```
akramal-riyashi@abdouz-VirtualBox:~$ roscore
.. logging to /home/akramal-riyashi/.ros/log/24af1092-083d-11ed-8d01-014d4e9e957f/roslaunch-abdouz-
VirtualBox-13038.log
Checking log directory for disk usage. This may take a while.
Press Ctrl-C to interrupt
Done checking log file disk usage. Usage is <1GB.

started roslaunch server http://abdouz-VirtualBox:46043/
ros_comm version 1.15.14


SUMMARY
========

PARAMETERS
 * /rosdistro: noetic
 * /rosversion: 1.15.14

NODES

auto-starting new master
process[master]: started with pid [13046]
ROS_MASTER_URI=http://abdouz-VirtualBox:11311/

setting /run_id to 24af1092-083d-11ed-8d01-014d4e9e957f
process[rosout-1]: started with pid [13057]
started core service [/rosout]
^C[rosout-1] killing on exit
[master] killing on exit
shutting down processing monitor...
... shutting down processing monitor complete
done
```