_t \vec{M}$$
 (1.4.3)

### 1.4 Wave Equations

(1.4.2) and (1.4.3) form a set of coupled inhomogeneous DE

$$\Box \begin{pmatrix} \vec{E} \\ \vec{H} \end{pmatrix} = \begin{pmatrix} \mu \partial_t \vec{J} + \vec{\nabla} (\frac{\rho}{\varepsilon}) + \vec{\nabla} \times \vec{M} \\ -\vec{\nabla} \times \vec{J} + \vec{\nabla} (\frac{\varrho}{\mu}) + \varepsilon \partial_t \vec{M} \end{pmatrix}$$
(1.4.4)

 $\square \equiv \nabla^2 - v^{-2} \partial_t^2$  is the d'Alembert operator with  $v = (\mu \varepsilon)^{-1/2}$ .

# 1.5 Energy Flow

# 1.5 Energy Flow

Considering the identity

$$\vec{\nabla} \cdot (\vec{E} \times \vec{H}) \equiv \vec{H} \cdot \vec{\nabla} \times \vec{E} - \vec{E} \cdot \vec{\nabla} \times \vec{H}$$
 (1.5.1)

We define the instantaneous Poynting vector  $\vec{S} = \vec{E} \times \vec{H}$  (W/m²)

$$\vec{\nabla} \cdot \vec{S} = \vec{H} \cdot \left( -\partial_t \vec{B} - \vec{M} \right) - \vec{E} \cdot \left( \partial_t \vec{D} + \vec{J} \right) =$$

$$-\partial_t \left( \frac{\mu}{2} \vec{H} \cdot \vec{H} \right) - \partial_t \left( \frac{\varepsilon}{2} \vec{E} \cdot \vec{E} \right) - \vec{H} \cdot \vec{M} - \vec{E} \cdot \vec{J}$$
(1.5.2)

# 1.5 Energy Flow

The term  $\frac{\varepsilon}{2}\vec{E}\cdot\vec{E}=w_e$  and  $\frac{\mu}{2}\vec{H}\cdot\vec{H}=w_m$  denote the electric and magnetic energy density, and  $\vec{H}\cdot\vec{M}+\vec{E}\cdot\vec{J}=p_l$  denotes the power loss/supply per unit volume. We rewrite the Poynting theorem as

$$\vec{\nabla} \cdot \vec{S} = -\partial_t (w_e + w_m) - p_l \tag{1.5.3}$$

and conduct integration over a finite volume V by applying the divergence theorem:

$$\oint_{S} \hat{n} \cdot \vec{S} ds = -\partial_t \int_{V} (w_e + w_m) dv - \int_{V} p_l dv \qquad (1.5.4)$$

A time domain signal can be decomposed into a spectrum of time harmonic components

$$f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} g(\omega) e^{i\omega t} d\omega$$
 (1.6.1)

with

$$g(\omega) = \int_{-\infty}^{\infty} f(t)e^{-i\omega t}d\omega \qquad (1.6.2)$$

The Fourier and inverse Fourier transform relationship is

$$g(\omega) = \mathfrak{F}[f(t)]$$

$$f(t) = \mathfrak{F}^{-1}[g(\omega)] \tag{1.6.3}$$

Now we consider the harmonic electric field at angular frequency  $\omega$ . We consider its phasor form

$$\vec{E}(\vec{r},t) = \Re[\vec{E}(\vec{r},\omega)e^{i\omega t}]$$
 (1.6.4)

Note that we use the same notation for both the time domain field and frequency domain field, and we will suppress its dependency when there is no ambiguity.

In general, the phasor field  $\overline{E}(\vec{r},\omega)$  is a complex number.

The time harmonic Maxwell's equation takes the form

$$\vec{\nabla} \times \vec{E} = -i\omega \vec{B} - \vec{M} \tag{1.6.5}$$

$$\vec{\nabla} \times \vec{H} = i\omega \vec{D} + \vec{J} \tag{1.6.6}$$

$$\vec{\nabla} \cdot \vec{D} = \rho \tag{1.6.7}$$

$$\vec{\nabla} \cdot \vec{B} = \varrho \tag{1.6.8}$$

The method to translate the time-domain equation to frequency domain is to replace  $\partial_t$  with  $i\omega$ , and vice versa.

Analyzing (1.6.6), with  $\vec{D} = \varepsilon \vec{E}$  and  $\vec{J} = \vec{J}_c + \vec{J}_i = \sigma \vec{E} + \vec{J}_i$ , we get

$$\vec{\nabla} \times \vec{H} = i\omega \left(\varepsilon - i\frac{\sigma}{\omega}\right) \vec{E} + \vec{J}_i \tag{1.6.9}$$

We define the complex permittivity as

$$\varepsilon_c = \varepsilon - i \frac{\sigma}{\omega} \tag{1.6.10}$$

In general  $\varepsilon = \varepsilon' - i\varepsilon''$ . We define the loss tangent of the medium as

$$\tan \delta = \frac{\varepsilon''}{\varepsilon'} + \frac{\sigma}{\omega \varepsilon'} \tag{1.6.11}$$

Medium with  $\tan \delta \ll 1$  is characterized as good dielectric, and with  $\tan \delta \gg 1$  is characterized as good conductor.

The d'Alembert operator in (1.4.4) in frequency domain becomes

$$\nabla^2 - \frac{(i\omega)^2}{1/\mu \varepsilon_c} = \nabla^2 + k^2$$
 (1.6.12)

where

$$k = \omega \sqrt{\mu \varepsilon_c} = k_R + i k_I \tag{1.6.13}$$

is the wavenumber. The square root of  $\varepsilon_c$  is chosen so that  $k_I$  relates to the physical attenuation of the wave propagation.

Several literatures uses  $\gamma^2=(\alpha+i\beta)^2=-\omega^2\mu\varepsilon_c=-k^2$ . The relationship between the real and imaginary parts are  $\alpha=-k_I$  and  $\beta=k_R$ .

# 1.7 Complex Poynting Theorem

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From 
$$\vec{E}(\vec{r},t) = \Re[\vec{E}(\vec{r})e^{i\omega t}] = (\vec{E}(\vec{r})e^{i\omega t} + \vec{E}^*(\vec{r})e^{-i\omega t})/2$$
, and 
$$\vec{S}(\vec{r},t) = (\Re[\vec{E}(\vec{r}) \times \vec{H}^*(\vec{r})] + \Re[\vec{E}(\vec{r}) \times \vec{H}(\vec{r})e^{i2\omega t}])/2$$
(1.7.1)

we have

$$\vec{S}_{\text{av}} = \Re\left[\vec{E}(\vec{r}) \times \vec{H}^*(\vec{r})/2\right] \tag{1.7.2}$$

Define the vector

$$\vec{S}(\vec{r}) = \vec{E} \times \vec{H}^*/2 \tag{1.7.3}$$

as the complex Poynting vector.

# 1.7 Complex Poynting Theorem

From the identity (1.5.1)

$$\vec{\nabla} \cdot \vec{S} = \vec{\nabla} \cdot \left(\frac{\vec{E} \times \vec{H}^*}{2}\right) = -i2\omega \left(\frac{\mu |\vec{H}|^2}{4} - \frac{\varepsilon |\vec{E}|^2}{4}\right) - \frac{\vec{E} \cdot \vec{J}^*}{2} - \frac{\vec{H}^* \cdot \vec{M}}{2} = -i2\omega (w_m - w_e) - p_l$$

$$(1.7.4)$$

is the complex Poynting theorem, where  $w_m = \mu \big| \vec{H} \big|^2/4$ ,  $w_e = \varepsilon \big| \vec{E} \big|^2/4$  and  $p_l = \big( \vec{E} \cdot \vec{J}^* + \vec{H}^* \cdot \vec{M} \big)/2$  are the time average electric and magnetic energy density and the time average power loss/supply.