

These are the slides of the lecture

Pattern Recognition
Winter term 2020/21
Friedrich-Alexander University of Erlangen-Nuremberg.

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Erlangen, January 8, 2021
Prof. Dr.-Ing. Andreas Maier

Pattern Recognition (PR)

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Winter Term 2020/21



Discriminant Analysis I



Discriminant Analysis

Discriminant analysis methods are *discriminative modeling* methods that model the posterior through its factorization

$$p(y|\mathbf{x}) = \frac{p(y) \cdot p(\mathbf{x}|y)}{\sum_y p(y) \cdot p(\mathbf{x}|y)}$$

Gaussian Classifier

We call the Bayesian classifier **Gaussian**, if the class conditional density $p(\mathbf{x}|y)$ is Gaussian, i. e.

$$\begin{aligned} p(\mathbf{x}|y) &= \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_y, \boldsymbol{\Sigma}_y) \\ &= \frac{1}{\sqrt{\det 2\pi \boldsymbol{\Sigma}_y}} e^{-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu}_y)^T \boldsymbol{\Sigma}_y^{-1} (\mathbf{x} - \boldsymbol{\mu}_y)} \end{aligned}$$

where

$\mathbf{x} \in \mathbb{R}^d$: d -dimensional feature vector

$\boldsymbol{\mu}_y \in \mathbb{R}^d$: mean vector of class y

$\boldsymbol{\Sigma}_y \in \mathbb{R}^{d \times d}$: positive definite covariance matrix.

Gaussian Classifier (cont.)

Facts about Gaussian classifiers:

- In general the decision boundary is **quadratic** in the components x_i of the feature vector \mathbf{x} .
- If all classes share the same covariance, the decision boundary is **linear** in the components x_i of the feature vector \mathbf{x} .
- If all covariance matrices are diagonal matrices, then we get a **Naïve Bayes** classifier.

Gaussian Classifier (cont.)

Facts about Gaussian classifiers (cont.):

- If the joint covariance matrix is Σ and priors are identical, classification requires the minimization of the Mahalanobis distance

$$y^* = \operatorname{argmin}_y \frac{1}{2} (\mathbf{x} - \boldsymbol{\mu}_y)^T \Sigma^{-1} (\mathbf{x} - \boldsymbol{\mu}_y)$$

Gaussian Classifier (cont.)

Facts about Gaussian classifiers (cont.):

- If the joint covariance matrix is Σ and priors are identical, classification requires the minimization of the **Mahalanobis distance**

$$y^* = \operatorname{argmin}_y \frac{1}{2} (\mathbf{x} - \boldsymbol{\mu}_y)^T \Sigma^{-1} (\mathbf{x} - \boldsymbol{\mu}_y)$$

- If all covariance matrices are the identity matrix, we get the **Nearest Neighbor** classifier based on the L_2 -norm:

$$y^* = \operatorname{argmin}_y \frac{1}{2} (\mathbf{x} - \boldsymbol{\mu}_y)^T (\mathbf{x} - \boldsymbol{\mu}_y)$$

The prototype vectors are the mean vectors.

Gaussian Classifier (cont.)

From linear to quadratic decision boundaries:

A compromise between linear and quadratic decision boundaries can be achieved by using **regularized covariance matrices**:

$$\Sigma_y(\alpha) = \alpha \Sigma_y + (1 - \alpha) \Sigma$$

where $\alpha \in [0, 1]$ and Σ denotes the joint covariance.

Obviously we have the extremes:

- Linear decision boundary: $\alpha = 0$
- Quadratic decision boundary: $\alpha = 1$

Feature Transform

Can we find a feature transform

$$\phi : \mathbb{R}^d \rightarrow \mathbb{R}^d$$

to generate features $\phi(\mathbf{x})$ that share the same covariance matrix?

Feature Transform (cont.)

The symmetric positive semidefinite covariance matrix $\Sigma \in \mathbb{R}^{d \times d}$ can be decomposed using SVD:

$$\Sigma =$$

Feature Transform (cont.)

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Feature Transform (cont.)

The symmetric positive semidefinite covariance matrix $\Sigma \in \mathbb{R}^{d \times d}$ can be decomposed using SVD:

$$\Sigma = \mathbf{U}\mathbf{D}\mathbf{U}^T = (\mathbf{U}\mathbf{D}^{\frac{1}{2}})(\mathbf{U}\mathbf{D}^{\frac{1}{2}})^T$$

Feature Transform (cont.)

The symmetric positive semidefinite covariance matrix $\Sigma \in \mathbb{R}^{d \times d}$ can be decomposed using SVD:

$$\Sigma = UDU^T = (UD^{\frac{1}{2}})(UD^{\frac{1}{2}})^T = (UD^{\frac{1}{2}}) \cdot I \cdot (UD^{\frac{1}{2}})^T$$

where $I \in \mathbb{R}^{d \times d}$ is the identity matrix.

Feature Transform (cont.)

The symmetric positive semidefinite covariance matrix $\Sigma \in \mathbb{R}^{d \times d}$ can be decomposed using SVD:

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where $\mathbf{I} \in \mathbb{R}^{d \times d}$ is the identity matrix.

- Determinant:

$$\det \Sigma = \prod_{i=1}^d d_{i,i},$$

where $d_{i,i}$ are the diagonal elements of \mathbf{D} , i. e. the **singular values**.

Feature Transform (cont.)

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- Determinant:

$$\det \Sigma = \prod_{i=1}^d d_{i,i},$$

where $d_{i,i}$ are the diagonal elements of \mathbf{D} , i. e. the **singular values**.

- Inverse:

$$\Sigma^{-1} = \mathbf{U}\mathbf{D}^{-1}\mathbf{U}^T = (\mathbf{U}\mathbf{D}^{-\frac{1}{2}}) \cdot \mathbf{I} \cdot (\mathbf{U}\mathbf{D}^{-\frac{1}{2}})^T$$

Feature Transform (cont.)

Now we incorporate this:

$$\mathcal{N}(\mathbf{x}; \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{\sqrt{\det 2\pi\boldsymbol{\Sigma}}} e^{-\frac{1}{2}(\mathbf{x}-\boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{x}-\boldsymbol{\mu})}$$

Feature Transform (cont.)

Now we incorporate this:

$$\begin{aligned}\mathcal{N}(\mathbf{x}; \boldsymbol{\mu}, \boldsymbol{\Sigma}) &= \frac{1}{\sqrt{\det 2\pi \boldsymbol{\Sigma}}} e^{-\frac{1}{2}(\mathbf{x}-\boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{x}-\boldsymbol{\mu})} \\ &= \frac{1}{\sqrt{\det 2\pi \boldsymbol{\Sigma}}} e^{-\frac{1}{2}(\mathbf{x}-\boldsymbol{\mu})^T (\mathbf{U}\mathbf{D}^{-\frac{1}{2}}) \cdot \mathbf{I} \cdot (\mathbf{U}\mathbf{D}^{-\frac{1}{2}})^T (\mathbf{x}-\boldsymbol{\mu})}\end{aligned}$$

Feature Transform (cont.)

Now we incorporate this:

$$\begin{aligned}
 \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}, \boldsymbol{\Sigma}) &= \frac{1}{\sqrt{\det 2\pi \boldsymbol{\Sigma}}} e^{-\frac{1}{2}(\mathbf{x}-\boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{x}-\boldsymbol{\mu})} \\
 &= \frac{1}{\sqrt{\det 2\pi \boldsymbol{\Sigma}}} e^{-\frac{1}{2}(\mathbf{x}-\boldsymbol{\mu})^T (\mathbf{U} \mathbf{D}^{-\frac{1}{2}}) \cdot \mathbf{I} \cdot (\mathbf{U} \mathbf{D}^{-\frac{1}{2}})^T (\mathbf{x}-\boldsymbol{\mu})} \\
 &= \frac{1}{\sqrt{\det 2\pi \boldsymbol{\Sigma}}} e^{-\frac{1}{2} \left((\mathbf{D}^{-\frac{1}{2}} \mathbf{U}^T) \mathbf{x} - (\mathbf{D}^{-\frac{1}{2}} \mathbf{U}^T) \boldsymbol{\mu} \right)^T \mathbf{I} \left((\mathbf{D}^{-\frac{1}{2}} \mathbf{U}^T) \mathbf{x} - (\mathbf{D}^{-\frac{1}{2}} \mathbf{U}^T) \boldsymbol{\mu} \right)}
 \end{aligned}$$

Feature Transform (cont.)

The classwise transform ϕ_y is even a linear function:

$$\mathbf{x}' = \phi_y(\mathbf{x}) = \mathbf{D}_y^{-\frac{1}{2}} \mathbf{U}_y^T \mathbf{x}$$

Feature Transform (cont.)

The classwise transform ϕ_y is even a linear function:

$$\mathbf{x}' = \phi_y(\mathbf{x}) = \mathbf{D}_y^{-\frac{1}{2}} \mathbf{U}_y^T \mathbf{x}$$

It is straight forward to show that \mathbf{x}' is normally distributed

$$p(\mathbf{x}'|y) = \mathcal{N}(\mathbf{x}'; \boldsymbol{\mu}'_y, \boldsymbol{\Sigma}'_y) = \mathcal{N}(\mathbf{x}'; \mathbf{D}_y^{-\frac{1}{2}} \mathbf{U}_y^T \boldsymbol{\mu}_y, I)$$


Feature Transform (cont.)

Conclusions:

- All classes y share the same covariance matrix that is the identity matrix.
- The decision boundary is linear.

Feature Transform (cont.)

Conclusions:

- All classes y share the same covariance matrix that is the identity matrix.
- The decision boundary is linear.
-  Huge disadvantage:
feature transform depends on class number y !
- If we have a classified training set, we can compute a transform for each class such that all covariance matrices are the identity matrix.
- Classification requires the application of different transforms.



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Linear Discriminant Analysis

Input: training data: $S = \{(\mathbf{x}_1, y_1), (\mathbf{x}_2, y_2), (\mathbf{x}_3, y_3), \dots, (\mathbf{x}_m, y_m)\}$

Linear Discriminant Analysis

Input: training data: $S = \{(\mathbf{x}_1, y_1), (\mathbf{x}_2, y_2), (\mathbf{x}_3, y_3), \dots, (\mathbf{x}_m, y_m)\}$

1. ML estimation of the **joint covariance matrix**:

$$\hat{\Sigma} = \frac{1}{m} \sum_{i=1}^m (\mathbf{x}_i - \mu_{y_i})(\mathbf{x}_i - \mu_{y_i})^T$$

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3. Assign transform:

$$\phi = \mathbf{D}^{-\frac{1}{2}} \mathbf{U}^T$$

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4. Compute mean vectors for all y

$$\mu'_y = \phi(\mu_y) = \mathbf{D}^{-\frac{1}{2}} \mathbf{U}^T \mu_y$$

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Input: training data: $S = \{(\mathbf{x}_1, y_1), (\mathbf{x}_2, y_2), (\mathbf{x}_3, y_3), \dots, (\mathbf{x}_m, y_m)\}$

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$$\mu'_y = \phi(\mu_y) = \mathbf{D}^{-\frac{1}{2}} \mathbf{U}^T \mu_y$$

Output: feature transform ϕ , transformed mean vectors μ'_y

Linear Discriminant Analysis (cont.)

Decision rule using sphered data $\phi(\mathbf{x})$:

$$y^* =$$

Linear Discriminant Analysis (cont.)

Decision rule using sphered data $\phi(\mathbf{x})$:

$$y^* = \underset{y}{\operatorname{argmax}} p(y|\phi(\mathbf{x}))$$

Linear Discriminant Analysis (cont.)

Decision rule using sphered data $\phi(\mathbf{x})$:

$$\begin{aligned} y^* &= \operatorname{argmax}_y p(y|\phi(\mathbf{x})) \\ &= \operatorname{argmax}_y \left\{ \log p(y) - \frac{1}{2} (\phi(\mathbf{x}) - \phi(\mu_y))^T (\phi(\mathbf{x}) - \phi(\mu_y)) \right\} \end{aligned}$$

Linear Discriminant Analysis (cont.)

Decision rule using sphered data $\phi(\mathbf{x})$:

$$\begin{aligned}
 y^* &= \operatorname{argmax}_y p(y|\phi(\mathbf{x})) \\
 &= \operatorname{argmax}_y \left\{ \log p(y) - \frac{1}{2} (\phi(\mathbf{x}) - \phi(\mu_y))^T (\phi(\mathbf{x}) - \phi(\mu_y)) \right\} \\
 &= \operatorname{argmin}_y \left\{ \frac{1}{2} \|\phi(\mathbf{x}) - \phi(\mu_y)\|_2^2 - \log p(y) \right\}
 \end{aligned}$$

where $\|\cdot\|_2$ denotes the L_2 norm.

Linear Discriminant Analysis (cont.)

Conclusions:

- If all classes share the **same prior**, the decision rule is the **Nearest Neighbor** decision rule, where transformed mean vectors serve as prototypes.
- The feature transform ϕ does not change the dimension of features.

Linear Discriminant Analysis (cont.)

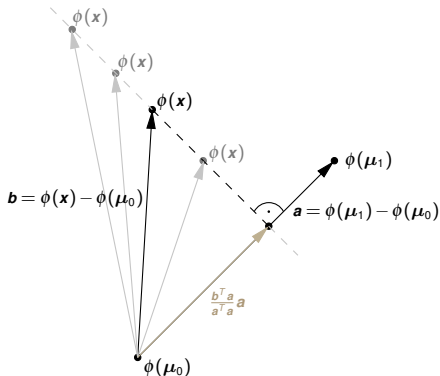


Fig.: Nearest Neighbor classification for two classes

Linear Discriminant Analysis (cont.)

2 classes: insights from geometrical analysis of sphered data

- Angle between $\phi(\mathbf{x})$ and $(\phi(\mu_1) - \phi(\mu_0))$ can be used for decision making.
- Decision rule:

$$y^* = \begin{cases} 0, & \text{if } \phi(\mathbf{x})^T (\phi(\mu_1) - \phi(\mu_0)) < \frac{1}{2} (\phi(\mu_1)^T \phi(\mu_1) - \phi(\mu_0)^T \phi(\mu_0)) \\ 1, & \text{otherwise.} \end{cases}$$

- Coordinate orthogonal to the 1-D subspace spanned by $(\phi(\mu_1) - \phi(\mu_0))$ does not affect relative distances.

Linear Discriminant Analysis (cont.)

K classes: insights from geometrical analysis of sphered data

- Class centroids span $(K - 1)$ -dimensional subspace.
- Relative differences are not affected by coordinates in the $(d - K + 1)$ -dimensional subspace that is orthogonal to the $(K - 1)$ -dimensional subspace spanned by class centroids.

Linear Discriminant Analysis (cont.)

Objective:

Will we gain an advantage if we transform features by

$$\phi : \mathbb{R}^d \rightarrow \mathbb{R}^k$$

in higher ($k > d$) or lower dimensional ($k < d$) spaces?

Lessons Learned

- Relationship between Bayesian classifier, Gaussian classifier, and Nearest Neighbor classifier.
- Mahalanobis distance
- Linear Discriminant Analysis is a regularized Nearest Neighbor classifier
- Class centroids span $(K - 1)$ -dimensional subspace



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Further Readings

You are required to be familiar with **linear algebra** and **matrix calculus**:

- SIAMS best selling book in the last decade:
Lloyd N. Trefethen, David Bau III:
Numerical Linear Algebra,
SIAM, Philadelphia, 1997.
- All about matrix derivatives and related problems is described in the Matrix Cookbook: <http://www.matrixcookbook.com>

Basics on **discriminant analysis** can be found in

- T. Hastie, R. Tibshirani, and J. Friedman:
**The Elements of Statistical Learning –
Data Mining, Inference, and Prediction**,
2nd edition, Springer, New York, 2009.

Comprehensive Questions

- What is a Gaussian classifier?
- What is the idea behind the feature transform for the LDA?
- Formulate the LDA for normally distributed classes.
- What is the dimensionality of the LDA subspace for K classes?