

Assignment 5 module 9

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This document contains the code for all examples in the Goal Programming module

Dewright Co.

Solve

Remarks

The ideal solution to this formulation obtained by applying the simplex approach has the following values: $y_{1m} = 0$, $y_{2p} = 8.33$, $y_{2m} = 0$, $y_{3p} = 0$, $x_1 = 8.33$, $x_2 = 0$, $x_3 = 1$, $y_{1p} = 0$, and $y_{3m} = 0$. can be The variables are listed in the formulation's order of appearance, followed by the solutions. Thus, y_1 and y_3 are both equal to 0. As a result, his first and third targets are entirely attained, while his hiring goal is exceeded by 8.33. (833 employees). Overachieving the intended result carries a 16.67 penalty. # Preemptive Goal Programming - Sequential Approach ## Dewright Co. - First Stage

Management went back to the initial problem statement outlined in the previous table after receiving unfavorable proposals to raise the company's staff by more than 20 percent. The extremely high cost of training 833 new hires has mostly been wasted, resulting in significant layoffs (a well-known certainly), making it challenging for businesses to recruit highly skilled workers in the country. Because of this, management came to the conclusion that preventing a workforce rise should be given very high priority. Additionally, management is aware that it will be extremely challenging for him to increase capital expenditures for new items above \$55 million, making avoiding capital expenditures above that level very challenging as well. need to be higher priority. ### Formulation and Solution $Z = 0$, $x_1 = 8$, and $y_{3m} = 15$ is the answer. We can go on to the second stage of optimization now that we have the best answer by setting y_{2p} and $y_{3p} = 0$ in the second stage formulation. ## Dewright Co. - Second Stage We can end here because the optimal solution is special and doesn't call for any further objectives. In the end, $x_1 = 5$, $x_2 = 0$, and $x_3 = 3.75$. The second priority goal (long-term profit ≥ 125) can only be met by 8.75 in full by this approach, but it fully satisfies the first priority goal (no unemployment). # Dewright Co. - Streamlined Approach In reality, there are two steps to this solution. The first priority goal is achieved, but the best option doesn't provide enough long-term advantages to meet the second priority goal. # Make maximum progress towards all goals

- Setting goals is a requirement for all goals in goal programming. What if some objectives are unrestricted? * Unrestricted targets have no minimum target (default). We therefore wish to simultaneously advance all objectives. Therefore, maximizing the minimal progress toward all goals is a good goal. 1. Express y_1^+ and y_1^- ; y_2^+ and y_2^- ; P using x_1 , x_2 , x_3

$$y_1^+ - y_1^- = 50 - 6x_1 - 4x_2 - 5x_3;$$

$$y_2^+ - y_2^- = 75 - 8x_1 - 7x_2 - 5x_3;$$

$$P = 20x_1 + 15x_2 + 25x_3;$$

2. Express management objective function

$$\text{Max } Z = 20x_1 + 15x_2 + 25x_3 - 6y_1^+ - 6y_1^- - 3y_2^-$$

3. Formulate and solve LP

```
library(lpSolveAPI)
gp_sl <- read.lp("C:/Users/Windows/Downloads/emax.lp")
gp_sl
```

```
## Model name:
##           X1      X2      X3      Y1P      Y1M      Y2M      Y2P
## Maximize   20     15     25     -6     -6     -3      0
## R1         6      4      5     -1      1      0      0 = 50
## R2         8      7      5      0      0      1     -1 = 75
## Kind       Std     Std     Std     Std     Std     Std     Std
## Type       Real    Real    Real    Real    Real    Real    Real
## Upper      Inf     Inf     Inf     Inf     Inf     Inf     Inf
## Lower       0      0      0      0      0      0      0
```

```
solve(gp_sl)
```

```
## [1] 0
```

```
get.objective(gp_sl)
```

```
## [1] 225
```

```
get.variables(gp_sl)
```

```
## [1] 0 0 15 25 0 0 0
```

Conclusion

$Z = 225$ mil d, $x_1 = x_2 = 0$, $x_3 = 15$, $y_{1p} = 25$, $y_{1m} = y_{2m} = y_{2p} = 0$. Profit is $25 \times 15 = 375$ mil d. Employment is 7500 which has 2500 employees more than the goal so $y_{1p} = 25$, $y_{1m} = 0$. Earnings next year is 75 millions of dollars which is the same with the goal so $y_{2m} = y_{2p} = 0$.