Do we need demographic data to forecast the state of plant populations?

- Andrew T. Tredennick^{1*}, Mevin B. Hooten^{2,3,4}, and Peter B. Adler¹
- ⁴ Department of Wildland Resources and the Ecology Center, 5230 Old Main Hill, Utah State University,
- 5 Logan, Utah 84322, USA; ²U.S. Geological Survey, Colorado Cooperative Fish and Wildlife Research
- 6 Unit, Department of Fish, Wildlife and Conservation Biology, Colorado State University, Fort Collins, CO
- ⁷ 80523-1403, USA; ³Department of Fish, Wildlife, and Conservation Biology, Colorado State University,
- ⁸ Fort Collins, CO 80523 USA; ⁴Department of Statistics, Colorado State University, Fort Collins, CO 80523
- 9 USA

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Summary

- 12 1. Rapid environmental change has generated growing interest in forecasts of future population
- trajectories. Traditional population models, typically built using detailed demographic observa-
- tions from one study site, can address the impacts of environmental change at one location, but
- are difficult to scale up to the landscape and regional scales relevant to management decisions.
- 2. An alternative is to build models using population-level data that are much easier to collect
- over broad spatial scales than individual-level data. However, it remains unclear if models built
- using aggregated individual-level data adequately capture the effects of density-dependence and
- environmental forcing that are necessary to generate skillful forecasts.
- 20 3. Here, we test the consequences of aggregating individual responses when forecasting the popu-
- lation states and trajectories of four perennial grass species in a semi-arid grassland in Montana,

^{*}Corresponding author: E-mail: atredenn@gmail.com

- USA. We parameterized two population models for each species, one based on individual-level
- ²³ data (survival, growth and recruitment) and one on population-level data (percent cover), and
- ²⁴ compared their forecasting skill and forecast horizons with and without the inclusion of climate
- 25 covariates. For both models we used Bayesian ridge regression to identify the optimal predictive
- 26 model in terms of climate covariate strengths.
- 27 **4.** Without climate effects included, we found no significant difference between the forecast-
- ing skill of models based on individual-level data and models based on population-level data.
- ²⁹ Climate effects were weak and caused only slight increases in forecasting skill. Increases in
- 30 skill were similar between model types except for one species where forecast accuracy from the
- 31 individual-level model was significantly higher than the accuracy from an equivalent population-
- 32 level model.
- 5. Synthesis. For our focal species at this particular location, and using our particular statistical
- models, demographic data was generally unnecessary to achieve skillful forecasts, though for cer-
- tain species forecast skill can be gained by using demographic data linked to climate covariates.
- We conclude that models based on aggregated individual-level data offer a practical alternative to
- 37 data-intensive demographic models when species do not respond strongly to interannual variation
- in weather, but when modeling species that do respond to climate drivers, demographically-based
- models can generate more skillful forecasts.
- 40 **Key-words:** forecasting, climate change, grassland, integral projection model, population
- 41 model, statistical regularization, ridge regression

Introduction

- Perhaps the greatest challenge for ecology in the 21st century is to forecast the impacts of envi-
- 44 ronmental change (Clark et al. 2001, Petchey et al. 2015). Forecasts require sophisticated mod-
- eling approaches that fully account for uncertainty and variability in both ecological process and
- 46 model parameters (Luo et al. 2011, but see Perretti et al. 2013 for an argument against modeling

the ecological process). The increasing statistical sophistication of population models (Rees and Ellner 2009) makes them promising tools for predicting the impacts of environmental change on species persistence and abundance. But reconciling the scales at which population models are parameterized and the scales at which environmental changes play out remains a challenge (Clark et al. 2010, 2012, Freckleton et al. 2011, Queenborough et al. 2011). The problem is that 51 most population models are built using data from a single study site because collecting those data, which involves tracking the fates of individuals plants, is so difficult. The resulting models cannot be applied to the landscape and regional scales relevant to decision-making without information 54 about how the fitted parameters respond to spatial variation in biotic and abiotic drivers (Sæther et al. 2007). The limited spatial extent of individual-level demographic datasets constrains our ability to use population models to address applied questions about the consequences of climate 57 change. Aggregate measures of population status, rather than individual performance, offer an intriguing alternative for modeling populations (Clark and Bjørnstad 2004, Freckleton et al. 2011). Population-level data cannot provide inference about demographic mechanisms, but might be sufficient for modeling future population states, especially since such data are feasible to collect across broad spatial extents (e.g., Queenborough et al. 2011). The choice between individual

and population-level data involves a difficult trade-off: while individual-level data leads to more
mechanistic models, population-level data can lead to models that can be applied over greater
spatial and temporal extents because the data are easier to collect over large spatial scales. An
open question is how much forecasting skill is lost when we build models based on population
rather than individual-level data.

To date, most empirical population modelers have relied on individual-level data, with few attempts to capitalize on population-level measures. An important exception was an effort by Taylor and Hastings (2004) to model the population growth rate of an invasive species to identify the best strategies for invasion control. They used a "density-structured" model where the state variable is a discrete density state rather than a continuous density measure. Such models do not

require individual-level demographic data and can adequately describe population dynamics. Building on Taylor and Hastings (2004), Freckleton et al. (2011) showed that density-structured models compare well to continuous models in theory, and Queenborough et al. (2011) provide empirical evidence that density-structured models are capable of reproducing population dynamics at landscape spatial scales, even if some precision is lost when compared to fully continuous models. However, previous tests of density-structured models have yet to assess their ability to forecast out-of-sample observations, and they have not included environmental covariates, which is necessary to make forecasts of population responses to climate change. 81 Addressing climate change questions with models fit to population-level data is potentially problematic. It is individuals, not populations, that respond to climate variables (Clark et al. 2012). Ignoring this fact amounts to an "ecological fallacy", where inference about the individual relies on statistical inference on the group (Piantadosi et al. 1988). Population growth (or decline) is the outcome of demographic processes such as survival, growth, and recruitment that occur at the level of individual plants. Climate can affect each demographic process in unique, potentially opossing, ways (Dalgleish et al. 2011). These unique climate responses may be difficult to resolve in statistical models based on population-level data where demographic processes are not identifiable. If important climate effects are missed because of the aggregation inherent in in population-level data, then population models built with such data will make uninformative or unreliable forecasts. Here, we compare the forecasting skill of statistical and population models based on aggregated, population-level data with models based on individual-level data. We used a demographic dataset that tracks the fates of individual plants from four species over 14 years to build two kinds of single-species population models, traditional models using individual growth, survival, and recruitment data and alternative models based on basal cover. We use the models to answer two questions: (1) Can population models fit using aggregated individual-level data (percent cover) produce forecasts as skillful as those from models fit to demographic data? And (2) Can population models fit using aggregated data adequately capture the influence of climate on population

growth and, in turn, produce forecasts as skillful as those from models fit to demographic data?

Materials and Methods

Study site and data

Our demographic data come from the Fort Keogh Livestock and Range Research Laboratory in 104 eastern Montana's northern mixed prairie near Miles City, Montana, USA (46° 19' N, 105° 48' W). The dataset is freely available on Ecological Archives¹ (Anderson et al. 2011), and interested readers should refer to the metadata for a complete description. The site is about 800 m above sea level and mean annual precipitation (1878-2009) is 334 mm, with most annual precipitation 108 falling from April through September. The community is grass-dominated, and we focused on the 109 four most abundant grass species: Bouteloua gracilis (BOGR), Hesperostipa comata (HECO), 110 Pascopyrum smithii (PASM), and Poa secunda (POSE) (Fig. 1). B. gracilis is a warm-season 111 perennial grass, whereas H. comata, P. smithii, and P. secunda are cool-season perennial grasses. 112 All species typically begin growth in the early spring, reach maximum growth and flower in early 113 to mid summer (May-June), and disperse seed in mid to late summer (July-September). 114 From 1932 to 1945 individual plants were identified and mapped annually in 44 1-m² quadrats 115 using a pantograph. The quadrats were distributed among six pastures, each assigned a grazing 116 treatment of light (1.24 ha/animal unit month), moderate (0.92 ha/aum), and heavy (0.76 ha/aum) stocking rates (two pastures per treatment). In this analysis we account for potential differences among the grazing treatments, but do not focus on grazing×climate interactions. The annual maps of the quadrats were digitized and the fates of individual plants tracked and extracted using 120 a computer program (Lauenroth and Adler 2008, Chu et al. 2014). The permanent quadrats have 121 not been relocated, but their distribution in six different pastures means the data represent a broad 122 spatial distribution for the study area. Daily climate data are available for the duration of the data 123 collection period (1932 - 1945) from the Miles City airport, Wiley Field, 9 km from the study 124

¹http://esapubs.org/archive/ecol/E092/143/

125 site.

We modeled each grass population based on two levels of data: individual and quadrat (Fig. 2). The individual data is the "raw" data. For the quadrat-level we data we simply sum individual 127 basal cover for each quadrat by species. This is equivalent to a near-perfect census of quadrat 128 percent cover because previous analysis shows that measurement error at the individual-level is 129 small (Chu and Adler 2014). Based on these two datasets we can compare population models 130 built using individual-level data and aggregated, quadrat-level data. At the individual level we 131 explicitly model three vital rates: growth (13 year-to-year transitions, 29 quadrats and 18,730 132 records across the four species), survival (13 years, 33 quadrats and 29,353 records across the 133 four species), and recruitment (13 years, 33 quadrats and 304 records across the four species). 134 At the quadrat level we model population growth as change in percent cover of quadrats with 135 non-zero cover in year t and in year t-1 (13 year-to-year transitions, 29 quadrats and 866 records 136 across the four species). For modeling population growth at the quadrat level we ignore within-137 quadrat extirpation and colonization events because they are very rare in our time series (N=16138 and N=13, respectively, across all species). Given the relatively broad spatial distribution of the quadrats we are studying, it is safe to assume that these events are in fact rare enough to be ignored for our purposes. All R code and data necessary to reproduce our analysis is archived on GitHub as release v1.0² 142 (http://github.com/atredennick/MicroMesoForecast/releases). That stable release will remain 143 static as a record of this analysis, but subsequent versions may appear if we update this work. We 144 have also deposited the v1.0 release on Dryad (link here after acceptance).

46 Stastical models of vital rates

At both levels of inference (individual and quadrat), the building blocks of our population models are vital rate regressions. For individual-level data, we fit regressions for survival, growth, and

 $^{^{2}}$ Note to reviewers: so that v1.0 will be associated with the published version of the manuscript, we have released v0.2 to be associated with this review version.

recruitment for each species. At the quadrat-level, we fit a single regression model for population growth. We describe the statistical models separately since fitting the models required different 150 approaches. For both model types, we fit vital rate models with and without climate covariates. 151 Models with climate effects contain five climate covariates that we chose a priori based on pre-152 vious model selection efforts using these data (Chu et al. in press) and expert advice (Lance 153 Vermeire, personal communication): "water year" precipitation at t-2 (lagppt); April through 154 June precipitation at t-1 and t (ppt1 and ppt2, respectively) and April through June temperature 155 at t-1 and t (TmeanSpr1 and TmeanSpr2, respectively), where t-1 to t is the transition of interest. 156 We also include interactions among same-year climate covariates (e.g., ppt1 × TmeansSpr1), 157 resulting in a total of seven climate covariates. 158 We fit all models using a hierarchical Bayesian approach. The models are fully descibed in Ap-159 pendix A, so here we focus on the main process and the model likelihood. For the likelihood models, \mathbf{y}^X is always the relevant vector of observations for vital rate X (X = S, G, R, or P) for 16 survival, growth, recruitment, or population growth). For example, y^S is a vector of 0's and 1's 162 indicating whether a genet survives from t to t+1, or not. All model parameters are speciesspecific, but we omit subscripts for species in model descriptions below to reduce visual clut-164 ter. For brevity, we only describe models with climate covariates included, but models without 165 climate covariates are exactly the same as the models described below, just without the climate 166

Vital rate models at the individual level We used logistic regression to model survival probability (s) of a genet:

effects.

167

$$\mathbf{y}^S \sim \text{Bernoulli}(\mathbf{s})$$
 (1)

$$logit[s(x, \mathbf{z}_t, w)] = \beta_{0,t} + \beta_{s,t}x + \beta_Q + \mathbf{z}_t' \boldsymbol{\beta}_c + \beta_{d,1}w + \beta_{d,2}(xw)$$
 (2)

where x is the log of genet basal area, $\beta_{0,t}$ is a year specific intercept intercept, β_Q is the random effect of quadrat group location, $\beta_{s,t}$ is the year-specific slope parameter for size, \mathbf{z} is a vector of

i climate covariates specific to year t, β_c is a vector of fixed climate effects of length i, $\beta_{d,1}$ is the effect of intraspecific crowding experienced by the focal genet (w), and $\beta_{d,2}$ is a size by crowding (xw) interaction effect.

We modeled growth as a Gaussian process describing genet size at time t+1 as a function of size at t and climate covariates:

$$\mathbf{y}^G \sim \text{Normal}(\boldsymbol{\mu}, \sigma_{x,t}^2)$$
 (3)

$$\mu(x, \mathbf{z}_t, w) = \beta_{0,t} + \beta_{s,t}x + \beta_Q + \mathbf{z}_t' \boldsymbol{\beta}_c + \beta_{d,1}w + \beta_{d,2}(xw)$$
(4)

where $\mu(x, \mathbf{z}_t, w)$ is log of predicted genet size at time t+1, and all other parameters are as described for the survival regression. We capture non-constant error variance in growth by modeling the variance around the growth regression ($\sigma_{x,t}^2$) as a nonlinear function of predicted genet size:

$$\sigma_{x,t}^2 = a \exp[b \times \mu(x, \mathbf{z}_t, w)] \tag{5}$$

where $\mu(x, \mathbf{z}_t, w)$ is log of predicted genet size predicted from the growth regression (Eq. 4), and a and b are constants.

Our data allows us to track new recruits, but we cannot assign a specific parent to new genets.

Therefore, we model recruitment at the quadrat level. We assume the number of individuals, y^R , recruiting at time t+1 in quadrat q follows a negative binomial distribution:

$$y_{q,t+1}^R \sim \text{NegBin}(\lambda_{q,t+1}, \phi)$$
 (6)

where λ is the mean intensity and ϕ is the size parameter. We define λ as a function of quadrat composition and climate in the previous year:

$$\lambda_{q,t+1} = C'_{q,t} \exp\left(\beta_{0,t} + \beta_Q + \mathbf{z}'_t \boldsymbol{\beta}_c + \beta_d \sqrt{C'_{q,t}}\right) \tag{7}$$

where C' is effective cover (cm²) of the focal species in quadrat q, and all other terms are as in the survival and growth regressions. Effective cover is a mixture of observed cover (C) in the focal quadrat (q) and the mean cover across the entire group (\bar{C}) of Q quadrats in which q is located:

$$C'_{q,t} = pC_{q,t} + (1-p)\bar{C}_{Q,t}$$
(8)

where p is a mixing fraction between 0 and 1 that is estimated within the model.

Population model at the quadrat level The statistical approach used to model aggregated data depends on the type of data collected. We have percent cover data, which can easily be transformed to proportion data. An obvious choice for fitting a linear model to proportion data is beta regression because the support of the beta distribution is [0,1], not including true zeros or ones. However, when we used fitted model parameters from a beta regression in a quadrat-based population model, the simulated population tended toward 100% cover for all species. We therefore chose a modeling approach based on a truncated log-normal likelihood. The model for quadrat cover change from time t to t+1 is

$$\mathbf{y}^P \sim \text{LogNormal}(\mu(x, \mathbf{z}_t), \sigma^2) \mathbf{T}[0, 1]$$
 (9)

$$\mu(x, \mathbf{z}_t) = \beta_{0,t} + \beta_{s,t} x + \beta_O + \mathbf{z}_t' \boldsymbol{\beta}_c \tag{10}$$

where $\mu(x, \mathbf{z}_t)$ is the log of proportional cover in quadrat q at time t+1, and all other parameters are as in the individual-level growth model (Eq. 4) except that x now represents log of proportional cover. The log normal likelihood includes a truncation (T[0,1]) to ensure that predicted values do not exceed 100% cover.

Model fitting and stastical regularization

Model fitting Our Bayesian approach to fitting the vital rate models required choosing appropriate priors for unknown parameters and deciding which, if any, of those priors should be hierarchical. We decided to fit models where all terms were fit by species. Within a species, we fit yearly size effects and yearly intercepts hierarchically where year-specific coefficients were drawn from global distributions representing the mean size effect and intercept. Quadrat random 217 effects were also fit hierarchically, with quadrat offsets being drawn from distributions with mean 218 zero and a shared variance term (independent Gaussian priors, Appendix A). Climate effects 219 were modeled as independent covariates whose prior distributions were determined by statistical 220 regularization (see **Statistical regularization: Bayesian ridge regression** below). 221 All of our analyses (model fitting and simulating) were conducted in R (R Core Team 2013). We 222 used the 'No-U-Turn' MCMC sampler in Stan (Stan Development Team 2014a) to estimate the 223 posterior distributions of model parameters using the package 'rstan' (Stan Development Team 224 2014b). We obtained posterior distributions for all model parameters from three parallel MCMC chains run for 1,000 iterations after discarding an initial 1,000 iterations. Such short MCMC chains may surprise readers more familiar with other MCMC samplers (i.e. JAGS or WinBUGS), but the Stan sampler is exceptionally efficient, which reduces the number of iterations needed to achieve convergence. We assessed convergence visually and made sure scale reduction factors 229 for all parameters were less than 1.1. For the purposes of including parameter uncertainty in our 230 population models, we saved the final 1,000 iterations from each of the three MCMC chains to 231 be used as randomly drawn values during population simulation. We report the posterior mean, 232 standard deviation, and 95% Bayesian Credible Intervals for every parameter of each model for 233 each species in Appendix B. 234

Statistical regularization: Bayesian ridge regression For models with climate covariates, our objective is to model the response of our focal grass species to interannual variation in climate, even if those responses are weak. Therefore, we avoid selecting among models with all possible combinations of climate covariates, and instead use Bayesian ridge regression to regu-

late, or constrain, the posterior distributions of each climate covariate (Hooten and Hobbs 2015). Ridge regression is a specific application of statistical regularization that seeks to optimize model 240 generality by trading off bias and variance. As the name implies, statistical regularization in-241 volves the use of a regulator that constrains an optimization. The natural regulator in a Bayesian 242 application is the prior on the coefficient of interest. Each of our statistical models includes the 243 effects of climate covariates via the term $\mathbf{z}_t'\boldsymbol{\beta}_c$ with prior $\boldsymbol{\beta}_c \sim \text{Normal}(\boldsymbol{\mu}_{\beta_c}, \sigma_{\beta_c}^2)$. Since we stan-244 dardized all climate covariates to have mean zero and variance one, we can set $\mu_{\beta_c}=0$ and let 245 $\sigma_{\beta_c}^2$ serve as the regulator that can shrink covariates toward zero – the smaller the prior variance, 246 the more the posteriors of β_c are shrunk toward zero, and the stronger the penalty (Hooten and 247 Hobbs 2015). 248 To find the optimal penalty (i.e., optimal value of the hyperparameter $\sigma_{\beta_c}^2$), we fit each statistical model with a range of values for $\sigma_{\beta_c}^2$ and compared predictive scores from leave-one-year-out 250 cross-validation. We performed the grid search over 24 values of $\sigma_{\beta_c}^2$, ranging from $\sigma_{\beta_c}^2 = 0.01$ to $\sigma_{\beta_c}^2=2.25$. For each statistical model and each species we fit $13\times 24=312$ models (13 years to leave out for cross-validation and 24 values of $\sigma_{\beta_c}^2$) – a total of 4,992 models. We calculated the log pointwise predictive density (lppd) to score each model's ability to predict the left-out data. Thus, for training data y_{train} and held-out data y_{hold} at a given value of σ_{θ}^2 across all MCMC 255 samples s = 1, 2, ..., S and all hold outs of data from year t to year T, and letting θ represent all 256 unknowns, lppd is 257

$$lppd_{CV} = \sum_{t=1}^{T} log_e \int [y_{t,hold}|\theta] [\theta|y_{train}] d\theta,$$
(11)

259 and computed as

$$\sum_{t=1}^{T} \log_e \left(\frac{1}{S} \sum_{s=1}^{S} (y_{t,hold} | \theta_{ts}) \right). \tag{12}$$

We chose the optimal prior variance for each species-statistical model combination as the one that produced the highest *lppd* and then fit each species-statistical model combination using the full data set for each species and the optimal prior variance.

Population models

With the posterior distribution of the vital rate statistical models in hand, it is straightforward to simulate the population models. We used an Integral Projection Model (IPM) to model populations based on individual-level data (Ellner and Rees 2006) and a quadrat-based version of an individually-based model (Quadrat-Based Model, QBM) to model populations based on quadrat-level data. We describe each in turn.

Integral projection model We use a stochastic IPM (Rees and Ellner 2009) that includes the climate covariates from the vital rate statistical models. In all simulations we ignore the random year effects so that interannual variation is driven solely by climate. We fit the random year effects in the vital rate regressions to avoid over-attributing variation to climate covariates. Our IPM follows the specification of Chu and Adler (2015) where the population of species j is a density function $n(u_j, t)$ giving the density of sized-u genets at time t. Genet size is on the natural log scale, so that $n(u_j, t)du$ is the number of genets whose area (on the arithmetic scale) is between e^{u_j} and e^{u_j+du} . The density function for any size v at time t+1 is

$$n(v_j, t+1) = \int_{L_j}^{U_j} k_j(v_j, u_j, \bar{w}_j(u_j)) n(u_j, t)$$
(13)

v and \bar{w}_j is a scalar representing the average intraspecific crowding experienced by a genet of 280 size u_i and species j. The integral is evaluated over all possible sizes between predefined lower 281 (L) and upper (U) size limits that extend beyond the range of observed genet sizes. 282 Since the IPM is spatially-implicit, we cannot calculate neighborhood crowding for specific 283 genets (w_{ij}) . Instead, we use an approximation (\bar{w}_i) that captures the essential features of neigh-284 borhood interactions (Adler et al. 2010). This approximation relies on a 'no-overlap' rule for 285 conspecific genets to approximate the overdispersion of large genets in space (Adler et al. 2010). 286 The population kernel is defined as the joint contributions of survival (S), growth (G), and recruit-287

where $k_j(v_j, u_j, \bar{w_j})$ is the population kernel that describes all possible transitions from size u to

ment (R):

$$k_j(v_j, u_j, \bar{w}_j) = S_j(u_j, \bar{w}_j(u_j))G_j(v_j, u_j, \bar{w}_j(u_j)) + R_j(v_j, u_j, \bar{w}_j),$$
(14)

290 289 and adding in newly recruited (R) individuals of an average sized one-year-old genet for the 29 focal species. Our stastical model for recruitment (R, described above) returns the number of 292 new recruit produced per quadrat. Following previous work (Adler et al. 2012, Chu and Adler 293 2015), we assume that fecundity increases linearly with size $(R_j(v_j,u_j,\bar{w_j})=e^{u_j}R_j(v_j,\bar{w_j}))$ to 294 incorporate the recruitment function in the spatially-implicit IPM. 295 We used random draws from the final 1,000 iterations, thinned by 10, from each of three MCMC 296 chains to carry-through parameter uncertainty into our population models. At each time step, we 297 randomly selected climate covariates from one of the 14 observed years. Then, we drew the full 298 parameter set (climate effects and density-dependence fixed effects) from a randomly selected 299 MCMC iteration. Relatively unimportant climate covariates (those that broadly overlap 0) will 300 have little effect on the mean of the simulation results, but can contribute to their variation. Since 301 our focus was on the contribution of density dependence and climate covariates to population 302 states, we set the random year effects and the random group effects to zero. 303

which means we are calculating growth (G) for individuals that survive (S) from time t to t+1

Quad-based model To simulate our quad-based model (QBM), we simply iterate the 304 quadrat-level statistical model (Eqs. 9-10). We use the same approach for drawing parameter 305 values as described for the IPM. After drawing the appropriate parameter set, we calculate the 306 mean response (log cover at $t+1 = \mu_{t+1}$) according to Eq. 10. We then make a random draw 307 from a [0,1] truncated lognormal distribution with mean equal to μ_{t+1} from Eq. 10 and the 308 variance estimate from the fitted model. We can then project the model forward by drawing a new 309 parameter set (unique to climate year and MCMC iteration) at each timestep. As with the IPM, random year effects are ignored for all simulations. 311

312 Model validation

To test each model's ability to forecast population states we made out-of-sample predictions us-313 ing leave-one-year-out cross validation. For both levels of modeling and for models with and 314 without climate covariates, we fit the vital rate models using observations from all years except 315 one, and then used those fitted parameters in the population models to perform a one-step-ahead 316 forecast for the year whose observations were withheld from model fitting. Within each observa-317 tion year, several quadrats were sampled. We made predictions for each observed quadrat in the 318 focal year, initializing each simulation with cover in the quadrat the previous year. Since we were 319 making quadrat-specific predictions, we incorporated the group random effect on the intercept for 320 both models. We repeated this procedure for all 13 observation years, making 100 one-step-ahead 32 forecasts for each quadrat-year combination with parameter uncertainty included via random 322 draw from the MCMC chain as described above. Random year effects were set to zero since year effects cannot be assigned to unobserved years. 324 This cross-validation procedure allowed us to compare accuracy and precision of the two mod-325 eling approaches (IPM versus QBM) with and without climate covariates. We first calculated 326 the median predicted cover across the 100 simulations for each quadrat-year and then calculated 327 forecast skill as the correlation (ρ) between forecasts and observations. We compared ρ between 328 model types and within model types between models with and without climate covariates using 329 a one-sided t test with adjusted degrees of freedom following Wilcox (2009) and standard er-330 rors calculated using the HC4 estimator of Cribari-Neto (2004). Statistical tests for differences 331 between ρ were conducted using R functions from Ye et al. (2015). 332

Forecast horizons

An important feature of any forecasting model is the rate at which forecast skill declines as the time between an observation and a forecast increases; the so-called ecological forecast horizon (Petchey et al. 2015). To assess the forecast horizons of our models, we iniate the model

with the population state at some time t and make sequential forecasts of the population at times $t+1, t+2, \dots, t+T$ where T is the maximum number of years between the initial year and the final year in our observations. For example, if we initialize the model with percent cover in 1940, 339 we are able to make five forecasts up to the year 1945. Models are not re-initialized with observa-340 tions between years. Thus, in our current example, the model forecast for percent cover in 1941 341 has a forecast horizon of one year, the forecast in 1942 has a forecast horizon of two years, and so 342 on. We ran these simulations for all model types (IPM with/without climate; QBM with/without 343 climate) using mean parameter values for all possible initial years. Then, for a given forecast hori-344 zon, we averaged the correlation between forecasts and observations. Note that these forecasts 345 are all made using in-sample data since we used model fits from the full data set. Nonetheless, 346 these simulations offer insight into the differences between model forecast horizons. 347

48 Results

Both the IPM and QBM generated skillful one-step-ahead forecasts for out-of-sample observations, with an average correlation between predictions and observations (ρ) of 0.# across all 350 models (Fig. 2). Without climate covariates, the accuracy of forecasts from the IPM were not sta-351 tistically greater than the accuracy of forecasts from the QBM. With climate covariates, the best 352 out-of-sample predictive model (highest lppd) for each species and vital rate typically resulted 353 from highly constrained priors on the climate effects (Fig. S1). Thus, the posterior distributions 354 of climate effects included in our models overlapped zero and generally shrunk toward zero, 355 though for some species-vital rate combinations important effects (80% credible interval does 356 not include zero) did emerge (Fig. 3). Despite the small effects, including climate covariates did 357 increase the accuracy of forecasts for all species except P. smithii (Fig. 2). However, increases 358 in accuracy due to the inclusion of climate covariates were not significant (P > 0.05) for all com-359 parisons of ρ between climate and no-climate forecasts within model types; Fig. 2). In only one 360 case were IPM forecasts significantly more accurate than the QBM (Fig. 2): forecast accuracy of 361

P. secunda percent cover from an IPM with climate covariates was greater than the accuracy from an equivalent QBM ($t_{(195)} = 1.72$, P = 0.043). The accuracy of both model's forecasts declined as the forecast horizon increased, but they did so at similar rates (Fig. 4). The only exception is for *P. secunda* where forecast accuracy appears to slightly increase with forecast horizon, after an initial decrease from a forecast horizon of one year (Fig. 4).

Discussion

Population models built using individual-level data allow inference on demographic processes, 368 but they can only forecast future population states across the (typically limited) spatial extent of 369 the observations. Population-level data are much easier to collect across broad spatial extents, 370 so models built using such data offer an appealing alternative to traditional population models 37 (Queenborough et al. 2011). However, density-structured models rely on the aggregation of individual-level data. This creates a potential problem if (1) such models inaccurately estimate density-dependence or (2) are to be used in a climate change context because it is individuals, not populations, that respond to climate (Clark et al. 2012). Can models based on population-level metrics generate forecasts that are as skillful as those generated from models based on individuallevel data? Are models based on population-level metrics as sensitive to climate as models based 377 on individual-level data? Do we need detailed demographic data to forecast the state of plant 378 populations? 379 Our comparison of a traditional, demographic population model without environmental forcing 380 (the IPM) to an equivalent model inspired by density-structured models (the QBM) showed that, 381 generally, IPM forecasts of out-of-sample plant population states were no more accurate than 382 forecasts from the QBM (Fig. 2; 'no-climate' bars). We expected the IPM to out-perform the 383 QBM since the IPM includes more mechanistic detail on the perennial plant life cycle, but this 384 was not the case. Our comparisons of forecast accuracy relied on one-step-ahead forecasts, but we also found no evidence that the rate at which forecast accuracy decays as forecast horizon

increases was different between models (Fig. 4). Thus, it appears that, without environmental forcing, the IPM and QBM generate equivalent forecasts. Such a finding confirms theoretical (Freckleton et al. 2011) and empirical work (Queenborough et al. 2011) showing that densitystructured models can be useful surrogates for demographic models when the goal is to estimate 390 or forecast population states over large spatial extents. Likewise, the equivalency of forecast 391 accuracy between the IPM and QBM held for all four species, when climate covariates are not 392 included, extending the generality of previous findings (e.g., Taylor and Hastings 2004, Queen-393 borough et al. 2011). 394 While the models did not differ in forecast accuracy when only density-dependence was allowed 395 to determine population dynamics, we expected that the inclusion of environmental forcing 396 would elucidate the differences between the models. Our expectation was the the IPM would out-397 perform the QBM when we included climate covariates because interannual variation in weather 398 can affect vital rates in unique ways (Dalgleish et al. 2011). Thus, estimates of climate effects on plant population growth may be biased or non-identifiable when the underlying statistical model 400 is fit using population-level data that integrates over the potentially unique climate responses of individual vital rates. However, IPM forecast accuracy was only significantly higher than the QBM for one species, *P. secunda* (Fig. 2, 'climate' bars). This result likely stems from the rela-403 tively weak climate effects in vital rate regressions (Fig. 3). If climate effects on vital rates are 404 weak, then models based on percent cover or density should fair well compared to models based 405 on individual-level data so long as density-dependence is adequately estimated (see Fig. 2 and 406 Freckleton et al. 2011). 407 Our naive expectation was that a single, relatively important climate effect in a vital rate re-408 gression would cause a discernable difference between IPM and QBM forecast skill because 409 individual-level responses may be less identifiable from percent cover data (Clark et al. 2012). 410 We actually found the opposite. Survival or recruitment regressions for B. gracilis, H. comata, 411 and P. smithii all included at least one relatively important climate effect, which we a posterior defined as a standardized coefficient whose 80% credible interval does not overlap zero (Fig. 3).

Yet, only the forecast skill for P. secunda differed between the IPM and QBM (Fig. 2). Our explanation is that while at least one vital regression for the other three species included a relatively strong climate effect, only *P. secunda* had a vital rate regression with several smaller climate effects all trending in the same direction (Fig. 3). Thus, it appears that the estimation of several 417 small effects, rather than a single relatively large effect, can lead to increased forecast skill. 418 The higher accuracy of the IPM with cliamte for *P. secunda* highlights the superiority of con-419 temporary model and variable selection approaches such as ridge regression and LASSO over 420 techniques that lead to excluding "non-significant" effects from final models. Especially in a 421 Bayesian forecasting framework, ridge regression allows researchers to include forcing variables 422 that we know are changing (e.g., temperature and precipitation) in final models even if the esti-423 mated effects are relatively small or even deemed unimportant due to noisy data, out of which 424 it is more difficult to estimate effects on interannual variation. Likewise, if a species is truly un-425 responsive to a given climate variable, statistical regularization techniques will shrink the mean and variance of a covariate estimate to zero (Hooten and Hobbs 2015). No amount of statistical 427 "machismo" during the model fitting stage can make up for including the appropriate candidate covariates, which we attempted to do based on our knowledge of this semi-arid plant community. However, the climate covariates we chose required aggregating daily weather data over specific time periods. It may be that we chose the wrong time periods over which to aggregate. New 431 methods using functional linear models (or splines) may offer a data-driven approach for identi-432 fying the appropriate time periods over which to aggregate to produce a tractable set of candidate 433 climate variables (Teller et al. 2016). 434 In conclusion, we found that demographic data was generally unnecessary to generate skillful 435 forecasts of plant population states. Such a finding is contrary to our expectations, but in agree-436 ment with recent theoretical (Freckleton et al. 2011) and emprical work (Queenborough et al. 437 2011). However, when we included climate covariates, we did achieve more skillful forecasts from the IPM for one species, P. secunda, that appears to respond consistently, but weakly, to several climate variables. Thus, we conclude that models based on population-level data, rather than

individual-level data, may be adequate for forecasting the state of plant populations for species
that do not respond consistently or strongly to climate. Unfortunately, our analysis, where climate
effects were relatively unimportant in vital rate regressions, did not allow us to sufficiently test
our prediction that individual-level data is neccessary to generate skillful forecasts if different
vital rates respond to climate in unique, potenially opposing, ways. Nonetheless, our results are
encouraging for the use of easy-to-collect percent cover for forecasting the state of plant populations.

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Tables

59 Figures

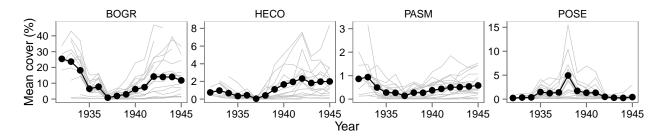


Figure 1: Time series of average percent cover over all quadrats for our four focal species: *Bouteloua gracilis* (BOGR), *Hesperostipa comata* (HECO), *Pascopyrum smithii* (PASM), and *Poa secunda* (POSE). Light grey lines show trajectories of individual quadrats. Note the different y-axis scales across panels.

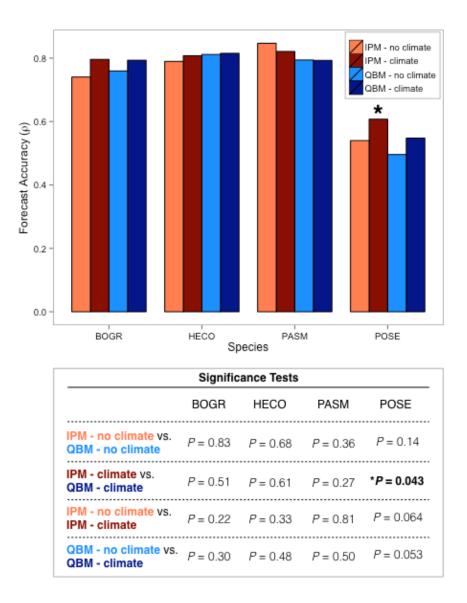
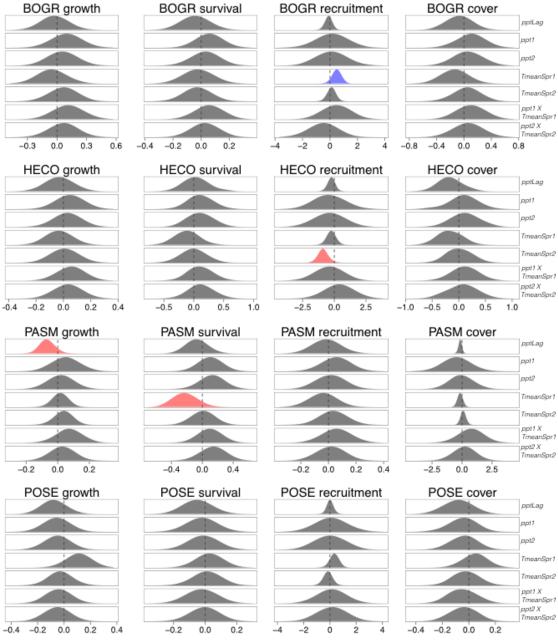


Figure 2: Comparison of one-step-ahead, out-of-sample forecast accuracy between the IPM and QBM models with and without the inclusion of climate covariates. Comparisons between equivalent IPM and QBM models indicate no significant difference in accuracy (P > 0.05 for all comparisons). Likewise, including climate covariates did not result in significantly higher forecast accuracy (P > 0.05 for all comparisons).



Standardized Coefficient Value

Figure 3: Posterior distributions of climate effects (β_C) for each species and vital rate statistical model. Since our priors were constrained via ridge-regression, we highlight climate effects whose 80% credible intervals do not overlap zero (red for negative coefficients, blue for positive coefficients). Kernel bandwidths of posterior densities were adjusted by a factor of 4 for visual clarity.

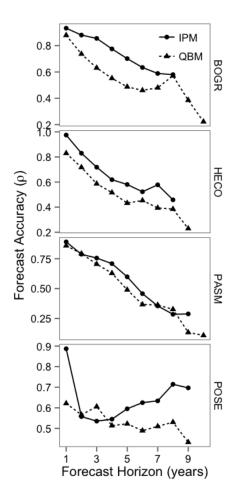


Figure 4: The forecast horizons for both models. Points show the average accuracy (ρ) across all forecasts at a given time horizon.

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