



Vehicle Detection for Cities

Machine Learning for Cities

By

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PROJECT GOAL



> Can we track the vehicle flows in real-time using traffic camera feeds?



Source: NYC DOT

Possible Uses:

- > Detecting and Tracking Congestions in real-time
- > Efficient Traffic Planning and Management

APPROACH

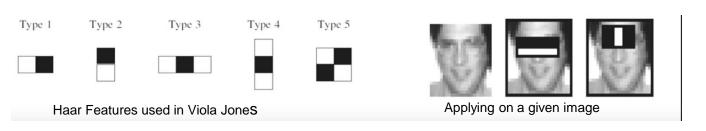


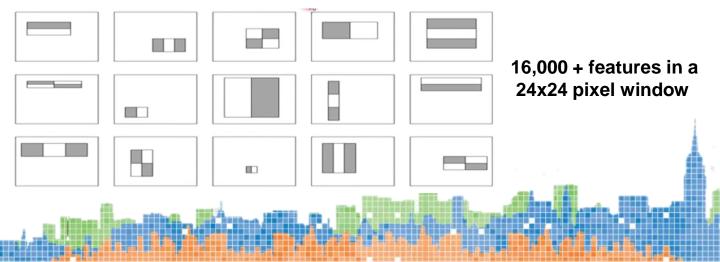
- > Shallow Learning Techniques:
 - 1) Using HOG Features and applying an SVM Classifier
 - 2) Using HAAR Features and applying a Cascade Classifier (In this presentation)

- > Deep Learning Techniques:
 - > Convolutional Neural Networks
 - > R-CNN



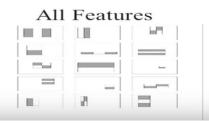
HAAR-like Features







Adaboost Classifier







- Only few set of features useful among 16,000 plus features.
- That's why, We have Adaboost.
- weighted combination of all features, each features is called a weak Classifier

$$F(x) = \alpha_1 f_1(x) + \alpha_2 f_2(x) + \alpha_3 f_3(x) + \dots$$

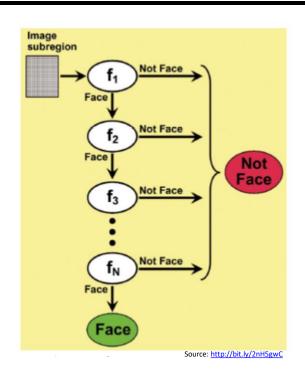
Strong classifier

Weak classifier

Disadvantage: High Computation Cost



Cascading





Training Function

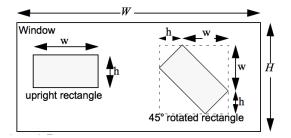
opencv_traincascade -data data -vec positives.vec
-bg bg.txt -numPos 1200 -numNeg 600 -numStages 10
-w 20 -h 20

boostType: GAB => Gentle AdaBoost

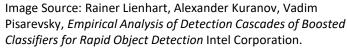
featureType: HAAR

mode: BASIC

=> Upright rectangle Haar-like features

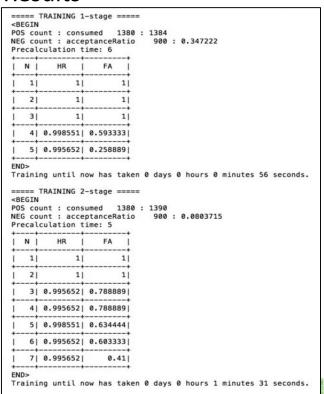








Results

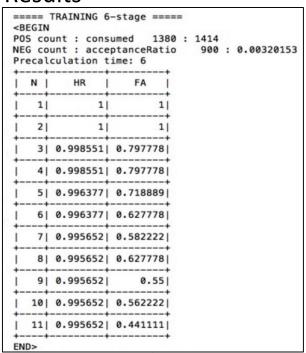


- N = Current feature for this cascade.
- HR = Hit Rate based on the Stage Threshold (hit rate/numPos)
- FA = False Alarm based on the Stage Threshold (false alarm rate / numNeg)

Stage Threshold = Value set to achieve accuracy of at least 50% in identification of positive vehicle images.



Results

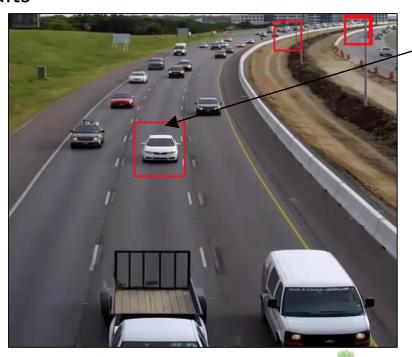


Training the Classifier - Stage 6

- Acceptance Ratio improves for each subsequent training stage.
- Acceptance Ratio value for -Stage 1 = 0.35
 Stage 2 = 0.08
 and Stage 6 = 0.0032



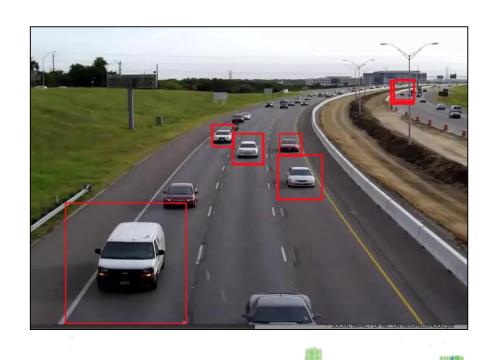
Results



Vehicle used to train the classifier

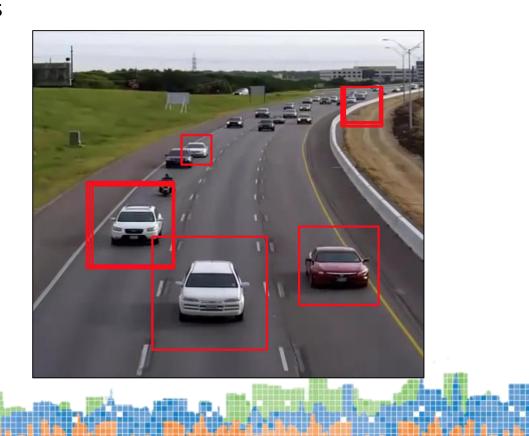


Results



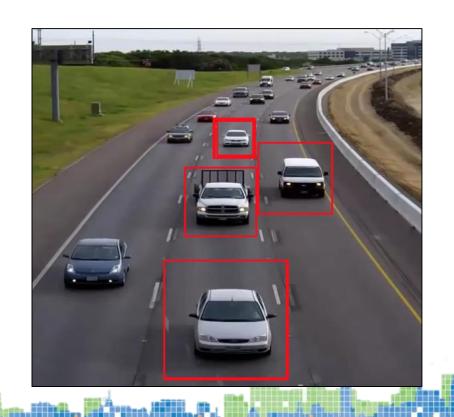


Results





Results



REFERENCES/ACK



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THANK YOU