Auto-vectorization

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What is vectorization?

$$\textit{Vectorization} = \textit{Loop unrolling} + \textit{packed SIMD instructions} \quad (1)$$

Loop unrolling: manually or by compiler

SIMD: SSE, AVX, Nano etc.

How to get them:

- write assembly
- compiler intrinsics
- special purpose language extensions eg. OpenCL, CUDA
- vectorizing compiler + guidelines

The simplest case

```
int A[1024], B[1024], C[1024];
// initialize A and B
for(int i = 0; i < 1024; ++i)
  C[i] = A[i] * B[i];
```

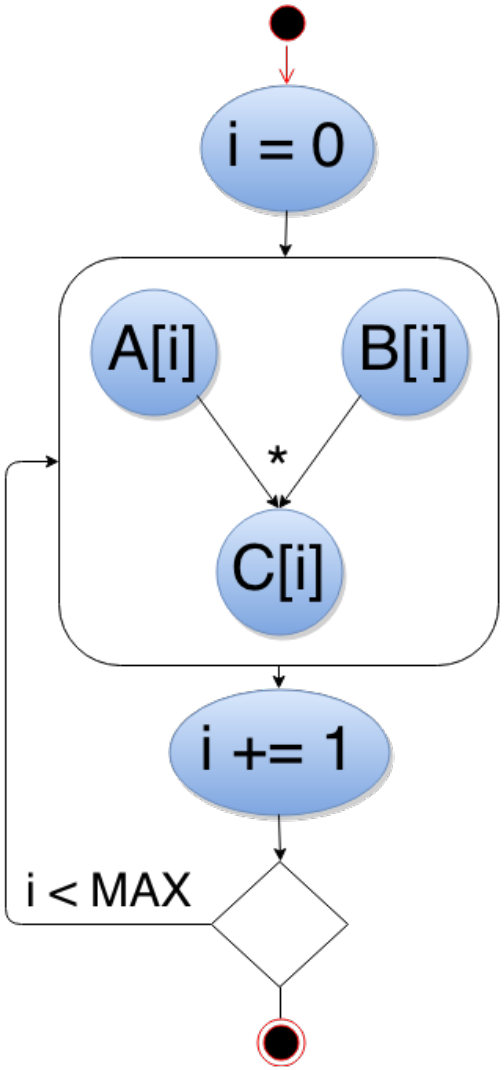
vectorized:

- -O2 and beyond
- speedup $\in [2, 8]$

not vectorized:

- -O0, -O1, -Og, -g, -no-vec
- operates on single entry at a time
- slow

Why was it vectorized?



Properties needed for vectorization:

- countable
- single entry, single exit
- no branching
- the innermost loop
- no function calls
- no data dependencies

Countable

(a) countable:

```
for(i = 0; i < MAX; ++i)
  C[i] = A[i] * B[i];
```

(b) uncountable:

```
for(i = 0; i < MAX; ++i)
{
  C[i] = A[i] * B[i];
  if(A[i] < B[i])
    MAX--;
}
```

Index cannot depend on the loop execution!

Single entry, single exit

(a) single exit:

```
for(i = 0; i < MAX; ++i)
  C[i] = A[i] * B[i];
```

(b) multiple exits:

```
for(i = 0; i < MAX; ++i)
{
  C[i] = A[i] * B[i];
  if(A[i] < B[i])
    break;
}
```

Vectorization could “skip” the termination condition!

No branching

(a) no branching?:

```
for(i = 0; i < MAX; ++i)
  if(A[i] != 0)
    C[i] = A[i];
  else
    C[i] = B[i];
```

(b) branching:

```
for(i = 0; i < MAX; ++i)
  switch(i % 3) {
  case 0: C[i] = A[i];
          break;
  case 1: C[i] = B[i];
          break;
  default: C[i] = 0;
  }
```

If statements implemented by “masking assignment” are ok.

Innermost loops

```
for(int i = 0; i < 10; ++i)
  for(j = 0; j < MAX; ++j)
    C[i][j] = A[i][j] * B[i][j];
```

- Only j-loop vectorized
- Outer-loop vectorization inefficient
- Can be enforced with #pragma SIMD
- Outer-loop vectorization possible after loop interchange

Function Calls

```
int compute(int a, int b);
...
for(i = 0; i < MAX; ++i)
  C[i] = compute(A[i], B[i]);
```

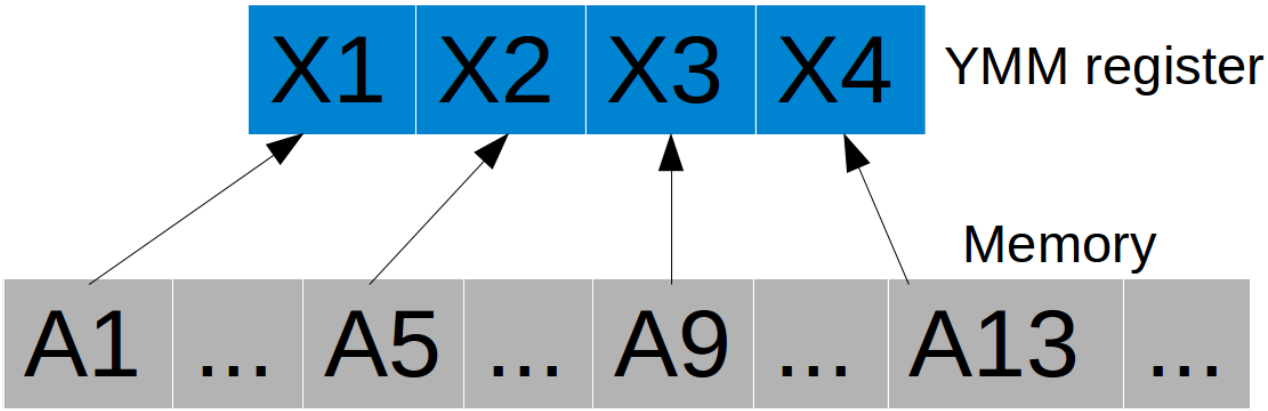
works if the function:

- can be inlined
- is declared as a vector function:

```
__attribute__((vector))
int compute(int a, int b);
```

- is compiler intrinsic function
- is one of the math functions: sin, cos, exp, pow, etc.

Non-contiguous Memory Access



- each entry loaded separately
- happens with non-unit stride and indirect adressing e.g.

```
C[i] = C[i] * A[i * 2];
C[i] = C[i] * A[B[i]];
```

Data Dependencies

Read-after-write (flow dependency): ×

```
for(i=1; i<MAX; ++i)
  A[i] = A[i-1] + 1;
```

Write-after-read (anti-dependency): ✓

```
for(i=1; i<MAX; ++i)
  A[i-1] = A[i] + 1;
```

Write-after-write (output dependency): ×

```
for(i=0; i<MAX; ++i)
  A[i - i%2] = A[i] * B[i];
```

Reduction: ✓

```
double sum = 0;
for(i=0; i<MAX; ++i)
  sum = sum + A[i];
```

Assumed Data Dependencies - Pointer Aliasing

```
void compute(int* A, int* B, int* C, int N) {
  for(int i = 0; i<N; ++i)
    C[i] = A[i] + B[i];
}
```

- C/C++ makes no assumptions about pointers:

```
compute(a, b, a);
```

is legal!