# Parallel and distribute programming

Author: Altaf khan

**Simulation matrix 4*4 fallowing assembly code 3.11 for SIMD Machine**
**(Using c#.Net)**

**Outline of Report**

## 1. Introduction:

In this project simulation is implemented which shows that how our SIMD machine works. Matrix is a vector product when A matrix is multiply B and C is resulted matrix, so C = A*B I will show these implementation in form of simulation and I will use 4 processor which execute concurrently.
In this process. A is broad cast to all processors and B value will be fetched from B matrix each time and multiply by A value which is broadcasted to each PE. Each process execute alone and save same result in C matrix C[i,j] position.
For this Assignment I will prefer to visual studio 2012 (C#.net) tool. This is new powerful tool which is easily available in market. As compare to other C# is friendlier so I implement C# to perform above tasks. If you want to know how to make project, You can visit this link: http://msdn.microsoft.com/en-us/library/ms173077%28v=vs.90%29.aspx [2] . I will focus on my own work and try explains every point in this report. I just show the diagram in which user can easily understand how can we start new project?

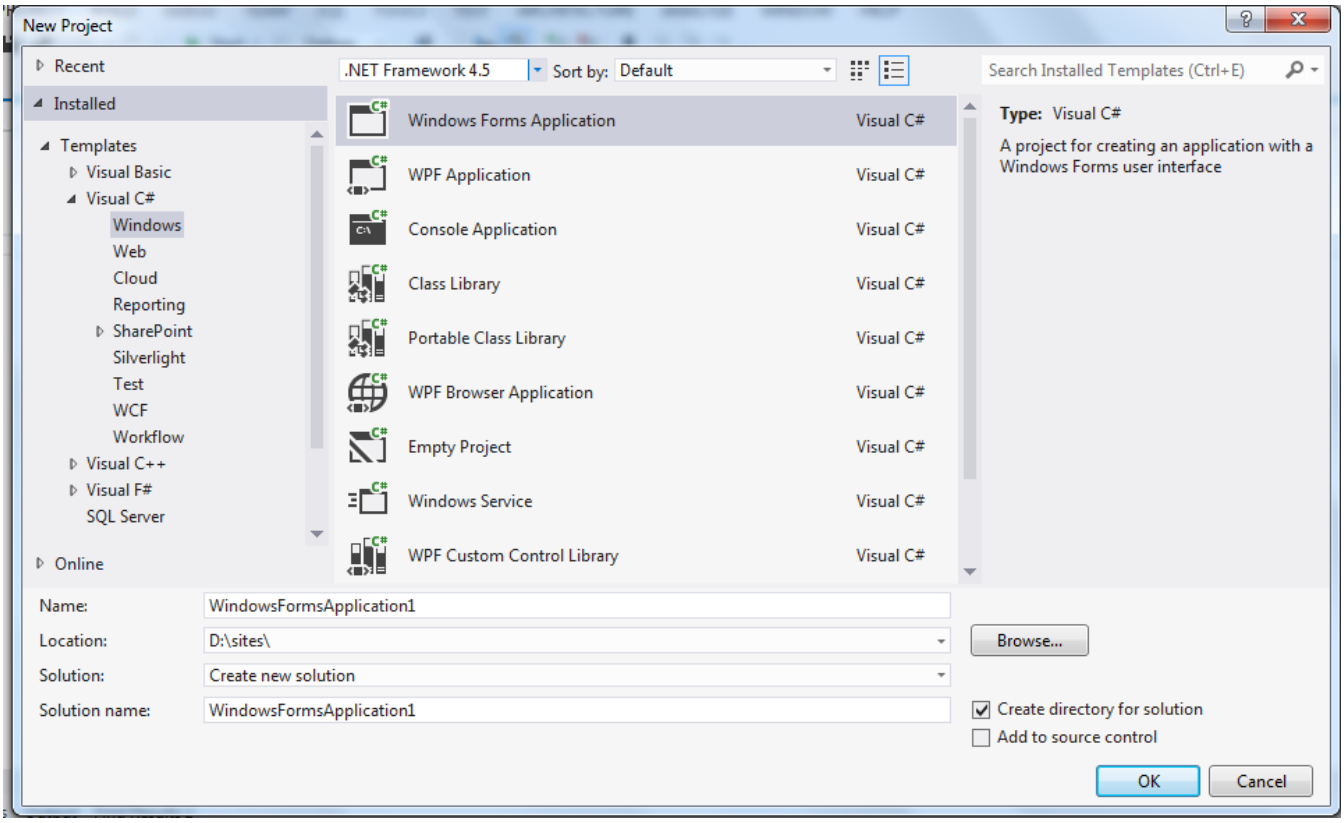


**Figure 1.1** how to make new project of C# window form?

## 2. Implementation and Simulation procedure:

1. First of all create new project. Select c# and console App.
2. Add front end elements and perform matrix ‘A’ matrix ‘B’ and matrix ‘C’.
3. Create two register ‘A’ and ‘R’
    a. A is accumulator and R is routing register
4. Add processors Elements p1 to p4 which is involved to solve this solution.
5. Create I,j and limit object to handle instruction.
6. Write Assembly code on right side which is use for execution.
7. Create 3 button, Start, initialize matrix and start matrix on top of program.

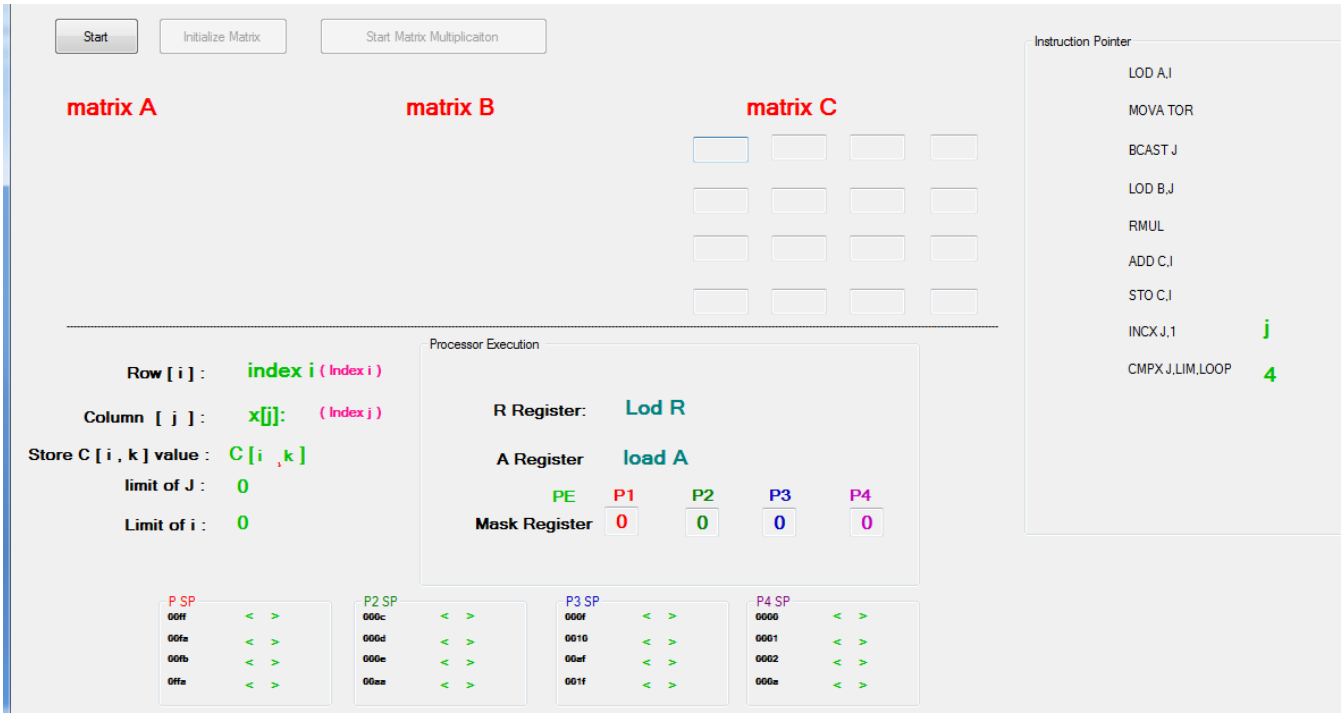


Figure 1.2 inter face of SIMD simulator for 4*4 matrix

8. Start buttion start the process. Means it initialize all value to zero.

It work fallowing these assembly instructions :

| | | |
|---|---|---|
| CLOAD | ZERO | Initialize all |
| CBCAST | | PE accumulators |
| MOVR | TOA | to zero |
| STO | C,I | Zero the I-th row of C. |

Start button work on above instruction. C load zero first then broadcast then move R to A. Hence shown in figure. Below


Figure1.3 initialize zero value to all matrix. R register is copy to A so both shows zero values.

9. Press the Initialize matrix button and assign value to matrix A and matrix B . like load matrix .

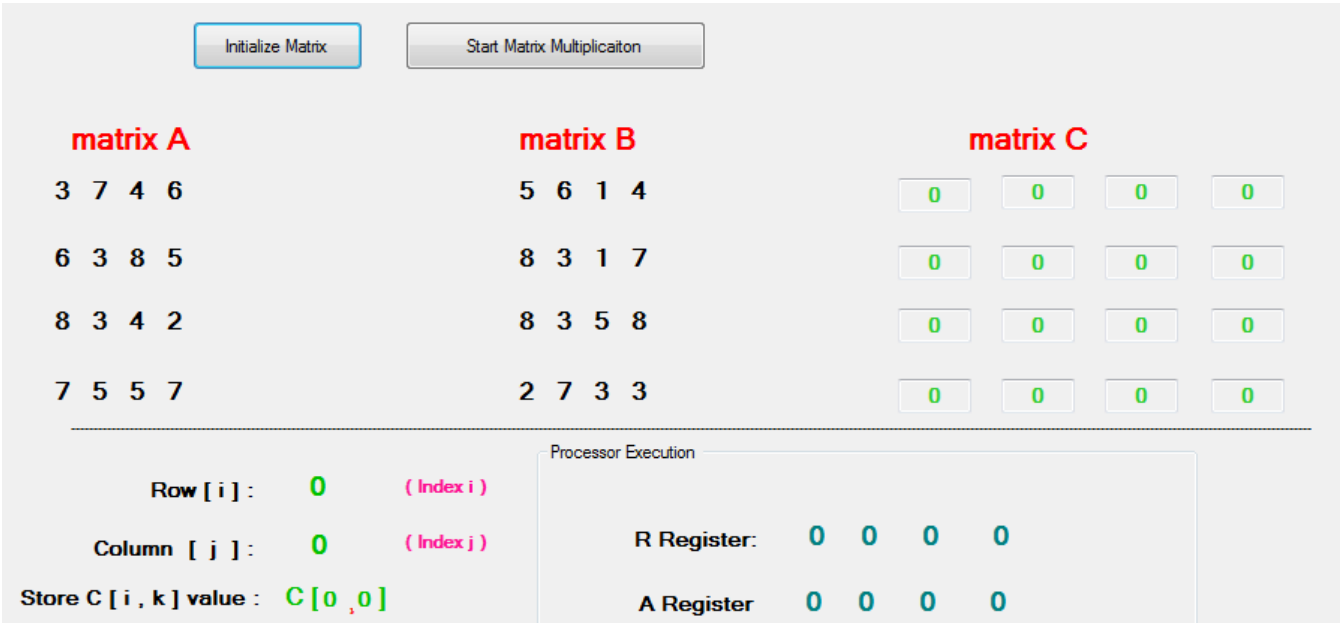


Figure 1.4 initialize value to matrix so now program wait for next instruction to lod value in A register.

10. Lod a value to AK register and next to also broad cast to each value every time to broad cast to R register .

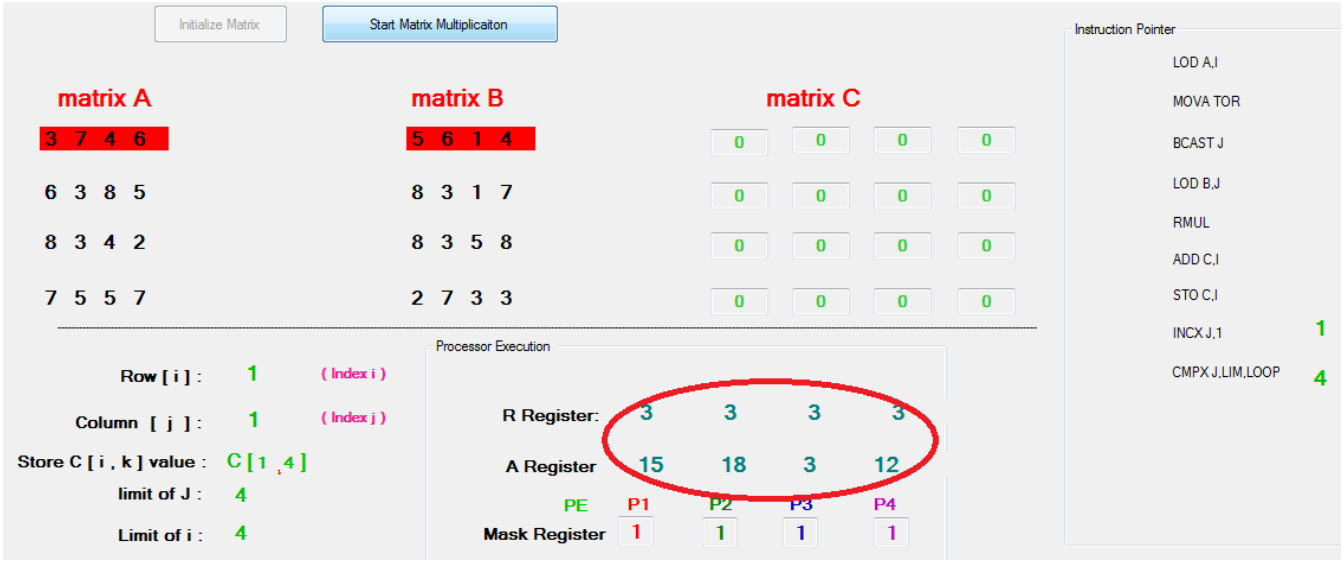


Figure 1.5 lod to A[k] and add to again Ak and 3 is first value which is broadcast to each PE. (Route Register).

11. Lod b and add with A and then store to C . and each time J is increased up to 4.

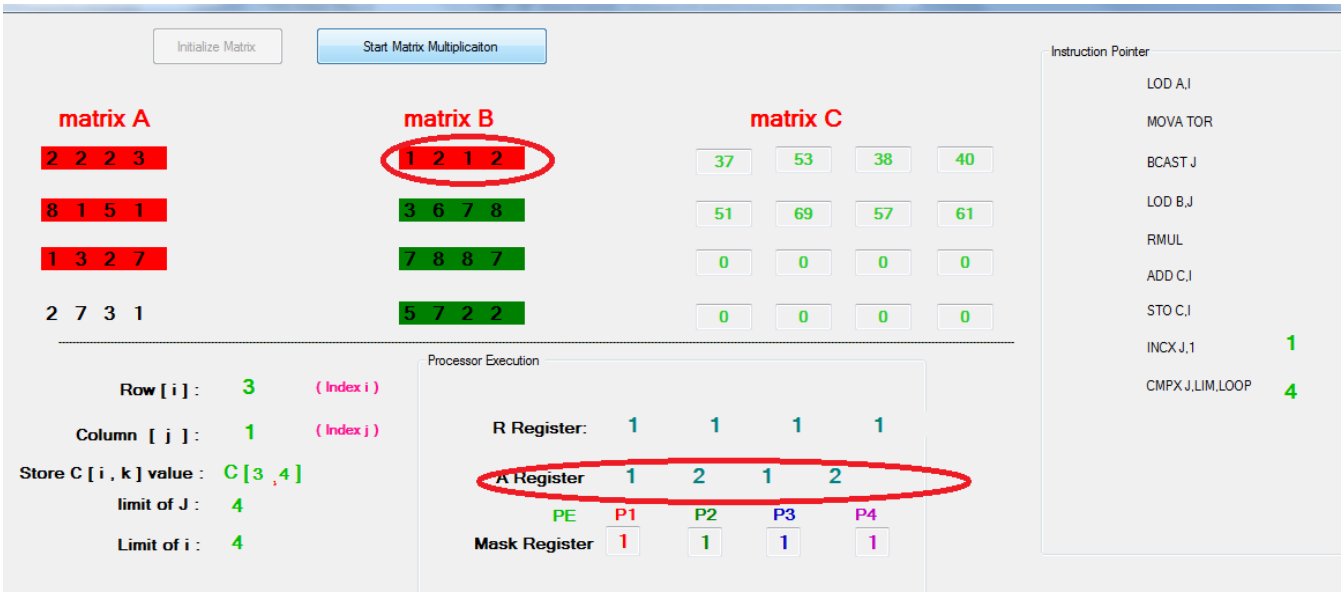


Figure 1.6 B lod to A[k] and then A add next calculation Rmul and result store to Ak.

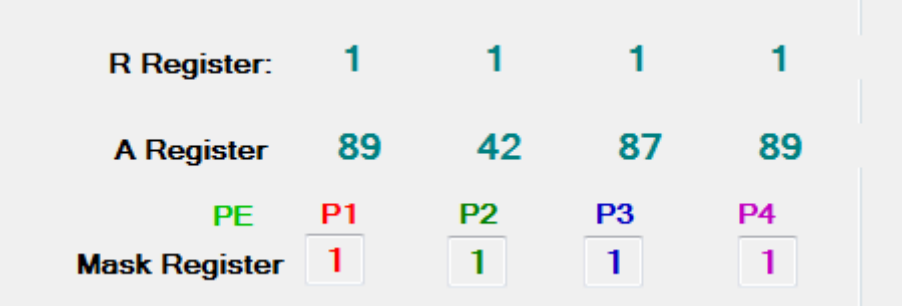


Figure 1.7 shows result multiply with B and store again to A and then it store to C. shown diagram 1.8.

12. This work repeatedly until i= 4.

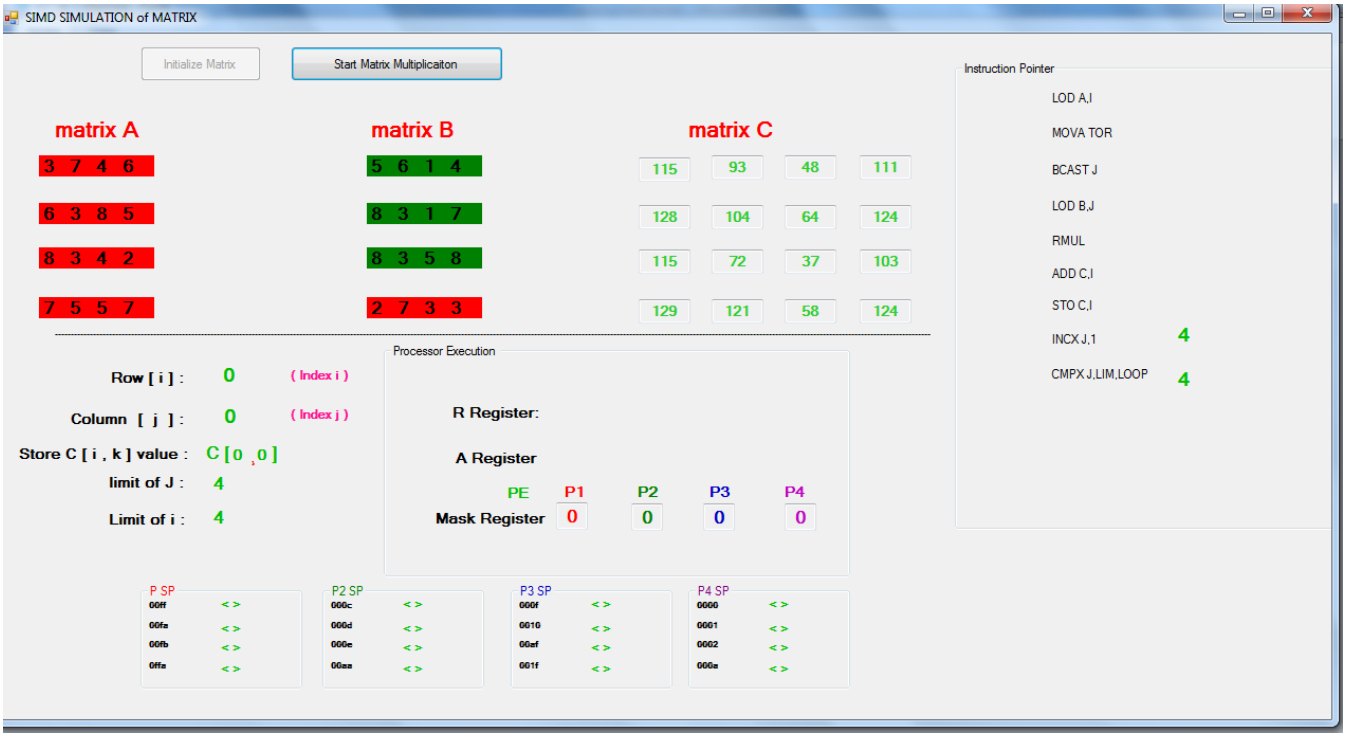


Figure 1.8 shows execution of full matrix result 4*4. End of result all result store in C matrix and all variable become.

13. Cs code file is here. First of all I shows the function list.

```
28  using System.Diagnostics;
29  using System.Threading.Tasks;
30  namespace bonespoint
31  {    public partial class Form1 : Form
32      {
33          private static System.Timers.Timer aTimer;
34          public Form1()...
40          int j = 0;int  m=0;
41          private void timer1_Tick(object sender, EventArgs e)...
94          protected void intializewith_zero()...
154         protected void mask()...
162         int[,] A = new int[4, 4];
163         int[,] R = new int[4, 4];
164         int[,] B = new int[4, 4];
165         Int64[,] C = new Int64[4, 4];
166         protected void rest()...
179         protected void initializeAandB()...
226         protected void load_AtoR(int xi)          ////////////////load  A to R each time with value of X[i]...
256         protected void Load_Bcast(int i, int j)...
264         protected void load_Bvalue(int j)...
274         private void Form1_Load(object sender, EventArgs e)...
278         private void btnload_c_Click(object sender, EventArgs e)...
283         protected void multiple_show(int i, int j)...
671         protected void indexofcode()...
684         protected void resetregister() ...
717         private void button1_Click(object sender, EventArgs e)...
725         private void Initialize_matx_Click(object sender, EventArgs e)...
732         private void str_multiplicaiton_Click(object sender, EventArgs e)...
739         private void timer4_Tick(object sender, EventArgs e)...
749             }
750     }
)%
```

Figure 1.9 illustrate line of code which is use behind the above program.

14. First of all timer1_tick() function is use for represent slow the program .
15. Declare integer matrix A .B  size 4 * 4 but C is int64 but because C is resultant matrix it may be use for  storing large value  .
16. **Initializewith _zero():**  this function is used for initialize zero to matrix  same work for broadcast zero to all PE and store also into the C matrix.
17. **Mask** is use for processor enable and disable .
18. Reset is simple for initialize again to all with zero . Simple reset function.
19. InitializeAandB() , this function use for Initialize value to  A and B matrix.
20. LodAtoR() function simple load A value to R register  during execution,
21. loadBcast() is use for brocast j value to R register , each value of A is broadcasted by this function.
22. LoadBvalue() this function is specially for load B value into Ak register.
23. multipleMatrixShow() , this function properties is that it has done multiplication with B and store to Ak to C matrix .
24. index ofcode() function illustrate to show arrows and index value which is incremented during simulation.
25. Last 4 are button which use to call above all program in sequence. _click() function are button which work on click events. All code is written on project CD.

In below memory location is shown in which data store , load A and then B and both multiply with each other**. Mask register** show when program execute all processor s[k] bit become one and all are executed when execution is finish every all PE mask disable .

Row and column is checked with I to 4 and j is also start 1 to 4. Limit is 4 for all iterations. This assembly code which is implemented here.

**3. Assembly code :**

```
CLOAD    ZERO              Initialize all
CBCAST                     PE accumulators
MOVR     TOA               to zero
STO      C,I               Zero the I-th row of C
LDXI     J,0               Initialize the column index
LDX      LIM,N             Loop limit is the matrix size
LOOP:    LOD      A,I      Fetch the row I of A
MOVA     TOR               and set up for routing
BCAST    J                 Broadcast A[I,J] to all PEs
LOD B,   J                 Get row J of B and perform
RMUL                       A[I,J]xB[J,k] for all k
ADD      C,I               C[I,k] ← C[I,k]+A[I,J]xB[J,k]
STO      C,I               for all k
INCX     J,1               Increment column of A
CMPX     J,LIM,LOOP        Loop if row of C not complete
```

Program 3-11. Matrix multiply SIMD assembly code for one row of the product matrix " [1]

**4. Reference:**


1. Book :fundamental of Parallel and distributed programming.(edition: 2003)
2. http://msdn.microsoft.com. (date : 5/20/2014)
3. http://stackoverflow.com/.