## **Diffusion Model**

## CMSC 25025 Final Project Akash Piya

## Question 1

As given in the paper,  $q_{t|t-1}(x_t|x_{t-1}) = \mathcal{N}\big(\sqrt{\alpha_t}x_{t-1}, (1-\alpha_t)I_d\big)$ . But through the reparameterization trick, we can write the above as

$$\begin{split} q_{t|t-1}(x_t|x_{t-1}) &= \sqrt{\alpha_t}x_{t-1} + \varepsilon_1\sqrt{(1-\alpha_t)} \\ q_{t-1|t-2}(x_{t-1}|x_{t-2}) &= \sqrt{\alpha_{t-1}}x_{t-2} + \varepsilon_2\sqrt{(1-\alpha_{t-1})} \\ \Rightarrow q_{t|t-2}(x_t|x_{t-2}) &= \sqrt{\alpha_t}\sqrt{\alpha_{t-1}}x_{t-2} + \sqrt{\alpha_t}\sqrt{1-\alpha_{t-1}}\varepsilon_2 + \sqrt{1-\alpha_t}\varepsilon_1 \end{split}$$

where  $\varepsilon_i \in \mathcal{N}(0, I)$ . Furthermore, we have that

$$\begin{split} q_{t-2|t-3}(x_{t-2}|x_{t-3}) &= \sqrt{\alpha_{t-2}}x_{t-3} + \varepsilon_3\sqrt{1-\alpha_{t-2}}\\ \Rightarrow q_{t|t-3}(x_t|x_{t-3}) &= \sqrt{\alpha_t\alpha_{t-1}\alpha_{t-2}}x_{t-3} + \sqrt{\alpha_t\alpha_{t-1}(1-\alpha_{t-2})}\varepsilon_3 + \sqrt{\alpha_t(1-\alpha_{t-1})}\varepsilon_2 + \sqrt{1-\alpha_t}\varepsilon_1 \end{split}$$

In this form a clear expression forms for  $q_{t|0}$  from the xpatterns above (with the substitution that  $\overline{a_t} = \prod_{s=1}^t \alpha_s$ ):

$$q_{t|0}(x_t|x_0) = \sqrt{\overline{\alpha_t}}x_0 + \sum_{i=1}^t \beta_i \varepsilon_i \text{ where } \beta_i = \sqrt{\left(1 - \alpha_{t-i+1}\right) \prod_{j=0}^{i-2} \alpha_{t-j}}$$

The sum is simply the sum of several standard normal distributions with variance  $\beta_i^2$  which is equivalent to a single normal distribution with mean 0 and the variance equal to the sum of all the individual variances.

$$\begin{split} \sum_{i=1}^3 \beta_i^2 &= \alpha_t \alpha_{t-1} (1 - \alpha_{t-2}) + \alpha_t (1 - \alpha_{t-1}) + (1 - \alpha_t) = 1 - \alpha_t \alpha_{t-1} \alpha_{t-2} \\ \Rightarrow \sum_{i=1}^t \beta_i^2 &= 1 - \prod_{s=1}^t \alpha_s = 1 - \overline{\alpha_t} \end{split}$$

Hence, we can then write  $q_{t|0}(x_t|x_0) = \sqrt{\overline{\alpha_t}}x_0 + \sqrt{1-\overline{\alpha_t}}\varepsilon$  where  $\varepsilon \sim \mathcal{N}(0,(1-\overline{\alpha_t})I_d)$  which implies that  $q_{t|0} \sim \mathcal{N}\left(\sqrt{\overline{\alpha_t}}x_0,(1-\overline{\alpha_t})I_d\right)$  by the reparameterization trick.

## **Question 2**

We are given that Eq 1 is

$$\int_{x_1,\dots,x_T} \log \left[ \frac{\prod_{s=1}^T p_{t-1|t}(x_{t-1}|x_t;\theta) p_T(x_T)}{\prod_{t=1}^T q_{t|t-1}(x_t|x_{t-1})} \right] \prod_{t=1}^T q_{t|t-1}(x_t|x_{t-1}) dx_1...dx_T$$

Letting  $z=(x_1,...,x_T)$  for a given  $x_0$ , we know that  $p(z)=\prod_{t=1}^T q_{t|t-1}(x_t \mid x_{t-1})$ . Hence the above expression can be viewed as an expected value function:

$$= \mathbb{E}_{z \sim (x_1, \dots x_T)} \left\lceil \log \left\lceil \frac{\prod_{s=1}^T p_{t-1|t}(x_{t-1}|x_t; \theta) p_{T(x_T)}}{1 - 1} \right\rceil \right\rceil$$