

Lab Notebook - Calvin Lee (calvinl4)

Date: 8/30

Objective: Brainstorm ideas for what we could do for our project

Several ideas were presented, and we all posted our ideas onto the website where necessary.

My idea that I wanted to push forward with is a computer vision based lock system that unlocks a door based on facial recognition. Another idea I had was to track a basketball shot and measure certain statistics about it to help the shooter have a better way to analyze their shot.

Date: 9/5

Objective: Finalize a plan for which idea we want to go through with

Of all of our project proposals, two got approved. We had one idea that was to correct the form of gym goers, and another one to measure the availability at the arc. The one we decided to go with is the availability idea, and to use a motion sensor to recognize whether or not someone is actually at the arc, and to transmit this data through a raspberry pi to a webserver.

Date: 9/7

Objective: Make changes to our idea to reflect what Professor Arne said.

He mentioned how it wouldn't make much sense to have a whole sensor system just to measure availability as it would be too complex for no reason. We ended up deciding on using a button for the initial signal, and to use a PIR sensor as a failsafe just in case the user forgets to push the button.

Date: 9/12

Objective: Start writing project proposal

We spent most of this time writing up our project proposal and finalizing some ideas about how we wanted to carry out our project. This is where we decided on our subsystems:

- machine sensor pcb to IoT device
- IoT device to AWS Server
- AWS Server to website
- load sensor to alarm

We also decided on using specific parts.

Gikfun button:

https://www.amazon.com/Gikfun-Waterproof-Button-Momentary-Arduino/dp/B07F8GBWGG/ref=asc_df_B07F8GBWGG/?tag=hyprod-20&linkCode=df0&hvadid=343224601369&hvpos=&hvn etw=g&hvrnd=2325432847971158710&hvpone=&hvptwo=&hvqmt=&hvdev=c&hvdvcmdl=&h vlocint=&hvlocphy=9022196&hvtargid=pla-757057055269&psc=1&tag=&ref=&adgrpid=707373 52522&hvpone=&hvptwo=&hvadid=343224601369&hvpos=&hvnetw=g&hvrnd=23254328479 71158710&hvqmt=&hvdev=c&hvdvcmdl=&hvlocint=&hvlocphy=9022196&hvtargid=pla-757057 055269

Alarm to alert the user if they dont press the button:

https://www.digikey.com/en/products/detail/tdk-corporation/PS1440P02BT/2236832?utm_adgroup=Alarms%2C%20Buzzers%2C%20and%20Sirens&utm_source=google&utm_medium=cpc&utm_campaign=Shopping_Product_Audio%20Products_NEW&utm_term=&utm_content=Alarms%2C%20Buzzers%2C%20and%20Sirens&gclid=Cj0KCQjw39uYBhCLARIsAD_SzMrocrG56djQZdtSr1banc2WuquRuRWNwZ3Xb1x-w5BqNdJqJw-9-HQaAjB5EALw_wcB

A network card to communicate with the raspberry pi:

<https://www.espressif.com/en/products/socs>

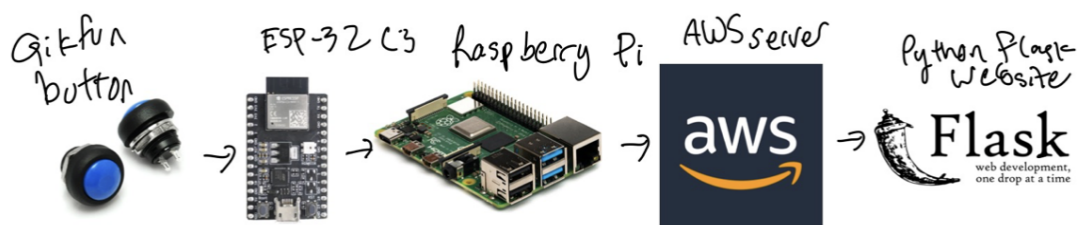
AWS to manage databases and cloud connections:

<https://docs.aws.amazon.com/iot/latest/developerguide/connecting-to-existing-device.html#gs-device-view-msg>

Date: 9/14

Objective: Finalize Project Proposal

Finalized proposal and added diagrams and pictures to support the presentation.



Decided on these high level requirements:

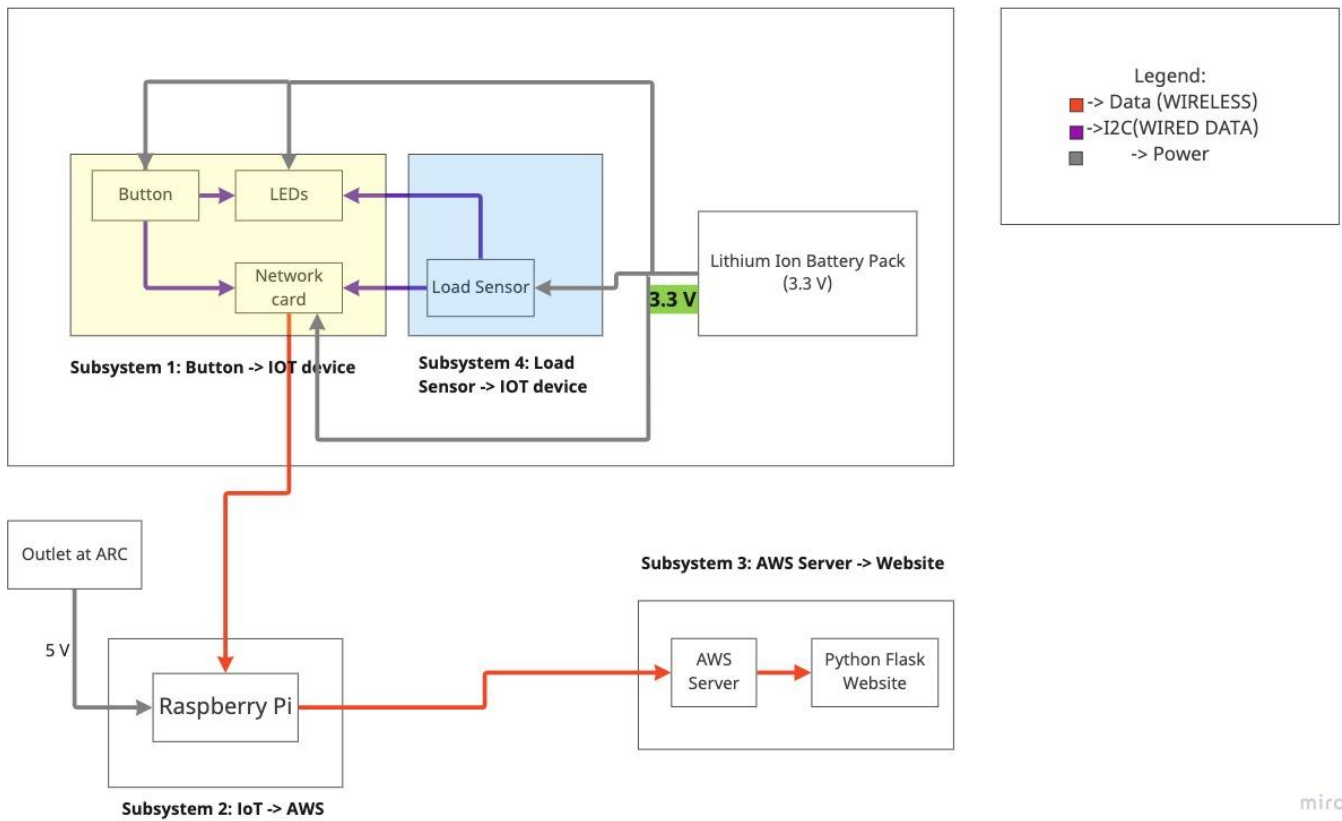
Battery Life: PCB should be able to last for multiple hours without a direct power source.

Multiple Machines Serviced: Our system will be able to support up to 5 machines being used.

Website Access: Multiple people will be able to access the website at one time

Designed our first draft block diagram with connections and subsystems labeled:

PCB



We decided on removing the alarm from the equation as we realized that it is not that practical of a feature.

References:

MQTT document:

<https://diyi0t.com/microcontroller-to-raspberry-pi-wifi-mqtt-communication/>

External battery for PCB:

https://www.google.com/shopping/product/589828306654039066?q=external%2Bcircular%2Bbattery%2Bfor%2Bpcb&client=safari&rls=en&sxsrf=ALiCzsZaA5BHehX59EQpairvZOfehFTwg%3A1663275125169&biw=1440&bih=735&dpr=2&prds=eto%3A2725741664819496371_0%2Clocal%3A1%2Cpid%3A1185675488743134041%2Cprmr%3A2%2Crsk%3APC_10260653902913479911&sa=X&ved=0ahUKEwiX2P6R15f6AhXpjlKEHVIACSgQ8wlluBE

Battery holders:

https://www.te.com/usa-en/product-2-1775485-1.html?te_bu=Cor&te_type=srch&te_campaign=ggl_usa_cor-ggl-usa-srch-smbmktg-fy22-googlefeed_sma_sma-2210_2&elqCampaignId=115724&mkwid=VDybDFVR%7Cpcrid%7C386964346943%7Cpkw%7C%7Cpmt%7C%7Cpdv%7Cc%7Cslid%7C%7Cproductid%7C2-1775485-1%7Cpgrid%7C78782457763%7Cptaid%7Cpla-298884436745%7C&utm_content=VDybDFVR%7Cpcrid%7C386964346943%7Cpkw%7C%7Cpmt%7C%7Cpdv%7Cc%7Cslid%7C%7Cproductid%7C2-1775485-1%7Cpgrid%7C78782457763%7Cptaid%7Cpla-298884436745&gclid=Cj0KCQjwmouZBhDSARIsALYcourXPqfM1fucoo39DQsdyYPBcSBieWtgXxXjzOOox1Y1Peppnti2pEOaAkw-EALw_wcB

Date: 9/19

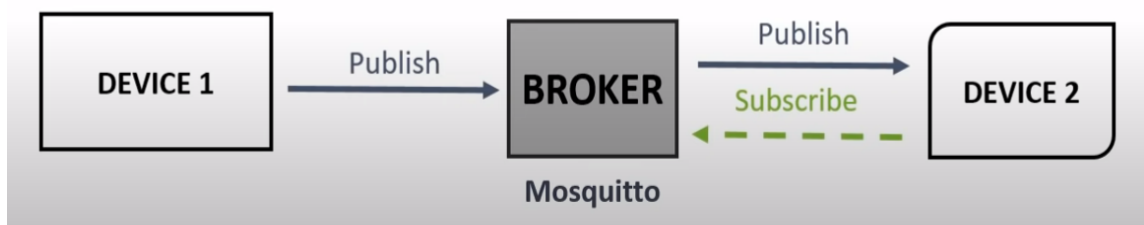
Objective: Begin first draft of Design document

Started writing the design document. One of the main differences from the project proposals is its inclusion of the requirements and verifications tables, or R/V tables for short. Here is an example:

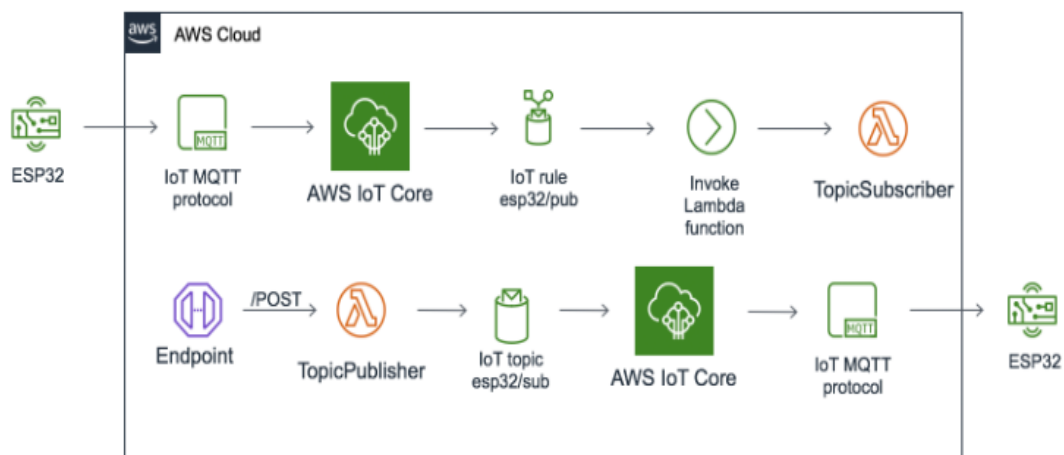
| Button Requirements | Verification |
|--|--|
| <p>Requirement 1: A button press should be able to send a MQTT packet to our IoT device.</p> | <p>Verification 1: On our IoT device, which will act as a MQTT server, we can verify what devices are requesting information on it, by a simple command on the IoT device.</p> |
| <p>Requirement 2: When a user presses the button to use the ARC machine, the red LED should light up to signify the machine is in use.</p> | <p>Verification 2: This can be easily verified by pressing the button on our system and visually checking the activation of the red led.</p> |
| <p>Requirement 3: When a user presses the button to use the ARC machine, the green LED should light up to signify the machine is not in use.</p> | <p>Verification 3: This can be easily verified by pressing the button on our system and visually checking the activation of the green led.</p> |
| <p>Requirement 4: Multiple machines must be able to send messages simultaneously</p> | <p>Verification 4: on the IoT device command line can be used to check what devices are trying to send messages to the device</p> |

| | |
|--|---|
| Requirement 5: Control subsystem should last 4 days without being recharged. | Verification 5: We will conduct tests to make sure the Control subsystem can last 4 days. |
|--|---|

This is a model of the MQTT publish/subscribe model that we will be using to communicate from the ESP-32 to the Raspberry PI



This is a model of how the AWS system will connect with our ESP-32 to update our database whenever a new availability signal is sent from the user.



We decided on using lithium ion batteries as they would be able to be recharged, causing less effort necessary on the ARC workers' end. In this way, they will only have to recharge with a USB-C cable, rather than needing to replace the batteries once the device dies. We did some preliminary battery life testing and came up with the result that our device should last about 5 days before it needs to recharge. This is the power calculations table:

| Component | Power Consumption | Power Consumption (5 days) |
|------------------------|--------------------------|----------------------------|
| Button | - | - |
| ESP32 | 55 mA * 17 hrs * 5 days | 4675 mAh |
| Battery Life Indicator | 10 mA * 17 hrs * 5 days | 850 mAh |
| LEDs | 12mA * 17 hrs * 5 days | 1020 mAh |
| PIR Sensor | 0.1 mA * 17 hrs * 5 days | 8.5 mAh |
| | | Total: 6553.5 mAh |

During this meeting, we also started to finalize the initial list of parts that we wanted to buy for our PCB. This includes a FireBeetle ESP-32 (which was chosen for its deep sleep capabilities), sensors, and all of our power subsystem components. The following is the table of all the items and how much they cost.

| Description | Manufacturer | Quantity | Extended Price | Link |
|--------------------------------|-------------------|----------|----------------|------------------------------|
| FireBeetle 2 ESP32-E MCU | FireBeetle | 2 | \$8.90 | link |
| Raspberry Pi 3 - Model B | Adafruit | 1 | \$35.00 | link |
| 12mm Button | Gikfun | 1 | \$8.78 | link |
| 5x Stemedu HC-SR501 PIR Sensor | Stemedu | 1 | \$9.99 | link |
| RGB LEDs | Adafruit | 1 | \$3.95 | link |
| 5x AM312 PIR Sensor | Aideepen | 1 | \$9.59 | Link updated |
| Rechargeable 18650 Battery | Panasonic | 4 | \$4.99 | link |
| Raspberry Pi 3 Power Adapter | Canakit | 1 | \$9.95 | link |
| 2x18650 Battery Holder | E-outstanding | 1 | \$8.99 | link |
| BQ2057CTS Charge Controller | Texas Instruments | 4 | \$1.56 | link |

| | | | | |
|---------------------------------------|----------|---|--------|----------------------|
| TP4056 USB C Li-Ion Charger Module | diymore | 1 | \$9.59 | link |
| 8GB Micro SD Card for Raspberry Pi | Verbatim | 1 | \$6.19 | link |
| MAX1797EUA+ | | | | |

Date: 10/5

Objective: Begin initial PCB design

Everyone in our group are computer engineers so none of us have ever made a PCB before. The PCB design homework was helpful, but did not give much intuition behind why we were doing the things that we were doing. This process was very time consuming, and we still have not really gotten too much done today. Mostly worked on trying to find and import footprints from different websites for all of the parts that we wanted in our PCB. We also found out that there were many parts that did not already have a footprint available on the web, necessarily forcing us to make these footprints on our own. These footprints are very crucial to the finished product, and any small mistake can make the parts impossible to solder onto the PCB.

Date: 10/6

Objective: Finish custom footprints and finish schematic

We were able to import all of our new custom footprints as well as all of the other footprints that are required. Today we started researching heavily into the peripheral components

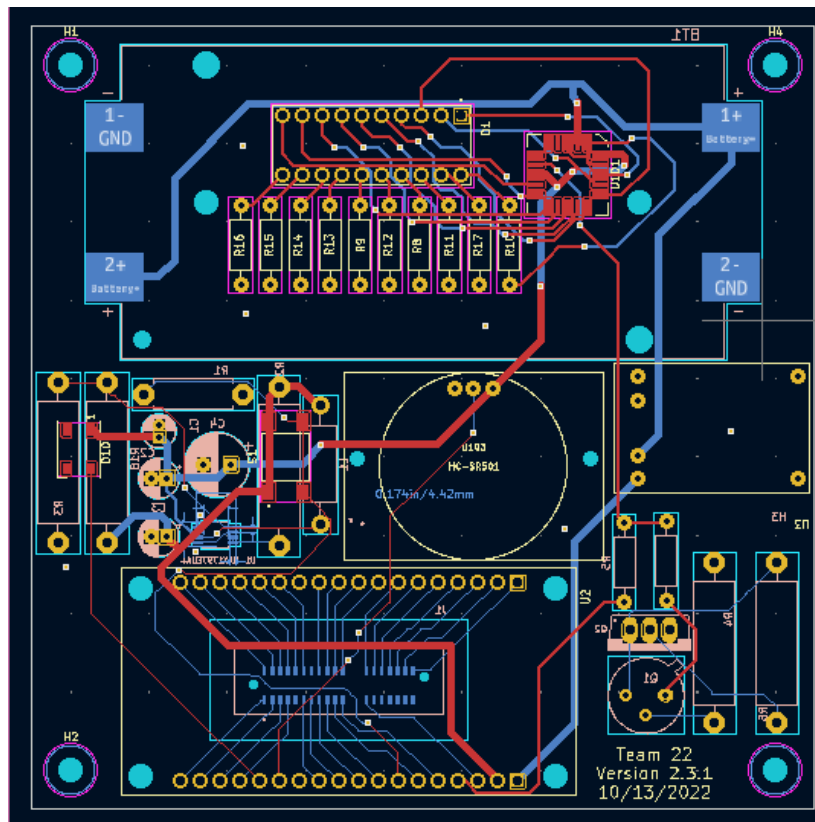
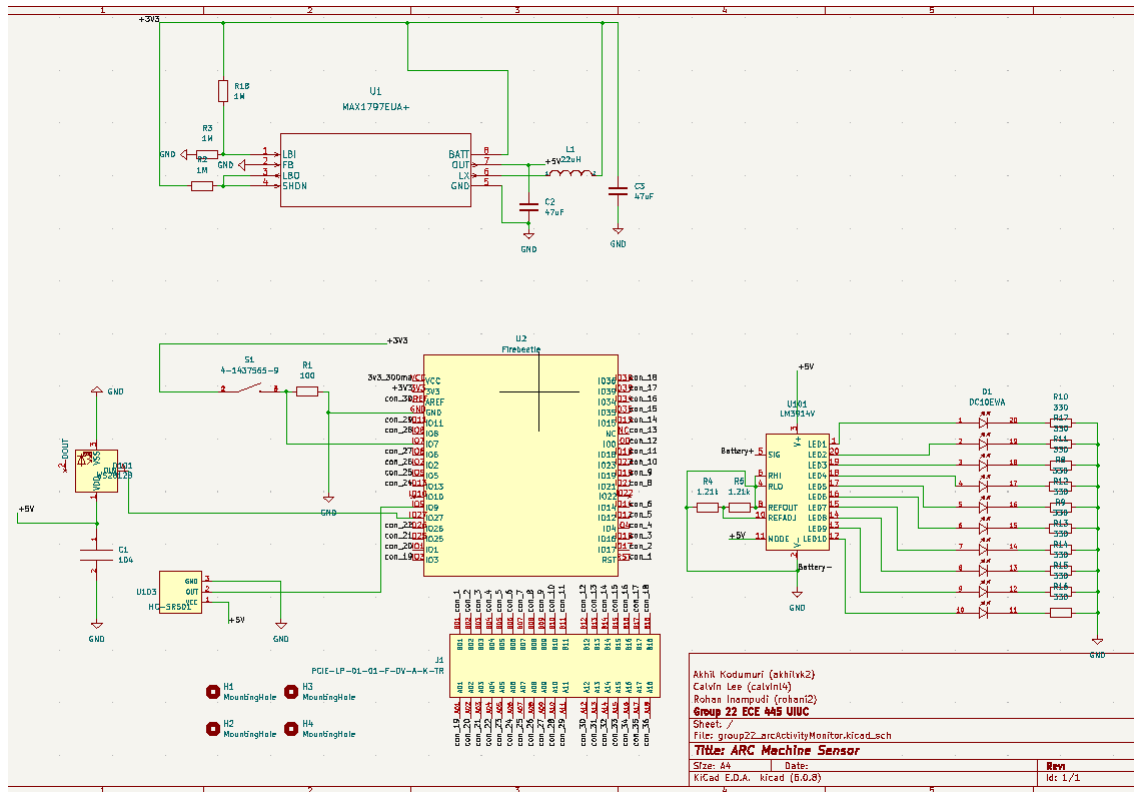
required around our main parts. We learned how to utilize datasheets extensively for real applications, such as looking at the typical applications portion of the datasheet to see what other parts (resistors, capacitors, inductors) are necessary for the part to function in the application that we wanted. We started compiling a full parts list including these additional parts.

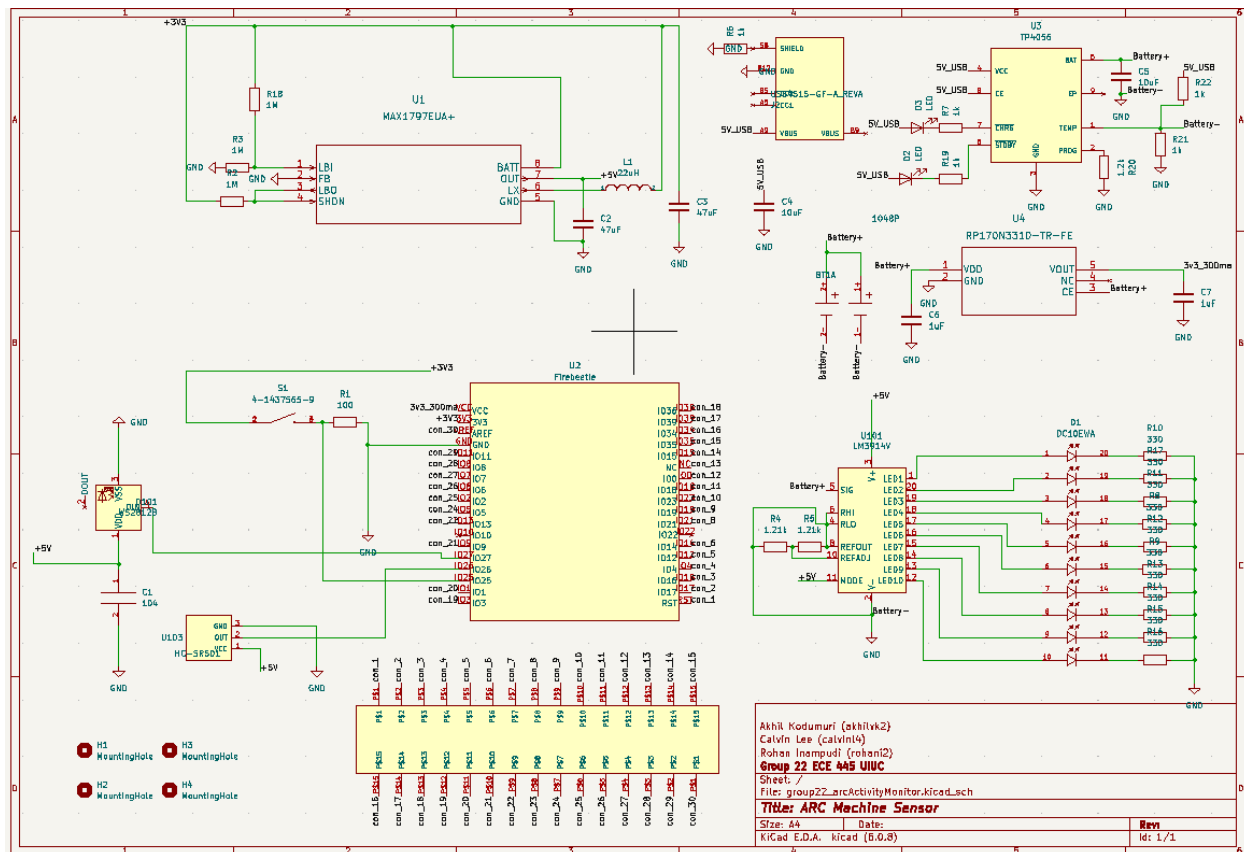
Date: 10/10

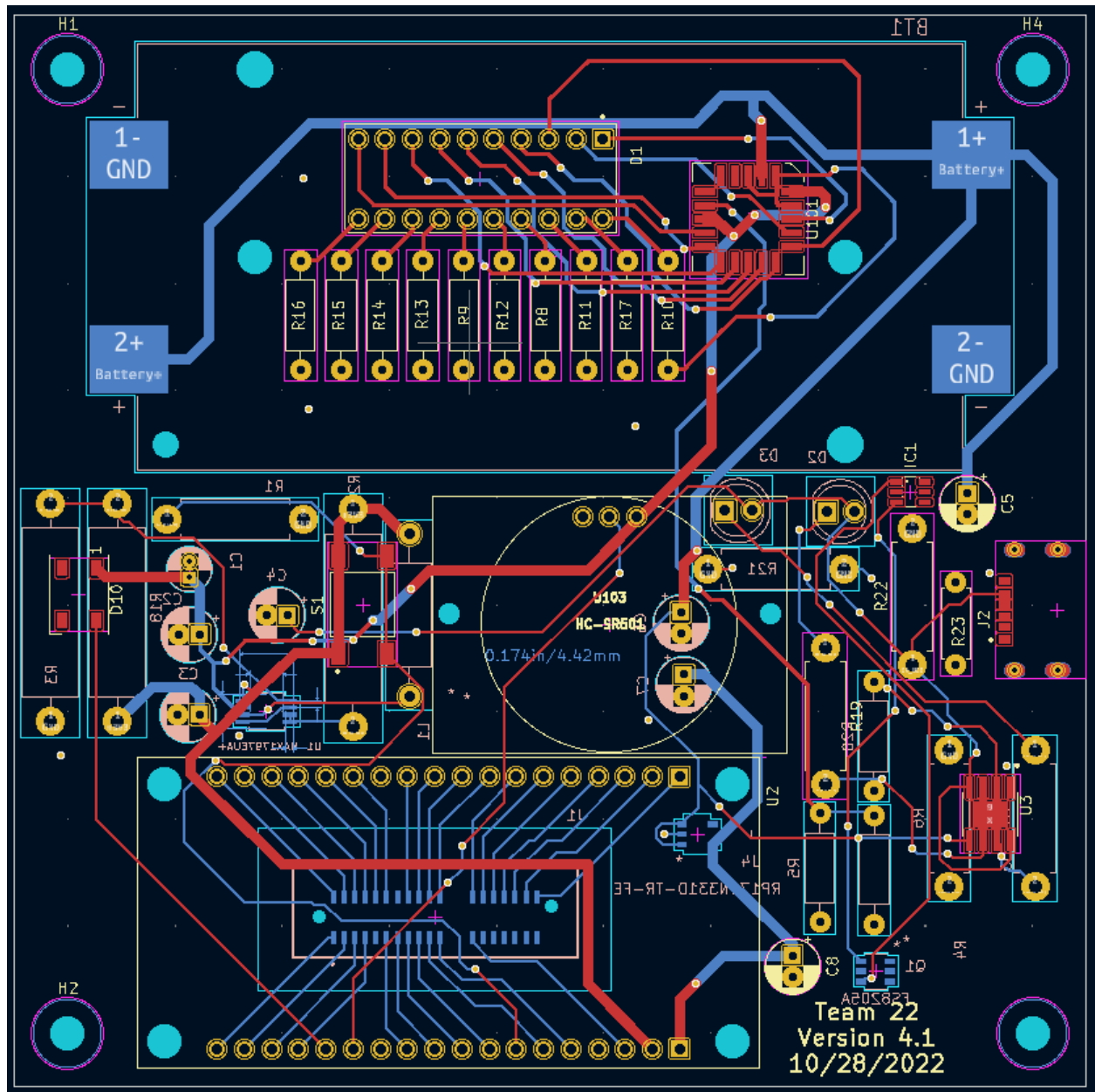
Objective: Finish PCB side and send it into PCB Way for first order

We had the entire schematic finished at the end of the last session. In this session we were able to finish the ERC as well as the DRC. We were able to connect all of the pieces on the footprint and got everything to pass the PCB review on PCB way. We also finished a finalized parts list with the links to buy as well as how much each part is. Attached is an image of PCB schematic and PCB as well as our parts list.

| Subsystem | Part | Quantity | Price / Unit | Subtotal for MVP | Vendor | Link |
|-----------------|-------------------|----------|--------------|-------------------------------|---------------------|---|
| Boost Converter | MAX1797EUA+ | 1 | \$6.00 | \$6.00 | Digikey | https://www.digikey.c |
| | 1M Resistor | 3 | \$0.15 | \$0.45 | Digikey | https://www.digikey.c |
| | 47uF Capacitor | 2 | \$0.10 | \$0.20 | Digikey | https://www.digikey.c |
| | 22uH Inductor | 1 | \$0.31 | \$0.31 | Digikey | https://www.digikey.c |
| Power | TP4056 - USBC | 1 | \$9.00 | \$9.00 | Amazon LLC | https://www.amazon |
| | 3.6V Rechargea | 2 | \$5.00 | \$10.00 | 18650 Battery Store | https://www.18650ba |
| | 2x 18650 Batter | 1 | \$7.35 | \$7.35 | Digikey | https://www.digikey.c |
| | LM3914 | 1 | \$3.11 | \$3.11 | Texas Instruments | https://www.ti.com/pr |
| | 1.2KOhm Resist | 2 | \$0.30 | \$0.60 | Digikey | https://www.digikey.c |
| | 330 Ohm Resist | 9 | \$0.10 | \$0.90 | Digikey | https://www.digikey.c |
| | Bar Graph Displ | 1 | \$3.80 | \$3.80 | Digikey | https://www.digikey.c |
| Microcontroller | FireBeetle 2 ESf | 1 | \$9.90 | \$9.90 | Dfrobot | https://www.dfrobot.c |
| | 2x19 Female Co | 1 | \$4.10 | \$4.10 | Mouser | https://www.mouser.c |
| | PIR Sensor (HC) | 1 | \$10.00 | \$10.00 | Amazon LLC | https://www.amazon |
| | LEDs (WS2812E | 1 | \$0.58 | \$0.58 | Digikey | https://www.digikey.c |
| | 0.1uF Capacitor | 1 | \$0.31 | \$0.31 | Digikey | https://www.digikey.c |
| | Tactile Switch (b | 1 | \$0.21 | \$0.21 | Digikey | https://www.digikey.c |
| | 200 Ohm Resist | 1 | \$1.80 | \$1.80 | | |
| | | | | \$68.62 | | |
| | | | | **** PRICE PER PCB (MVP) **** | | |
| IOT | Raspberry Pi 3 - | 1 | \$35.00 | \$35 | Adafruit | https://www.adafruit.c |
| | Pi Power Adapte | 1 | \$9.95 | \$9.95 | Amazon LLC | https://www.amazon |
| | 8GB Micro SD C | 1 | \$6.19 | \$6.19 | Amazon LLC | https://www.amaz |







Date: 10/24

Objective: Research into the software side of things

Because our updated PCB that Gruev wanted us to make did not deliver with the first PCB order, our team focused on figuring out the exact logistics of how we wanted to implement the

software side of things. We decided that AWS was not fit for our use case since AWS generally is expecting several thousands requests at once, and in our project, we would not be expecting more than fifty requests realistically. We therefore decided to pivot to a locally host MySQL workbench database, as well as a locally hosted python flask website. We also found some resources online on how to use the MQTT protocol.

Date: 10/31

Objective: Start testing and working on building out our project

Our PCB was finally delivered and all of our parts came in as well. We immediately realized that a couple of our custom footprints were incorrect, and that we had wired a couple of the components incorrectly as well. We knew we had to reorder new components, but we first tried to breadboard out whatever components we could so that we could make sure there were no other revisions that were necessary.

Date: 11/10

Objective: Get prepared for the mock demo next week

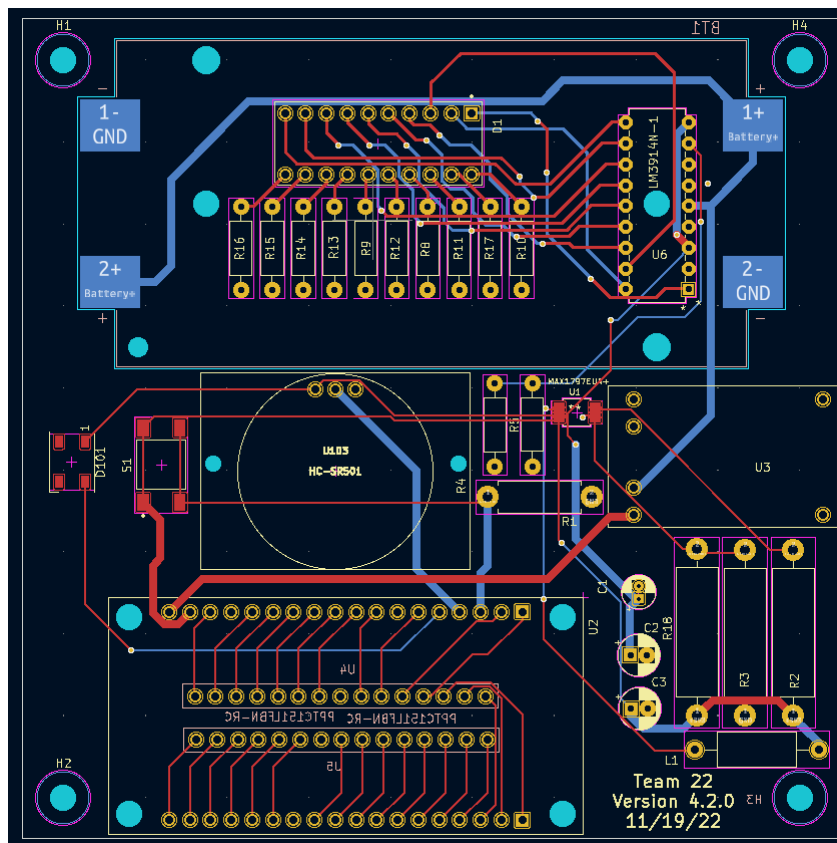
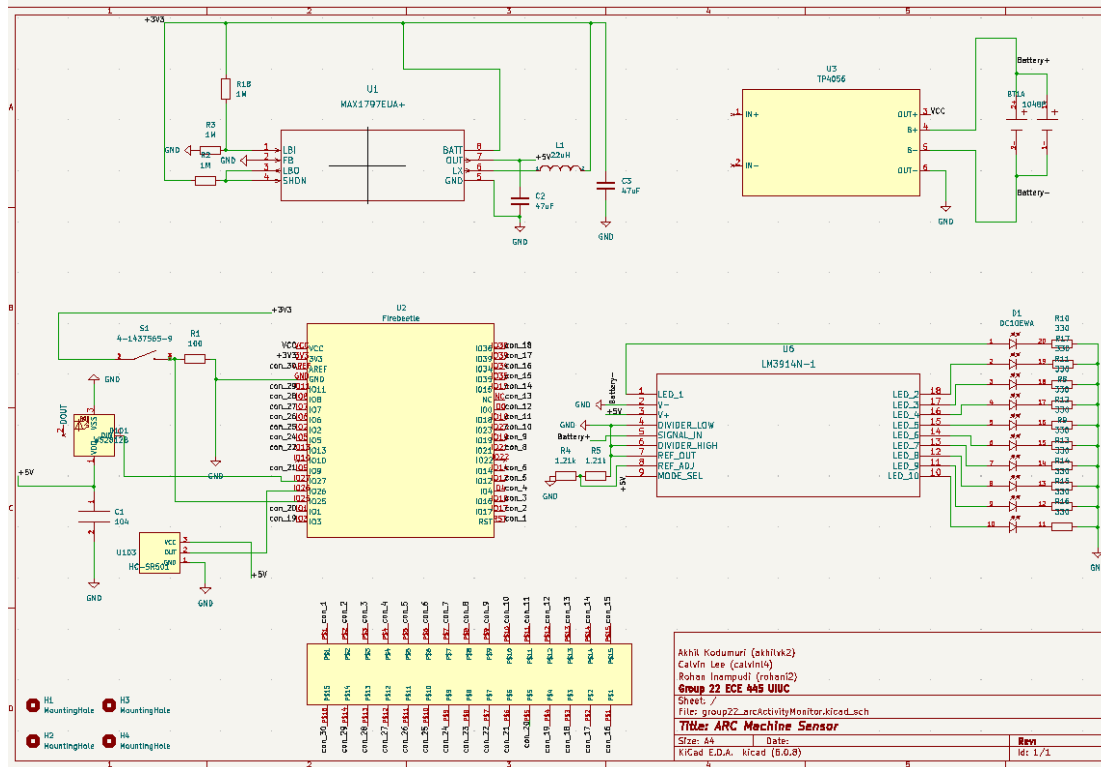
We weren't able to meet up last week because most of our team members were busy with exams. Mock demo is next week and we wanted to make sure that we have something ready to demonstrate. Unfortunately, our group member Akhil got sick at that point and was unable to help out, so me and Rohan decided to focus on software. We started working on building out the basics of the website and making sure that requests were able to go through. Attached is an image of the table on our website that is updated through python scripts:

| Menu | |
|------------|--------------|
| Station ID | Availability |
| 1 | Available |
| 2 | Available |
| 3 | Taken |
| 4 | Available |

Date: 11/19

Objective: Remake PCB one final time

When our new pcb came in we realized that there were still a decent amount of errors, and that we needed to create a new final version with the original USB-C module so that we can cut back on the amount of places things would go wrong. We spent time creating a new PCB, but we were also able to get the entire website working, as well as the flow from the ESP-32 to the website. The script for the button as well as the PIR motion sensor failsafe was also implemented at this time. We sent in our order for a new PCB and had it shipped to my house over break to solder.



Date: 11/26

Objective: Solder new PCB

Our new PCB came in and I spent time in my dad's lab to solder our entire PCB together. I was able to, but once I did we realized that the ESP-32 was not getting enough power and was unable to supply 3.3V throughout our system. This was a fatal flaw, and we knew that we would not have a working PCB available to demonstrate for the final demo. We decided that a fully breadboarded demo is our only option, and we moved forward with that in mind.

Date: 11/30

Objective: Finish up final demo

This was our final working day. We were able to get our entire system breadboarded out, and were able to connect all of our subsystems together so that they would work in unison. We also implemented an email notification system so that people can sign up for certain gym spots and our system will let them know if it becomes available. It is unfortunate that we were unable to get the PCB to work, but we definitely learned a lot of things along the way that will help if I was to do anything similar in the future. We're ready for demo!

Sign Up

Email Address

- ☐ Rack 1
- ☐ Rack 2
- ☐ Rack 3
- ☐ Rack 4

Date: 12/5

Objective: Create slides for final demo and work on final paper

We created all the slides for the final demo and created a new block diagram to better represent how our final system unfolded. We also put together all of our results and combined them into our final paper, which we also finished in this session. Finally done with the class!

Attached are some of the new diagrams that we created for the final paper.

