Freescale Semiconductor

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Freescale KSDK USB Stack Developing New Application User's Guide

1 Read Me First

This document provides the detailed steps to develop a new application based on the existing classes in the USB Unified Stack. There are two parts in this document:

- Developing a new USB device application
- Developing a new USB host application

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2 Developing a New USB Device Application

2.1 Application interfaces

The interface definition between the application and the classes includes the calls shown in the following table:

API Call	Description
Class Initialize	This API is used to initialize not only the class but also the lower driver layers.
Receive Data	This API is used by the application to receive the data from the host system.
Send Data	This API is used by the application to send the data to the host system.
USB descriptor related callback	Handles the callback to get the descriptor.
USB Device call back function	Handles the callback by the class driver to inform the application about various USB bus events.
USB Class specific call back function	Handles the specific callback of the class.
USB Vendor call back function	This is an optional callback and is not mandatory for the application to support it. This callback is used to propagate any vendor specific request that the host system sends.
Periodic Task	This is an API call by the application to the class, so that it can complete some tasks that it may want to execute in non-interrupt context.

2.2 How to develop a new device application

Perform these steps to develop a new device application:

- 1. Create a new application directory under .../usb/example/device/xxx to locate the application source files and header files. The xxx is the class name, such as HID and CDC. The name of this directory is the same as the class name that the application is based on, such as HID and CDC. For example, /usb/example/device/hid/hid test
- 2. Copy the following files from the similar existing applications to the application directory that is created in Step 1.

```
usb_descriptor.c
usb_descriptor.h
```

- The usb_descriptor.c and usb_descriptor.h files contain the USB descriptors that are dependent on the application and the class driver.
- 3. Copy the bm directory from the similar existing application directory to the new application directory. Remove the unused project directory from the bm directory. Modify the project directory name to the new application project name. For example, if we want to create toolchain-IAR, board-frdmk64 class-hid related application, then we can create the new application hid_test based on a similar existing application hid mouse.

```
Change \verb| usb/example/device/hid/hid_mouse/bm/iar/dev_hid_mouse_frdmk64f_bm| to \verb| usb/example/device/hid/hid_test/bm/iar/dev_hid_test_frdmk64f_bm|
```

- 4. Modify the project file name to the new application project file name, for example, from dev_hid_mouse_frdmk64f_bm.ewp to dev_hid_test_frdmk64f.ewp. You can globally replace the existing name to the new project name by editing the project files. The dev_hid_test_frdmk64f_bm.ewp file includes the new application project setting.
- 5. Create a new source file to implement the main application functions and callback functions. The name of this file is similar with the new application name, such as mouse.c and keyboard.c.

The following sections describe the detailed steps to change application files created in the steps above to correspond with the new application.

2.2.1 Changing the usb_descriptor.c file

This file contains the class driver interface. It also contains USB standard descriptors such as device descriptor, configuration descriptor, string descriptor, and the other class specific descriptors that are provided to class driver when required.

The lists below show user modifiable variables for an already implemented class driver. The user should also modify the corresponding MACROs defined in the usb_descriptor.h file

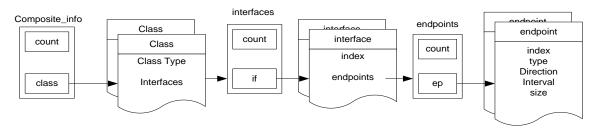
• Endpoint structures: Endpoint structure describes the property of endpoint such as the endpoint number, size, direction, and type. This array should contain all the mandatory endpoints defined by USB class specifications.

Data structure of endpoint descriptor:

```
typedef struct usb ep struct
{
                         ep_num; /* endpoint number
                                                                */
   uint8 t
                                    /* type of endpoint
   uint8 t
                                                                */
                         type;
   uint8 t
                         direction; /* direction of endpoint
                                                                */
                         size;
                                     /* buffer size of endpoint */
   uint32 t
} usb ep struct t;
/* Strucutre Representing Endpoints and number of endpoints user want*/
typedef struct usb endpoints
{
   uint8 t
                         count;
```

```
usb ep struct t*
                          ep;
} usb endpoints t;
/* Strucutre Representing interface*/
typedef struct usb if struct
   uint8 t
                          index;
    usb endpoints t
                          endpoints;
} usb if struct t;
/* Strucutre Representing how many interfaces in one class type*/
typedef struct _usb_interfaces_struct
   uint8 t
                          count;
   usb if struct t*
                          interface;
} usb interfaces_struct_t;
/* Strucutre Representing class info*/
typedef struct usb class struct
{
    class type
                            type;
    usb interfaces struct t interfaces;
} usb class struct t;
/* Strucutre Representing composite info*/
typedef struct usb composite info struct
{
   uint8 t
                          count;
   usb class struct t*
                          class;
} usb composite info struct t;
```

A brief diagram about the relationship between these items is as follows:



Sample code implementation of endpoint descriptor for HID class is given below:

```
usb_ep_struct_t g_ep[HID_DESC_ENDPOINT_COUNT] =
{
    HID ENDPOINT,
```

```
USB INTERRUPT PIPE,
    USB SEND,
    HID ENDPOINT PACKET SIZE
};
/* structure containing details of all the endpoints used by this device */
usb endpoints t g usb desc ep =
{
    HID DESC ENDPOINT COUNT,
    g ep
};
static usb if struct t g usb if[1];
usb class struct t g usb dec class =
    USB CLASS HID,
        {
           1,
           g usb if
 } ;
```

g_device_descriptor

This variable contains the USB Device Descriptor.

Sample code implementation of device descriptor for HID class is given below:

```
uint8 t g device descriptor[DEVICE DESCRIPTOR SIZE] =
                                           /* Device Descriptor Size
                                                                              * /
   DEVICE DESCRIPTOR SIZE,
   USB DEVICE DESCRIPTOR,
                                           /* Device Type of descriptor
                                                                              */
   0x00, 0x02,
                                           /* BCD USB version
                                                                              * /
                                           /* Device Class is indicated in
   0x00,
                                               the interface descriptors
                                                                              */
                                           /* Device Subclass is indicated
   0x00,
                                               in the interface descriptors
   0x00,
                                           /* Device Protocol
                                                                              * /
                                           /* Max Packet size
                                                                              * /
   CONTROL MAX PACKET SIZE,
   0xA2,0x15,
                                           /* Vendor ID
                                                                              * /
   0x01,0x01,
                                           /* Product ID (0x0101 for KBD)
                                                                             * /
                                           /* BCD Device version
                                                                              * /
   0x02,0x00,
                                           /* Manufacturer string index
                                                                             * /
   0 \times 01.
   0x02.
                                           /* Product string index
                                                                              */
   0x00,
                                           /* Serial number string index
                                                                              * /
   0x01
                                           /* Number of configurations
                                                                              * /
```

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};

• g config descriptor

This variable contains the USB Configuration Descriptor.

Sample code implementation of configuration descriptor for HID class is given below:

```
uint8 t g config descriptor[CONFIG DESC SIZE] =
    CONFIG ONLY DESC SIZE, /* Configuration Descriptor Size - always 9 bytes*/
    USB CONFIG DESCRIPTOR, /* "Configuration" type of descriptor */
    CONFIG DESC SIZE, 0x00, /* Total length of the Configuration descriptor */
                            /* NumInterfaces */
    1,
                            /* Configuration Value */
    1,
    Ο,
                            /* Configuration Description String Index*/
    (USBCFG DEV SELF POWER << USB DESC CFG ATTRIBUTES SELF POWERED SHIFT) |
(USBCFG_DEV_REMOTE_WAKEUP << USB_DESC_CFG_ATTRIBUTES_REMOTE_WAKEUP_SHIFT),
    /* S08/CFv1 are both self powered (its compulsory to set bus powered)*/
    /* Attributes.supportRemoteWakeup and self power */
    0x32,
                            /* Current draw from bus */
    /* Interface Descriptor */
    IFACE ONLY DESC SIZE,
    USB IFACE DESCRIPTOR,
    0x00,
    0x00,
    HID DESC ENDPOINT COUNT,
    0x03,
    0x01,
    0x01, /* 0x01 for keyboard */
    0x00,
    /* HID descriptor */
    HID ONLY DESC SIZE,
    USB HID DESCRIPTOR,
    0 \times 00, 0 \times 01,
    0x00,
    0x01,
    0x22,
    0x3F,0x00, /* report descriptor size to follow */
    /*Endpoint descriptor */
    ENDP ONLY_DESC_SIZE,
    USB ENDPOINT DESCRIPTOR,
    HID ENDPOINT | (USB SEND << 7),
    USB INTERRUPT PIPE,
```

```
HID_ENDPOINT_PACKET_SIZE, 0x00,
0x0A
};
```

String Descriptors

Users can modify string descriptors to customize their product. String descriptors are written in the UNICODE format. An appropriate language identification number is specified in USB_STR_0. Multiple languages support can also be added.

Sample code implementation of string descriptors for the HID class application is given below:

```
/* number of strings in the table not including 0 or n. */
uint8 t g usb str 0[USB STR 0 SIZE+USB STR DESC SIZE] =
{
    sizeof(g_usb_str_0),
    USB STRING DESCRIPTOR,
    0x09,
    0x04/*equivalent to <math>0x0409*/
};
uint8 t g usb str 1[USB STR 1 SIZE+USB STR DESC SIZE] =
    sizeof(g usb str 1),
    USB STRING DESCRIPTOR,
    'F',0,
    'R',0,
    'E',0,
    'E',0,
    'S',0,
    'C',0,
    'A',0,
    'L',0,
    'E',0,
    '',0,
    'S',0,
    'E',0,
    'M',0,
    'I',0,
    'C',0,
    '0',0,
    'N',0,
    'D',0,
    'U',0,
    'C',0,
    'T',0,
    '0',0,
```

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```
'R',0,
    '',0,
    'I',0,
    'N',0,
    'C',0,
    1.1,0
};
uint8_t g_usb_str_2[USB_STR_2_SIZE+USB_STR_DESC_SIZE] =
    sizeof(g usb str 2),
    USB_STRING_DESCRIPTOR,
    'M',0,
    'C',0,
    'U',0,
    ' ',0,
    'K',0,
    'E',0,
    'Y',0,
    'B',0,
    '0',0,
    'A',0,
    'R',0,
    'D',0,
    '',0,
    'D',0,
    'E',0,
    'M',0,
    '0',0,
    '',0
} ;
uint8 t g usb str n[USB STR n SIZE+USB STR DESC SIZE] =
    sizeof(g_usb_str_n),
    USB STRING DESCRIPTOR,
    'B',0,
    'A',0,
    'D',0,
    ' ',0,
    'S',0,
    'T',0,
    'R',0,
    'I',0,
```

```
'N',0,
    'G',0,
    '',0,
    'I',0,
    'N',0,
    'D',0,
    'E',0,
    'X',0
};
uint8 t g string desc size[USB MAX STRING DESCRIPTORS+1] =
{
    sizeof(g_usb_str_0),
    sizeof(g usb str 1),
    sizeof(g usb str 2),
    sizeof(g usb str n)
};
uint8 t *g string descriptors[USB MAX STRING DESCRIPTORS+1] =
    g usb str 0,
    g usb str 1,
    g usb str 2,
g_usb_str_n
};
usb_language_t g_usb_language[USB_MAX_SUPPORTED_INTERFACES] =
{
    (uint16 t) 0 \times 0409,
    g string descriptors,
    g string desc size
} ;
usb all languages t g languages =
    g_usb_str_0,
    sizeof(g usb str 0),
    USB_MAX_LANGUAGES_SUPPORTED,
    g_usb_language
};
```

Standard Descriptor Table

Users can modify the standard descriptor table to support additional class specific descriptors and vendor specific descriptors.

Sample implementation for HID Class application is given below:

```
uint32 t g std desc size[USB MAX STD DESCRIPTORS+1] =
    Ο,
    DEVICE DESCRIPTOR SIZE,
    CONFIG DESC SIZE,
    0, /* string */
    0, /* Interfdace */
    0, /* Endpoint */
    #if HIGH SPEED DEVICE
        DEVICE QUALIFIER DESCRIPTOR SIZE,
        OTHER SPEED CONFIG DESCRIPTOR SIZE,
        0, /* Device Qualifier */
        0, /* other sppedconfig */
    #endif
    REPORT DESC SIZE
};
uint8 t *g std descriptors[USB MAX STD DESCRIPTORS+1] =
{
   NULL,
    g device descriptor,
    g config descriptor,
    NULL, /* string */
    NULL, /* Interfdace */
    NULL, /* Endpoint */
    #if HIGH SPEED DEVICE
        g device qualifier descriptor,
        g other speed config descriptor,
    #else
        NULL, /* Device Qualifier */
        NULL, /* other sppedconfig*/
    #endif
    g report descriptor
};
```

g valid config values

This variable contains valid configurations for a device. This value remains fixed for a device.

```
uint 8 constg valid config values[USB MAX CONFIG SUPPORTED+1]={0,1};
```

• g_alternate_interface

This variable contains valid alternate interfaces for a given configuration. Sample implementation uses a single configuration. If the user implements additional alternate interfaces, the

USB_MAX_SUPPORTED_INTERFACES macro (usb_descriptor.h) should be changed accordingly.

```
static uint 8 g alternate interface[USB MAX SUPPORTED INTERFACES];
```

The following interfaces are required to be implemented by the application in usb_descriptor.c. These interfaces are called by class drivers.

• USB Desc Get Descriptor

This interface function is invoked by the Class driver. This call is made when the Class driver receives the GET_DESCRIPTOR call from the Host. Mandatory descriptors that an application is required to implement are as follows:

- Device Descriptor
- o Configuration Descriptor
- Class Specific Descriptors (For example, for HID class implementation, Report Descriptor, and HID Descriptor)

Apart from the mandatory descriptors, an application should also implement various string descriptors as specified by the Device Descriptor and other configuration descriptors.

Sample code for HID class application is given below:

```
* @name USB Desc Get Descriptor
 * @brief The function returns the correponding descriptor
* @param handle: handle
* @param type : type @param type
                    : type of descriptor requested
* @param sub_type : string index for string descriptor * @param index : string descriptor language Id
 * @param descriptor : output descriptor pointer
 * @param size : size of descriptor returned
* @return USB OK
                                  When Successfull
        USBERR_INVALID REQ TYPE when Error
 *******************************
uint8_t USB_Desc_Get Descriptor
   hid handle handle,
   uint8 t type,
   uint8 t str num,
   uint16 t index,
   uint8 t * *descriptor,
   uint32 t *size
)
{
```

```
UNUSED ARGUMENT (handle)
switch(type)
  case USB REPORT DESCRIPTOR:
      type = USB MAX STD DESCRIPTORS;
      *descriptor = (uint8_t *)g_std_descriptors [type];
      *size = g_std_desc_size[type];
    }
    break;
  case USB HID DESCRIPTOR:
      type = USB CONFIG DESCRIPTOR ;
      *descriptor = (uint8_t *)(g_std_descriptors [type]+
                            CONFIG ONLY DESC SIZE+IFACE ONLY DESC SIZE);
      *size = HID ONLY DESC SIZE;
    }
    break;
  case USB STRING DESCRIPTOR:
    {
        if(index == 0)
        {
            /* return the string and size of all languages */
                *descriptor =
                     (uint8 t *)g languages.languages supported string;
            *size = g_languages.languages_supported_size;
            else
        {
            uint8 t lang id=0;
            uint8 t lang index=USB MAX LANGUAGES SUPPORTED;
            for(;lang_id< USB_MAX LANGUAGES SUPPORTED;lang id++)</pre>
                /* check whether we have a string for this language */
                        g languages.usb language[lang id].language id)
                   /* check for max descriptors */
                    if(str num < USB MAX STRING DESCRIPTORS)</pre>
                     { /* setup index for the string to be returned */
                        lang index=str num;
                     }
                    break;
                }
            }
                /* set return val for descriptor and size */
                *descriptor = (uint8 t *)
```

```
g languages.usb language[lang id].lang desc[lang index];
                *size =
                    g_languages.usb_language[lang_id].
                                         lang desc size[lang index];
        }
    }
    break;
  default :
    if (type < USB MAX STD DESCRIPTORS)
        /* set return val for descriptor and size*/
        *descriptor = (uint8 t *)g std descriptors [type];
        /* if there is no descriptor then return error */
            *size = g std desc size[type];
        if(*descriptor == NULL)
            return USBERR INVALID REQ TYPE;
    else /* invalid descriptor */
       return USBERR INVALID REQ TYPE;
    break;
}/* End Switch */
return USB OK;
```

USB Desc Get Interface

This interface function is invoked by the Class driver. This function returns a pointer to the alternate interface for the specified interface. This routine is called when the Class driver receives the GET_INTERFACE request from the Host.

Sample code for the HID class application is given below:

```
USBERR INVALID REQ TYPE
                                 when Error
*************************
uint8 t USB Desc Get Interface
   hid handle handle,
   uint8 t interface,
   uint8_t * alt interface
)
{
   UNUSED ARGUMENT (handle)
   /* if interface valid */
   if(interface < USB MAX SUPPORTED_INTERFACES)</pre>
       /* get alternate interface*/
       *alt interface = g alternate interface[interface];
       return USB OK;
   return USBERR INVALID REQ TYPE;
}
```

USB Desc Set Interface

This interface function is called from the Class driver. This function sets an alternate interface for a specified interface. This routine is called when the Class driver receives the SET_INTERFACE request from the host.

Sample code for the HID class application is given below:

```
uint8_t USB_Desc_Set_Interface
(
    hid_handle handle,
    uint8_t interface,
    uint8_t alt_interface
)
{
    UNUSED_ARGUMENT (handle)
    /* if interface valid */
    if(interface < USB_MAX_SUPPORTED_INTERFACES)
    {
        /* set alternate interface*/
        g_alternate_interface[interface]=alt_interface;
        return USB_OK;
    }
    return USBERR_INVALID_REQ_TYPE;
}</pre>
```

• USB Set Configation

This function is used to set the device configuration.

Sample code for the HID class application is given below:

```
uint8_t USB_Set_Configation
(
    hid_handle handle, uint8_t config
)
{
    UNUSED_ARGUMENT(handle)
    return USB_OK;
}
```

USB_Desc_Get_Entity

This function is used to get some descriptor related entities which will be used in the USB stack. For example, for the eventual endpoint configuration, one device may have several different configuration descriptors, so the endpoint configuration may be different. The finalized configuration can be obtained only after the Host calls the SET_CONFIGURATION, and then the USB stack can get all the correct information about the interfaces and endpoints through the USB CLASS INFO selector.

Sample code for the HID class application is given below:

```
uint8_t USB_Desc_Get_Entity(hid_handle handle,entity_type type, uint32_t * object)
{
    switch (type)
    {
        case USB_CLASS_INFO:
            g_usb_if[0].index = 1;
            g_usb_if[0].endpoints = g_usb_desc_ep;
            *object = (unsigned long)&g_usb_dec_class;
            break;
        default :
            break;
}/* End Switch */
return USB_OK;
}
```

2.2.2 Changing the usb_descriptor.h file

This file is mandatory for the application to implement. The usb_descriptor.c file includes this file for function prototype definitions. When the user modifies usb_descriptor.c, MACROs in this file should also be modified.

2.2.3 Changing the application file

1. Main application function

The main application function is provided by two functions: APP_init and APP_task.

Sample code for the HID class application is given below:

```
void APP init(void)
   hid config struct t config struct;
    OS Mem zero(&g keyboard, sizeof(keyboard global variable struct t));
    OS Mem zero(&config struct, sizeof(hid config struct t));
#if (OS ADAPTER ACTIVE OS == OS ADAPTER MQX)
    g_keyboard.rpt_buf = (uint8_t*)OS Mem alloc uncached align(KEYBOARD BUFF SIZE,
32);
    if(NULL == g keyboard.rpt buf)
        printf("\nMalloc error in APP init\n");
        return;
    OS Mem zero(g keyboard.rpt buf, KEYBOARD BUFF SIZE);
#endif
    printf("\nbegin to test keyboard\n");
    config struct.hid application callback.callback = USB App Callback;
    config struct.hid application callback.arg = &g keyboard.app handle;
    config struct.class specific callback.callback = USB App Param Callback;
    config struct.class specific callback.arg = &g keyboard.app handle;
    config struct.desc callback ptr = &g desc callback;
   USB Class HID Init(CONTROLLER ID, &config struct, &g keyboard.app handle);
}
void APP task()
    USB HID Periodic Task();
```

2. USB device call back function

Sample code for the HID class application is given below:

```
void USB_App_Callback(uint8_t event_type, void* val,void* arg)
{
    UNUSED_ARGUMENT (arg)
    UNUSED ARGUMENT (val)
```

```
switch (event type)
{
        case USB DEV EVENT BUS RESET:
            g keyboard.keyboard init = FALSE;
            break;
        case USB DEV EVENT ENUM COMPLETE:
            g keyboard.keyboard init = TRUE;
            g process times = 1;
            KeyBoard Events Process();/* run the coursor movement code */
            break;
        case USB DEV EVENT ERROR:
            /* user may add code here for error handling
               NOTE: val has the value of error from h/w^*/
            break;
        default:
            break;
    return;
```

3. USB Class specific call back function

Sample code for the HID class application is given below:

```
uint8_t USB_App_Param Callback
    uint8 t request,
   uint16 t value,
    uint8 t ** data,
   uint32 t* size,
   void* arg
)
{
    uint8 t error = USB OK;
    uint8 t index = (uint8 t)((request - 2) & USB HID REQUEST TYPE MASK);
    if ((request == USB DEV EVENT SEND_COMPLETE) && (value == USB_REQ_VAL_INVALID))
    {
        if((g keyboard.keyboard init)&& (arg != NULL))
                #if COMPLIANCE TESTING
                    uint32 t g compliance delay = 0x009FFFFFF;
                    while (g compliance delay--);
                #endif
                KeyBoard Events Process();/* run the coursor movement code */
```

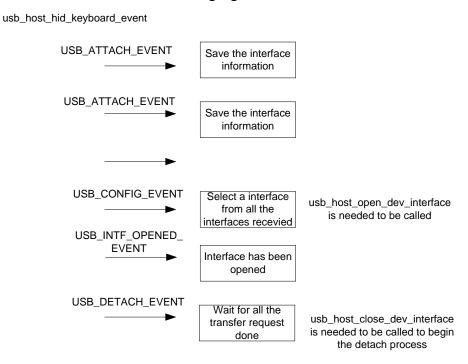
```
}
        return error;
    /* index == 0 for get/set idle, index == 1 for get/set protocol */
    *size =0;
    /* handle the class request */
    switch (request)
        case USB HID GET REPORT REQUEST :
            *data = &g keyboard.rpt buf[0]; /* point to the report to send */
            *size = KEYBOARD BUFF SIZE; /* report size */
            break;
        case USB HID SET REPORT REQUEST :
            for (index = 0; index < KEYBOARD BUFF_SIZE ; index++)</pre>
            \{ /* copy the report sent by the host */
                  g keyboard.rpt_buf[index] = *(*data + index);
    //
            break;
        case USB HID GET IDLE REQUEST :
            /* point to the current idle rate */
            *data = &g keyboard.app request params[index];
            *size = REQ DATA SIZE;
            break;
case USB HID SET IDLE REQUEST :
            /* set the idle rate sent by the host */
            g keyboard.app request params[index] = (uint8 t) ((value & MSB MASK) >>
                                                       HIGH BYTE SHIFT);
            break;
        case USB HID GET PROTOCOL REQUEST :
            /\star point to the current protocol code
               0 = Boot Protocol
               1 = Report Protocol*/
            *data = &g_keyboard.app_request_params[index];
            *size = REQ DATA SIZE;
            break;
        case USB HID SET PROTOCOL REQUEST :
            /* set the protocol sent by the host
                 0 = Boot Protocol
                 1 = Report Protocol*/
```

3 Developing a New USB Host Application

3.1 Background

In the USB system, the host software controls the bus and talks to the target devices under the rules defined by the specification. A device is represented by a configuration that is a collection of one or more interfaces. Each interface comprises one or more endpoints. Each endpoint is represented as a logical pipe from the application software perspective.

The host application software registers for services with the USB host stack and describes the callback routines inside the driver info table. The following figure shows the enumeration and detach flow.



The USB host stack is a few lines of code executed before starting communication with the USB device. The examples on the USB stack are written with class drivers APIs. Class drivers work with the host API as a supplement to the functionality. They make it easy to achieve the target functionality (see example sources for details) without dealing with the implementation of standard routines. The following code steps are taken inside a host application driver for any specific device.

3.2 How to develop a new host application

3.2.1 Creating a project

Perform the following steps to create a project.

1. Create a new application directory under .../usb/example/host/xxx to locate the application source files and header files. The xxx is the class name, such as HID and CDC. The name of this directory is the same as the class name that the application is based on, such as HID and CDC. For example,

```
/usb/example/host/hid/test
```

2. Copy the bm directory from the similar existing applications directory to the new application directory. Remove the unused project directory from the bm directory. Modify the project directory name to the new application project name. For example, if we want to create toolchain-IAR, board-frdmk64 class-hid related application, then we can create the new application test base on a similar existing application mouse.

```
Change usb/example/host/hid/mouse/bm/iar/host_hid_mouse_frdmk64f_bm to usb/example/host/hid/test/bm/iar/host hid test frdmk64f bm
```

- 3. Modify the project file name to the new application project file name, for example, from host_hid_mouse_frdmk64f_bm.ewp to host_hid_test_frdmk64f_bm.ewp. Then you can globally replace the existing name to the new project name by editing the project files. The host hid test frdmk64f bm.ewp file includes the new application project setting.
- 4. Create a new source file to implement the main application function and the callback function. The new_app.h file contains the application types and definitions. The new_app.c file contains the driver information, callback functions, event functions, and main function.

3.2.2 Defining a driver information table

A driver information table defines the devices that are supported and handled by this target application. This table defines the PID, VID, class, and subclass of the USB device. The host/device stack generates an attached callback when a device matches this table entry. The application now can communicate with the device. The following structure defines one member of the table. If the Vendor-Product pair does not match a device, then Class, Subclass, and Protocol are checked to match. Use 0xFF in Subclass and Protocol structure member to match any Subclass/Protocol.

The following is a sample driver information table. See the example source code for samples. The following table defines all HID KEYBOARD devices that are boot subclasses. A terminating NULL entry in the table is always created for search end.

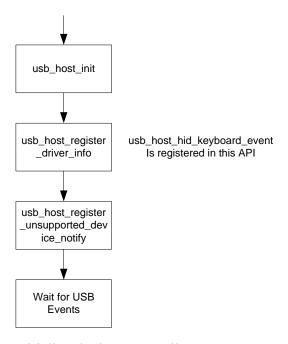
Because two classes (HID and HUB) are used in the HID KEYBOARD application, the DriverInfoTable variable has three elements. There are two event callback functions for two classes:

```
usb host hid keyboard event for the HID class and usb host hub device event for the HUB class.
   /* Table of driver capabilities this application wants to use */
   static usb host driver info tDriverInfoTable[] = {
            \{0x00, 0x00\},
                                /* Vendor ID per USB-IF
                                                                       */
            \{0x00, 0x00\},
                                                                       */
                                 /* Product ID per manufacturer
            USB CLASS HID,
                                 /* Class code
            USB SUBCLASS HID BOOT, /* Sub-Class code
            USB PROTOCOL HID KEYBOARD, /* Protocol
                                 /* Reserved
            usb host hid keyboard event /* Application call back function
       },
       /* USB 1.1 hub */
```

```
{
        \{0x00, 0x00\},
                            /* Vendor ID per USB-IF
        \{0x00, 0x00\},
                             /* Product ID per manufacturer
        USB CLASS HUB,
                             /* Class code
        USB SUBCLASS HUB_NONE, /* Sub-Class code
        USB PROTOCOL HUB ALL, /* Protocol
                             /* Reserved
        usb host hub device event /* Application call back function
    },
    {
        \{0x00, 0x00\},
                                                                   */
                            /* All-zero entry terminates
        \{0x00, 0x00\},
                             /* driver info list.
                                                                   */
        0,
        0,
        0,
        0,
        NULL
} ;
```

3.2.3 Main application function flow

In the main application function, it is necessary to follow these steps



1. Initialize the host controller.

The first step required to act as a host is to initialize the stack in a host mode. This allows the stack to install a host interrupt handler and initialize the necessary memory required to run the stack. The following example illustrates this:

```
status = usb host init(CONTROLLER ID, &host handle);
```

2. Register services.

Once the host is initialized, the USB host stack is ready to provide services. An application can register for services as documented in *Freescale USB Stack Host API Reference Manual* (USBHOSTAPIRM). The host API document describes how the application is registered for this device, because the driver information table already registers a callback routine. The following example shows how to register for a service on the host stack:

```
status = usb host register driver info(host handle, (void *)DriverInfoTable);
```

3. Register the unsupported device notify. Register a callback function to get all the information about the unsupported device.

```
status = usb_host_register_unsupported_device_notify(host_handle,
usb host hid unsupported device event);
```

3.2.4 Event callback function

After the software has registered the driver info table and register for other services, it is ready to handle devices. In the USB Host stack, customers do not have to write any enumeration code. When the device is connected to the host controller, the USB Host stack enumerates the device and finds how many interfaces are supported. In addition, for each interface, it scans the registered driver information tables and finds which application has registered for the device. It provides a callback if the device criteria matches the table. The application software has to choose the interface. You can implement the event callback function as follows:

```
void usb host hid keyboard event (
/* [IN] pointer to device instance */
usb device instance handledev handle,
/* [IN] pointer to interface descriptor */
usb interface descriptor handleintf handle,
/* [IN] code number for event causing callback */
uint 32 event code)
INTERFACE DESCRIPTOR PTR intf ptr = (INTERFACE DESCRIPTOR PTR) intf handle;
switch (event_code) {
case USB ATTACH EVENT:
case USB CONFIG EVENT:
<Add your code here>
break;
case USB INTF EVENT:
<Add your code here>
break;
case USB DETACH EVENT:
```

```
<Add your code here>
break;
}
```

Here is the sample code for the HID KEYBOARD application. In this code, the kbd_hid_device variable contains all the states and pointers used by the application to control or operate the device:

```
static void usb host hid keyboard event
(
    /* [IN] pointer to device instance */
    usb device instance handledev handle,
    /* [IN] pointer to interface descriptor */
    usb interface descriptor handleintf handle,
    /* [IN] code number for event causing callback */
    uint32 t event code
)
usb device interface struct t* pHostIntf =
(usb device interface struct t*)intf handle;
interface descriptor t* intf ptr = pHostIntf->lpinterfaceDesc;
    switch (event code)
        case USB ATTACH EVENT:
            kbd interface info[kbd interface number] = pHostIntf;
            kbd interface number++;
            printf("---- Attach Event ----\r\n");
            printf("State = %d", kbd hid device.DEV STATE);
            printf(" Interface Number = %d", intf ptr->bInterfaceNumber);
            printf(" Alternate Setting = %d", intf ptr->bAlternateSetting);
            printf(" Class = %d", intf ptr->bInterfaceClass);
            printf(" SubClass = %d", intf ptr->bInterfaceSubClass);
            printf(" Protocol = %d\r\n", intf ptr->bInterfaceProtocol);
            break;
        case USB CONFIG EVENT:
            if (kbd hid device.DEV STATE == USB DEVICE IDLE)
                kbd hid device.DEV HANDLE = dev handle;
                kbd hid device.INTF HANDLE = kbd hid get interface();
                kbd_hid_device.DEV_STATE = USB_DEVICE_ATTACHED;
            }
            else
                printf("HID device already attached - DEV STATE = %d\r\n",
kbd hid device.DEV STATE);
```

```
}
            break;
        case USB INTF OPENED EVENT:
            printf("---- Interfaced Event ----\r\n");
            kbd hid device.DEV STATE = USB DEVICE INTERFACE OPENED;
            break;
        case USB DETACH EVENT:
            <Add your code here>
        default:
            printf("HID Device state = %d??\r\n", kbd hid device.DEV STATE);
            kbd hid device.DEV STATE = USB DEVICE IDLE;
            break;
   }
   /* notify application that status has changed */
   OS_Event_set(kbd_usb event, USB EVENT CTRL);
}
```

3.2.5 Selecting an interface on the device

If the interface handle is obtained, the application software can select the interface that a retrieve pipe handles. The following code demonstrates this procedure:

3.2.6 Sending/Receiving data to/from the device

The transfer flow is quite simple: Call the usb_class_xxx_xxxx API to begin the transfer. The transfer result will be notified by the callback function registered in the usb_class_xxx_xxxx API parameter.

The HID Keyboard host uses the following code to receive data from the device:

```
kbd_hid_com->class_ptr = kbd_hid_device.CLASS_HANDLE;
kbd_hid_com->callback_fn = usb_host_hid_keyboard_recv_callback;
kbd_hid_com->callback_param = 0;
```

status = usb_class_hid_recv_data(kbd_hid_com, kbd_buffer, kbd_size);

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