

Module - I

Theory of Estimation

01: Point Estimation

- * The main objective of statistical analysis is to draw valid conclusion about (P) population on the basis of a sample drawn from the (P) .
- * Statistical inference is the process of making inferences about the unknown aspects of distri... of the (P) based on samples taken from it.
- * The unknown aspects may be the form of distri... / the values of paramtrs involved in it.
- * Statistical inference bcz the conclusions sample about the
- * Statistical inference into 2 areas →
 - ① Estimation of paramtrs.
 - ② ~~Test~~ Test of hypothesis. = It is a type of statistical decision probm.
It is a rule / procedure whether to accept / reject the hypothesis on the basis of sample values obtained.
- * The technique of coming to conclusion regarding the values of the unknown parameters based on the info provided by a sample → problem of estimation

This estimation can be made into two ways

1) point estimation

2) interval estimation (ranges $\rightarrow (a-100)$)

2) interval estimation (ranges $\rightarrow (a-100)$)

Point estimation = (p.e.)

* If from the observation in the sample a single value is calculated as an estimate of the unknown parameter.

* The procedure is $\rightarrow \hat{P}(\cdot)$.

* And we refer to the value of the statistic as a point estimate. This statistic represents a guess of a person estimating the (p) parameter method of estimating the (p) parameter represents the value produced by the estimator.

Properties \rightarrow

* There are 4 criteria commonly used for finding a good estimator, they are,

- 1) Unbiasedness estimator
- 2) Consistency
- 3) Efficiency
- 4) Sufficiency.

Unbiasedness =

If it is a statistic that has an expected value equal to the unknown true value of the (p) parameter being estimated.

* An estimator not having this (prop) is said to be biased.

* Let 'x' be r.v. having the pdf $f(x, \theta)$ where θ may be unknown.

Let x_1, x_2, \dots, x_n be a random sample taken from the (p) represented by x. Let $t_n = t(x_1, x_2, \dots, x_n)$ be an estimator of parameter θ . If $E(t_n) = \theta$ for every n then the estimator is (respectively) unbiased estimator.

$t_n \rightarrow$ unbiased estimator.

* Let x_1, x_2, \dots, x_n be a random sample drawn from a given (p) with mean μ and variance σ^2 , if the estimator

and \bar{x} is an unbiased estimator of μ .

Now prove $E(\bar{x}) = \mu$.

We know that

$$E(\bar{x}) = \frac{1}{n} E\left(\sum_{i=1}^n x_i\right)$$

$$= \frac{1}{n} E(x_1 + x_2 + \dots + x_n)$$

$$= \frac{1}{n} [E(x_1) + E(x_2) + \dots + E(x_n)]$$

$$\rightarrow \text{as } E(x_i) = \mu$$

$$= \frac{1}{n} [N + N + \dots + N]$$

$$= \frac{1}{n} [n\mu]$$

$$E(\bar{x}) = \mu$$

Hence sample mean is an unbiased estimator of μ mean.

2) Let x_1, x_2, \dots, x_n be a random sample from a normal distribution $N(\mu, \sigma^2)$. If $t = \frac{1}{n} \sum_{i=1}^n x_i^2$ is an unbiased estimator of $\mu + 1$.

$$N(\mu, \sigma^2) \rightarrow \text{a. } \therefore \sigma = 1$$

$$N(\mu, 1) \rightarrow \text{a. } \therefore \sigma = 1$$

$$\text{a.s.} \rightarrow$$

$$\begin{aligned} E(x_i) &= \mu \\ V(x_i) &= 1 \end{aligned}$$

$$\text{To prove } t = \frac{1}{n} \sum_{i=1}^n x_i^2$$

$$\begin{aligned} E(t) &= E(x_i)^2 - (E(x))^2 \\ &= E(x_i)^2 - \mu^2 \\ E(x_i)^2 &= \sum_{i=1}^n x_i^2 = \mu^2 + 1 \end{aligned}$$

$$t = \frac{1}{n} \sum_{i=1}^n x_i^2$$

$$E(t) = \frac{1}{n} E\left(\sum_{i=1}^n x_i^2\right)$$

$$\begin{aligned} &= \frac{1}{n} \sum_{i=1}^n E(x_i^2) = \frac{1}{n} \cdot n (\mu^2 + 1) \\ E(t) &= \mu^2 + 1 \end{aligned}$$

$$t \text{ is an unbiased estimator of } \mu^2 + 1.$$

$$\mu^2 + 1$$

② Consistency =

The estimator $t_n = t(x_1, x_2, \dots, x_n)$ is parametrically consistent if it converges to 0 in probability, i.e. for

$\theta \rightarrow$ consistent

$$\lim_{n \rightarrow \infty} P(|t_n - \theta| \leq \epsilon) = 1$$

$$\lim_{n \rightarrow \infty} P(|t_n - \theta| \geq \epsilon) = 0.$$

The estimators satisfying above condition

are \rightarrow weakly consistent estimators

Theorem \rightarrow

An estimator t_n is such that $E(t_n) = \theta_n$

$\Rightarrow V(t_n) \xrightarrow{n \rightarrow \infty} 0$

The estimator t_n is said to be consistent for θ .

$$\begin{aligned} E(t_n^2) - \mu^2 &= 1 \\ t_n^2 &= \mu^2 + 1 \end{aligned}$$

$$\begin{aligned} \text{By Chebycheff's inequality for any giv} \\ \text{no., however small } \epsilon &\text{ we have} \\ \text{for } \epsilon > 0, \text{ we have} \\ P(|t_n - \theta_n| \geq \epsilon) &\leq \frac{V(t_n)}{\epsilon^2} \quad \text{on} \\ P(|t_n - \theta_n| < \epsilon) &> 1 - \frac{V(t_n)}{\epsilon^2} \end{aligned}$$

$$\begin{aligned} \text{Thus we can write } |t_n - \theta| &= |t_n - \theta - (\theta_n - \theta)| \\ &> |t_n - \theta| - |\theta_n - \theta|. \end{aligned}$$

$$\begin{aligned} P(|t_n - \theta| - |\theta_n - \theta| < \epsilon) &> 1 - \frac{V(t_n)}{\epsilon^2}. \\ P(|t_n - \theta| < |\theta_n - \theta| + \epsilon) &> 1 - \frac{V(t_n)}{\epsilon^2}. \end{aligned}$$

$$\begin{aligned} \text{Since } \theta_n \xrightarrow{n \rightarrow \infty} \theta, \quad |\theta_n - \theta| &= \epsilon, \\ \text{hence } P(|t_n - \theta| < \epsilon_1 + \epsilon) &> 1 - \frac{V(t_n)}{\epsilon^2} \end{aligned}$$

$$\text{Since } V(t) \rightarrow 0, \text{ hence } \frac{V(t_n)}{\epsilon^2} \xrightarrow{n \rightarrow \infty} 0.$$

$$P(|t_n - \theta| < \epsilon) > 1 - \frac{V(t_n)}{\epsilon^2} \xrightarrow{n \rightarrow \infty} 1.$$

hence t_n is a consistent estimator ($t_n \rightarrow \theta$)

If t is a consistent estimator of θ then t^2 is also a consistent estimator of θ^2 .

As since t is c. & o. of θ , we have

$\leftarrow (3 > |o - t|) \wedge (t \text{ even})$

To prove: $\lim_{n \rightarrow \infty} (1^2 - 0^2) = 1$

$$1 \leq x \leq 3$$

$$1 \longleftarrow (3; g - 1; 3) \longrightarrow 0$$

$$\lim_{n \rightarrow \infty} \left(\frac{1}{n} \sum_{k=1}^n f\left(\frac{k}{n}\right) \right) = \int_0^1 f(x) dx$$

$$\lim_{n \rightarrow \infty} \frac{1}{n^2} \left((a + \epsilon)^2 - a^2 \right) = 0$$

$$+ \epsilon^2 \lambda^2 < \delta^2 + 2\delta\epsilon + \epsilon^2) \rightarrow$$

use model $t = \frac{2}{\pi} \arcsin(\sin \theta)$

$$\lim_{n \rightarrow \infty} P\left(\epsilon^2 - 2\epsilon\delta < t^2 - \delta^2 < \epsilon^2 + 2\delta\epsilon\right) \rightarrow 1$$

$$\lim_{\epsilon \rightarrow 0} (\epsilon^2 - 2\epsilon \alpha + t^2 - \theta^2) = (-2\epsilon)^2$$

$$e^2 - 2ec\theta - \frac{2e^2}{c} < t^2 - \theta^2$$

$$-\epsilon^2 - 2\epsilon \rho < t^2 - \rho^2$$

$$= (\epsilon^* + 2\epsilon_0) \cdot c$$

$$(\text{lim } \varphi(-\epsilon^2 + 2\zeta)) < t^2 - \delta^2 < \zeta^2 + 2\delta\epsilon \quad \rightarrow$$

$$\lim_{n \rightarrow \infty} E_n = \varepsilon^2 + 2\cdot \varepsilon \cdot \theta$$

$$\lim_{n \rightarrow \infty} \varphi(-\varepsilon_1 < t^{2-\alpha^2} < \varepsilon_1)$$

$$= \left(\frac{3}{2} x^{\frac{1}{2}} - \frac{1}{2} \right) e^{-x}$$

→ \vec{E} \vec{B} \vec{v}

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ency =

we have to choose

I always sample distances usually take the largest vessel, has the smallest vessel with a smaller vessel will

be concentrated closely to the true value, will deviate less from the true value than the (C) units. The larger variations may be considered to be more efficient than the smaller.

* let t_1 & t_2 be 2 ~~conveniences~~
payments & to choose the shift - unbiased
(e) I would reasonably consider them
as ~~conveniences~~. (i.e.) It is $\left(t_1\right)$ than
it is said to be more efficient than to
it as ~~convenience~~ or (e) uses, its

* efficiency \rightarrow relative efficiency of t_2 with respect to t_1 .

15. x_1, x_2, x_3 are 3 independent random variables with mean 4 and variance 2. If $t_1 = x_1 + x_2 - x_3$ and $t_2 = 2x_1 + 3x_2 - 4x_3$. Find estimates of μ and variance of t_1 and t_2 .

$$t_1 \leq t_2 = (\dots) + \varepsilon(\overline{x}_2) - \varepsilon(\overline{x}_3)$$

$$1 + n^3 = 7^3$$

$$\begin{aligned} e(t_2) &= 2e(t_0) + 3 \stackrel{e(t_2) - 4e(t_3)}{=} \\ &= 2N + 3N - NH = N \end{aligned}$$

$t_1 \neq t_2$ \rightarrow $m = n$ (es)

v(t) is smallest in 1/ greater in 2.

$$v(t_1) = v(x_1) + v(x_2) + v(x_3)$$

$$= \sigma^2 + \sigma^2 + \sigma^2 = 3\sigma^2$$

$$v(t_2) = 2v(x_1) + 3v(x_2) + 4v(x_3)$$

$$= 2\sigma^2 + 3\sigma^2 + 4\sigma^2 =$$

$$(\sigma^2 \text{ corresponds } 2^2, 3^2, 4^2)$$

$$= 4\sigma^2 + 9\sigma^2 + 16\sigma^2 = 29\sigma^2$$

; t₁ is more efficient than t₂.

relative e. of t₂ with respect to t₁,

$$\frac{v(t_1)}{v(t_2)} = \frac{3\sigma^2}{29\sigma^2} = \frac{3}{29}$$

Sufficiency

* In (e) it is said to be sufficient if it provides all info contained in the sample in respect of estimating the parameters θ.

* we have explained the concept of sufficiency of an (e). In many cases a relatively easy criterion for examining an (e) for sufficiency has been developed. This is → Fisher Neyman Factorisation Theorem.

This gives a necessary & sufficient condition for an (e) 't' to be sufficient for a parameter θ.

Factorisation Theorem ⇒

Let x_1, x_2, \dots, x_n be a random sample of size n from a (P) with density (f)

where θ denotes the parameter which

may be unknown.

Then a statistic t = t(x₁, x₂, ..., x_n) is sufficient if it and only if the joint (prob) density (f_{t,θ}) of x_1, x_2, \dots, x_n (known as likelihood of the sample) is capable of being expressed in the form

$$L(x_1, x_2, \dots, x_n; \theta) = L_t(x_1, x_2, \dots, x_n)$$

where the L_t(x₁, x₂, ..., x_n) is now free of the

does not involve the parameter θ in the

L_t(x, θ) is non negative depending on

the parameter θ.

i) S.t. the sample mean is sufficient for estimating the parameter θ in regression distribution?

$$f(x, \theta) = \frac{f(x, \theta)}{x!}, x = 0, 1, \dots, n > 0$$

If x_1, x_2, \dots, x_n are sample values

want to write in the form of →

$$L(x_1, x_2, \dots, x_n, \theta) = f(x_1, \theta) \cdot f(x_2, \theta) \cdots f(x_n, \theta)$$

$$= \frac{e^{-\theta} \theta^{x_1}}{x_1!} \cdot \frac{e^{-\theta} \theta^{x_2}}{x_2!} \cdots \frac{e^{-\theta} \theta^{x_n}}{x_n!}$$

$$= e^{-n\theta} \cdot e^{-n\theta} \cdot e^{-n\theta} \text{ times } \frac{x_1! \cdot x_2! \cdots x_n!}{x_1! \cdot x_2! \cdots x_n!}$$

$$= \frac{e^{-n\theta} \cdot \theta^{x_1+n\theta} \cdots \theta^{x_n+n\theta}}{x_1! \cdot x_2! \cdots x_n!}$$

$$= \frac{e^{-nx} n^x}{x_1! \dots x_n!}$$

$$= \frac{e^{-nx} n^x}{x_1! \dots x_n!} = \frac{n^x e^{-nx}}{(x_1! x_2! \dots x_n!)^{1/x}} = \frac{e^{-nx} n^x}{x_1! x_2! \dots x_n!}$$

$$\bar{x}(x_1, x_2, \dots, x_n) = \frac{1}{n} (x_1 + x_2 + \dots + x_n)$$

by factorization (i) the sample mean \bar{x} is a sufficient (ii) of λ

2) S.T. \bar{x} is a (i) of ' p ' when Sample of size n are taken from binomial (p) with parameters N & p (N given). $q = 1-p$.

$$f(x, p) = N(x, p^x q^{n-x})$$

$$= N(x, p^x (1-p)^{n-x}) \quad x = 0, 1, 2, \dots, n.$$

$$L(x_1, x_2, \dots, x_n; p) = f(x, p)$$

$$= n! x_1 p^{x_1} (1-p)^{n-x_1} \cdot n! x_2 p^{x_2} (1-p)^{n-x_2} \cdots$$

$$N(x_1, p^x (1-p)^{n-x})$$

$$= N(x_1) N(x_2) \cdots N(x_n) \frac{p^{x_1} (1-p)^{n-x_1}}{x_1!} \cdots \frac{p^{x_n} (1-p)^{n-x_n}}{x_n!}$$

\Rightarrow symmetric Rao inequality =

let x be a continuous R.V with pdf $f(x, \theta)$ & the likelihood (i) 'L' & let ' t ' be an unbiased (ii) of some (θ) as 0, say $T(\theta)$, then

$$V(t) \geq \left[\frac{T'(\theta)}{E\left(\frac{\partial \log L}{\partial \theta}\right)^2} \right]$$

$$E\left(\frac{\partial \log L}{\partial \theta}\right)^2 = -E\left[\frac{\partial^2 \log L}{\partial \theta^2}\right]$$

$\int_{\Omega} x$ is (i) of p

we can write the Rao inequality as,

Completeness =

Let x_1, x_2, \dots, x_n denote a random sample from a population with density $f(x, \theta)$. Let $t = t(x_1, x_2, \dots, x_n)$ be a statistic then t is said to be complete for θ if it is the only unbiased (i) of θ , i.e. $E[t] = \theta$ the statistic such that

(Prob) 1.

$$t = t(\infty) \quad h(t) \Rightarrow h(t) = 0$$

always surely

$$(ii) P(h(t) = 0) = 1$$

e.g. let x_1, x_2, \dots, x_n be random sample from binomial distribution given by $f(x, p) = p^x (1-p)^{n-x}$ then $t = \sum_{i=1}^n x_i$ is a complete statistic for p .

Rao's incomplete statistic for p

$$V(\theta) \geq - \left[\frac{(\tau'(\theta))^2}{E\left(\frac{\partial^2 \log L}{\partial \theta^2}\right)} \right]$$

comes from

Normal

$$\frac{(\tau'(\theta))^2}{E\left(\frac{\partial^2 \log L}{\partial \theta^2}\right)} \rightarrow \text{C. rao lower bound}$$

Note →

* If $t = \theta$, then $\tau(\theta) = \tau'(\theta) = 1$, then

θ becomes,

$$V(\theta) \geq - \frac{1}{E\left(\frac{\partial^2 \log L}{\partial \theta^2}\right)}$$

\Rightarrow min variance unbiased (e) = (MVUE)

Let x_1, x_2, \dots, x_n be a random sample from normal

pmf $f(x, \mu)$. Let $t = t(x_1, x_2, \dots, x_n)$ be an \mathbb{O} of θ such that,

a) $t = \theta$ (i.e.) t is an unbiased (e)

b) $V(t)$ is < than variance of any other unbiased (e), then t is the min variance unbiased (e) of θ .

\Rightarrow min variance unbiased (e) = (MVUE)

Let x be a random s.v with pdf $f(x, \theta)$ & let t be an unbiased (e) of

Lawe (e) or say $\tau(\theta)$, then variance of t is called min v. bounded (MVU).

as the (e) of $\tau(\theta)$ is true estimator attaining tiny bound for every θ in true parameter space → MVUE

D) Let x_1, x_2, \dots, x_n be a random sample from normal pmf with unknown mean μ & it non-variance σ^2 , find the C. rao lower bound for μ .

A) Lower bound $\rightarrow \frac{(\tau'(\theta))^2}{E\left(\frac{\partial^2 \log L}{\partial \theta^2}\right)}$

$$\text{normal distn. pdf } f(x, \mu) = \frac{1}{\sigma \sqrt{2\pi}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}, -\infty \leq x \leq \infty.$$

The likelihood (L),

$$L = \prod_{i=1}^n f(x_i, \mu)$$

$$= \prod_{i=1}^n \frac{1}{\sigma \sqrt{2\pi}} e^{-\frac{(x_i-\mu)^2}{2\sigma^2}}$$

$$L = \left(\frac{1}{\sigma \sqrt{2\pi}} \right)^n e^{-\frac{1}{2\sigma^2} \sum_{i=1}^n (x_i-\mu)^2}$$

$$\log L = \text{constant} - \frac{1}{2\sigma^2} \sum_{i=1}^n (x_i-\mu)^2$$

$$\frac{\partial \log L}{\partial \mu} = -\frac{1}{\sigma^2} \sum_{i=1}^n (x_i-\mu) \times -1$$

$$= \frac{1}{\sigma^2} \sum_{i=1}^n (x_i-\mu)$$

$$\left(\frac{\partial \log L}{\partial \mu} \right)^2 = \frac{1}{\sigma^4} \sum_{i=1}^n (x_i-\mu)^2$$

$$E\left(\frac{\partial \log L}{\partial \mu}\right)^2 = \frac{1}{n} E n (x_i-\mu)^2$$

$$= \frac{n}{\sigma^2} E ((x_i - \mu)^2)$$

$$= \frac{n}{\sigma^2} \text{Var}(x_i) = \frac{n}{\sigma^2} \sigma^2 = \frac{n}{\sigma^2}$$

$$\tau(\theta) = T(\theta) = 2.$$

$$\tau(\theta) = 0$$

$$\tau(\mu) = \mu.$$

$$T(\mu) = 1$$

$$\Rightarrow \frac{(\tau(\mu))^2}{E(\frac{\partial \log f}{\partial \mu})^2} = \frac{1}{n} = \frac{\sigma^2}{n}$$

(by lemma)

$$f(x, \lambda) = \frac{\bar{x}^n}{x!} \lambda^n, x=0, 1, 2, \dots$$

$$A) f(x, \lambda) = \frac{\bar{x}^n}{x!} \lambda^n$$

Likelihood (L),

$$L = \prod_{i=1}^n f(x_i, \lambda) = \frac{\lambda^n}{\prod_{i=1}^n x_i!} e^{-n\lambda} \lambda^{2x_i}$$

$$\begin{aligned} \log L &= \log (\bar{x}^n \lambda^n) - \sum \log x_i \\ &= -n\lambda + \sum_{i=1}^n \log \lambda - \sum \log x_i! \end{aligned}$$

$$\frac{\partial \log L}{\partial \lambda} = -n + \frac{\sum x_i}{\lambda}$$

$$= -n + \frac{n\bar{x}}{\lambda} = \frac{n}{\lambda} (\bar{x} - \lambda)$$

$$\text{Now } t = \bar{x}, t(0) = \gamma$$

$$A(0) = \frac{1}{\lambda}$$

$$\boxed{\frac{\partial \log L}{\partial \lambda} = [t - t(0)] \cdot A(0)}$$

$$V(t) = \frac{\tau'(t)}{\tau(t)} = \frac{1}{t} = \frac{n}{\lambda}$$

hence \bar{x} is MVUE with $V(\bar{x}) = n/\lambda$.

\Rightarrow Methods of ~~moments~~ estimation =

- a) methods of moments
b) " " of max likelihood.

c) methods of moments =

let X be a RV with PDF $f(x, \theta)$,
let M_x' be the r^{th} moment about origin

$$[M_x' = E(x^r)]$$

In general M_x' will be non 0 if θ

$$[M_x' = M_x'(\theta)]$$

let x_1, x_2, \dots, x_n be a random sample of size n drawn from the population with PDF $f(x_i, \theta)$, then r^{th} sample moment will be, $[M_x' = \frac{1}{n} \sum_{i=1}^n x_i^r]$

(in sample)

let $m_x' = M_x'$ to solve for θ . let $\hat{\theta}$ be the sol'n at θ , then $\hat{\theta}$ be the estimator obtained by the method of moments.

(P&O) \rightarrow

- * moment estimators are asymptotically unbiased.
- * they are consistent estimators.
- * they are fairly general conditions, true under moment estimators are

asymptotically normal.

Q) Estimate ' \hat{p} ' in the Sampling from binomial

(P) $f(x_1, \dots, x_n; p) = \prod_{i=1}^n p^{x_i} (1-p)^{1-x_i}$, $x=0, 1, 2, \dots, n$ by method of moments?

A) Take a random sample x_1, x_2, \dots, x_n from the binomial (p)

$$\begin{cases} M_x' = e^p \\ M_x'' = \frac{1}{n} \sum x_i \end{cases} \quad \begin{cases} m_1' = p \\ m_2' = p(1-p) \end{cases}$$

binomial dist'n
law $\Rightarrow m_1' = np$

$$m_1' = \frac{1}{n} \sum x_i = \bar{x}$$

$$np = \bar{x}$$

$$p = \bar{x}/n$$

$$\text{Then } \hat{p} = \bar{x}/n$$

D) Method of max likelihood =

Suppose that x is a rv x_1, x_2, \dots, x_n is dig of x . having the pdf $f(x, \theta)$ also x_1, x_2, \dots, x_n are observed sample values

then the likelihood $L(\theta)$ is

$$L(x_1, x_2, \dots, x_n, \theta) = f(x_1, x_2, \dots, x_n, \theta) = f(x_1, \theta) f(x_2, \theta) \dots f(x_n, \theta)$$

$$L(x_1, x_2, \dots, x_n, \theta) = \prod_{i=1}^n f(x_i, \theta)$$

The likelihood $L(\theta)$ can also be denoted as $L(x, \theta)$ or $L(\theta)$.

The prob of finding the max likelihood

estimator is the prob of finding $L(\theta)$.
the value of θ that maximizes $L(\theta)$.
It there exist a $\theta = \hat{\theta}(x_1, x_2, \dots, x_n)$ of the sample values which maximizes L for values in θ , then $\hat{\theta} \rightarrow$ max likelihood estimator of θ ($\hat{\theta}_{MLE}$)

Thus $\hat{\theta}$ is a soln, if any of $\frac{\partial L}{\partial \theta} = 0$ if

likelihood $\rightarrow L(\theta)$

$$\frac{\partial^2 L}{\partial \theta^2} < 0$$

L is max at the same value of θ . Thus $\hat{\theta}_{MLE}$ is the soln of the eq.

$$\frac{\partial \log L}{\partial \theta} = 0, \text{ provided } \frac{\partial^2 \log L}{\partial \theta^2} < 0$$

In test case, we must find the value of parameters that maximise the likelihood

of θ .

C).

$$L(x, \theta) = \prod_{i=1}^n f(x_i, \theta)$$

$$\frac{\partial L}{\partial \theta} = 0 \quad \left. \frac{\partial^2 L}{\partial \theta^2} < 0 \right\} \text{Roughly condition } L(\hat{\theta}, \theta) \text{ max condn.}$$

(P.S.) \rightarrow
MLE are consistent.

- * MLE are consistent.
- * The distribution of MLE tends to normality for large samples.

- * MLE is most efficient.
- * MLE is sufficient, it suffices.

exist.

- * MLE are non-necessarily unbiased.
- * MLE have invariance property.

- t mle of θ $\{ \text{then} \}$ inaccuracy (pro)
- g(t) mle of $g(\theta)$

$$\frac{1}{\lambda} = \frac{n}{\sum x_i}$$

$$\bar{x} = \frac{\sum x_i}{n} = \bar{x}$$

) find the max likelihood (e) of poisson
Param λ of poission distri..

A) $f(x, \lambda) = \frac{e^{-\lambda} \lambda^x}{x!} \quad x = 0, 1, \dots, n \quad \lambda > 0.$

~~L(x)~~ =

The likely hood (e) of random sample
 x_1, x_2, \dots, x_n of observations from this
sample is

$$\begin{aligned} L(x, \lambda) &= \prod_{i=1}^n f(x_i, \lambda) \\ &= \frac{e^{-\lambda}}{x_1!} \cdot \frac{e^{-\lambda} \lambda^{x_1}}{x_2!} \cdot \frac{e^{-\lambda} \lambda^{x_2}}{x_3!} \cdots \frac{e^{-\lambda} \lambda^{x_n}}{x_n!} \\ &= e^{-n\lambda} \cdot \lambda^{x_1} \cdot \lambda^{x_2} \cdots \lambda^{x_n} \\ &\quad \frac{1}{x_1! \cdot x_2! \cdots x_n!} \end{aligned}$$

hence \bar{x} is the mle

$$\begin{aligned} \frac{\partial \log L}{\partial \lambda} &= -n + \sum_{i=1}^n x_i \\ \frac{\partial^2 \log L}{\partial \lambda^2} &< 0 \end{aligned}$$

$$\bar{x} = \frac{\sum x_i}{n}$$

$$\begin{aligned} \bar{x} &= \frac{\sum x_i}{n} \\ \sum x_i &= \bar{x} n \end{aligned}$$

= Least squares estimators :-

usually this method is used to fit a curve at the curve $y = f(x_1, a_0, a_1, a_2, \dots, a_n)$
where a_i 's are unknown parameters to a
set of 'n' sample observations (x_i, y_i)
 $(x_1, y_1), \dots, (x_n, y_n)$ from a bivariate population,
 $\check{y} = \log \sum_{i=1}^n a_i x_i + \log a_0$ ——————
 $\sum_{i=1}^n \log a_i x_i!$
 $\log a_0 = -n\lambda + \sum x_i \log \lambda - \frac{1}{2} \sum \log x_i!$

By the method of least squares we
minimise the sum of squares of the
error to the observed or estimated
values given by,

$$S = \sum_{i=1}^n (y_i - f(x_i, a_0, a_1, \dots, a_n))^2$$

$$\frac{\partial S}{\partial a_j} = -n + \frac{\sum x_i}{\lambda} = 0$$

$$J = ?$$

object to variations in $(\alpha_0, \alpha_1, \dots, \alpha_n)$
for S is to be min we have

$$\left[\frac{\partial S}{\partial \alpha_i} = 0 \right] \text{ for } i=0, 1, 2, \dots, n$$

This one \rightarrow Normal eqs.
Solving this eqs, we get the least square
 $\hat{\alpha}_0, \hat{\alpha}_1, \dots, \hat{\alpha}_n$.

\Rightarrow Method of min Variance :-

Let x_1, x_2, \dots, x_n be a sample drawn
from a (P) with pdf $f(x, \theta)$, then
the likelihood L is,

$$L = \prod_{i=1}^n f(x_i, \theta)$$

The prob is to find a statistic
 $t = t(x_1, x_2, \dots, x_n)$ such that

$$e(t) = \int_L t L dx = \mathcal{Y}(\theta)$$

$$\Rightarrow e(t) = \int_L (t - \mathcal{Y}(\theta))^2 L dx = 0 \quad \text{---}$$

$$\Rightarrow V(t) = \int_L (t - e(t))^2 L dx$$

$$= \int_L (t - \mathcal{Y}(\theta))^2 L dx \quad \text{---} \quad \text{is min}$$

In other words, we have to minimise ---
subject to the condition ---

$$\text{here } \int_a^b dx = \int_a^b \int_a^b \dots dx_1 dx_2 \dots dx_n$$