

Module - III

Memory & File Management

classmate

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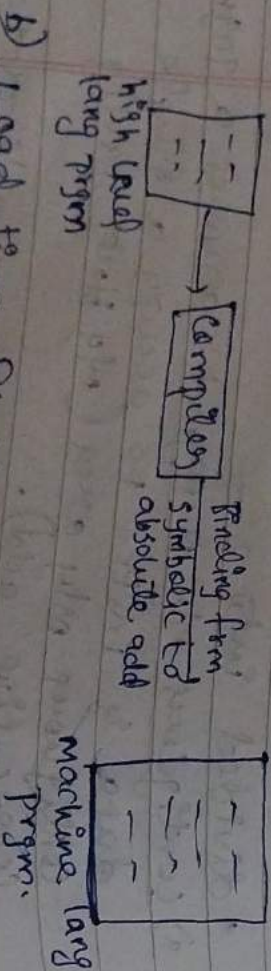
⇒ Memory Management:

- * Mly managmnt module of os is concerned with the managmnt primary mly.
- * manages primary mly & moves processes back & forth b/w main mly & disk during execution.
- * It checks how much mly is to be allocated to processes.
- * CPU fetches instr. from mly according to the value of the prog. counter.
- * main aim of this is to achieve efficient utilization of mly.
- * It is required
 - ↳ to minimize fragmenⁿ issues
 - ↳ to maintain data integrity
 - ↳ to proper utilization of main mly.
- * divided into 2 —
 - a) Contiguous mly managmnt: assumes a prog's data & instr. to occupy a single contiguous mly area (mly blocks having consecutive add).
 - b) Non-contiguous mly.m: a prog's data & instr. may occupy many non-contiguous mly area (mly blocks hving non-consecutive add)

⇒ Background:

I Add Binding:

- * means mapping comp instr. & data to loc in RAM.
 - * high level prgm are loaded into mly by their execution in the CPU.
 - * mly management unit (MMU) translates logical add into physical add.
- Mapping a logical add to a physical add → add binding / add mapping.
- * 3 types -
- compile-time add - B:
- It the compiler is responsible for performing add binding then it is C-t-add. B.
 - It will be done before loading the prgm into mly.



- Load time Binding:
- It will be done after loading the prgm into mly.

- This type of add binding will be done by the OS mly manager.

c) Execution time binding:

- It will be postponed even after loading the prgm into mly.
- It is done by the processor at the time of prgm execution.

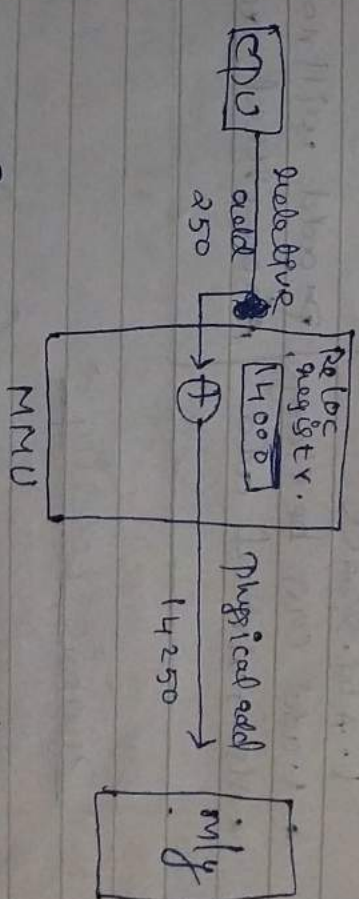


Fig: Load time binding.

II Logical vs Physical add space:

- | Logical add's | Physical add's |
|--|---|
| <ul style="list-style-type: none"> * It is a virtual add generated by CPU * User can view the logical add of prgm * User uses loaded to | <ul style="list-style-type: none"> It is a loc in mly unit. ~ never view Physical add of prgm User can not directly |

access the physical add.

- * I. add is generated by the CPU
- * Set of all I. add generated by CPU in reference to program is referred as I. add. space
- * I. add can be change
- * Also \rightarrow virtual add

access Physical add.

- * P. add is computed by MMU.
- * Set of P. add mapped to the corresponding I. add is referred as P. add. space.
- * P. add will not change
- * Also \rightarrow real add.

III. Dynamic Loading :

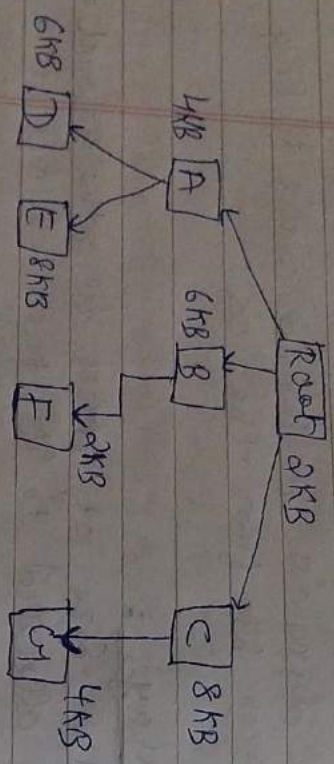
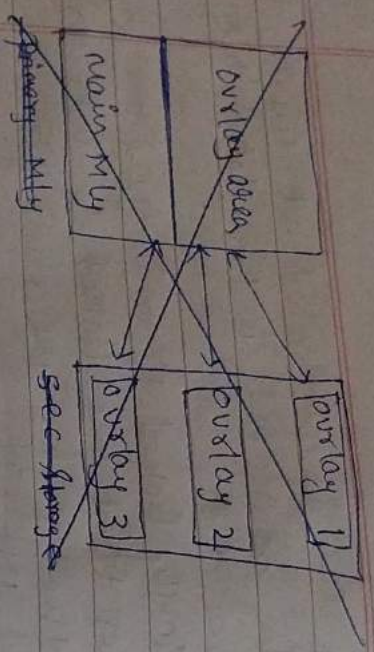
- * Also \rightarrow load on call (LORAC)
- * A routine is not loaded until it is called
- * All routines are kept on disk in a relocatable load format.
- * ADV \rightarrow unused routine is never loaded.
- * does not require special Spt. from the OS.
- * Dynamic linking : process of collecting & combining various pieces of code & data into a single relocatable file from multiple obj files.

* Linking can be performed at compile time, when the source code is translated into machine code.

- * Dynamically linked libraries (DLL) are system libraries that are linked to user program when the program are run. Also \rightarrow shared libraries.
- * Unlike dynamic loading, dynamic linking requires help from the OS.

IV. overlays :

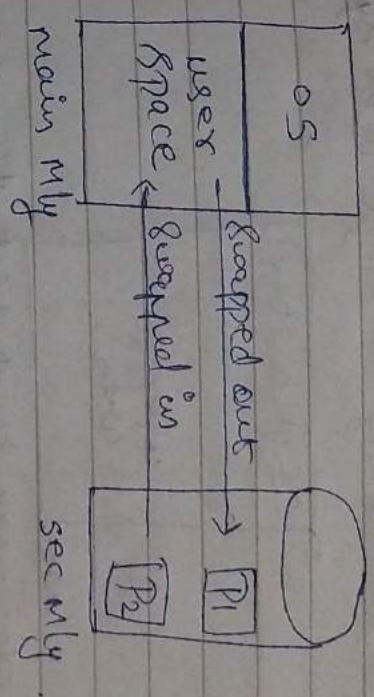
- * If the size of process is $>$ the amount of memory allocated to it, then overlays are used to execute such program.
- * An overlay is a part of program, which has the same load origin as some other parts of the program.
- * used to reduce the main memory req. of a program.
- * A program containing overlays is \rightarrow an overlay-structured program \rightarrow consists of a permanently resident portion \rightarrow rest is set of overlays.
- * ADV \rightarrow using less memory
- * also ADV \rightarrow faster since programing easy.



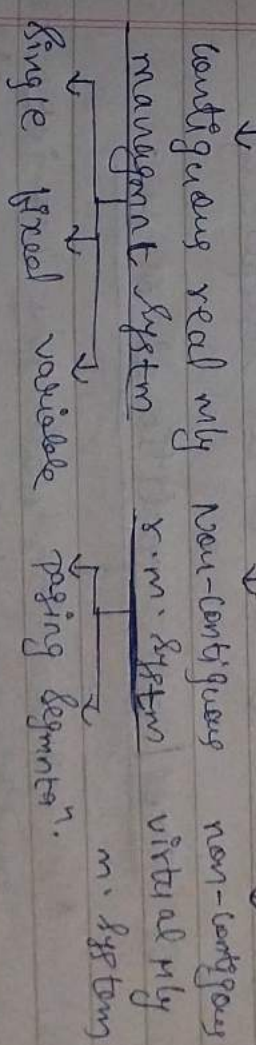
Sweeping :

- * Temporary removal of suspended processes from mly to sec & storage disk & then subsequent bringing back \rightarrow (S).
- * 3th responsibility -
- selection of CP to swap out
- " " " swap in
- Allocation & management of swap space
- * size of main mly is limited.
- * once a CP is selected for swap out,

the swapper begins to swap it out. It has traditionally been used to implement multiprogramming systems.



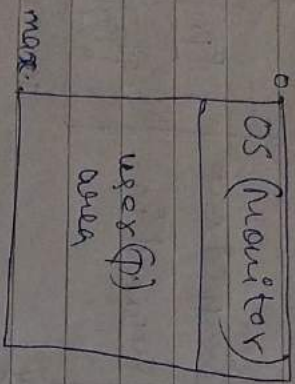
* mly management schemes / techniques



I contiguous mly Allocation :

- 1) Single c.m. management :
- * Here, the physical mly is \div into 2 contiguous areas.
- * It is simple & easy. Basically the OS needs to keep track of the first & last

- loc. available for allocation to user P.
- * A new user (P) may be activated upon termination of the running (P).
- * ~~only~~ partitioning in single user system -

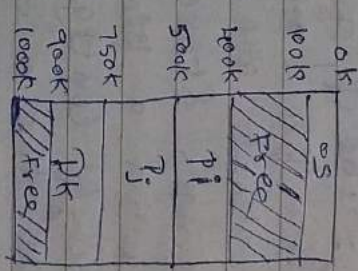


- * A single way to protect the OS code from user program is to place the OS in ROM.
- * Adv \rightarrow it lies in its simplicity.

2) Fixed/Static partitioned M.M :

- * In c.p. allocation, main memory is \div into several partitions. Depending on how partitioning are created & modified, only partitioning may be static / dynamic.
- * In static P. only management scheme, the available memory is logically \div into several partitions during system generation (P). These partitions could be of different sizes & cannot be changed.

- * 1 (P) may be executed out of a given partition at any time, the no. of distinct partitioning represents an upper limit on the no. of active (P)s in a system. This figure \rightarrow degree of multiprogramming.



3) Dynamic variable P. mly. m :

- * It was developed to overcome some of the problems associated with fixed P. mly. m like program of internal fragmentation, restrictions of degree of multiprogramming, the no. of partitions & their sizes are variable, partitions are not defined at the time of system generation.
- * partitions are defined dynamically in accordance with the req. of incoming (P)s.
- * here, OS must keep track of both partitions & free memory.
- * (common cell) for selection of a free area

of mly for creation of a partitioning -
 * first-fit, next-fit
 * best-fit
 * worst-fit.

4) Fragmentation: The ϕ of dividing a comp file such as data file | an executable pg file into fragments - that are stored in diff parts of a comp's storage medium.
 * This can hpn when a file is too large to fit into a single contiguous block of free space on the medium

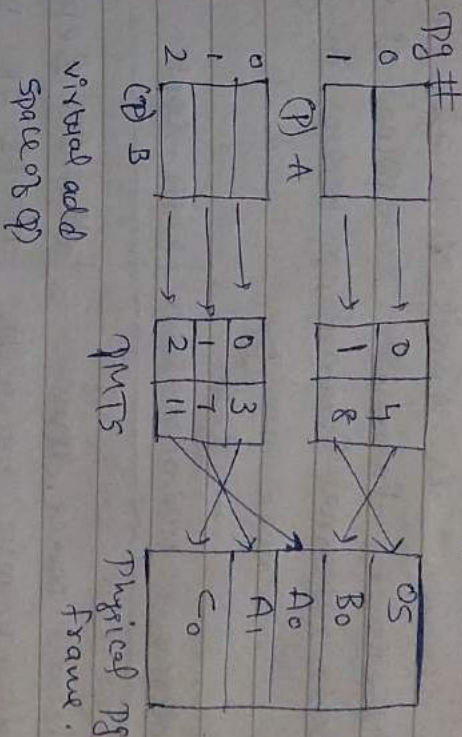
* 2 types -
 a) Internal (ϕ): occurs when there is unused space within a mly block.
 b) External (ϕ): occurs when a storage medium has many small blocks scattered throughout it.

II Non-Contiguous Mly m:

1) Paging:

* mly m. scheme that removes the req. of contiguous allocation of physical mly.
 * Add mapping is used to maintain the illusion of contiguity of virtual add space of a (p).

* Basically, physical mly is \div into num of fixed-size slots \rightarrow page frames
 * virtual add space of a (p) is also split into fixed size blocks of same size \rightarrow pgs



* Adv \rightarrow reduced fragmⁿ \rightarrow Drawn \rightarrow used complicity \rightarrow mly thrashing
 \rightarrow efficient use of mly

2) Segmentation:

* Allows breaking of the virtual add space of a single (p) into variable sized logical blocks \rightarrow segments.
 * A segment can be obtained as a logical grping of info.
 * segments are formed at prog translation time by grping together the logically related items.

- | | |
|-----------------------------|------------------------|
| * contiguous mly allocation | non-contiguous mly. A. |
|-----------------------------|------------------------|

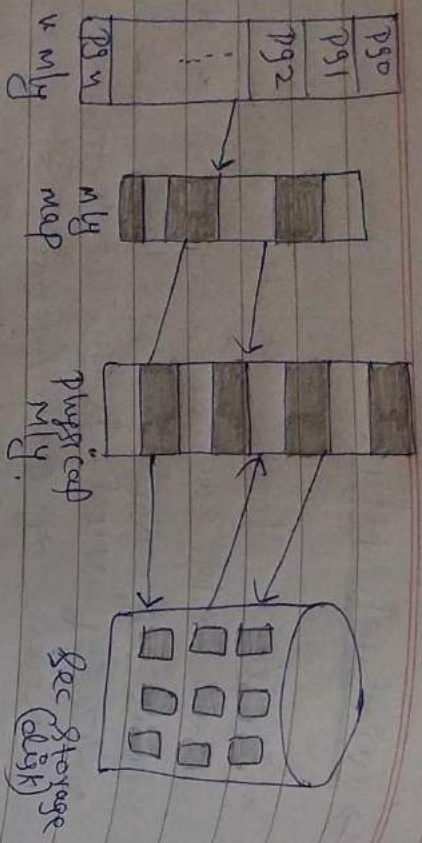
→ Virtual mfg:

- * Demand Pging :

As the no. of PPs & no. of Pgs. in mainly for each PP rose, at some point of time, all Pg frames became occupied.

Only management with
attendance policy.

- * Adv - as program, more efficient use of mly
 - * Dis - complex hardware & s/w required.
- ↳ possibility of thrashing must be handled at design stage.



⇒ Page Replacement :-

* In an OS that uses paging for mly management a pg replacement (al) is needed to decide which pg needs to be replaced when a new pg comes in.

* A pg fault hps when a running pgn accesses a mly pg that is mapped into the virtual add space bt not loaded in physical mly. Since actual physical mly is much smaller than virtual mly, pg fault hps.

I FIFO Pg.R :-

Simplest P.R (al). here, OS keeps track of all pgs in the mly in a queue, the oldest pg is in the front of the queue. When a pg needs to be replaced pg in the front of the queue is selected for removal.

pg fault → ~~pg~~ → pg which is not present in the main mly
pg hit - (hit) → " eg present "

reference	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
reference str	1	0	1	2	0	3	0	4	2	3	0	3	1	2	0
pg found	1	1	1	2	2	2	2	4	4	4	0	0	0	0	0
"	1	0	0	0	0	3	3	3	2	2	2	2	1	1	1
"	2	1	1	1	1	1	0	0	0	3	3	3	3	2	2

pg fault → main mly full so pg. 12 hpus, so according to FIFO, 1 swapped to disk

② - here 0 is already present in reference str so write like this. (i.e) hit

now of pg hits → 3

$$\text{hit ratio} = \frac{\text{now of hits}}{\text{total no. of refnces}} = \frac{3}{15} \times 100 = 20\%$$

now of pg faults → 12

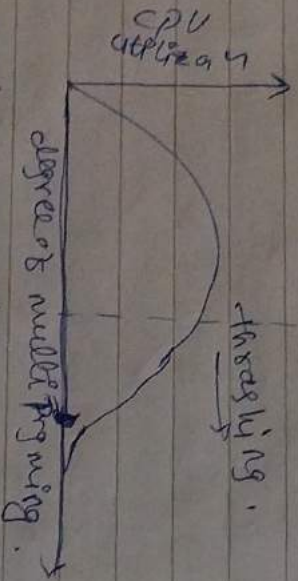
$$\text{pg faults ratio} = \frac{\text{now of pg faults}}{\text{total no. of refnces}} = \frac{12}{15} \times 100 = 80\%$$

II LRU (least recently used) pg.R :-

* Here, pg will be replaced which is least recently used.
* It belongs to a long cls of stack replacement (al).
* eg →

→ Thrashing:

- * A situation when system is spending most of the time in servicing pg fault (swapping) than executing the actual process
- * occurs when a comp's virtual mly resources are overused, leading to pg faults
- * Bcz of thrashing, cpu utilization is going to be reduced



- * (ad) during thrashing → global pg.R
↳ local pg.R.

* Causes of thrashing:

- If cpu utilization is too low, we rise the degree of multiprogramming by introducing a new system. A global pg.R (ad) is used.
- CPU utilization is plotted against degree of m.p
- As degree of m.p rise, CPU utilization also rises

- * Techniques to prevent thrashing:
1) Locality model (3) pg fault trace
2) working-set model

⇒ Files:

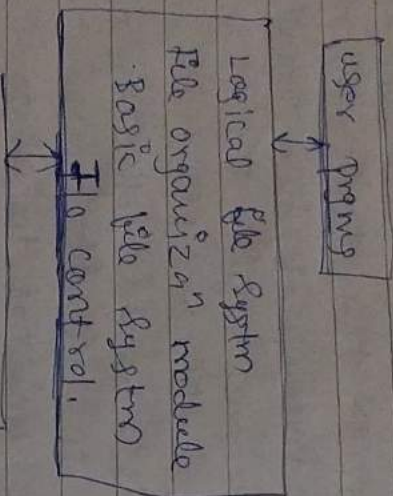
- * The file management module of OS → F.Systm
It provides the resource abstraction typically associated with sec storage.
- * It hides all the device specific aspects of file management from user.
- * F.Systm maps files to physical media & accesses these files via storage device.
- * A file is a named collection of logically related info & it is the smallest allotment unit of logical sec storage.
- * Objectives → minimizes the chances of lost / destroyed data.

→ provide I/O syst for multiple users
→ provide I/O syst for a variety of storage device types.

- * (1) → create file, file space on disk
→ write to file
→ read from file
→ alt directory entry
→ reposition: move read/write position.

→ File System Stx:
needs to be predefined format in such a way that an OS understands.

* 3 types in OS → 1st file → series of char
 2nd file → " of bytes
 3rd source file → " of 1's & 0's.



- a) File control level consist of device drivers & interrupt handlers to transfer info b/w the main mty & the disk system.
- b) Basic file system deals with blocks of data that are exchanged with disk tape system.
- c) File organization module knows about files & their logical blocks. Each file's logical blocks are numbered from 0 to N.
- d) Logical file system manages metadata info. Metadata includes all of the file system str except the actual data.

II File organization:

* Refers to logical structuring of the records as determined by the way in which they are accessed.

* "map file organization" techniques are—
 1) file file org → data are collected in the order in which they arrive.

The purpose of file is simply to accumulate the mass of data & save it.

a) sequential file org → here, a fixed format is used for rec. The key field uniquely identifies the rec, thus key values for diff rec are always diff.

3) Indexed sequential file org → maintaining the key characteristic of the sequential file, rec are organized in sequence based on a key field.

4) Indexed file org → used mostly in appln where themselves of info is critical & where data are rarely processed.

5) Direct / Hashed file org → direct file makes use of hashing on the key value. This was explained in Appendix 8A. They used where rapid access is required.

III File Allocation:

- on sec storage, a file consists of a collection of blocks.
- The OS is responsible for allocating blocks to files. This raises a management issue.
- 1) space on sec storage must be allocated to files
- 2) it is necessary to keep track of the space available for allocation.
- with variable-size portions, we need to be concerned with "fragm" of free space, possible alternative strategies are First fit, best fit & nearest fit.
- 3 major methods for ~~the~~ allocating sec storage space are—
- 1) Contiguous F.A:
 - here each file occupies a contiguous set of blocks on the disk,
 - directory entry for a file with c. f. a contains \rightarrow add of starting block
 - length of allocated portion,
 - Adv \rightarrow both sequential & direct access are sytmd by this.
 - Dis \rightarrow fixing file size is difficult

2) Linked list / chained non c. f. a:

- here, each file is a linked list of disk blocks which need not be contiguous.
- The disk blocks can be scattered anywhere on the disk.
- The directory entry contains a pointer to the starting & the ending file block.
- Adv \rightarrow very flexible in terms of size.

3) Indexed F.A:

- here, a single block known as index block contains the pointers to all the blocks occupied by a file.
- Each file has its own index block.
- Adv \rightarrow It overcomes the probm of "ext fragm"
- Dis \rightarrow pointer overhead for indexed FA is $>$ linked allocation.
- Allocation may be on the basis of either fixed-size blocks / variable-size portions.

IV Free-Space management:

- It is a critical aspect of OS as it involves managing the available storage space on the hard disk/sec devices.
- To keep track of free-disk space,

the OS maintains a free-space list.

- * when a file is deleted, its disk space is added to the free-space list.
- * free-space list can be maintained by OS by following ways —

1) Bit vector:

- here, each block is represented by 1 bit.
- If the block is free, the bit is 1, if the block is allocated the bit is 0.
- A bit table has the adv that it is easy to find 11 a contiguous grp of free blocks.

2) Linked list:

- It is to link together all the free disk blocks, keeping a pointer to the first free block in a spc loc on the disk.
- This scheme is not efficient, to traverse the list, we must read each block.

3) Grouping:

- Stores the add of the free blocks in the 1st free block.
- 1st free block stores the add of some say n free blocks. out of these n blocks, 1st n-1 blocks are free & last block contains the add of next free blocks.

2) Counting:

- Stores the add of 1st free disk block & a no. of free contiguous disk blocks that follow the 1st block.
- Every entry in the list contains —

1) add of 1st free disk block

2) A no. n.

- * adv — faster access to free blocks
- ↳ easy to implement
- * dis — limited scalability.
- ↳ our head is at risk of data loss.