


read_sensor



```
graph LR; A[read_sensor] --> B[get_data_from_sensor]
```

The diagram consists of two rectangular boxes connected by a horizontal blue arrow. The first box on the left is filled with a dark gray color and contains the text 'read_sensor'. The second box on the right is white with a dark gray border and contains the text 'get_data_from_sensor'. A solid blue arrow points from the right side of the first box to the left side of the second box, indicating a flow or sequence.

get_data_from_sensor