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Composite Device User's Guide

1 Overview

This document describes steps to implement the composite device based on the USB stack.

The USB Stack provides two composite device demos, *hid+audio* and *msc+cdc*. However, users can create composite devices to fit their needs. This document is a detailed step-by-step guide to create a customizable composite device.

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2 Introduction

The composite device combines multiple independent functionalities by unifying independent functionality code into one example. For example, the single functionality code for CDC is provided in the CDC example and the single functionality code for MSC is provided in the MSC example. Creating the CDC+MSC composite device example requires combining the CDC example code and MSC example code into a single example.

Composite device descriptors are combined from the single-function device descriptors. There are two single-function devices and each device has only one interface descriptor in its configuration descriptor. If the composite device is combined using two single function devices, the interface descriptor of each device should be merged into the composite device configuration descriptor.

Implementing a composite device involves combining the descriptors and the functionality of the single function devices.

3 Setup

Before developing the composite device, the user needs to:

- 1. Decide how many classes to include in this composite device.
- 2. Decide which types of classes to include in this composite device, for example, HID + AUDIO, HID + HID, etc.
- 3. Prepare the device descriptor depending on use case. Particularly, the IAD should be used for AUDIO/VIDEO class, (see www.usb.org/developers/docs/whitepapers/iadclasscode r10.pdf)
- 4. Ensure that the functionality of the single function device code is valid.

3.1 Design Steps

- 1. Prepare the descriptor-related data structure to ensure that correct information about the customized composite device is relayed to the USB device stack. See Section 4.
- 2. Prepare the descriptors array and ensure the descriptors are consistent with the descriptor-related data structure. See Section 5.
- 3. Implement the specific descriptor-related callback function which the USB Device stack will call to get the device descriptor. See Section 5.

4 USB Composite Device Structures

All these structures are defined in the USB stack code. The structures describe the class and are consistent with the descriptor. They are also used in examples.

4.1 usb composite info struct t

This structure is required for the composite device and relays interface numbers and endpoint numbers of each interface to the class driver.

This is an example for a composite device MSD + CDC:

```
static usb_composite_info_struct_t usb_composite_info =
{
    . count = 2,
    . class = usb_dec_class,
};
```

The variable "count" holds the number of classes included in the composite device. Because composite device MSD+CDC includes two classes, the value of variable "count" is 2.

The type of "class" is usb class struct t. See the next section for more information.

4.2 usb_class_struct_t

This structure is required for the composite device and provides information about each class.

This is an example for the composite device MSD + CDC:

Type represents the type of each class included in the composite device. For example, the type of MSD class is USB CLASS MSC.

Interfaces include detailed interface information about the class, including interface count, ep count, ep type and ep direction. See next section for more information. Number "2" means that the CDC class has two interfaces. The interface list is "usb_cdc_if". Number "1" means that the MSD class has one interface. The interface list is "usb msd if". See next section for more information.

4.3 usb_interfaces_struct_t

This structure is required for the composite device and provides information about each class.

Prototype:



```
} usb_interfaces_struct_t;
```

Description:

count: interface numbers for each class.

interface: interface information list.

4.4 usb_if_struct_t

This structure is required for the composite device and provides information about each interface.

Prototype:

Description:

index: interface index in the interface descriptor.

endpoints: ep information struct.

This is an example for the composite device MSD + CDC:

CDC:

```
static usb_if_struct_t usb_cdc_if[2] = {
    USB_DESC_INTERFACE(0, 1, cic_ep),
    USB_DESC_INTERFACE(1, 2, dic_ep),
};
In USB_DESC_INTERFACE(0, 1, cic_ep):
```

Number "0" holds the index of the CDC class control interface. In other words, in the interface descriptor, the interface number is 0.

Number "1" means that the ep number of this interface is 1.

"cic ep" is ep detail information structure. See section 4.6 for more information.

MSD:

```
static usb_if_struct_t usb_msd_if[1] = {
    USB_DESC_INTERFACE(2, 2, msd_ep),
};
In USB_DESC_INTERFACE(2, 2, msd ep):
```

The first number "2" holds the index of the MSD class control interface. In other words, in the interface descriptor, the interface number is 2.

The second number "2" means that the ep number of this interface is 2.

"cic ep" is ep detail information structure. See next section 3.6 for more information.

4.5 usb_endpoints_t

This structure is required for the composite device and provides ep information for each interface.

4.6 usb_ep_struct_t

This structure is required for the composite device and provides ep information.

This is an example for the composite device MSD + CDC:

This is CDC class control interface endpoint information.

5 USB descriptor functions

5.1 USB descriptor

The descriptors for each class can be obtained from the class-related examples and class spec. For composite device, the user should combine multiple class descriptors. Note:

- 1. Interface number in the configuration descriptor must be the correct interface number value.
- 2. The endpoint number value in each endpoint descriptor must be consistent with the structures in Section 1.

5.2 USB_Desc_Get_Descriptor

This function provides all standard descriptors, such as descriptor for device and class. All composite devices must implement USB_STRING_DESCRIPTOR and USB_STANDARD_DESCRIPTOR. If the class has a class-specific descriptor, it needs to be added to this function. For example, for HID class, the USB_REPORT_DESCRIPTOR needs to be added.

USB_Desc_Get_Descriptor is provided in the example when a composite device is HID + HID. Omit part can be a reference in the USB Stack.

```
uint8_t USB_Desc_Get_Descriptor(...)
{

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```



5.3 USB_Desc_Get_Entity

This function provides information about a class driver. Any composite equipment must implement the USB COMPOSITE INFO and the USB CLASS INTERFACE INDEX INFO.

For Audio class, add the USB AUDIO UNITS.

For MSC, add the USB MSC LBA INFO.

For PHDC, add the USB PHDC QOS INFO.

This is an example for the composite device HID + HID.

Note:

USB_CLASS_INTERFACE_INDEX_INFO get the index of class arrange. It is the position of usb_class_struct_t array for a class.

5.4 USB_Set_Configation

This is a most common configuration and the USB_Set_Configation can be empty. For a composite device, if you complete this function, you should determine which class the handle needs.

This is an example for the two CDC devices:

6 USB Stack Configurations

1. Class Configuration



This section provides more information whenever two or more same classes are used in the composite device.

To reduce the footprint, the released USB stack does not support multiple instances of the same class in the default configuration. If two or more same classes are used in the composite device, the user needs to configure the class.

- For HID class, MAX HID DEVICE must be configured in the usb hid.h
- For CDC class, MAX_CDC_DEVICE must be configured in the usb_cdc.h
- For MSD class, MAX_MSC_DEVICE must be configured in the usb_msc.h
- For audio class, MAX_AUDIO_DEVICE must be configured in the usb_audio.h
- For PHDC class, MAX_PHDC_DEVICE must be configured in the usb_phdc.h
- For Composite class driver, CONFIG MAX must be configured in the usb composite.c

The value of the configuration depends on use cases and user's needs.

For example, for the composite device HID+HID, the MAX_HID_DEVICE must be set to 2, and the CONFIG MAX must be set to 2.

- 2. USB Stack Configuration
- For the composite device, the USBCFG_DEV_COMPOSITE must be set to 1 in the usb device config.h.

Note:

USBCFG_DEV_MAX_ENDPOINTS must not be less than "max used endpoint number + 1". "max used endpoint number" means the max endpoint number the example uses.

7 Application template

The main difference between the composite devices and other devices is application. Designing a composite device application is to design a composite device demo.

7.1 Application structure template

For a general device, a demo contains only one class. However, for the composite device, a demo contains more than one class. Likewise, a structure is required to manage the application involving more than one class.

```
class_config_struct_t composite_device_config_list[COMPOSITE_CFG_MAX];
}composite_device_struct_t;

composite_device: the handle point to composite device. Returned by USB_Composite_Init. composite_device_config_callback: function callback list and count. composite_device_config_list: function callback list.

Function n structure: structure to application of a class. Just like HID mouse, hid_mouse_struct_t hid_mouse;
HID mouse is an example to show function n structure.
```

This is an example for a composite device hid mouse + keyboard:

Prototype:

7.2 Application initialization process

- 1. Before initializing the USB stack by calling the USB_Composite_Init, the composite_device_config_list and composite_device_config_callback are assigned values respectively. For example, for hid mouse, the steps are as follows:
 - o g_composite_device need to be declared as global variables, as the type composite device struct t.
 - b. Declare: class config struct t* hid mouse config callback handle;
 - Then hid_mouse_config_callback_handle = &g_composite_device.composite_device_config_list[HID_MOUSE_INTERFACE_I NDEX];

c.

- hid_mouse_config_callback_handle->composite_application_callback.callback = hid_mouse_app_callback;
- o hid mouse app callback amended as Hid USB App Device Callback
- hid_mouse_config_callback_handle->composite_application_callback.arg =
 &g composite device.hid mouse;
- hid_mouse_config_callback_handle->class_specific_callback.callback = hid_mouse_app_param_callback;



- o hid_mouse_app_param_callback
- amended as
- Hid_USB_App_Class_Callback
- hid_mouse_config_callback_handle->class_specific_callback.arg =
 &g_composite_device.hid_mouse;
- o hid_mouse_config_callback_handle->desc_callback_ptr = &g_desc_callback;
- o hid_mouse_config_callback_handle->type = USB_CLASS_HID;
- OS_Mem_zero(&g_composite_device.hid_mouse, sizeof(hid_mouse_struct_t));

2.

- g_composite_device.composite_device_config_callback.count = 2;
- g_composite_device.composite_device_config_callback.class_app_callback = g composite device.composite device config_list;
- 3. Call USB Composite Init
- USB_Composite_Init(CONTROLLER_ID, &g_composite_device.composite_device_config_callback, &g_composite_device.composite_device);
- 4. Get a handle for each class.

For example, hid mouse:

- g_composite_device.hid_mouse.app_handle =
 (hid_handle_t)g_composite_device.composite_device_config_list[HID_MOUSE_INTERF
 ACE_INDEX].class_handle;
- 5. Initialize each class application.

Such as, hid mouse:

• hid mouse init(&g composite device.hid mouse);

8 CDC+CDC Composite device example

For this section, we use CDC+CDC composite device as an example.

8.1 USB Composite Device Structure examples

```
/* two cdc classes */
static usb_composite_info_struct_t usb_composite_info =
  2,
  usb dec class,
};
/* two cdc classes definition */
static usb class struct t usb dec class[USB MSD CDC CLASS MAX] =
{
    USB_CLASS_CDC,
    USB_DESC_CONFIGURATION(USB_CDC_IF_MAX, usb_cdc_if),
  },
    USB CLASS CDC,
    USB_DESC_CONFIGURATION(USB_CDC_IF_MAX, usb_cdc2 if),
  },
};
/* cdc1 definition: cdc has two interfaces */
static usb_if_struct_t usb_cdc_if[USB_CDC_IF_MAX] = {
  USB_DESC_INTERFACE(0, CIC_ENDP_COUNT, cic_ep),
  USB_DESC_INTERFACE(1, DIC_ENDP_COUNT, dic_ep),
};
/* cdc2 definition: cdc has two interfaces */
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```



```
static usb if struct t usb cdc2 if[USB CDC IF MAX] = {
  USB DESC INTERFACE(2, CIC ENDP COUNT, cic ep2),
 USB_DESC_INTERFACE(3, DIC_ENDP_COUNT, dic_ep2),
};
/* cdc1 endpoints definition: interface1 has one endpoint, interface2 has two endpoints*/
usb_ep_struct_t cic_ep[CIC_ENDP_COUNT] = {
    #if CIC NOTIF ELEM SUPPORT
     CIC_NOTIF_ENDPOINT,
      USB_INTERRUPT_PIPE,
      USB SEND,
     CIC\_NOTIF\_ENDP\_PACKET\_SIZE
    #endif
};
usb ep_struct_t dic_ep[DIC_ENDP_COUNT] = {
    #if DATA CLASS SUPPORT
      {
        DIC BULK IN ENDPOINT,
        USB BULK PIPE,
       USB SEND,
        DIC BULK IN_ENDP_PACKET_SIZE
      },
       DIC BULK OUT ENDPOINT,
        USB BULK PIPE,
        USB RECV,
        DIC BULK OUT ENDP PACKET SIZE
```

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```
#endif
};
/* cdc2 endpoints definition: interface1 has one endpoint, interface2 has two endpoints */
usb_ep_struct_t cic_ep2[CIC_ENDP_COUNT] = {
   #if CIC_NOTIF_ELEM_SUPPORT
     CIC2_NOTIF_ENDPOINT,
     USB INTERRUPT PIPE,
     USB_SEND,
     CIC_NOTIF_ENDP_PACKET_SIZE
   #endif
};
usb_ep_struct_t dic_ep2[DIC_ENDP_COUNT] = {
   #if DATA CLASS SUPPORT
       DIC2 BULK IN ENDPOINT,
       USB BULK PIPE,
       USB_SEND,
       DIC_BULK_IN_ENDP_PACKET_SIZE
      },
       DIC2 BULK OUT ENDPOINT,
       USB_BULK_PIPE,
       USB_RECV,
       DIC_BULK_OUT_ENDP_PACKET_SIZE
```



#endif
};

8.2 USB Composite Device descriptor examples

Modify the product ID in device descriptor. The other does not need to change.

Change interface number as shown in configuration descriptor.

Copy two CDC configuration descriptors from the CDC example or msc+cdc example and change the endpoint number to be consistent with Section 8.1.

8.2.1 USB_Desc_Get_Descriptor

```
/* string descriptor get from usb all languages t g languages */
/* other descriptor get from g_std_descriptors array */
uint8 t USB Desc Get Descriptor(...)
    if (type == USB STRING DESCRIPTOR)
    {
        if(index == 0)
            *descriptor = (uint8_t *)g_languages.languages_supported_string;
            *size = g languages.languages supported size;
        }
        else
            uint8 t lang id=0;
            uint8_t lang_index=USB_MAX_LANGUAGES_SUPPORTED;
            for(;lang id< USB MAX LANGUAGES SUPPORTED;lang id++)</pre>
                if(index == g languages.usb language[lang id].language id)
                    if(str num < USB MAX STRING DESCRIPTORS)
                        lang index=str num;
                    break;
                }
            *descriptor =
              (uint8 t *)g languages.usb language[lang id].lang desc[str num];
            *size =
                  g_languages.usb_language[lang_id].lang_desc_size[lang_index];
    }
    else if (type < USB MAX STD DESCRIPTORS+1)</pre>
        *descriptor = (uint8_t *)g_std_descriptors [type];
        if(*descriptor == NULL)
            return USBERR INVALID REQ TYPE;
```

```
*size = g_std_desc_size[type];
}
else
{
    return USBERR_INVALID_REQ_TYPE;
}
return USB_OK;
}
```

8.2.2 USB_Desc_Get_Entity

```
/* USB CLASS INTERFACE INDEX INFO: Return different index based on different handle */
/* USB_COMPOSITE_INFO: return usb_composite_info defined in section 1*/
uint8_t USB_Desc_Get_Entity(uint32_t handle, entity_type type, uint32_t * object)
    switch (type)
    {
        case USB CLASS INFO:
           break;
        case USB CLASS INTERFACE INDEX INFO:
            *object = 0xff;
            for (int i = 0; i < 2; i++)
                if (handle == (uint32_t)g_composite_device.cdc_vcom)
                {
                    *object = (uint32 t)CDC VCOM INTERFACE INDEX;
                    break;
                else if (handle == (uint32_t)g_composite_device.msc_disk.app_handle)
                    *object = (uint32 t) MSC DISK INTERFACE INDEX;
                    break;
            }
           break;
        case USB COMPOSITE INFO:
            *object = (uint32 t) &usb composite info;
            break;
        default :
           break;
    }/* End Switch */
    return USB OK;
```

8.2.3 USB_Set_Configation



8.3 USB Composite Device application example

8.3.1 Class Configuration

USBCFG_DEV_COMPOSITE is set to 1 in usb_device_config.h

MAX_CDC_DEVICE is set to 2 in usb_cdc.h

USBCFG_DEV_MAX_ENDPOINTS is set to 9 in usb_device_config.h

8.3.2 CDC+CDC Application structure

```
/* cdc struct t represents cdc class */
typedef struct composite device struct
   composite handle t
                             composite device;
   cdc struct t
                              cdc vcom1;
   cdc struct t
                              cdc vcom2;
   composite config struct t composite device config callback;
                            composite_device_config_list[COMPOSITE_CFG_MAX];
   class config struct t
}composite_device_struct t;
/* cdc struct t is as follow. */
/* It contain variables for one cdc class. */
typedef struct cdc variable struct
{
   cdc handle t cdc handle;
   uint8 t g curr recv buf[DATA BUFF SIZE];
   uint8 t g curr send buf[DATA BUFF SIZE];
   uint8_t g_recv_size;
   uint8_t g_send_size;
   bool start app;
   bool start transactions;
   uint8 t out endpoint;
   uint8 t in endpoint;
}cdc struct t;
```

8.3.3 CDC+CDC Application

1. composite device struct t g composite device;

```
2.
/* call cdc vcom preinit by parameter cdc struct t */
cdc vcom preinit(&g composite device.cdc vcom1);
cdc vcom preinit(&g composite device.cdc vcom2);
3. /* Init cdc1: use callback functions defined by existing examples; use
g composite device.cdc vcom1 as parameter for callback */
  cdc vcom config callback handle =
&g composite device.composite device config list[CDC VCOM INTERFACE INDEX];
  cdc vcom config callback handle->composite application callback.callback =
VCom USB App Callback;
VCom USB App Callback amended as VCom USB App Device Callback
  cdc vcom config callback handle->composite application callback.arg =
&g composite device.cdc vcom1;
  cdc vcom config callback handle->class specific callback.callback =
(usb class specific handler func)VCom USB Notif Callback;
VCom USB Notif Callback amended as VCom USB App Class Callback
  cdc vcom config callback handle->class specific callback.arg =
&g composite device.cdc vcom1;
  cdc vcom config callback handle->desc callback ptr = &desc callback;
cdc vcom config callback handle->type = USB CLASS CDC;
4. /* Init cdc2: use callback functions defined by existing examples; use
g composite device.cdc vcom2 as parameter for callback */
  msc disk config callback handle =
&g composite device_config_list[MSC_DISK_INTERFACE_INDEX];
  msc disk config callback handle->composite application callback.callback =
VCom USB App Callback; //SG
VCom USB App Callback amended as VCom USB App Device Callback
  msc disk config callback handle->composite application callback.arg =
&g composite device.cdc vcom2; //SG
  msc_disk_config_callback handle->class specific callback.callback =
(usb class specific handler func) VCom USB Notif Callback;
```



```
VCom USB Notif Callback amended as VCom USB App Class Callback
  msc disk config callback handle->class specific callback.arg =
&g composite device.cdc vcom2; //SG
  msc disk config callback handle->desc callback ptr = &desc callback;
msc disk config callback handle->type = USB CLASS CDC;
5.
  g composite device.composite device config callback.count = 2;
g composite device.composite device config callback.class app callback =
g composite device.composite device config list;
6. /* composite init function call */
USB Composite Init(CONTROLLER ID,
&g composite device.composite device config callback,
&g composite device.composite device);
7. /* save the handle for each cdc device */
  g composite device.cdc vcom1.cdc handle =
(cdc handle t)g composite device.composite device config list[CDC VCOM INTERFACE I
NDEX].class handle;
g composite device.cdc vcom2.cdc handle =
(cdc handle t)g composite device.composite device config list[1].class handle;
8. /* init some fields of g composite device.cdc vcom1 and g composite device.cdc vcom1*/
  g composite device.cdc vcom1.out endpoint = DIC BULK OUT ENDPOINT;
  g composite device.cdc vcom2.out endpoint = DIC2 BULK OUT ENDPOINT;
  g composite device.cdc vcom1.in endpoint = DIC BULK IN ENDPOINT;
  g composite device.cdc vcom2.in endpoint = DIC2 BULK IN ENDPOINT;
9. /* cdc vcom init call. Step8 can be moved to this function code. */
  cdc vcom init(&g composite device.cdc vcom1);
cdc vcom init(&g composite device.cdc vcom2);
```

```
10. /* app tasks: call cdc_vcom_task by cdc_struct_t parameter*/
void APP_task()
{
    while(TRUE)
    {
       cdc_vcom_task((void*)&g_composite_device.cdc_vcom1);
       cdc_vcom_task((void*)&g_composite_device.cdc_vcom2);
    }
}
```



9 Revision history

This table summarizes revisions to this document since the release of the previous version

Table 1 Revision History				
Revision number	Date	Substantive changes		
0	12/2014	Initial release		

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