Do we need demographic data to forecast plant population dynamics?

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Summary

- 1 Rapid environmental change has generated growing interest in forecasts of future population trajectories. Traditional population models built with detailed demographic obser
 - vations from one study site can address the impacts of environmental change at particular

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locations, but are difficult to scale up to the landscape and regional scales relevant to management decisions. An alternative is to build models using population-level data which are much easier to collect than individual-level data over broad spatial scales. However, it is unknown whether models built using population-level data adequately capture the effects of density-dependence and environmental forcing that are necessary to generate skillful forecasts.

- 29 Here, we test the consequences of aggregating individual responses when forecasting the
 20 population states and trajectories of four perennial grass species in a semi-arid grassland in
 21 Montana, USA. We parameterized two population models for each species, one based on
 22 individual-level data (survival, growth and recruitment) and one on population-level data
 23 (percent cover), and compared their forecasting skill and forecast horizons with and with24 out the inclusion of climate covariates. For both models we used Bayesian ridge regression
 25 to weight the influence of climate covariates for optimal prediction.
 - 3 In the absence of climate effects, we found no significant difference between the forecasting skill of models based on individual-level data and models based on population-level data. Climate effects were weak, but increased forecasting skill for two species. Increases in skill with climate covariates were similar between model types.
- 4 In our case study, percent cover models generated forecasts as skillful as those from a
 demographic model. For the goal of forecasting, models based on aggregated individuallevel data may offer a practical alternative to data-intensive demographic models. Long
 time series of percent cover data already exist for many plant species. Modelers should
 exploit these data to predict the impacts of environmental change.
- Key-words: forecasting, climate change, grassland, integral projection model, population model, statistical regularization, ridge regression

47 Introduction

Perhaps the greatest challenge for ecology in the 21st century is to forecast the impacts of environmental change (Clark et al. 2001, Petchey et al. 2015). Forecasts require sophisticated modeling approaches that fully account for uncertainty and variability in both ecological process and model parameters (Luo et al. 2011, but see Perretti et al. 2013). The increasing statistical sophis-51 tication of population models (Rees and Ellner 2009) makes them promising tools for predicting 52 the impacts of environmental change on species persistence and abundance. But reconciling the 53 scales at which population models are parameterized with the scales at which environmental changes play out remains a challenge (Clark et al. 2010, 2012, Freckleton et al. 2011, Queenborough et al. 2011). Most population models are built using demographic data from a single study site because tracking the fates of individuals is so difficult. The resulting models cannot be applied to the landscape and regional scales relevant to decision-making without information about how the estimated parameters respond to spatial variation in biotic and abiotic drivers (Sæther et al. 2007). The limited spatial extent of individual-level demographic datasets constrains our ability to use population models to address applied questions about the consequences of climate change. Aggregate measures of population status, rather than individual performance, offer an intriguing alternative for modeling populations (Clark and Bjørnstad 2004, Freckleton et al. 2011). 64 Population-level data cannot provide inference about demographic mechanisms, but might be sufficient for modeling future population states, especially because population-level data, such as plant percent cover, are feasible to collect across broad spatial extents (e.g., Queenborough et 67 al. 2011). The choice between individual and population-level data involves a difficult trade-off: while individual-level data are necessary for mechanistic models, population-level data enable models that can be applied over greater spatial and temporal extents. An open question is how much forecasting skill is lost when we build models based on population rather than individuallevel data.

To date, most empirical population modelers have relied on individual-level data, with few attempts to capitalize on population-level measures. An important exception was an effort by Taylor and Hastings (2004) to model the population growth rate of an invasive species to identify the best strategies for invasion control. They used a "density-structured" model where the state variable is a discrete density state rather than a continuous density measure. Such models do not require individual-level demographic data and can adequately describe population dynamics. Building on Taylor and Hastings (2004), Freckleton et al. (2011) showed that density-structured models compare well to continuous models in theory, and Queenborough et al. (2011) provide 80 empirical evidence that density-structured models are capable of reproducing population dynam-81 ics at landscape spatial scales, even if some precision is lost when compared to fully continuous models. However, previous tests of density-structured models have yet to assess their ability to 83 forecast out-of-sample observations, and they have not included environmental covariates, which are necessary to forecast population responses to climate change. Addressing climate change questions with models fit to population-level data is potentially problematic. Population growth (or decline) is the outcome of demographic processes such as survival, growth, and recruitment that occur at the level of individual plants. Climate can affect each demographic process in unique, potentially opposing, ways (Dalgleish et al. 2011). These unique climate responses may be difficult to resolve in statistical models based on population-level data where demographic processes are not identifiable. Futhermore, models based on aggregated data may reflect short-term effects of one vital rate more than others whose importance may only 92 emerge over the long-term. For example, a one-year change in a plant species' cover or biomass might reflect individual growth or shrinkage, whereas the long-term trajectory of the population might be more influenced by recruitment. The same is true for density dependence: intraspecific density depedence may act most strongly on vital rates, like recruitment, that are difficult to identify from population-level data. If density dependence and/or important climate effects are missed 97 because of the aggregation inherent in in population-level data, then population models built with such data will make uninformative or unreliable forecasts.

We compared the forecasting skill of statistical and population models based on aggregated, population-level data with the skill of models based on individual-level data. We used a demo-101 graphic dataset that tracks the fates of individual plants from four species over 14 years to build 102 two kinds of single-species population models, traditional models using individual growth, sur-103 vival, and recruitment data and alternative models based on population-level (basal cover) data. 104 We simulated the models to answer two questions motivated by the fact that the effects of in-105 traspecific competition (density dependence) and interannual weather variability act at the level 106 of the individual (Clark et al. 2011). First, can population models fit using aggregated individual-107 level data (percent cover) adequately capture density dependence to produce forecasts as skillful 108 as those from models fit to demographic data? Second, can population models fit using aggre-109 gated data adequately capture the influence of climate on population growth and, in turn, produce 110 forecasts as skillful as those from models fit to demographic data? 111

Materials and Methods

113 Study site and data

Our demographic data come from a northern mixed grass prairie at the Fort Keogh Livestock 114 and Range Research Laboratory near Miles City, Montana, USA (46° 19' N, 105° 48' W). The 115 dataset is available on Ecological Archives¹ (Anderson et al. 2011), and interested readers should 116 refer to the metadata for a complete description. The site is 800 m above sea level and mean 117 annual precipitation (1878-2009) is 334 mm, with most annual precipitation falling from April 118 through September. The community is grass-dominated, and we focused on the four most abun-119 dant grass species: Bouteloua gracilis (BOGR), Hesperostipa comata (HECO), Pascopyrum 120 smithii (PASM), and Poa secunda (POSE) (Fig. 1). B. gracilis is a warm-season perennial grass, 121 whereas H. comata, P. smithii, and Poa secunda are cool-season perennial grasses. The growing season begins in early spring (typically in April) and lasts through mid-summer (typically in

¹http://esapubs.org/archive/ecol/E092/143/

124 June).

From 1932 to 1945, individual plants were identified and mapped annually in 44 1-m² quadrats 125 using a pantograph. The quadrats were distributed among six pastures, each assigned a grazing 126 treatment of light (1.24 ha/animal unit month), moderate (0.92 ha/aum), and heavy (0.76 ha/aum) 127 stocking rates (two pastures per treatment). In this analysis, we accounted for potential differ-128 ences among the grazing treatments, but do not focus on grazing×climate interactions. The an-129 nual maps of the quadrats were digitized and the fates of individual plants tracked and extracted 130 using a computer program (Lauenroth and Adler 2008, Chu et al. 2014). The permanent quadrats 131 have not been relocated, but their distribution in six different pastures means the data represent a 132 broad spatial distribution for the study area. Daily climate data are available for the duration of 133 the data collection period (1932 - 1945) from the Miles City airport, Wiley Field, 9 km from the 134 study site. 135

We modeled each grass population based on two levels of data: individual and quadrat. The 136 individual data are the "raw" data. For the quadrat-level data we simply sum individual basal 137 cover for each quadrat by species. This is equivalent to a near-perfect census of quadrat percent 138 cover because measurement error at the individual-level is small (Chu and Adler 2015). Based on 139 these two datasets of 13 year-to-year transitions, we can compare population models built using 140 individual-level data and aggregated, quadrat-level data. At the individual level, we explicitly 141 model three vital rates: growth, survival, and recruitment. At the quadrat level, we model popula-142 tion growth as change in percent cover of quadrats with non-zero cover in year t and in year t-1, 143 ignoring within-quadrat extirpation and colonization events because they are very rare in our time 144 series (N=16 and N=13, respectively, across all species). Sample sizes for each species and 145 vital rate model are shown in Table 1. 146

All R code and data necessary to reproduce our analysis is archived on GitHub as release v1.0² (http://github.com/atredennick/MicroMesoForecast/releases). We have also deposited the v1.0

²Note to reviewers: so that v1.0 will be associated with the published version of the manuscript, we have released v0.2 to be associated with this review version.

release on Dryad (link here after acceptance).

50 Statistical models of vital rates

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are vital rate regressions. For individual-level data, we fit regressions for survival, growth, and 152 recruitment for each species. At the quadrat-level, we fit a single regression model for population 153 growth. We describe the statistical models separately because they required different approaches. 154 For both model types, we fit vital rate models with and without climate covariates. Models with 155 climate effects contain five climate covariates that we chose a priori based on previous model 156 selection efforts using these data (Chu et al. 2016) and expert advice (Lance Vermeire, personal 157 communication): "water year" precipitation at t-2 (lagppt); April through June precipitation at t-1 158 and t (ppt1 and ppt2, respectively) and April through June temperature at t-1 and t (TmeanSpr1 159 and TmeanSpr2, respectively), where t-1 to t is the transition of interest. We also include interactions among same-year climate covariates (e.g., ppt1 × TmeansSpr1), resulting in a total of seven 16 climate covariates. We fit all models using a hierarchical Bayesian approach. We focus on the main process and the model likelihood in what follows (full model descriptions are in the Supporting Information). For 164 the likelihood models, \mathbf{v}^X is always the relevant vector of observations for vital rate X (X = S, G, 165 R, or P) for survival, growth, recruitment, or population growth). For example, \mathbf{y}^S is a vector of 166 Os and 1s indicating whether a genet survives from t to t+1, or not, for all observation years and 167 quadrats. All model parameters are species-specific, but we omit subscripts for species in model 168 descriptions below to reduce visual clutter. For brevity, we only describe models with climate 169 covariates included, but models without climate covariates are simply the models described below 170 with the climate effects removed. 171

At both levels of inference (individual and quadrat), the building blocks of our population models

Vital rate models at the individual level We used logistic regression to model the probability that genet i in quadrat q survives from time t to t+1 ($s_{i,q,t}$):

$$y_{i,q,t}^S \sim \text{Bernoulli}(s_{i,q,t}),$$
 (1)

$$logit(s_{i,q,t}) = \beta_{0,t} + \beta_{s,t} x_{i,q,t} + \beta_{Q,q} + \mathbf{z}_t' \boldsymbol{\beta}_c + \beta_{d,1} w_{i,t} + \beta_{d,2} (x_{i,q,t} w_{i,q,t}),$$
(2)

where $x_{i,q,t}$ is the log of genet i basal area at time t, $\beta_{0,t}$ is a year specific intercept, $\beta_{Q,q}$ is the 175 174 random effect of the qth quadrat to account for spatial location, $\beta_{s,t}$ is the year-specific slope 176 parameter for size, \mathbf{z} is a vector of p climate covariates specific to year t, $\boldsymbol{\beta}_c$ is a vector of fixed 177 climate effects of length p, $\beta_{d,1}$ is the effect of intraspecific crowding experienced by the focal 178 genet at time t ($w_{i,q,t}$), and $\beta_{d,2}$ is a size by crowding ($x_{i,q,t}w_{i,q,t}$) interaction effect. 179 We follow the approach of Chu and Adler (2015) to estimate crowding, assuming that the crowd-180 ing experienced by a focal genet depends on distance to each neighbor genet and the neighbor's 181 size, u: 182

$$w_{i,q,t} = \sum_{k} e^{-\delta d_{ik,q,t}^2} u_{k,q,t}.$$
 (3)

In equation 3, $w_{i,t}$ is the crowding that genet i in year t experiences from conspecific neighbors in quadrat q. The spatial scale over which conspecific neighbors exert influence on any genet is determined by δ . The function is applied for all k conspecific genets that neighbor the focal genet at time t, and $d_{ik,q,t}$ is the distance between genet i and conspecific genet k in quadrat q. We use regression-specific (survival and growth) δ values estimated by Chu and Adler (2015).

We modeled growth as a Gaussian process describing log genet size ($y_{i,q,t+1}^G$) at time t+1 in

quadrat q as a function of log size at time t and climate covariates:

 $y_{i,q,t+1}^G \sim \text{Normal}(\mu_{i,q,t+1}, \sigma_{x_{i,q,t+1}}^2),$ (4)

$$\mu_{i,q,t+1} = \beta_{0,t} + \beta_{s,t} x_{i,q,t} + \beta_{Q,q} + \mathbf{z}_t' \boldsymbol{\beta}_c + \beta_{d,1} w_{i,q,t} + \beta_{d,2} (x_{i,q,t} w_{i,q,t}),$$
(5)

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where $\mu_{i,q,t+1}$ is log of genet *i*s predicted size at time t+1, and all other parameters are as described for the survival regression. We capture non-constant error variance in growth by modeling the variance in the growth regression ($\sigma_{xi,q,t+1}^2$) as a nonlinear function of predicted genet size:

$$\sigma_{x_{i,q,t+1}}^2 = a \exp[b \times \mu_{i,q,t+1}], \tag{6}$$

where $\mu_{i,q,t+1}$ is log of predicted genet size predicted from the growth regression (Eq. 4), and a and b are constants.

Our data allows us to track new recruits, but we cannot assign a specific parent to new genets.

Therefore, we model recruitment at the quadrat level. We assume the number of individuals,

 $y_{q,t+1}^R$, recruiting at time t+1 in quadrat q follows a negative binomial distribution:

$$y_{q,t+1}^R \sim \text{NegBin}(\lambda_{q,t+1}, \phi),$$
 (7)

where λ is the mean intensity and ϕ is the size parameter. We define λ as a function of quadrat composition and climate in the previous year:

$$\lambda_{q,t+1} = \tilde{c}_{q,t} \exp\left(\beta_{0,t} + \beta_{Q,q} + \mathbf{z}_t' \boldsymbol{\beta}_c + \beta_d \sqrt{\tilde{c}_{q,t}}\right), \tag{8}$$

where $\tilde{c}_{q,t}$ is effective cover (cm²) of the focal species in quadrat q at time t, and all other terms are as in the survival and growth regressions. Effective cover is a mixture of observed cover (c) in the focal quadrat (q) and the mean cover across the entire group (\bar{c}) of Q quadrats in which q is located:

$$\tilde{c}_{q,t} = pc_{q,t} + (1-p)\bar{c}_{Q,t},$$
(9)

where p is a mixing fraction between 0 and 1 that is estimated when fitting the model.

Population model at the quadrat level The statistical approach used to model aggregated data depends on the type of data collected. We have percent cover data, which can easily be transformed to proportion data in our case because plant areas were scaled by plot area. An obvious choice for fitting a linear model to proportion data is beta regression because the support of the beta distribution is (0,1), which does not include true zeros or ones. However, when we used fitted model parameters from a beta regression in a quadrat-based population model, the simulated population tended toward 100% cover for all species. We therefore chose a modeling approach based on a truncated log-normal likelihood. The model for quadrat cover change from time t to

$$y_{q,t+1}^P \sim \text{LogNormal}(\mu_{q,t+1}, \sigma^2)_0^1, \tag{10}$$

$$\mu_{q,t+1} = \beta_{0,t} + \beta_{s,t} x_{q,t} + \beta_{Q,q} + \mathbf{z}_t' \boldsymbol{\beta}_c, \tag{11}$$

where $\mu_{q,t+1}$ is the log of proportional cover in quadrat q at time t+1, and all other parameters are as in the individual-level growth model (Eq. 4) except that x now represents log of proportional cover. The log normal likelihood includes a truncation (subscript 0, superscript 1) to ensure that predicted values do not exceed 100% cover.

Model fitting and statistical regularization

Model fitting Our Bayesian approach to fitting the vital rate models required choosing appropriate priors for unknown parameters and deciding which, if any, of those priors should be hierarchical. For each species, we fit yearly size effects and yearly intercepts hierarchically, where
year-specific coefficients were drawn from global distributions representing the mean size effect
and intercept. Quadrat random effects were also fit hierarchically, with quadrat offsets being
drawn from distributions with mean zero and a shared variance term (independent Gaussian priors). Climate effects were modeled as independent covariates whose prior distributions were
optimized for prediction using statistical regularization (see Statistical regularization: Bayesian

ridge regression below).

All of our analyses (model fitting and simulating) were conducted in R (R Core Team 2013). 235 We used the 'No-U-Turn' Hamiltonian Monte Carlo sampler in Stan (Stan Development Team 236 2014a) to estimate the posterior distributions of model parameters using the package rstan 237 (Stan Development Team 2014b). We obtained posterior distributions for all model parameters 238 from three parallel MCMC chains run for 1,000 iterations after discarding an initial 1,000 iter-230 ations. Such short MCMC chains are possible because the Stan sampler reduces the number of 240 iterations needed to achieve convergence. We assessed convergence visually and checked that 241 scale reduction factors for all parameters were less than 1.1. There were six instances where the 242 scale reduction factor for a particular parameter was greater than 1.1. In those cases, we checked 243 the traceplots of the violating parameter and discovered that one chain, out of three, was poorly 244 behaved. Therefore, we removed that chain from the analysis, leaving two well-mixed and con-245 verged chains for those six parameters. For the purposes of including parameter uncertainty in our population models, we retained the final 1,000 iterations from each of the three MCMC chains to be used as randomly drawn values during population simulation. We report the posterior mean, standard deviation, and 95% Bayesian Credible Intervals for every parameter of each model for each species in the Supporting Information (Tables S5-S20).

Statistical regularization: Bayesian ridge regression For models with climate covariates, our objective is to model the response of our focal grass species to interannual variation in 252 climate, even if those responses are weak. Therefore, we avoid selecting among models with all 253 possible combinations of climate covariates, and instead use Bayesian ridge regression to regu-254 late, or constrain, the posterior distributions of each climate covariate (Gerber et al. 2015, Hooten 255 and Hobbs 2015). Ridge regression is a specific application of statistical regularization that seeks 256 to optimize model generality by trading off bias and variance. As the name implies, statistical reg-257 ularization involves the use of a regulator that constrains an optimization. The natural regulator in 258 a Bayesian application is the prior on the coefficient of interest. Each of our statistical models includes the effects of climate covariates via the term $\mathbf{z}_t'\boldsymbol{\beta}_c$ with prior $\boldsymbol{\beta}_c \sim \text{Normal}(\boldsymbol{\mu}_{\beta_c}, \sigma_{\beta_c}^2 \mathbf{I})$. Because we standardized all climate covariates to have mean zero and variance one, we set $\boldsymbol{\mu}_{\beta_c} = 0$ and let $\sigma_{\beta_c}^2$ serve as the regulator that shrinks covariates toward zero – the smaller the prior variance, the more the posteriors of $\boldsymbol{\beta}_c$ are shrunk toward zero, and the stronger the penalty (Hooten and Hobbs 2015).

To find the optimal penalty (i.e., optimal value of the hyperparameter $\sigma_{\beta_c}^2$), we fit each statistical 265 model with a range of values for $\sigma_{\beta_c}^2$ and compared predictive scores from leave-one-year-out 266 cross-validation. We performed the grid search over 24 values of $\sigma_{\beta_c}^2$, ranging from $\sigma_{\beta_c}^2=0.01$ 267 to $\sigma_{\beta_c}^2=2.25$. For each statistical model and each species, we fit $13\times 24=312$ iterations of 268 the model fitting algorithm to search $\sigma_{\beta_c}^2$ for the optimal value (13 years to leave out for cross-269 validation and 24 values of $\sigma_{\beta_c}^2$) – a total of 4,992 model fits. We calculated the log pointwise 270 predictive density (lppd) to score each model's ability to predict the left-out data (Gelman et al. 2014). Thus, for training data y_{train} and held-out data y_{hold} at a given value of σ_{θ}^2 across all MCMC samples s = 1, 2, ..., S and all hold outs of data from year t to year T, and letting θ represent all unknowns, lppd is

$$lppd_{CV} = \sum_{t=1}^{T} log_e \int [y_{t,hold}|\theta] [\theta|y_{train}] d\theta,$$
(12)

and computed as

$$\sum_{t=1}^{T} \log_e \left(\frac{1}{S} \sum_{s=1}^{S} (y_{t,\text{hold}} | \theta_{ts}) \right). \tag{13}$$

We chose the optimal prior variance for each species-statistical model combination as the one that produced the highest *lppd* and then fit each species-statistical model combination using the full data set for each species and the optimal prior variance. We calculated the *lppd* from posterior samples using the algorithm from Vehtari et al. (2016).

Population models

Using samples from the posterior distribution of the vital rate statistical models, it is straightforward to simulate the population models. We used an Integral Projection Model (IPM) to simulate populations based on individual-level data (Ellner and Rees 2006) and a quadrat-based version of an individually-based model (Quadrat-Based Model, QBM) to simulate populations based on quadrat-level data. We describe each in turn.

Integral projection model We use a stochastic IPM (Rees and Ellner 2009) to simulate our focal populations based on the vital rate regressions described above. In all simulations, we ignore the random year effects so that interannual variation is driven solely by climate. We fit the random year effects in the vital rate regressions to avoid over-attributing variation to climate covariates. Our IPM follows the specification of Chu and Adler (2015) where the population of species j is $n(u_j, t)$, giving the density of sized-u genets at time t. Genet size is on the natural log scale, so that $n(u_j, t)du$ is the number of genets whose area (on the arithmetic scale) is between e^{u_j} and e^{u_j+du} . The function for any size v at time t+1 is

$$n(v_j, t+1) = \int_{L_j}^{U_j} k_j(v_j, u_j, \bar{w}_j(u_j)) n(u_j, t) du_j,$$
(14)

where $k_j(v_j, u_j, \bar{w_j})$ is the population kernel that describes all possible transitions from size u to v and \bar{w}_i is a scalar representing the average intraspecific crowding experienced by a genet of 298 size u_i and species j. The integral is evaluated over all possible sizes between predefined lower 299 (L) and upper (U) size limits that extend beyond the range of observed genet sizes. 300 The IPM is spatially-implicit, thus, we cannot calculate neighborhood crowding for specific 30 genets (w_{ij}) . Instead, we use an approximation (\bar{w}_i) that captures the essential features of neigh-302 borhood interactions (Adler et al. 2010). This approximation relies on a 'no-overlap' rule for conspecific genets to approximate the overdispersion of large genets in space (Adler et al. 2010). 304 The population kernel is defined as the joint contributions of survival (S), growth (G), and recruit-305

ment (R):

$$k_j(v_j, u_j, \bar{w}_j) = S_j(u_j, \bar{w}_j(u_j))G_j(v_j, u_j, \bar{w}_j(u_j)) + R_j(v_j, u_j, \bar{w}_j),$$
(15)

which means we are calculating growth (G) for individuals that survive (S) from time t to t+1308 307 and adding in newly recruited (R) individuals of an average sized one-year-old genet for the focal 309 species. Note the S, G, and R are incorporated in the IPM using the fitted vital rate regressions. 310 Our statistical model for recruitment (R, described above) returns the number of new recruits 311 produced per quadrat. Following previous work (Adler et al. 2012, Chu and Adler 2015), we 312 assume that fecundity increases linearly with size $(R_j(v_j, u_j, \bar{w}_j) = e^{u_j} R_j(v_j, \bar{w}_j))$ to incorporate 313 the recruitment function in the spatially-implicit IPM. 314 We used random draws from the final 1,000 iterations from each of three MCMC chains for 315 each vital rate regression to carry-through parameter uncertainty into our population models. At 316 each time step, we drew the full parameter set (climate effects and density-dependence fixed 317 effects) from a randomly selected MCMC iteration. Relatively unimportant climate covariates 318 (those that broadly overlap 0) will have little effect on the mean of the simulation results, but can 319 contribute to their variation. To retain temporal variation associated with random year effects, we 320 used posterior estimates of the mean temporal effect and the standard deviation of that effect to 321 generate a random year effect for unobserved years. That is, for some future year T, the intercept 322 is $\beta_{0,T} \sim \text{Normal}(\beta_0, \sigma_{\beta_0})$ and the effect of size is $\beta_{s,T} \sim \text{Normal}(\beta_s, \sigma_{\beta_s})$. 323

Quad-based model To simulate our quad-based model (QBM), we iterate the quadrat-level statistical model (Eqs. 9-10). We use the same approach for drawing parameter values as described for the IPM. After drawing the appropriate parameter set, we calculate the mean response (log cover at t+1 is μ_{t+1}) according to Eq. 10. We make a random draw from a [0,1] truncated lognormal distribution with mean equal to μ_{t+1} from Eq. 10 and the variance estimate from the fitted model. We project the model forward by drawing a new parameter set (unique to climate year and MCMC iteration) at each timestep. Random year effects are included as described above

for the IPM.

332 Model validation

To test each model's ability to forecast population states, we made out-of-sample predictions 333 using leave-one-year-out cross validation. For both levels of modeling and for models with and 334 without climate covariates, we fit the vital rate models using observations from all years except 335 one, and then used those fitted parameters in the population models to perform a one-step-ahead 336 forecast for the year whose observations were withheld from model fitting. Within each obser-337 vation year, several quadrats were sampled. We made predictions for each observed quadrat in 338 each focal year, initializing each simulation with cover in the quadrat the previous year. Because 339 we were making quadrat-specific predictions, we incorporated the group random effect on the 340 intercept for both models. We repeated this procedure for all 13 observation years, making 100 one-step-ahead forecasts for each quadrat-year combination with parameter uncertainty included 342 via random draw from the MCMC chain as described above. As described above, year-specific parameters for left-out data were drawn from the posterior distribution of the mean intercept. This cross-validation procedure allowed us to compare accuracy and precision of the two modeling approaches (IPM versus QBM) with and without climate covariates. We first calculated 346 the median predicted cover across the 100 simulations for each quadrat-year and then calculated 347 forecast skill as the correlation (ρ) between forecasts and observations. We calculated forecast 348 error as mean absolute error (MAE) between forecasts and observations. We compared ρ and 349 MAE between model types and within model types between models with and without climate 350 covariates using one-sided t tests with adjusted degrees of freedom following Wilcox (2009) and 351 standard errors calculated using the HC4 estimator of Cribari-Neto (2004). Statistical tests were 352 conducted using algorithms from Ye et al. (2015).

Forecast horizons

An important feature of any forecasting model is the rate at which forecast skill declines as the 355 time between an observation and a forecast increases; the so-called ecological forecast horizon 356 (Petchey et al. 2015). To assess the forecast horizons of our models, we initiate the forecast 357 model with the population state at some time t and make sequential forecasts of the population 358 at times $t+1, t+2, \ldots, t+T$ where T is the maximum number of years between the initial 359 year and the final year of our observations. For example, if we initialize the forecast model with 360 percent cover in 1940, we are able to make five forecasts up to the year 1945. Forecast models 361 are not re-initialized with observations between years. Thus, in our current example, the model 362 forecast for percent cover in 1941 has a forecast horizon of one year, the forecast in 1942 has a 363 forecast horizon of two years, and so on. We performed these simulations for all model types 364 (IPM with/without climate; QBM with/without climate) using mean parameter values for all possible initial years. For a given forecast horizon, we averaged the correlation between forecasts 366 and observations. Note that these forecasts are all made using in-sample data because we used model fits from the full data set. Nonetheless, these simulations offer insight into the differences 368 among model forecast horizons. 369

70 Results

The IPM and QBM generated one-step-ahead forecasts of similar skill for out-of-sample observations, with an average correlation between predictions and observations (ρ) of 0.72 across all models and species (Fig. 2). Without climate covariates, the accuracy of forecasts from the IPM were not statistically greater than the accuracy of forecasts from the QBM (Fig. 2) and overall error was similar (mean absolute error; Fig. S1, Supporting Information). With climate covariates, the best out-of-sample predictive model (highest lppd) for each species and vital rate typically resulted from highly constrained priors on the climate effects (Fig. S2, Supporting Information). Thus, the posterior distributions of climate effects included in our models overlapped zero and

generally shrunk toward zero, though for some species-vital rate combinations, important effects (80% credible interval does not include zero) did emerge (Fig. 3). 380 Despite the weak climate effects, including climate covariates did increase the accuracy of fore-381 casts for two species: B. gracilis and Poa secunda (Fig. 2). However, only for B. gracilis were 382 the skill increases statistically significant at $\alpha = 0.05$ for the IPM $(t_{(279)} = 1.70, P = 0.045)$ and 383 the QBM ($t_{(279)} = 1.80$, P = 0.037). Similarly, forecast error decreased significantly with the in-384 clusion of climate covariates for the B. gracilis IPM ($t_{(280)} = -3.72$, P = 0.029) and QBM ($t_{(280)}$ 385 = -3.34, P < 0.0001), and for the $Poa\ secunda\ IPM\ (t_{(196)}$ = -1.90, P < 0.0001) and QBM ($t_{(196)}$ = 386 -2.47, P = 0.007) (Fig. S2, Supporting Information). In no case did including climate covariates 387 significantly decrease forecast skill (Table S21), despite small changes in the mean skill (Fig. 2). 388 IPM forecasts were significantly more accurate than the QBM in only one case (Fig. 2): forecast 389 accuracy of P. smithii percent cover from an IPM with climate covariates was greater than the 390 accuracy from the QBM with climate covariates ($t_{(215)} = 1.92$, P = 0.028). However, adding 391 climate covariates decreased the skill of both models, and the difference between the IPM and 392 QBM emerges only because skill decreased less for the IPM than the QBM. Results from all 393 pairwise statistical tests are shown in Table S22 of the Supporting Information. 394 With climate covariates included, the accuracy of both models' forecasts declined as the forecast 395 horizon increased, but they did so at similar rates (Fig. 4). The only exception is for *Poa secunda*, 396 where QBM forecast accuracy remained steady as the forecast horizon increases, whereas IPM 397 forecast accuracy declined (Fig. 4). 398

Discussion

Population models built using individual-level data provide inference on demographic processes, but they can only forecast future population states across the (typically limited) spatial extent of the observations. Population-level data are much easier to collect across broad spatial extents, so models built using such data offer an appealing alternative to traditional population models (Queenborough et al. 2011). However, density-structured models rely on the aggregation of individual-level data. Given that individuals, not populations, respond to intraspecific competition and weather (Clark et al. 2011), can models based on population-level metrics generate forecasts that are as skillful as those generated from models based on individual-level data? Are models based on population-level metrics as sensitive to climate forcing as models based on individual-level data?

Our comparison of a traditional, demographic population model without environmental forcing (the IPM) to an equivalent model inspired by density-structured models (the QBM) showed
that, generally, IPM forecasts of out-of-sample plant population states were no more accurate
than forecasts from the QBM (Fig. 2; 'no-climate' bars). This result overturned our expectation
that the IPM would out-perform the QBM, thanks to its mechanistic representation of the perennial life cycle, and confirms theoretical (Freckleton et al. 2011) and empirical work (Taylor and
Hastings 2004, Queenborough et al. 2011) showing that density-structured models can be useful
surrogates for demographic models when the goal is to estimate or forecast population states over
large spatial extents.

We also expected the inclusion of environmental forcing to reveal more differences between 419 the models. Interannual variation in weather can affect vital rates in different ways (Dalgleish 420 et al. 2011), so, estimates of climate effects on plant population growth may be biased or non-421 identifiable when the underlying statistical model is fit using population-level data that integrates 422 over the potentially unique climate responses of individual vital rates. We found some evidence 423 that the QBM failed to detect climate effects for three species (B. gracilis, H. comata, and Poa 424 secunda), where important climate effects were identified in the individual vital rate models but 425 not in the percent cover model (Fig. 3). However, for the two species where including climate 426 covariates increased forecast accuracy (B. gracilis and Poa secunda), forecast skill (Fig. 2) and 427 error (Fig. S2) were equivalent between the IPM and QBM. 428

The higher accuracy of the IPM and QBM with climate covariates for B. gracilis and Poa se-

cunda highlights the advantage of contemporary modeling and variable selection approaches such as ridge regression and LASSO over techniques that would exclude "non-significant" ef-431 fects from final models. Ridge regression allows researchers to retain covariates whose effects may be difficult to identify in noisy data or short time series. This is especially important when 433 forecasting the impacts of climate variability, where it is important to include to effects of forcing 434 variables (e.g., temperature and precipitation) even of such effects are difficult to identify. Indeed, 435 we failed to detect strong climate effects in the QBM for B. gracilis and Poa secunda, but includ-436 ing climate covariates still improved forecasting skill (Fig. 2). If a species is truly unresponsive 437 to a given climate variable, statistical regularization techniques will shrink the mean and variance 438 of a covariate estimate toward zero (Hooten and Hobbs 2015). Of course, no matter what model 439 selection approach is adopted, a critical step is identifying the appropriate candidate covariates, 440 which we attempted to do based on our knowledge of this semi-arid plant community. However, 441 the climate covariates we chose required aggregating daily weather data over discrete time peri-442 ods. It is possible that we did not choose the optimal time periods over which to aggregate. New 443 methods using functional linear models (or splines) may offer a data-driven approach for identi-444 fying the appropriate time periods over which to aggregate to produce a tractable set of candidate 445 climate variables (Teller et al. 2016). We also expected IPM forecast accuracy to decline at a lower rate than the QBM as the forecast 447 horizon increased. In principle, more mechanistic models should produce better predictions, 448 especially under novel conditions (Evans 2012, Schindler and Hilborn 2015). In our case, the 449 IPM explicitly models the influence of weather on recruitment and survival, effects that may be 450 poorly represented in the QBM because recruitment and survival mainly affect small plants that 451 contribute little to year-to-year changes in percent cover. Over time, of course, the addition and 452 subtraction of small plants can have large effects on population growth, so explicitly modeling 453 these effects could contribute to a longer forecast horizon. However, we found no evidence for a 454 difference between the IPM and QBM forecast horizons (Fig. 4). 455

Our comparison of a model based on individual-level data with one based on percent cover data

is not an exhaustive test. Understanding the reasons why the percent cover-based model matched the skill of a demographic model for our focal species may help us anticipate situations in which a percent-cover approach would fail. First, for none of our species did a climate covariate have a 459 strong negative effect on one vital rate and a strong positive effect on a different vital rate (Fig. 3). 460 As noted by Freckleton et al. (2011), complex age or stage structure can compromise predictions 461 from models that aggregate over life-histories, and the same should be true when aggregating 462 across vital rates with contrasting responses to climate drivers. Second, our particular recruit-463 ment model is already so aggregated – it averages across seed production, germination and es-464 tablishment – that it may fail to detect important demographic responses to climate, putting our 465 individual-based model and percent cover model on more equal footing. More finely resolved 466 recruitment data might help our individual-based model outperform the population-level model. 467 As advocated by Freckleton et al. (2011), knowledge of a species' population ecology should 468 guide the modeling approach. 469 In conclusion, we found that models based on individual-level demographic data generally failed to generate more skillful population forecasts than models based on population-level data. This finding runs counter to our expectations, but is consistent with recent theoretical (Freckleton et al. 2011) and empirical work (Queenborough et al. 2011). Moreover, for the two species where 473 including climate covariates improved forecast skill, both models generated equally skillful one-474 step-ahead forecasts. Thus, we conclude that models based on population-level data, rather than 475 individual-level data, may be adequate for forecasting the states and dynamics of plant popu-476 lations. Unfortunately, our analysis, where climate effects were relatively unimportant in vital 477 rate regressions, did not allow us to sufficiently test our prediction that individual-level data is 478 neccessary to generate skillful forecasts if different vital rates respond to climate in unique, po-479 tentially opposing, ways. Nonetheless, our results are encouraging for the use of easy-to-collect 480 population-level data for forecasting the state of plant populations. 481

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Data Accessibility

The data used in this paper have been archived on Ecological Archives: http://esapubs.org/
archive/ecol/E092/143/. All data and R code necessary to reproduce our work has been
deposited on Dryad (link) and is also available on GitHub (http://github.com/atredennick/
MicroMesoForecast).

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Tables

Table $\underline{\text{1: Description of data.}}$ The observations span 13 year-to-year transitions.

Species	Vital Rate Model	Num. Obs.	Num. Quadrats
B. gracilis	Growth	5670	29
	Survival	10102	33
	Recruitment	304	33
	Percent cover	281	29
H. comata	Growth	1990	16
	Survival	3257	18
	Recruitment	304	18
	Percent cover	171	17
P. smithii	Growth	8052	19
	Survival	11344	19
	Recruitment	304	19
	Percent cover	217	19
Poa secunda	Growth	3018	18
	Survival	4650	18
	Recruitment	304	18
	Percent cover	197	18

Figures 589

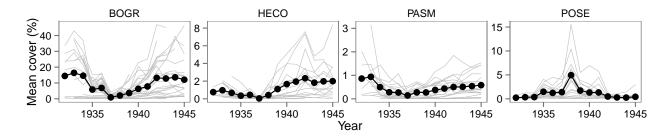


Figure 1: Time series of average percent cover over all quadrats for our four focal species: *Bouteloua gracilis* (BOGR), *Hesperostipa comata* (HECO), *Pascopyrum smithii* (PASM), and *Poa secunda* (POSE). Light grey lines show trajectories of individual quadrats. Note the different y-axis scales across panels.

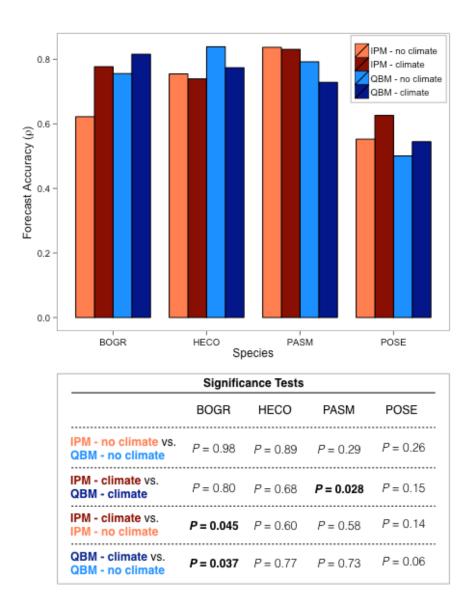


Figure 2: Comparisons of one-step-ahead, out-of-sample forecast accuracy between the IPM and QBM models with and without the inclusion of climate covariates. For each comparison, *P*-values are from one-sided *t* tests designed to assess whether the first model in the comparison statement had higher accuracy than the second model in the comparison statement (see details in Table S22). In no case did adding climate covariates decrease forecast accuracy (Table S21). Species codes are as in Fig. 1.

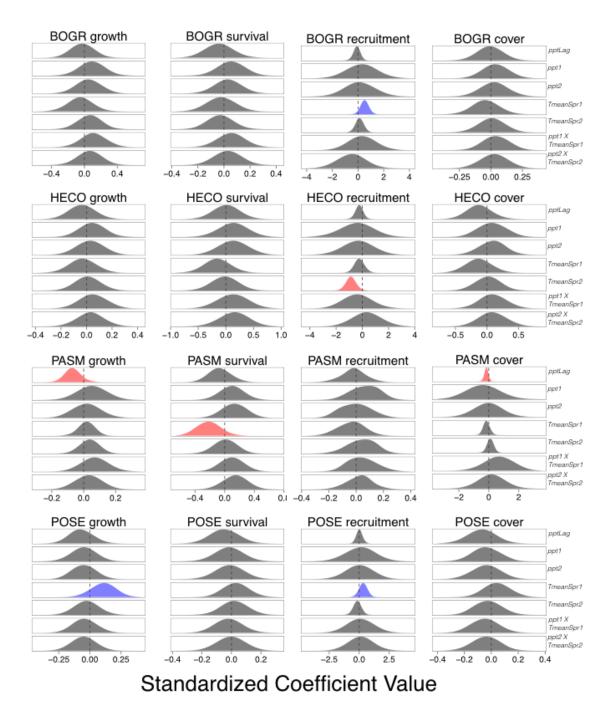


Figure 3: Posterior distributions of climate effects (β_C) for each species and vital rate statistical model. Because our priors were constrained via ridge-regression, we highlight climate effects whose 80% credible intervals do not overlap zero (red for negative coefficients, blue for positive coefficients). Kernel bandwidths of posterior densities were adjusted by a factor of 4 for visual clarity. Species codes are as in Fig. 1.

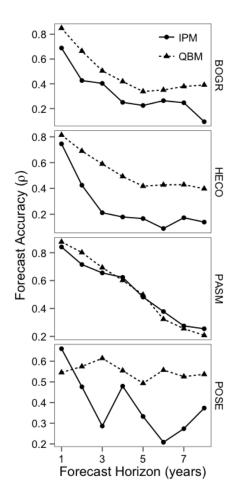


Figure 4: The forecast horizons for both models with climate covariates included. Points show the average accuracy (ρ) across all forecasts at a given time horizon. We only examine the forecast accuracy of models with climate covariates included because in no case did including climate covariates significantly decrease accuracy (see Fig. 2). Species codes are as in Fig. 1.