Anastasios Kontaxoglou

Chelidonous 37, Kifisia, Athens, Greece, 14564

□ (+30)6949493541 | ■ a.kontaxoglou@gmail.com | ★ akontaxoglou.github.io/

Education

The University of Tokyo (UTokyo)

Tokyo, Japan

DOCTOR OF PHILOSOPHY (Ph.D.) IN AERONAUTICS & ASTRONAUTICS (INCLUDING 6 MONTHS AS A RESEARCH STUDENT)

Apr. 2019 - Sep. 2022

in collaboration with Japan Aerospace Exploration Agency (JAXA)

Department of Aeronautics and Astronautics, Intelligent Space Systems Laboratory (ISSL)

Supervisor: NAKASUKA Shinichi (https://www.space.t.u-tokyo.ac.jp/nlab/index_e.html)

Topic: "A Multifidelity Simulation Framework for Digital Twin Modelling of Spacecraft" - Multifidelity thermal analysis for small satellites, using

Deep Learning and Finite Element modelling.

Scholarship: Fully funded by the MEXT Scholarship of the Japanese government.

Hong Kong University of Science and Technology (HKUST)

Clear Water Bay, Hong Kong SAR

M.Sc. in Aeronautical Engineering (1-year; 60 ECTS)

Sept. 2017 - Nov. 2018

in partnership with Ecole Nationale de l'Aviation Civile (ENAC)

Final GPA: 3.52/4

Thesis: "Constructal Law Analysis of Orbital Launch Vehicles" - Allometric rules for orbital launch vehicles. Future trends prediction.

National Technical University of Athens (NTUA)

Athens, Greece

DIPLOMA IN ELECTRICAL AND COMPUTER ENGINEERING (B.Sc. & M.Sc. 5-YEAR JOINT DEGREE; 300 ECTS)

Oct. 2011 - July 2017

Concentration: Systems and Electronics

Minor: Biomedical Engineering

Thesis: "Uncalibrated Robot Visual Servoing" - Robotic manipulator-camera system with unknown parameters, backstepping logic, adaptive control & higher order neural networks.

Experience

Intracom Defense S.A. (https://www.intracomdefense.com)

Athens, Greece

SYSTEM SAFETY ENGINEER

May 2023 - May 2024 (1 year & 1 month)

Responsibilities:

- Working on the Low Observable Tactical Unmanned System (LOTUS) tactical UAV project, co-funded by the European Defence Industrial Development Program (EDIDP) and national MODs.
- Contributed to the aircraft's function decomposition.
- Performed FHA, FTA, CCA, PASA, PSSA on the LOTUS UAV based on ARP4761 and ED279.
- Determined subsystem DALs to support ARP4754A process.
- Contributed to LOTUS airworthiness (AEP4671) and interoperability (STANAG4586) requirements.
- Contributed to system integration.
- Used SCADE Architect and Medini Analyze by ANSYS for system design and safety analysis.
- Collaborated daily with international partners for project coordination.
- NATO/EU/GR Secret

BETA CAE Systems Japan (https://www.beta-cae.jp)

Yokohama, Japan

INTERNSHIP

Nov. 2020 - Dec. 2021 (1 year & 2 months)

Responsibilities: Used ANSA Pre-processor to treat vehicle models, built plug-ins for meshing and kinetics, tested new ANSA tools. 3D modelling, kinetics and CFD. Python was used for most simulations.

Skills

Systems Engineering Safety Analysis: FHA, PSSA, FTA, CCA, FMEA; Requirements Engineering

Control Engineering Robotics - Control/Kinematics, Attitude Control, Non-linear Control, Optimal Control

Software Tools Medini Analyze, SCADE Architect, Pytorch, Keras, MATLAB / Simulink, C/C++, OrCAD, TFX, Microsoft Office

Soft Skills AGILE, Willing to learn & ability to work in a multicultural environment.

Languages & Awards.

Greek Native Proficiency

English Full Professional Proficiency

Japanese Pre-Intermediate Proficiency (JLPT N4)

JUNE 1, 2024