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**Pattern Recognition**  
*Winter term 2020/21*  
*Friedrich-Alexander University of Erlangen-Nuremberg.*

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Erlangen, January 8, 2021  
Prof. Dr.-Ing. Andreas Maier

# Pattern Recognition (PR)

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Winter Term 2020/21



# Adaptive Segmentation of MRI Data



## Introduction

Magnetic Resonance Imaging (MRI) is an important acquisition technique.

It features:

- high spatial resolution
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Several applications require the **segmentation** (classification) of the acquired images into **tissue types**.

## Introduction (cont.)

Difficulties arise from:

- missing intensity normalization (like Hounsfield units in CT)

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(a) with bias field



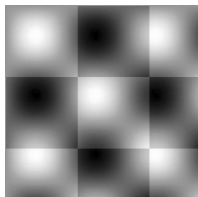
(b) corrected

Fig.: MRI intensity inhomogeneity (Courtesy of F. Jäger)



## Introduction (cont.)

Effect of the bias field on ML segmentation:



(a)

Fig.: Synthetic image (a) overlaid with artificial bias field (b), result of ML segmentation (c), result after modeling bias field within segmentation (d) (Courtesy of W. Wells).

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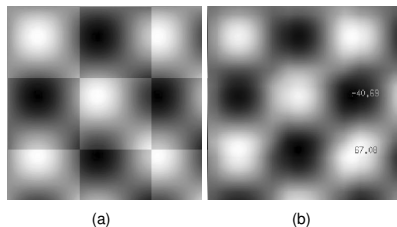


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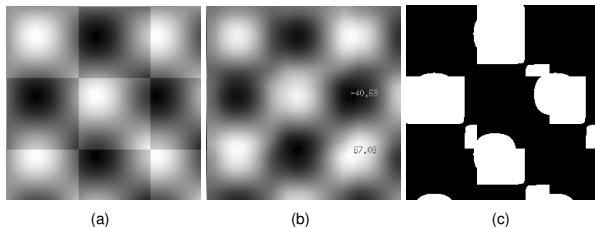


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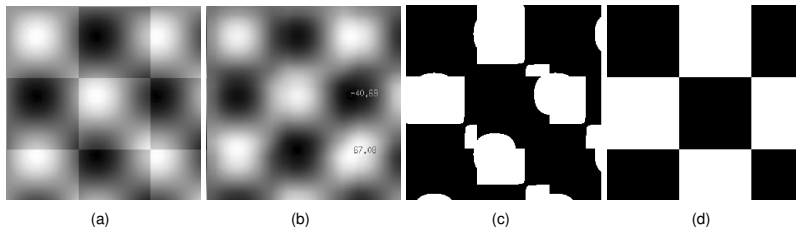


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W. M. Wells et al. presented an approach to improve MR brain segmentation (1996):

- statistical approach to intensity-based segmentation of MRI
- statistical modeling of bias field (smoothness constraint)
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Typical EM problem:

- The missing data is the tissue class assignment for each pixel.
- If the tissue was classified, the bias field could easily be computed.
- If the bias field was known, the tissue classification would be much easier.



## Bias Field Model

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$$Y_i = \log X_i = \log \tilde{X}_i + \beta_i, \text{ with } \beta_i = \log B_i$$

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- The bias field is then:

$$\beta = (\beta_0, \beta_1, \dots, \beta_{n-1})^T$$

with  $n$  being the number of voxels.

## Bias Field Model (cont.)

- The bias field is assumed to change smoothly over the entire image domain.
- It is modeled by an  $n$ -dimensional zero mean Gaussian prior:

$$p(\beta) = \mathcal{N}(\beta; 0, \Psi_\beta)$$

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### Notes:

- $\Psi_\beta$  is a  $n \times n$ -dimensional covariance matrix
- $\Psi_\beta$  is too large to compute directly in practice
- Instead of the full covariance matrix, a banded estimate is chosen in practice.



# Bayesian Approach

Variables:

$Y_i$	log-transformed observed intensity at $i$ -th voxel
$\Gamma_i$	tissue class of the $i$ -th voxel
$\mu_\Gamma$	mean intensity for tissue class $\Gamma$
$\psi_\Gamma$	variance of tissue class $\Gamma$

The intensities are assumed to be scalar values, therefore:  $\mu_\Gamma, \psi_\Gamma \in \mathbb{R}$

## Bayesian Approach (cont.)

Assuming **statistical independence** of the intensities, the probability density for the entire image  $\mathbf{Y} = (Y_0, Y_1, \dots, Y_{n-1})^T$  is:

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with

$$p(Y_i|\Gamma, \beta_i) = \mathcal{N}(Y_i; \mu_{\Gamma} + \beta_i, \psi_{\Gamma})$$

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Observations so far:

- Each tissue class is modeled with a normal distribution.



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- Each tissue class is modeled with a normal distribution.
- The modeling of the observed intensity distribution yields a Gaussian mixture model.
- $p(\Gamma)$  is a stationary prior probability for the tissue class.
- The estimators for the GMM are non-linear!

## Bayesian Approach (cont.)

Using Bayes rule to derive an objective function for the bias field:

$$p(\beta|\mathbf{Y}) = \frac{p(\mathbf{Y}|\beta)p(\beta)}{p(\mathbf{Y})}$$

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$$\begin{aligned}\hat{\beta} &= \operatorname{argmax}_{\beta} p(\beta|\mathbf{Y}) \\ &= \operatorname{argmax}_{\beta} \log p(\beta|\mathbf{Y}) \\ &= \operatorname{argmax}_{\beta} (\log p(\mathbf{Y}|\beta) + \log p(\beta))\end{aligned}$$

## Gradient Computation

At the optimum, the gradient w. r. t.  $\beta$  has to be zero:

$$\frac{\partial}{\partial \beta_i} \log p(\beta | \mathbf{Y}) = \frac{\partial}{\partial \beta_i} (\log p(\mathbf{Y} | \beta) + \log p(\beta))$$



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 &= \frac{\partial}{\partial \beta_i} \left( \sum_j \log p(Y_j | \beta_j) + \log p(\beta) \right) \\
 &= \frac{\frac{\partial}{\partial \beta_i} p(Y_i | \beta_i)}{p(Y_i | \beta_i)} + \frac{\frac{\partial}{\partial \beta_i} p(\beta)}{p(\beta)} \\
 &\stackrel{!}{=} 0.
 \end{aligned}$$

## Gradient Computation (cont.)

$$\frac{\frac{\partial}{\partial \beta_i} p(Y_i | \beta_i)}{p(Y_i | \beta_i)} = \frac{\sum_{\Gamma} p(\Gamma) \frac{\partial}{\partial \beta_i} \mathcal{N}(Y_i; \mu_{\Gamma} + \beta_i, \psi_{\Gamma})}{\underbrace{\sum_{\Gamma} p(\Gamma) \mathcal{N}(Y_i; \mu_{\Gamma} + \beta_i, \psi_{\Gamma})}_{\text{substitute GMM}}}$$

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 &= \frac{\sum_{\Gamma} p(\Gamma) \mathcal{N}(Y_i; \mu_{\Gamma} + \beta_i, \psi_{\Gamma}) \psi_{\Gamma}^{-1} (Y_i - \mu_{\Gamma} - \beta_i)}{\sum_{\Gamma} p(\Gamma) \mathcal{N}(Y_i; \mu_{\Gamma} + \beta_i, \psi_{\Gamma})}
 \end{aligned}$$

## Gradient Computation (cont.)

$$\begin{aligned}
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 &= \frac{\sum_{\Gamma} p(\Gamma) \mathcal{N}(Y_i; \mu_{\Gamma} + \beta_i, \psi_{\Gamma}) \psi_{\Gamma}^{-1} (Y_i - \mu_{\Gamma} - \beta_i)}{\sum_{\Gamma} p(\Gamma) \mathcal{N}(Y_i; \mu_{\Gamma} + \beta_i, \psi_{\Gamma})} \\
 &= \sum_{\Gamma} w_{i\Gamma} (\psi_{\Gamma}^{-1} (Y_i - \mu_{\Gamma} - \beta_i))
 \end{aligned}$$

Weight for the  $i$ -th voxel and tissue class  $\Gamma$ :

$$w_{i\Gamma} := \frac{p(\Gamma) \cdot \mathcal{N}(Y_i; \mu_{\Gamma} + \beta_i, \psi_{\Gamma})}{\sum_{\Gamma} p(\Gamma) \cdot \mathcal{N}(Y_i; \mu_{\Gamma} + \beta_i, \psi_{\Gamma})}$$

## Gradient Computation (cont.)

Rewriting the equation:

$$\frac{\frac{\partial}{\partial \beta_i} p(y_i | \beta_i)}{p(y_i | \beta_i)} = \sum_{\Gamma} w_{i\Gamma} (\psi_{\Gamma}^{-1}(y_i - \mu_{\Gamma} - \beta_i))$$

## Gradient Computation (cont.)

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 &= \sum_{\Gamma} w_{i\Gamma} \psi_{\Gamma}^{-1} (y_i - \mu_{\Gamma}) - \sum_{\Gamma} w_{i\Gamma} \psi_{\Gamma}^{-1} \beta_i \\
 &= \bar{R}_i - \overline{\psi^{-1}}_i \beta_i
 \end{aligned}$$

Mean residual:

$$\bar{R}_i := \sum_{\Gamma} w_{i\Gamma} \psi_{\Gamma}^{-1} (y_i - \mu_{\Gamma})$$

Mean inverse variance:

$$\overline{\psi^{-1}}_i := \sum_{\Gamma} w_{i\Gamma} \psi_{\Gamma}^{-1}$$



## Gradient Computation (cont.)

Finishing gradient computation:

$$\begin{aligned}
 \nabla_{\beta} \log p(\beta | \mathbf{Y}) &= \bar{\mathbf{R}} - \overline{\Psi}^{-1} \beta + \frac{\nabla_{\beta} p(\beta)}{p(\beta)} \\
 &= \bar{\mathbf{R}} - \overline{\Psi}^{-1} \beta - \Psi_{\beta}^{-1} \beta \\
 &\stackrel{!}{=} 0
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It follows that:

$$\hat{\beta} = \mathbf{H} \bar{\mathbf{R}} \quad \text{with} \quad \mathbf{H} \equiv \left[ \overline{\Psi}^{-1} + \Psi_{\beta}^{-1} \right]^{-1}$$

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$\mathbf{H}$  is a linear operator that is applied to the mean residual field.

In fact,  $\hat{\beta}$  can be obtained by low pass filtering of  $\bar{\mathbf{R}}$  and  $\overline{\Psi}^{-1}$ .

# EM-Algorithm

EM-Algorithm for the adaptive segmentation problem:

$$w_{i\Gamma} \leftarrow \frac{\rho(\Gamma) \cdot \mathcal{N}(Y_i | \mu_\Gamma + \beta_i, \psi_\Gamma)}{\sum_\Gamma \rho(\Gamma) \cdot \mathcal{N}(Y_i | \mu_\Gamma + \beta_i, \psi_\Gamma)} \quad (1)$$

$$\hat{\beta} \leftarrow H\bar{R} \quad (2)$$

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- **E-step:** equation (1) yields the posterior tissue class probabilities for a known bias field
- **M-step:** equation (2) yields the new bias field for the current estimates for the tissue probabilities
- **Result:** iterating 5-10 times between the E- and the M-step is usually sufficient

## Results

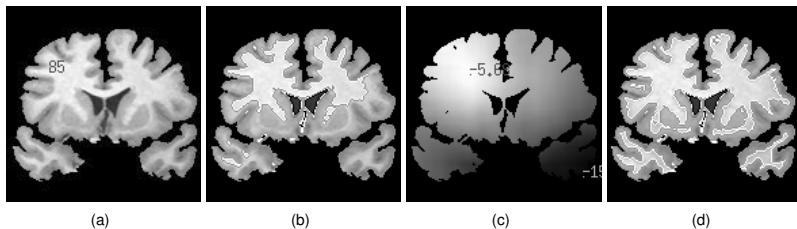


Fig.: Results of conventional segmentation (b) compared to adaptive segmentation (d) with computed bias field (c) on brain image (a) (Courtesy of W. Wells).



## Results (cont.)

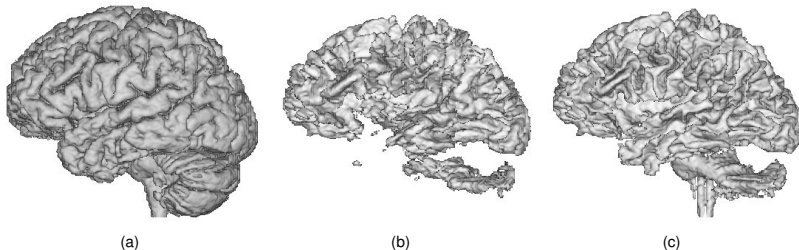


Fig.: Gray matter surface (a) for the previous image example, white matter surface of the conventional algorithm (b) and for the adaptive segmentation (c) (Courtesy of W. Wells).

## Results (cont.)

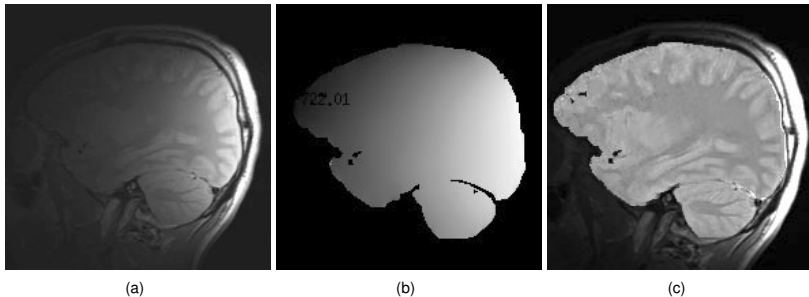


Fig.: MRI image with bias field (a), computed bias field (b) and image corrected at the brain region (c) (Courtesy of W. Wells).

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Extensions of the algorithm:

- incorporation of atlases for spatial probability maps of tissue classes
- definition of vector space for probabilistic atlases to get shape models
- voxel neighborhood relations modeled by Markov random fields
- incorporation into Bayesian model that is solved by EM approach

## Model Extensions (cont.)

Result using an extended model:

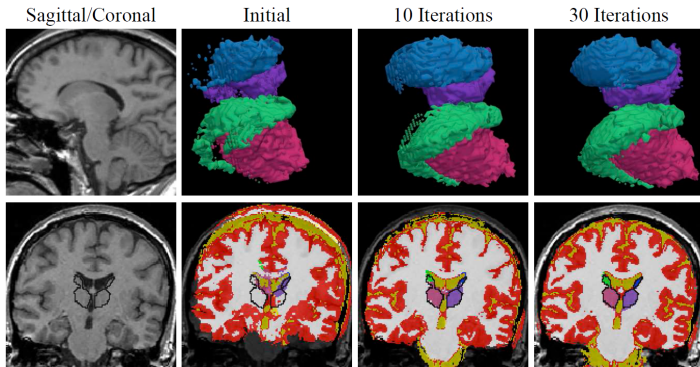


Fig.: MRI segmentation of the thalamus and caudate using an atlas-based EM segmentation algorithm (Courtesy of K. Pohl).

## Lessons Learned

- Bayesian approach for MRI data segmentation
- incorporation of bias field estimation
- nonlinear problem is solved iteratively using EM algorithm
- improvement of results by incorporating atlases



**Pattern  
Recognition  
Lab**



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**TECHNISCHE FAKULTÄT**

**Next Time in**

# **Pattern Recognition**



## Further Readings

- Original paper on adaptive MRI segmentation:  
W. M. Wells, R. Kikinis, W. E. L. Grimson, F. Jolesz:  
[Adaptive segmentation of MRI data](#),  
IEEE Transactions on Medical Imaging, 15:429-442, 1996.
- F. Jäger, J. Hornegger:  
[Nonrigid registration of joint histograms for intensity standardization in magnetic resonance imaging](#),  
IEEE Transactions on Medical Imaging, 28(1):137-150, 2009.

## Further Readings (cont.)

Extensions of the model with shape models, atlas registration and MRFs:

- K. M. Pohl, J. Fisher, J. J. Levitt, M. E. Shenton, R. Kikinis, W. E. L. Grimson, W. M. Wells:  
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## Comprehensive Questions

- What is the idea of combined MR segmentation and bias field correction?
- What is the E-step in this context?
- What is the M-step?
- How can the update formulas be derived?