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**Due:** 10/06/2025 2pm 11:59 PM ET

# (1) Written Problems

# (1.1) Hard-Coding Networks

So, for this problem, we need to create a neural network that can identify a superlative superincreasing sequence. Our input vector is  $\mathbb{R}^{1\times 4}$ , our hidden layer is  $\mathbb{R}^{1\times 3}$ , and our output layer is  $\{0,1\}\in\mathbb{R}^{1\times 1}$ . It's recommended to use the hard threshold activation function and the indicator activation function.

My approach to this problem is to use each hidden neuron to test each step of the superincreasing sequence. So the first neuron will test if  $x_2 > x_1$ , the second neuron will test if  $x_3 > x_1 + x_2$ , and the third neuron will test if  $x_4 > x_1 + x_2 + x_3$ . Because superincreasing sequences must be **strictly increasing**, ties will be treated as failures. The output neuron will then use the indicator function to check that all three hidden neurons "passed" their tests.

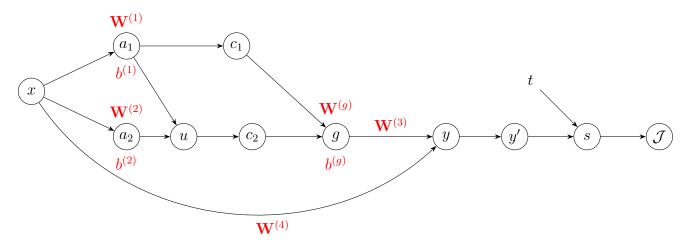
Our hidden layer weights and biases are:

$$\mathbf{W}^{(1)} = \begin{pmatrix} 1 & -1 & 0 & 0 \\ 1 & 1 & -1 & 0 \\ 1 & 1 & 1 & -1 \end{pmatrix} \quad \mathbf{b}^{(1)} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \mathbf{w}^{(2)} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \quad b^{(2)} = 1$$

Our first hidden neurons are all using the hard threshold activation function, and our output neuron is using the indicator activation function. From row 1, a value of 0 is considered a pass, and a value of 1 is considered a fail. From row 2, any value outside of [-1,1] is a failure. Hence, the weights of second row are all 1s, and the bias is 1.

# (1.2) Backpropagation

# Computational Graph



### **Backwards Pass**

$$\overline{\mathcal{J}} = 1$$

$$\overline{\mathbf{s}} = -\overline{\mathcal{J}} = -1 \cdot 1 = -1$$

$$\overline{\mathbf{y}'} = \overline{\mathbf{s}}(\mathbf{y} - \mathbf{t}) = \mathbf{t} - \mathbf{y}$$

$$\overline{\mathbf{y}} = \overline{\mathbf{y}'} \cdot \operatorname{softmax'}(\mathbf{y})$$

$$\overline{\mathbf{g}} = \mathbf{W}^{(3)T} \cdot \overline{\mathbf{y}}$$

$$\overline{\mathbf{W}^{(3)}} = \overline{\mathbf{y}} \cdot \mathbf{g}^{T}$$

$$\overline{\mathbf{W}^{(g)}} = \overline{\mathbf{g}} \cdot \begin{pmatrix} \mathbf{c}_{1} \\ \mathbf{c}_{2} \end{pmatrix}^{T}$$

$$\overline{b^{(g)}} = \overline{\mathbf{g}}$$

$$\overline{c_{1}} = \mathbf{W}_{c_{1}}^{(g)} \cdot \overline{\mathbf{g}}$$

$$\overline{c_{2}} = \mathbf{W}_{c_{2}}^{(g)} \cdot \overline{\mathbf{g}}$$

$$\overline{\mathbf{u}} = \overline{c_{2}} \cdot \operatorname{ReLU'}(c_{2})$$

$$\overline{\mathbf{W}^{(2)}} = \overline{\mathbf{u}} \cdot \mathbf{x}^{T}$$

$$\overline{b^{(2)}} = \overline{\mathbf{a}_{2}}$$

$$\overline{\mathbf{a}_{2}} = \overline{\mathbf{u}}$$

$$\overline{\mathbf{W}^{(1)}} = \overline{\mathbf{a}_{1}} \cdot \mathbf{x}^{T}$$

$$\overline{b^{(1)}} = \overline{\mathbf{a}_{1}}$$

$$\overline{\mathbf{a}_{1}} = \overline{\mathbf{u}} + \overline{c_{1}} \cdot \sigma'(a_{1})$$

$$\overline{\mathbf{x}} = \mathbf{W}^{(1)T} \cdot \overline{\mathbf{a}_{1}} + \mathbf{W}^{(2)T} \cdot \overline{\mathbf{a}_{2}} + \mathbf{W}^{(4)T} \cdot \overline{\mathbf{y}}$$

# (1.3) Automatic Differentiation

#### Compute Hessian

Our loss function is

$$L(\mathbf{x}) = \frac{1}{2} \mathbf{x}^T \mathbf{v} \mathbf{v}^T \mathbf{x}$$

A quick simplification (note that  $\mathbf{v}^T\mathbf{x}$  is a scalar, so it's equal to its own transpose):

$$L(\mathbf{x}) = \frac{1}{2} \mathbf{x}^T \mathbf{v} \mathbf{v}^T \mathbf{x}$$
$$= \frac{1}{2} (\mathbf{v}^T \mathbf{x}) (\mathbf{x}^T \mathbf{v})$$
$$= \frac{1}{2} (\mathbf{v}^T \mathbf{x})^2$$

We can see that this is a quadratic form  $(\frac{1}{2}\mathbf{x}^T\mathbf{v}\mathbf{v}^T\mathbf{x} = \frac{1}{2}\mathbf{x}^T\mathbf{A}\mathbf{x})$ .

So, the gradient is:

$$\nabla L(\mathbf{x}) = \frac{1}{2}(\mathbf{A} + \mathbf{A}^T)\mathbf{x}$$
$$= \frac{1}{2}(\mathbf{v}\mathbf{v}^T + \mathbf{v}^T\mathbf{v})\mathbf{x}$$
$$= \mathbf{v}\mathbf{v}^T\mathbf{x}$$

And the Hessian is:

$$\nabla^2 L(\mathbf{x}) = \mathbf{A}$$
$$= \mathbf{v} \mathbf{v}^T$$

Now that we have the correct Hessian formula, lets plug in our values for  ${\bf v}$  and then solve for  ${\bf x}$ 

$$\mathbf{v}^{T} = [3, 1, 4] \implies \mathbf{v} = \begin{pmatrix} 3 \\ 1 \\ 4 \end{pmatrix}$$

$$\nabla^{2} L(\mathbf{x}) = \mathbf{v} \mathbf{v}^{T}$$

$$= \begin{pmatrix} 3 \\ 1 \\ 4 \end{pmatrix} \begin{pmatrix} 3 & 1 & 4 \end{pmatrix}$$

$$= \begin{pmatrix} 9 & 3 & 12 \\ 3 & 1 & 4 \\ 12 & 4 & 16 \end{pmatrix}$$

$$\mathbf{x}^{T} = [2, 1, 3] \implies \mathbf{x} = \begin{pmatrix} 2 \\ 1 \\ 3 \end{pmatrix}$$

$$\nabla^{2}L(\mathbf{x}) = \begin{pmatrix} 9 & 3 & 12 \\ 3 & 1 & 4 \\ 12 & 4 & 16 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \\ 3 \end{pmatrix}$$

$$= \begin{pmatrix} 9 \cdot 2 + 3 \cdot 1 + 12 \cdot 3 \\ 3 \cdot 2 + 1 \cdot 1 + 4 \cdot 3 \\ 12 \cdot 2 + 4 \cdot 1 + 16 \cdot 3 \end{pmatrix}$$

$$= \begin{pmatrix} 57 \\ 19 \\ 76 \end{pmatrix}$$

**Computation Cost** The cost of explicitly computing the Hessian using automatic differentiation is  $O(n^2)$ , where n is the dimension of  $\mathbf{x}$ . This is because the Hessian is an  $n \times n$  matrix, and each entry requires O(1) time to compute. Therefore, the total time complexity is  $O(n^2)$ .

However, we could compute the Hessian-vector product efficiently using the formula  $\nabla^2 L(\mathbf{x}) = \mathbf{v}(\mathbf{v}^T\mathbf{x})$ . This would only require O(n) time, since we only need to compute the dot product  $\mathbf{v}^T\mathbf{x}$  and then scale  $\mathbf{v}$  by that scalar.

## 1.3.1 Vector-Hessian Products

Hah, looks like I got a bit ahead of myself in the previous section. We'll explicitly compute the vector-Hessian product here.

$$\mathbf{z} = \mathbf{H}\mathbf{y} = (\mathbf{v}\mathbf{v}^T)\mathbf{y}$$
  
 $\mathbf{v}^T = [4, 2, 1]$   
 $\mathbf{y}^T = [2, 2, 1]$ 

Reverse-mode autodiff:

$$\mathbf{v}^{T}\mathbf{y} = 4 \cdot 2 + 2 \cdot 2 + 1 \cdot 1 = 13$$
$$\mathbf{z} = 13 \cdot \begin{pmatrix} 4 \\ 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 52 \\ 26 \\ 13 \end{pmatrix}$$

Forward-mode autodiff:

$$\mathbf{v}\mathbf{v}^T = \begin{pmatrix} 16 & 8 & 4 \\ 8 & 4 & 2 \\ 4 & 2 & 1 \end{pmatrix}$$

$$\mathbf{z} = \begin{pmatrix} 16 & 8 & 4 \\ 8 & 4 & 2 \\ 4 & 2 & 1 \end{pmatrix} \begin{pmatrix} 2 \\ 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 52 \\ 26 \\ 13 \end{pmatrix}$$

## Computation Efficiency

$$\mathbf{H} = \mathbf{v}\mathbf{v}^T$$
 $\mathbf{Z} = \mathbf{H}\mathbf{y}_1\mathbf{y}_2^T = \mathbf{v}(\mathbf{v}^T\mathbf{y}_1)\mathbf{y}_2^T$ 

Let's evaluate how many operations this takes using forward-mode and reverse-mode autodiff.

 $\mathbf{v} \in \mathbb{R}^n, \mathbf{y}_1 \in \mathbb{R}^n, \mathbf{y}_2 \in \mathbb{R}^m$ 

Reverse-mode autodiff: 
$$\mathbf{y}_2\mathbf{y}_1^T = \mathbf{Y} \in \mathbb{R}^{n \times m} = O(nm) \text{ operations to compute}$$

$$\mathbf{v}^T\mathbf{Y} = \mathbf{a} \in \mathbb{R}^{1 \times m} = O(n^2) \text{ operations to compute}$$

$$\mathbf{va} = \mathbf{Z} \in \mathbb{R}^{n \times m} = O(nm) \text{ operations to compute}$$

$$\text{Total: } O(nm) + O(n^2) + O(nm) = O(n^2 + nm) \text{ operations}$$

$$= O(n^2) \text{ if } m \leq n. \quad O(nm) \text{ if } m > n$$

$$\mathbf{Forward\text{-mode}}$$

$$\mathbf{vv}^T = \mathbf{H} \in \mathbb{R}^{n \times n} = O(n^2) \text{ operations to compute}$$

$$\mathbf{Hy}_1 = \mathbf{z} \in \mathbb{R}^{n \times 1} = O(n^2) \text{ operations to compute}$$

 $\mathbf{H}\mathbf{y}_1 = \mathbf{z} \in \mathbb{R}^{n \times 1} = O(n^2) \text{ operations to compute}$   $\mathbf{z}\mathbf{y}_2^T = \mathbf{Z} \in \mathbb{R}^{n \times m} = O(nm) \text{ operations to compute}$ Total:  $O(n^2) + O(n^2) + O(nm) = O(n^2 + nm)$  operations

We can see that if m < n reverse-mode is more efficient, and if m > n forward-mode is more efficient.

# hw1 code adk2164

October 5, 2025

# 1 Programming Assignment 1: Learning Distributed Word Representations

Due Date: October 4, 2023 by 2pm

Submission: You must submit two files: 1. [] A PDF file containing your writeup, which will be the PDF export of this notebook (i.e., by printing this notebook webpage as PDF). Note that after you generate the PDF file of the Notebook, you will need to concatenate it with the PDF file of your solutions to written problems. Make sure that the relevant outputs (e.g. print\_gradients() outputs, plots, etc.) are included and clearly visible. The concatenated PDF file needs to be submitted to GradeScope. 2. [] The hw1\_code\_<YOUR\_UNI>.ipynb iPython Notebook, where <YOUR\_UNI> is your uni. This file needs to be submitted to the CourseWorks assignment page.

The programming assignments are individual work.

You should attempt all questions for this assignment. Most of them can be answered at least partially even if you were unable to finish earlier questions. If you think your computational results are incorrect, please say so; that may help you get partial credit.

#### 2 Introduction

In this assignment we will learn about word embeddings and make neural networks learn about words. We could try to match statistics about the words, or we could train a network that takes a sequence of words as input and learns to predict the word that comes next.

This assignment will ask you to implement a linear embedding and then the backpropagation computations for a neural language model and then run some experiments to analyze the learned representation. The amount of code you have to write is very short but each line will require you to think very carefully. You will need to derive the updates mathematically, and then implement them using matrix and vector operations in NumPy.

#### 3 Starter code and data

First, perform the required imports for your code:

```
[1]: from kret_studies import *
  from kret_studies.notebook import *
  from kret_studies.complex import *
```

Loaded environment variables from /Users/Akseldkw/Desktop/Columbia/COMS4776/.env.

```
[2]: import collections
  import pickle
  import numpy as np
  import os
  from tqdm import tqdm
  import pylab
  from six.moves.urllib.request import urlretrieve
  import tarfile
  import sys

TINY = 1e-30
  EPS = 1e-4
  nax = np.newaxis
```

If you're using colaboratory, this following script creates a folder - here we used 'A1' - in order to download and store the data. If you're not using colaboratory, then set the path to wherever you want the contents to be stored at locally.

You can also manually download and unzip the data from  $[http://www.cs.columbia.edu/\sim zemel/Class/Nndl/files/a1_data.tar.gz]$  and put them in the same folder as where you store this notebook.

Feel free to use a different way to access the files data.pk,  $partially\_trained.pk$ , and  $raw\_sentences.txt$ .

The file  $raw\_sentences.txt$  contains the sentences that we will be using for this assignment. These sentences are fairly simple ones and cover a vocabulary of only 250 words (+ 1 special [MASK] token word).

```
def get_file(
    fname, origin, untar=False, extract=False, archive_format="auto", __
 ⇔cache_dir="data"
):
    datadir = os.path.join(cache_dir)
    if not os.path.exists(datadir):
        os.makedirs(datadir)
    if untar:
        untar_fpath = os.path.join(datadir, fname)
        fpath = untar_fpath + ".tar.gz"
    else:
        fpath = os.path.join(datadir, fname)
    print("File path: %s" % fpath)
    if not os.path.exists(fpath):
        print("Downloading data from", origin)
        error msg = "URL fetch failure on {}: {} -- {}"
        try:
            try:
               urlretrieve(origin, fpath)
            except URLError as e:
                raise Exception(error_msg.format(origin, e.errno, e.reason))
            except HTTPError as e:
                raise Exception(error_msg.format(origin, e.code, e.msg))
        except (Exception, KeyboardInterrupt) as e:
            if os.path.exists(fpath):
                os.remove(fpath)
            raise
    if untar:
        if not os.path.exists(untar_fpath):
            print("Extracting file.")
            with tarfile.open(fpath) as archive:
                archive.extractall(datadir)
        return untar_fpath
    if extract:
        _extract_archive(fpath, datadir, archive_format)
    return fpath
```

```
[4]: # Download the dataset and partially pre-trained model
    drive_location = "/Users/Akseldkw/coding/Columbia/COMS4776-Data/data"
    get_file(
        fname="a1_data",
```

```
origin="http://www.cs.columbia.edu/~zemel/Class/Nndl/files/a1_data.tar.gz",
    untar=True,
    cache_dir=drive_location,
)
PARTIALLY_TRAINED_MODEL = drive_location + "/" + "partially_trained.pk"
data_location = drive_location + "/" + "data.pk"
```

File path: /Users/Akseldkw/coding/Columbia/COMS4776-Data/data/a1\_data.tar.gz Extracting file.

/var/folders/dj/k5kk5wk90vvcnb\_wphpw490r0000gn/T/ipykernel\_40096/1658915410.py:5 2: DeprecationWarning: Python 3.14 will, by default, filter extracted tar archives and reject files or modify their metadata. Use the filter argument to control this behavior.

archive.extractall(datadir)

We have already extracted the 4-grams from this dataset and divided them into training, validation, and test sets. To inspect this data, run the following:

```
[5]: data = pickle.load(open(data_location, "rb"))
    print(data["vocab"][0]) # First word in vocab is [MASK]
    print(data["vocab"][1])
    print(len(data["vocab"])) # Number of words in vocab
    print(data["vocab"]) # All the words in vocab
    print(data["train_inputs"][:10]) # 10 example training instances
```

```
[MASK]
all
251
['[MASK]', np.str_('all'), np.str_('set'), np.str_('just'), np.str_('show'),
np.str_('being'), np.str_('money'), np.str_('over'), np.str_('both'),
np.str_('years'), np.str_('four'), np.str_('through'), np.str_('during'),
np.str_('go'), np.str_('still'), np.str_('children'), np.str_('before'),
np.str_('police'), np.str_('office'), np.str_('million'), np.str_('also'),
np.str_('less'), np.str_('had'), np.str_(','), np.str_('including'),
np.str_('should'), np.str_('to'), np.str_('only'), np.str_('going'),
np.str_('under'), np.str_('has'), np.str_('might'), np.str_('do'),
np.str_('them'), np.str_('good'), np.str_('around'), np.str_('get'),
np.str_('very'), np.str_('big'), np.str_('dr.'), np.str_('game'),
np.str_('every'), np.str_('know'), np.str_('they'), np.str_('not'),
np.str_('world'), np.str_('now'), np.str_('him'), np.str_('school'),
np.str_('several'), np.str_('like'), np.str_('did'), np.str_('university'),
np.str_('companies'), np.str_('these'), np.str_('she'), np.str_('team'),
np.str_('found'), np.str_('where'), np.str_('right'), np.str_('says'),
np.str_('people'), np.str_('house'), np.str_('national'), np.str_('some'),
np.str_('back'), np.str_('see'), np.str_('street'), np.str_('are'),
np.str_('year'), np.str_('home'), np.str_('best'), np.str_('out'),
np.str_('even'), np.str_('what'), np.str_('said'), np.str_('for'),
np.str_('federal'), np.str_('since'), np.str_('its'), np.str_('may'),
```

```
np.str_('state'), np.str_('does'), np.str_('john'), np.str_('between'),
np.str_('new'), np.str_(';'), np.str_('three'), np.str_('public'), np.str_('?'),
np.str_('be'), np.str_('we'), np.str_('after'), np.str_('business'),
np.str_('never'), np.str_('use'), np.str_('here'), np.str_('york'),
np.str ('members'), np.str ('percent'), np.str ('put'), np.str ('group'),
np.str_('come'), np.str_('by'), np.str_('$'), np.str_('on'), np.str_('about'),
np.str_('last'), np.str_('her'), np.str_('of'), np.str_('could'),
np.str_('days'), np.str_('against'), np.str_('times'), np.str_('women'),
np.str_('place'), np.str_('think'), np.str_('first'), np.str_('among'),
np.str_('own'), np.str_('family'), np.str_('into'), np.str_('each'),
np.str_('one'), np.str_('down'), np.str_('because'), np.str_('long'),
np.str_('another'), np.str_('such'), np.str_('old'), np.str_('next'),
np.str_('your'), np.str_('market'), np.str_('second'), np.str_('city'),
np.str_('little'), np.str_('from'), np.str_('would'), np.str_('few'),
np.str_('west'), np.str_('there'), np.str_('political'), np.str_('two'),
np.str_('been'), np.str_('.'), np.str_('their'), np.str_('much'),
np.str_('music'), np.str_('too'), np.str_('way'), np.str_('white'),
np.str_(':'), np.str_('was'), np.str_('war'), np.str_('today'), np.str_('more'),
np.str_('ago'), np.str_('life'), np.str_('that'), np.str_('season'),
np.str_('company'), np.str_('-'), np.str_('but'), np.str_('part'),
np.str_('court'), np.str_('former'), np.str_('general'), np.str_('with'),
np.str_('than'), np.str_('those'), np.str_('he'), np.str_('me'),
np.str_('high'), np.str_('made'), np.str_('this'), np.str_('work'),
np.str_('up'), np.str_('us'), np.str_('until'), np.str_('will'), np.str_('ms.'),
np.str_('while'), np.str_('officials'), np.str_('can'), np.str_('were'),
np.str_('country'), np.str_('my'), np.str_('called'), np.str_('and'),
np.str_('program'), np.str_('have'), np.str_('then'), np.str_('is'),
np.str_('it'), np.str_('an'), np.str_('states'), np.str_('case'),
np.str_('say'), np.str_('his'), np.str_('at'), np.str_('want'), np.str_('in'),
np.str_('any'), np.str_('as'), np.str_('if'), np.str_('united'), np.str_('end'),
np.str_('no'), np.str_(')'), np.str_('make'), np.str_('government'),
np.str_('when'), np.str_('american'), np.str_('same'), np.str_('how'),
np.str_('mr.'), np.str_('other'), np.str_('take'), np.str_('which'),
np.str_('department'), np.str_('--'), np.str_('you'), np.str_('many'),
np.str ('nt'), np.str ('day'), np.str ('week'), np.str ('play'),
np.str_('used'), np.str_("'s"), np.str_('though'), np.str_('our'),
np.str ('who'), np.str ('yesterday'), np.str ('director'), np.str ('most'),
np.str_('president'), np.str_('law'), np.str_('man'), np.str_('a'),
np.str_('night'), np.str_('off'), np.str_('center'), np.str_('i'),
np.str_('well'), np.str_('or'), np.str_('without'), np.str_('so'),
np.str_('time'), np.str_('five'), np.str_('the'), np.str_('left')]
[[ 28 26 90 144]
 [184 44 249 117]
 [183 32 76 122]
 [117 247 201 186]
 [223 190 249
                6]
 [ 42 74 26
               32]
 [242 32 223 32]
```

[223 32 158 144] [74 32 221 32] [42 192 91 68]]

Now data is a Python dict which contains the vocabulary, as well as the inputs and targets for all three splits of the data. data['vocab'] is a list of the 251 words in the dictionary; data['vocab'][0] is the word with index 0, and so on. data['train\_inputs'] is a 372,500 x 4 matrix where each row gives the indices of the 4 consecutive context words for one of the 372,500 training cases. The validation and test sets are handled analogously.

Even though you only have to modify two specific locations in the code, you may want to read through this code before starting the assignment.

# 4 Part 1: GLoVE Word Representations (16pts)

In this part of the assignment, you will implement a simplified version of the GLoVE embedding (please see the handout for detailed description of the algorithm) with the loss defined as

$$L(\{\mathbf{w}_i, \tilde{\mathbf{w}}_i, b_i, \tilde{b}_i\}_{i=1}^V) = \sum_{i=1}^V \sum_{j=1}^V \left(\mathbf{w}_i^\top \tilde{\mathbf{w}}_j + b_i + \tilde{b}_j - \log X_{ij}\right)^2$$

Note that each word is represented by two d-dimensional embedding vectors  $\mathbf{w}_i, \tilde{\mathbf{w}}_i$  and two scalar biases  $b_i, \tilde{b}_i$ .

Answer the following questions:

# 4.1 1.1. GLoVE Parameter Count [1pt]

Given the vocabulary size V and embedding dimensionality d, how many parameters does the GLoVE model have? Note that each word in the vocabulary is associated with 2 embedding vectors and 2 biases.

1.1 **Answer**: Parameters = 2Vd + 2V = 2V(d+1)

# 4.2 1.2. Expression for gradient $\frac{\partial L}{\partial \mathbf{w}_i}$ and $\frac{\partial L}{\partial \mathbf{b}_i}$ [6pts]

Write the expression for  $\frac{\partial L}{\partial \mathbf{w}_i}$  and  $\frac{\partial L}{\partial \mathbf{b}_i}$ , the gradient of the loss function L with respect to parameter vector  $\mathbf{w}_i$  and  $\mathbf{b}_i$ . The gradient should be a function of  $\mathbf{w}, \tilde{\mathbf{w}}, b, \tilde{b}, X$  with appropriate subscripts (if any).

#### 1.2 **Answer**:

$$\begin{split} L(\{\mathbf{w}_i, \tilde{\mathbf{w}}_i, b_i, \tilde{b}_i\}_{i=1}^V) &= \sum_{i=1}^V \sum_{j=1}^V \left(\mathbf{w}_i^\top \tilde{\mathbf{w}}_j + b_i + \tilde{b}_j - \log X_{ij}\right)^2 \\ \frac{\partial L}{\partial \mathbf{w}_i} &= \sum_{j=1}^V 2 \left(\mathbf{w}_i^\top \tilde{\mathbf{w}}_j + b_i + \tilde{b}_j - \log X_{ij}\right) \tilde{\mathbf{w}}_j \\ \frac{\partial L}{\partial b_i} &= \sum_{j=1}^V 2 \left(\mathbf{w}_i^\top \tilde{\mathbf{w}}_j + b_i + \tilde{b}_j - \log X_{ij}\right) \end{split}$$

### 4.3 1.3. Implement the gradient update of GLoVE. [6pts]

#### See YOUR CODE HERE Comment below for where to complete the code

We have provided a few functions for training the embedding:

- calculate\_log\_co\_occurence computes the log co-occurrence matrix of a given corpus
- train\_GLoVE runs momentum gradient descent to optimize the embedding
- loss\_GLoVE:
- INPUT  $V \times d$  matrix W (collection of V embedding vectors, each d-dimensional);  $V \times d$  matrix W\_tilde;  $V \times 1$  vector b (collection of V bias terms);  $V \times 1$  vector b\_tilde;  $V \times V$  log co-occurrence matrix.
- OUTPUT loss of the GLoVE objective
- grad\_GLoVE: TO BE IMPLEMENTED.
- INPUT:
  - $-V \times d$  matrix W (collection of V embedding vectors, each d-dimensional), embedding for first word;
  - $-V \times d$  matrix W tilde, embedding for second word;
  - $-V \times 1$  vector **b** (collection of V bias terms);
  - $-V \times 1$  vector b tilde, bias for second word;
  - $-V \times V$  log co-occurrence matrix.
- OUTPUT:
  - $-V \times d$  matrix grad\_W containing the gradient of the loss function w.r.t. W;
  - $-V \times d$  matrix grad\_W\_tilde containing the gradient of the loss function w.r.t. W\_tilde;
  - $-V \times 1$  vector grad\_b which is the gradient of the loss function w.r.t. b.
  - $-V \times 1$  vector grad\_b\_tilde which is the gradient of the loss function w.r.t. b\_tilde.

Run the code to compute the co-occurrence matrix. Make sure to add a 1 to the occurrences, so there are no 0's in the matrix when we take the elementwise log of the matrix.

```
if symmetric:
    log_co_occurence[input[1], input[0]] += 1
    log_co_occurence[input[2], input[1]] += 1
    log_co_occurence[input[3], input[2]] += 1
    delta_smoothing = 0.5 # A hyperparameter. You can play with this if you_
want.
    log_co_occurence += delta_smoothing # Add delta so log doesn't break on_
o's.
    log_co_occurence = np.log(log_co_occurence)
    return log_co_occurence
```

[9]: vocab\_size

[9]: 251

TO BE IMPLEMENTED: Calculate the gradient of the loss function w.r.t. the parameters W,  $\tilde{W}$ ,  $\mathbf{b}$ , and  $\mathbf{b}$ . You should vectorize the computation, i.e. not loop over every word. The reading of the matrix cookbook from https://www.math.uwaterloo.ca/~hwolkowi/matrixcookbook.pdf might be useful.

$$\begin{split} L(\{\mathbf{w}_i, \tilde{\mathbf{w}}_i, b_i, \tilde{b}_i\}_{i=1}^V) &= \sum_{i=1}^V \sum_{j=1}^V \left(\mathbf{w}_i^\top \tilde{\mathbf{w}}_j + b_i + \tilde{b}_j - \log X_{ij}\right)^2 \\ \frac{\partial L}{\partial \mathbf{w}_i} &= \sum_{j=1}^V 2 \left(\mathbf{w}_i^\top \tilde{\mathbf{w}}_j + b_i + \tilde{b}_j - \log X_{ij}\right) \tilde{\mathbf{w}}_j \\ \frac{\partial L}{\partial b_i} &= \sum_{j=1}^V 2 \left(\mathbf{w}_i^\top \tilde{\mathbf{w}}_j + b_i + \tilde{b}_j - \log X_{ij}\right) \end{split}$$

```
else:
        W_tilde = t.cast(np.ndarray, W_tilde)
        b_tilde = t.cast(np.ndarray, b_tilde)
        return np.sum(
            (
                W @ W_tilde.T
                + b @ np.ones([1, n])
                + np.ones([n, 1]) @ b_tilde.T
                - log_co_occurence
            )
            ** 2
        )
def grad_GLoVE(
    W: np.ndarray,
    W_tilde: np.ndarray | None,
    b: np.ndarray,
    b_tilde: np.ndarray | None,
    log_co_occurence: np.ndarray,
):
    "Return the gradient of GLoVE objective w.r.t W and b."
    "INPUT: W - Vxd; W_tilde - Vxd; b - Vx1; b_tilde - Vx1; log_co_occurence:
 →VxV"
    "OUTPUT: grad_W - Vxd; grad_W_tilde - Vxd, grad_b - Vx1, grad_b_tilde - Vx1"
    n, _ = log_co_occurence.shape
    if not W_tilde is None and not b_tilde is None:
        loss = (
            W @ W_tilde.T
            + b @ np.ones([1, n])
            + np.ones([n, 1]) @ b_tilde.T
            - 0.5 * (log_co_occurence + log_co_occurence.T)
        )
        coef = 2
        grad_W = coef * (W_tilde.T @ loss).T
        grad_W_tilde = coef * (W.T @ loss).T
        grad_b = coef * (np.ones([1, n]) @ loss).T
        grad_b_tilde = coef * (np.ones([n, 1]).T @ loss).T
    else:
        loss = (
            W @ W.T
            + b @ np.ones([1, n])
            + np.ones([n, 1]) @ b.T
            - 0.5 * (log_co_occurence + log_co_occurence.T)
        grad_W = 4 * (W.T @ loss).T
```

```
grad_W_tilde = None
       grad_b = 4 * (np.ones([1, n]) @ loss).T
       grad_b_tilde = None
   return grad_W, grad_W_tilde, grad_b, grad_b_tilde
def train_GLoVE(
   W: np.ndarray,
   W_tilde: np.ndarray | None,
   b: np.ndarray,
   b_tilde: np.ndarray | None,
   log_co_occurence_train: np.ndarray,
   log_co_occurence_valid: np.ndarray,
   n_epochs: int,
   do_print: bool = False,
):
   "Traing W and b according to GLoVE objective."
   n, _ = log_co_occurence_train.shape
   learning_rate = 0.05 / n # A hyperparameter. You can play with this if
 you want.
   for epoch in range(n_epochs):
       grad_W, grad_W_tilde, grad_b, grad_b_tilde = grad_GLoVE(
           W, W_tilde, b, b_tilde, log_co_occurence_train
       W = W - learning_rate * grad_W
       b = b - learning_rate * grad_b
       if not grad_W_tilde is None and not grad_b_tilde is None:
           W_tilde = W_tilde - learning_rate * grad_W_tilde
           b_tilde = b_tilde - learning_rate * grad_b_tilde
       train_loss, valid_loss = loss_GLoVE(
           W, W_tilde, b, b_tilde, log_co_occurence_train
       ), loss_GLoVE(W, W_tilde, b, b_tilde, log_co_occurence_valid)
       if do_print:
           print(
               f"Train Loss: {train_loss}, valid loss: {valid_loss}, grad_norm:
 return W, W_tilde, b, b_tilde, train_loss, valid_loss
```

Train the GLoVE model for a range of embedding dimensions

```
[100]: """NOTE only rerun cell to reset cached values"""

Asym_W_final_2d, Asym_b_final_2d = None, None
Asym_W_tilde_final_2d, Asym_b_tilde_final_2d = None, None
W_final_2d, b_final_2d = None, None
```

```
model_vals: dict[tuple[int, str, str], float] = {}
[101]: np.random.seed(1)
       n epochs = 500 # A hyperparameter. You can play with this if you want.
       embedding_dims = np.array(
           [1, 2, 5, 8, 10, 32, 64, 128, 256, 512, 1024, 2048, 4096]
       ) # Play with this
       # embedding_dims = np.array([1, 2, 10, 128, 256, 1024, 4096]) # Play with this
       # Store the final losses for graphing
[102]: | # If you want to see diagnostic information during training
       def train_GloVE(
           embedding dims: np.ndarray, do_print: bool = False, recompute: bool = False
       ):
           for embedding_dim in tqdm(embedding_dims):
               if not recompute and embedding_dim in [key[0] for key in model_vals.
        ⇒keys()]:
                   # don't re-train if we've already trained this embedding size
                   print(f"Skipping embedding dim {embedding_dim} since already_
        ⇔trained")
                   continue
               else:
                   print(f"Training embedding dim {embedding_dim}")
               init_variance = 0.1 # A hyperparameter. You can play with this if you_
        \rightarrow want.
               W = init_variance * np.random.normal(size=(vocab_size, embedding_dim))
               W_tilde = init_variance * np.random.normal(size=(vocab_size,_
        →embedding_dim))
               b = init_variance * np.random.normal(size=(vocab_size, 1))
               b_tilde = init_variance * np.random.normal(size=(vocab_size, 1))
               if do print:
                   print(f"Training for embedding dimension: {embedding_dim}")
               # Train Asym model on Asym Co-Oc matrix
                   Asym_W_final,
                   Asym_W_tilde_final,
                   Asym_b_final,
                   Asym_b_tilde_final,
                   train_loss,
                   valid_loss,
               ) = train_GLoVE(
                   W,
                   W_tilde,
```

```
b_tilde,
           asym_log_co_occurence_train,
           asym_log_co_occurence_valid,
          n_epochs,
          do_print=do_print,
       if embedding_dim == 2:
           # Save a parameter copy if we are training 2d embedding for u
\hookrightarrow visualization later
           global Asym_W_final_2d, Asym_b_final_2d, Asym_W_tilde_final_2d,__
→Asym_b_tilde_final_2d
           Asym_W_final_2d = Asym_W_final
           Asym_W_tilde_final_2d = Asym_W_tilde_final
           Asym_b_final_2d = Asym_b_final
           Asym_b_tilde_final_2d = Asym_b_tilde_final
      model_vals[(embedding_dim, "Asym", "train")] = train_loss
      model_vals[(embedding_dim, "Asym", "val")] = valid_loss
       # asymModel_asymCoOc_final_train_losses += [train_loss]
       # asymModel_asymCoOc_final_val_losses += [valid_loss]
      if do_print:
           print(f"Final validation loss: {valid_loss}")
       # Train Sym model on Asym Co-Oc matrix
      W_final, W_tilde final, b_final, b_tilde_final, train_loss, valid_loss_
⇒= (
           train_GLoVE(
               W,
               None,
               b,
               None,
               asym_log_co_occurence_train,
               asym_log_co_occurence_valid,
               n_epochs,
               do_print=do_print,
           )
      )
       if embedding dim == 2:
           # Save a parameter copy if we are training 2d embedding for
⇔visualization later
           global W_final_2d, b_final_2d
           W_final_2d = W_final
           b_final_2d = b_final
      model_vals[(embedding_dim, "Sym", "train")] = train_loss
      model_vals[(embedding_dim, "Sym", "val")] = valid_loss
      if do_print:
           print(f"Final validation loss: {valid_loss}")
```

```
def model_dict_to_list(
    model_vals: dict[tuple[int, str, str], float],
    sym: t.Literal["Sym", "Asym"],
    train_or_val: t.Literal["train", "val"],
):
    return [
         val
        for key, val in model_vals.items()
         if key[1] == sym and key[2] == train_or_val
    1
train_GloVE(embedding_dims=embedding_dims, do_print=False, recompute=False)
asymModel_asymCoOc_final_train_losses = model_dict_to_list(model_vals, "Asym", u

¬"train")

asymModel_asymCoOc_final_val_losses = model_dict_to_list(model_vals, "Asym", __

¬"val")

symModel_asymCoOc_final_train_losses = model_dict_to_list(model_vals, "Sym", u

¬"train")

symModel_asymCoOc_final_val_losses = model_dict_to_list(model_vals, "Sym", __
  ⇔"val")
  0%1
               | 0/13 [00:00<?, ?it/s]
Training embedding dim 1
               | 1/13 [00:00<00:10, 1.14it/s]
  8%1
Training embedding dim 2
              | 2/13 [00:01<00:09, 1.21it/s]
Training embedding dim 5
             | 3/13 [00:02<00:08, 1.20it/s]
Training embedding dim 8
             | 4/13 [00:04<00:10, 1.14s/it]
31%|
Training embedding dim 10
 38%1
             | 5/13 [00:05<00:10, 1.31s/it]
Training embedding dim 32
46%1
             | 6/13 [00:08<00:11, 1.67s/it]
Training embedding dim 64
            | 7/13 [00:10<00:10, 1.79s/it]
54%|
```

```
Training embedding dim 128
62%|
            | 8/13 [00:12<00:09, 1.96s/it]
Training embedding dim 256
           | 9/13 [00:15<00:08, 2.15s/it]
Training embedding dim 512
           | 10/13 [00:18<00:08, 2.67s/it]
77%|
Training embedding dim 1024
85%1
           | 11/13 [00:24<00:07, 3.61s/it]
Training embedding dim 2048
92%|
          | 12/13 [00:34<00:05, 5.46s/it]
Training embedding dim 4096
          | 13/13 [00:54<00:00, 4.16s/it]
100%|
```

Plot the training and validation losses against the embedding dimension.

### 4.4 1.4. Effect of embedding dimension d [3pts]

Train the both the symmetric and asymmetric GLoVe model with varying dimensionality d by running the cell below. Comment on: 1. Which d leads to optimal validation performance for the asymmetric and symmetric models? 2. Why does / doesn't larger d always lead to better validation error? 3. Which model is performing better, and why?

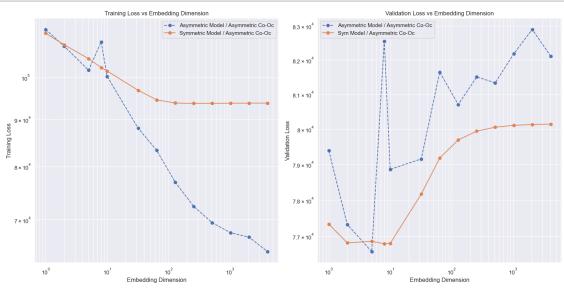
#### 1.4 Answer:

- 1. Larger d leads to better training loss for both models, but the validation loss increases after d=10 for both models.
- 2. Overfitting is likely occurring, as evidenced by the divergence between training and validation losses at higher embedding dimensions.
- 3. The Asymmetric model performs much better in training, but doesn't generalize as well as the symmetric model, and has worse validation loss across all values of d

```
[85]: fig, ax = uks_mpl.subplots(2, 1, 8, 8) # my personal matplotlib wrapper func
ax[0].loglog(
    embedding_dims,
    asymModel_asymCoOc_final_train_losses,
    label="Asymmetric Model / Asymmetric Co-Oc",
    marker="o",
    linestyle="--",
)
ax[0].loglog(
    embedding_dims,
    symModel_asymCoOc_final_train_losses,
    marker="o",
    label="Symmetric Model / Asymmetric Co-Oc",
```

```
ax[0].set_xlabel("Embedding Dimension")
ax[0].set_ylabel("Training Loss")
ax[1].loglog(
    embedding_dims,
    asymModel_asymCoOc_final_val_losses,
    label="Asymmetric Model / Asymmetric Co-Oc",
    linestyle="--",
    marker="o",
ax[1].loglog(
    embedding_dims,
    symModel_asymCoOc_final_val_losses,
    label="Sym Model / Asymmetric Co-Oc",
    marker="o",
)
ax[1].set_xlabel("Embedding Dimension")
ax[1].set_ylabel("Validation Loss")
ax[0].set_title("Training Loss vs Embedding Dimension")
ax[1].set_title("Validation Loss vs Embedding Dimension")
uks_mpl.style_axes(fig, ax)
fig
```

[85]:



# 5 Part 2: Training the model (26pts)

We will modify the architecture slightly from the previous section, inspired by BERT (Devlin et al., 2018). Instead of having only one output, the architecture will now take in N=4 context words, and also output predictions for N=4 words. See Figure 2 diagram in the handout for the diagram of this architecture.

During training, we randomly sample one of the N context words to replace with a [MASK] token. The goal is for the network to predict the word that was masked, at the corresponding output word position. In practice, this [MASK] token is assigned the index 0 in our dictionary. The weights  $W^{(2)} = \text{hid\_to\_output\_weights}$  now has the shape  $NV \times H$ , as the output layer has NV neurons, where the first V output units are for predicting the first word, then the next V are for predicting the second word, and so on. We call this as concatenating output units across all word positions, i.e. the (j+nV)-th column is for the word j in vocabulary for the n-th output word position. Note here that the softmax is applied in chunks of V as well, to give a valid probability distribution over the V words. Only the output word positions that were masked in the input are included in the cross entropy loss calculation:

There are three classes defined in this part: Params, Activations, Model. You will make changes to Model, but it may help to read through Params and Activations first.

$$C = -\sum_{i}^{B} \sum_{n}^{N} \sum_{j}^{V} m_{n}^{(i)}(t_{n,j}^{(i)} \log y_{n,j}^{(i)}),$$

Where  $y_{n,j}^{(i)}$  denotes the output probability prediction from the neural network for the *i*-th training example for the word *j* in the *n*-th output word, and  $t_{n,j}^{(i)}$  is 1 if for the *i*-th training example, the word *j* is the *n*-th word in context. Finally,  $m_n^{(i)} \in \{0,1\}$  is a mask that is set to 1 if we are predicting the *n*-th word position for the *i*-th example (because we had masked that word in the input), and 0 otherwise.

There are three classes defined in this part: Params, Activations, Model. You will make changes to Model, but it may help to read through Params and Activations first.

```
[86]: class Params(object):

"""A class representing the trainable parameters of the model. This class has five fields:

word_embedding_weights, a matrix of size V x D, where V is the number of words in the vocabulary

and D is the embedding dimension.

embed_to_hid_weights, a matrix of size H x ND, where H is the number of hidden units. The first D

columns represent connections from the embedding of the first → context word, the next D columns

for the second context word, and so on. There are N context words.

hid_bias, a vector of length H

hid_to_output_weights, a matrix of size NV x H

output_bias, a vector of length NV"""
```

```
def __init__(
      self,
      word_embedding_weights: np.ndarray,
      embed_to_hid_weights: np.ndarray,
      hid_to_output_weights: np.ndarray,
      hid_bias: np.ndarray,
      output_bias: np.ndarray,
  ):
      self.word embedding weights = word embedding weights
      self.embed to hid weights = embed to hid weights
      self.hid_to_output_weights = hid_to_output_weights
      self.hid bias = hid bias
      self.output_bias = output_bias
  def copy(self):
      return self.__class__(
          self.word_embedding_weights.copy(),
          self.embed_to_hid_weights.copy(),
          self.hid_to_output_weights.copy(),
          self.hid_bias.copy(),
          self.output_bias.copy(),
      )
  Oclassmethod
  def zeros(cls, vocab size: int, context len: int, embedding dim: int,
→num hid: int):
      """A constructor which initializes all weights and biases to 0."""
      word_embedding_weights = np.zeros((vocab_size, embedding_dim))
      embed_to_hid_weights = np.zeros((num hid, context_len * embedding dim))
      hid_to_output_weights = np.zeros((vocab_size * context_len, num_hid))
      hid bias = np.zeros(num hid)
      output_bias = np.zeros(vocab_size * context_len)
      return cls(
          word_embedding_weights,
          embed_to_hid_weights,
          hid_to_output_weights,
          hid_bias,
          output_bias,
      )
  Oclassmethod
  def random_init(
      cls,
      init_wt: float,
      vocab_size: int,
      context len: int,
```

```
embedding_dim: int,
      num_hid: int,
  ):
       """A constructor which initializes weights to small random values and \Box
⇔biases to 0."""
      word embedding weights = np.random.normal(
          0.0, init_wt, size=(vocab_size, embedding_dim)
      )
      embed_to_hid_weights = np.random.normal(
          0.0, init_wt, size=(num_hid, context_len * embedding_dim)
      hid_to_output_weights = np.random.normal(
          0.0, init_wt, size=(vocab_size * context_len, num_hid)
      hid_bias = np.zeros(num_hid)
      output_bias = np.zeros(vocab_size * context_len)
      return cls(
          word_embedding_weights,
          embed_to_hid_weights,
          hid_to_output_weights,
          hid bias,
          output_bias,
      )
  ###### The functions below are Python's somewhat oddball way of overloading_
⇔operators, so that
  ###### we can do arithmetic on Params instances. You don't need to
⇔understand this to do the assignment.
  def __mul__(self, a: float):
      return self.__class_ (
          a * self.word_embedding_weights,
          a * self.embed_to_hid_weights,
          a * self.hid_to_output_weights,
          a * self.hid_bias,
          a * self.output_bias,
      )
  def __rmul__(self, a: float):
      return self * a
  def __add__(self, other: "Params"):
      return self.__class__(
          self.word_embedding_weights + other.word_embedding_weights,
          self.embed_to_hid_weights + other.embed_to_hid_weights,
           self.hid_to_output_weights + other.hid_to_output_weights,
           self.hid_bias + other.hid_bias,
```

```
self.output_bias + other.output_bias,
               )
          def __sub__(self, other: "Params"):
               return self + -1.0 * other
[87]: class Activations(object):
           """A class representing the activations of the units in the network. This_{\sqcup}
        ⇔class has three fields:
           embedding_layer, a matrix of B x ND matrix (where B is the batch size, D is_{\sqcup}
       → the embedding dimension,
                   and N is the number of input context words), representing the
       →activations for the embedding
                   layer on all the cases in a batch. The first D columns represent \Box
       \hookrightarrow the embeddings for the
                   first context word, and so on.
          hidden_layer, a B x H matrix representing the hidden layer activations for ____
        \hookrightarrow a batch
           output_layer, a B x V matrix representing the output layer activations for_
        \hookrightarrow a batch
           .....
          def init (
               self,
               embedding layer: np.ndarray,
               hidden_layer: np.ndarray,
               output_layer: np.ndarray,
          ):
               self.embedding_layer = embedding_layer
               self.hidden_layer = hidden_layer
               self.output_layer = output_layer
      def get_batches(inputs: np.ndarray, batch_size: int, shuffle: bool = True):
           """Divide a dataset (usually the training set) into mini-batches of a given \Box
       \Rightarrowsize. This is a
           'generator', i.e. something you can use in a for loop. You don't need to \sqcup
       \hookrightarrowunderstand how it
          works to do the assignment."""
          if inputs.shape[0] % batch_size != 0:
               raise RuntimeError(
                   "The number of data points must be a multiple of the batch size."
          num_batches = inputs.shape[0] // batch_size
```

```
if shuffle:
   idxs = np.random.permutation(inputs.shape[0])
   inputs = inputs[idxs, :]

for m in range(num_batches):
   yield inputs[m * batch_size : (m + 1) * batch_size, :]
```

In this part of the assignment, you implement a method which computes the gradient using back-propagation. To start you out, the *Model* class contains several important methods used in training:

- compute\_activations computes the activations of all units on a given input batch
- compute\_loss computes the total cross-entropy loss on a mini-batch
- evaluate computes the average cross-entropy loss for a given set of inputs and targets

You will need to complete the implementation of two additional methods which are needed for training, and print the outputs of the gradients.

## 2.1 Implement gradient with respect to output layer inputs [8pts] \* [] TO BE IMPLE-MENTED: compute\_loss\_derivative computes the derivative of the loss function with respect to the output layer inputs.

In other words, if C is the cost function, and the softmax computation for the j-th word in vocabulary for the n-th output word position is:

$$y_{n,j} = \frac{e^{z_{n,j}}}{\sum_{l} e^{z_{n,l}}}$$

This function should compute a  $B \times NV$  matrix where the entries correspond to the partial derivatives  $\partial C/\partial z_j^n$ . Recall that the output units are concatenated across all positions, i.e. the (j+nV)-th column is for the word j in vocabulary for the n-th output word position.

#### 5.1 2.2 Implement gradient with respect to parameters [8pts]

□ TO BE IMPLEMENTED: back\_propagate is the function which computes the gradient of the loss with respect to model parameters using backpropagation. It uses the derivatives computed by compute\_loss\_derivative. Some parts are already filled in for you, but you need to compute the matrices of derivatives for embed\_to\_hid\_weights, hid\_bias, hid\_to\_output\_weights, and output\_bias. These matrices have the same sizes as the parameter matrices (see previous section).

In order to implement backpropagation efficiently, you need to express the computations in terms of matrix operations, rather than for loops. You should first work through the derivatives on pencil and paper. First, apply the chain rule to compute the derivatives with respect to individual units, weights, and biases. Next, take the formulas you've derived, and express them in matrix form. You should be able to express all of the required computations using only matrix multiplication, matrix transpose, and elementwise operations — no for loops! If you want inspiration, read through the code for Model.compute\_activations and try to understand how the matrix operations correspond to the computations performed by all the units in the network.

To make your life easier, we have provided the routine checking.check\_gradients, which checks your gradients using finite differences. You should make sure this check passes before continuing with the assignment.

```
[88]: class Model(object):
         ⇒various methods used in training
         the model and visualizing the learned representations. It has two fields:
             params, a Params instance which contains the model parameters
             vocab, a list containing all the words in the dictionary; vocab[0] is \sqcup
      \hookrightarrow the word with index
                   0, and so on."""
         def __init__(self, params: Params, vocab: list[str]):
             self.params = params
            self.vocab = vocab
            self.vocab size = len(vocab)
             self.embedding_dim = self.params.word_embedding_weights.shape[1]
             self.embedding_layer_dim = self.params.embed_to_hid_weights.shape[1]
             self.context_len = self.embedding_layer_dim // self.embedding_dim
             self.num_hid = self.params.embed_to_hid_weights.shape[0]
         def copy(self):
            return self.__class__(self.params.copy(), self.vocab[:])
         @classmethod
         def random_init(
            cls.
            init_wt: float,
            vocab: list,
            context_len: int,
            embedding_dim: int,
            num_hid: int,
         ):
             \hookrightarrow standard\ deviation\ init\_wt
             and initializes the biases to all zeros."""
            params = Params.random init(
                init_wt, len(vocab), context_len, embedding_dim, num_hid
            return Model(params, vocab)
         def indicator_matrix(
             self, targets: np.ndarray, mask_zero_index: bool = True
         ) -> np.ndarray:
```

```
"""Construct a matrix where the (k + j*V)th entry of row i is 1 if the
\rightarrow j-th target word
                 for example i is k, and all other entries are 0.
                 Note: if the j-th target word index is 0, this corresponds to the \sqcup
\hookrightarrow [MASK] token,
                                  and we set the entry to be 0.
                 batch_size, context_len = targets.shape
                 expanded_targets = np.zeros((batch_size, context_len * len(self.vocab)))
                 targets_offset = np.repeat(
                            (np.arange(context_len) * len(self.vocab))[np.newaxis, :],
                            batch size,
                           axis=0,
                 ) # [[0, V, 2V], [0, V, 2V], ...]
                 targets += targets_offset
                 for c in range(context_len):
                            expanded_targets[np.arange(batch_size), targets[:, c]] = 1.0
                            if mask_zero_index:
                                       # Note: Set the targets with index 0, V, 2V to be zero since it
⇔corresponds to the [MASK] token
                                      expanded_targets[np.arange(batch_size), targets_offset[:, c]] = __
→0.0
                 return expanded_targets
       def compute_loss_derivative(
                self,
                 output_activations: np.ndarray,
                 expanded_target_batch: np.ndarray,
                 target_mask: np.ndarray,
       ):
                 r"""Compute the derivative of the multiple target position
\neg cross-entropy loss function \n"
                            For example:
                     [y_{0}, 0] \dots y_{V-1} [y_{V}, \dots, y_{2*V-1}] [y_{2*V} \dots_{u}]
\neg y_{1}, 3*V-1] [y_{3*V} \dots y_{i,4*V-1}]
                     Where for colum j + n*V,
                            y_{j} + n*V = e^{2j} + n*V / sum_{m=0}^{V-1} e^{2m} + n*V / 
\hookrightarrow for n=0,\ldots,N-1
```

```
This function should return a dC / dz matrix of size [batch_size x_{\sqcup}]
⇔(vocab_size * context_len)],
        where each row i in dC / dz has columns 0 to V-1 containing the \Box
⇔gradient the 1st output
        context word from i-th training example, then columns vocab_size to_{\sqcup}
⇒2*vocab_size - 1 for the 2nd
        output context word of the i-th training example, etc.
        C is the loss function summed acrossed all examples as well:
            C = - \sup\{i, j, n\} \; mask_{\{i, n\}} \; (t_{\{i, j + n*V\}} \; log \; y_{\{i, j + n*V\}})_{, \sqcup} 
\hookrightarrow for j=0,\ldots,V, and n=0,\ldots,N
        where mask \{i,n\} = 1 if the i-th training example has n-th context word
\hookrightarrow as the target,
        otherwise mask \{i,n\} = 0.
        The arguments are as follows:
            output\_activations - A [batch\_size x (context\_len * vocab\_size)]_{\sqcup}
\hookrightarrow tensor,
                 for the activations of the output layer, i.e. the y j's.
            expanded\_target\_batch - A [batch\_size (context\_len * vocab\_size)]_{\sqcup}
\hookrightarrow tensor.
                 where expanded_target_batch[i, n*V: (n+1)*V] is the indicator_
⇔vector for
                 the n-th context target word position, i.e. the (i, j + n*V)_{i,j}
⇔entry is 1 if the
                 i'th example, the context word at position n is j, and O_{i,j}
\rightarrow otherwise.
            target_mask - A [batch_size x context_len x 1] tensor, where
\Rightarrow target_mask[i,n] = 1
                 if for the i'th example the n-th context word is a target \Box
\neg position, otherwise 0
        Outputs:
            loss\_derivative - A [batch\_size x (context\_len * vocab\_size)]_{\sqcup}
\hookrightarrow matrix.
                 where loss_derivative[i,0:vocab_size] contains the gradient
                 dC / dz_0 for the i-th training example gradient for 1st output
                 context word, and loss_derivative[i,vocab_size:2*vocab_size] for
                 the 2nd output context word of the i-th training example, etc.
        11 11 11
        ################################
                                          YOUR CODE HERE
```

```
# Reshape output activations and expanded target batch for easier
\hookrightarrow computation
      batch_size = output_activations.shape[0]
      context len = self.context len
      vocab_size = self.vocab_size
      output_activations_reshaped = output_activations.reshape(
          batch_size, context_len, vocab_size
      expanded_target_batch_reshaped = expanded_target_batch.reshape(
          batch_size, context_len, vocab_size
      target_mask reshaped = target_mask.reshape(batch_size, context_len, 1)
      # Compute the loss derivative: dC/dz = y - t, masked
      loss_derivative = (
          output_activations_reshaped - expanded_target_batch_reshaped
      ) * target_mask_reshaped
      loss_derivative = loss_derivative.reshape(batch_size, context_len *_
⇔vocab size)
      # print(
            loss_derivative,
            output_activations.shape,
            expanded_target_batch.shape,
            target mask.shape,
      # )
      return loss_derivative
def compute_loss(
      self, output_activations: np.ndarray, expanded_target_batch: np.ndarray
  ) -> float:
      """Compute the total loss over a mini-batch. expanded_target_batch is_\_
\hookrightarrow the matrix obtained
      by calling indicator_matrix on the targets for the batch."""
      return -np.sum(expanded_target_batch * np.log(output_activations +__
→TINY))
  def compute_activations(self, inputs: np.ndarray) -> Activations:
      """Compute the activations on a batch given the inputs. Returns an\sqcup
\hookrightarrow Activations instance.
```

```
You should try to read and understand this function, since this will \sqcup
⇒qive you clues for
      how to implement back_propagate."""
      batch_size = inputs.shape[0]
      if inputs.shape[1] != self.context len:
           raise RuntimeError(
               f"Dimension of the input vectors should be {self.context_len}, __
→but is instead {inputs.shape[1]}"
       # Embedding layer
       # Look up the input word indies in the word_embedding_weights matrix
       embedding_layer_state = np.zeros((batch_size, self.embedding_layer_dim))
      for i in range(self.context_len):
           embedding_layer_state[
               :, i * self.embedding_dim : (i + 1) * self.embedding_dim
           ] = self.params.word_embedding_weights[inputs[:, i], :]
       # Hidden layer
       inputs_to_hid = (
           np.dot(embedding_layer_state, self.params.embed_to_hid_weights.T)
           + self.params.hid_bias
       # Apply logistic activation function
      hidden_layer_state = 1.0 / (1.0 + np.exp(-inputs_to_hid))
       # Output layer
      inputs_to_softmax = (
           np.dot(hidden_layer_state, self.params.hid_to_output_weights.T)
           + self.params.output_bias
      )
       # Subtract maximum.
       \# Remember that adding or subtracting the same constant from each input_\sqcup
\hookrightarrow to a
       # softmax unit does not affect the outputs. So subtract the maximum to
       # make all inputs \leq 0. This prevents overflows when computing their
\hookrightarrow exponents.
      inputs_to_softmax -= inputs_to_softmax.max(1).reshape((-1, 1))
       # Take softmax along each V chunks in the output layer
      output_layer_state = np.exp(inputs_to_softmax)
      output_layer_state_shape = output_layer_state.shape
      output_layer_state = output_layer_state.reshape(
           (-1, self.context_len, len(self.vocab))
```

```
output_layer_state /= output_layer_state.sum(
          axis=-1, keepdims=True
      ) # Softmax along each target word
      output_layer_state = output_layer_state.reshape(
          output_layer_state_shape
      ) # Flatten back
      return Activations(
          embedding_layer_state, hidden_layer_state, output_layer_state
      )
  def back_propagate(
      self,
      input_batch: np.ndarray,
      activations: Activations,
      loss_derivative: np.ndarray,
  ) -> Params:
       """Compute the gradient of the loss function with respect to the \sqcup
\hookrightarrow trainable parameters
      of the model. The arguments are as follows:
            input batch - the indices of the context words
           →Model.compute_activations
            loss_derivative - the matrix of derivatives computed by \Box
⇒compute_loss_derivative
      Part of this function is already completed, but you need to fill in the ⊔
\rightarrow derivative
      computations for hid\_to\_output\_weights\_grad, output\_bias\_grad, _{\square}
⇔embed_to_hid_weights_grad,
       and hid\_bias\_grad. See the documentation for the Params class for a_{\sqcup}
\rightarrow description of what
      these matrices represent."""
      # The matrix with values dC / dz_j, where dz_j is the input to the jth_{\sqcup}
⇔hidden unit,
      # i.e. h_j = 1 / (1 + e^{-z_j})
      hid_deriv: np.ndarray = (
          np.dot(loss_derivative, self.params.hid_to_output_weights)
          * activations.hidden_layer
          * (1.0 - activations.hidden_layer)
      )
       ###############################
                                     YOUR CODE HERE
```

```
hid_to_output_weights_grad: np.ndarray = (
          loss_derivative.T @ activations.hidden_layer
      output_bias_grad: np.ndarray = np.sum(loss_derivative, axis=0)
      embed_to_hid_weights_grad: np.ndarray = (
          hid_deriv.T @ activations.embedding_layer
      hid_bias_grad: np.ndarray = np.sum(hid_deriv, axis=0)
# The matrix of derivatives for the embedding layer
      embed_deriv = np.dot(hid_deriv, self.params.embed_to_hid_weights)
      # Embedding layer
      word_embedding_weights_grad = np.zeros((self.vocab_size, self.
→embedding dim))
      for w in range(self.context_len):
          word_embedding_weights_grad += np.dot(
              self.indicator_matrix(
                 input_batch[:, w : w + 1], mask_zero_index=False
              ).T,
              embed_deriv[:, w * self.embedding_dim : (w + 1) * self.
→embedding_dim],
          )
      return Params(
          word_embedding_weights_grad,
          embed to hid weights grad,
          hid_to_output_weights_grad,
          hid_bias_grad,
          output_bias_grad,
      )
  def sample_input_mask(self, batch_size: int) -> np.ndarray:
      """Samples a binary mask for the inputs of size batch_size x context_len
      For each row, at most one element will be 1.
      mask_idx = np.random.randint(self.context_len, size=(batch_size,))
      mask = np.zeros(
          (batch_size, self.context_len), dtype=int
      ) # Convert to one hot B \times N, B batch size, N context len
      mask[np.arange(batch_size), mask_idx] = 1
      return mask
  def evaluate(self, inputs: np.ndarray, batch_size: int = 100):
      """Compute the average cross-entropy over a dataset.
```

```
inputs: matrix of shape D x N"""
      ndata = inputs.shape[0]
      total = 0.0
      for input_batch in get_batches(inputs, batch_size):
          mask = self.sample_input_mask(batch_size)
          input batch masked = input batch * (1 - mask)
          activations = self.compute_activations(input_batch_masked)
          target_batch_masked = input_batch * mask
          expanded_target_batch = self.indicator_matrix(target_batch_masked)
          cross_entropy = -np.sum(
              expanded_target_batch * np.log(activations.output_layer + TINY)
          total += cross_entropy
      return total / float(ndata)
  def display_nearest_words(self, word: str, k: int = 10):
      """List the k words nearest to a given word, along with their distances.
_ II II II
      if word not in self.vocab:
          print(f'Word "{word}" not in vocabulary.')
          return
      # Compute distance to every other word.
      idx = self.vocab.index(word)
      word_rep = self.params.word_embedding_weights[idx, :]
      diff = self.params.word_embedding_weights - word_rep.reshape((1, -1))
      distance = np.sqrt(np.sum(diff**2, axis=1))
      # Sort by distance.
      order = np.argsort(distance)
      order = order[
          1 : 1 + k
      ] # The nearest word is the query word itself, skip that.
      for i in order:
          print(f"{self.vocab[i]}: {distance[i]}")
  def word_distance(self, word1: str, word2: str) -> float:
       """Compute the distance between the vector representations of two words.
if word1 not in self.vocab:
          raise RuntimeError(f'Word "{word1}" not in vocabulary.')
```

```
if word2 not in self.vocab:
    raise RuntimeError(f'Word "{word2}" not in vocabulary.')

idx1, idx2 = self.vocab.index(word1), self.vocab.index(word2)
word_rep1 = self.params.word_embedding_weights[idx1, :]
word_rep2 = self.params.word_embedding_weights[idx2, :]
diff = word_rep1 - word_rep2
return np.sqrt(np.sum(diff**2))
```

## 5.2 2.3 Print the gradients [8pts]

To make your life easier, we have provided the routine check\_gradients, which checks your gradients using finite differences. You should make sure this check passes before continuing with the assignment. Once check\_gradients() passes, call print\_gradients() and include its output in your write-up.

```
[89]: def relative_error(a: float, b: float):
          return np.abs(a - b) / (np.abs(a) + np.abs(b))
      def check_output_derivatives(
          model: Model, input_batch: np.ndarray, target_batch: np.ndarray
      ):
          def softmax(z):
              z = z.copy()
              z -= z.max(-1, keepdims=True)
              y = np.exp(z)
              y /= y.sum(-1, keepdims=True)
              return y
          batch_size = input_batch.shape[0]
          z = np.random.normal(size=(batch_size, model.context_len, model.vocab_size))
          y = softmax(z).reshape((batch_size, model.context_len * model.vocab_size))
          z = z.reshape((batch_size, model.context_len * model.vocab_size))
          expanded_target_batch = model.indicator_matrix(target_batch)
          target_mask = expanded_target_batch.reshape(
              -1, model.context_len, len(model.vocab)
          ).sum(axis=-1, keepdims=True)
          loss_derivative = model.compute_loss_derivative(
              y, expanded_target_batch, target_mask
          )
          if loss_derivative is None:
              print("Loss derivative not implemented yet.")
              return False
```

```
if loss_derivative.shape != (batch_size, model.vocab_size * model.
 print(
            "Loss derivative should be size {} but is actually {}.".format(
                (batch_size, model.vocab_size), loss_derivative.shape
        return False
   def obj(z: np.ndarray):
        z = z.reshape((-1, model.context_len, model.vocab_size))
        y = softmax(z).reshape((batch_size, model.context_len * model.
 ⇔vocab_size))
        return model.compute_loss(y, expanded_target_batch)
   for count in range(1000):
        i, j = np.random.randint(0, loss_derivative.shape[0]), np.random.
 →randint(
            0, loss_derivative.shape[1]
        )
       z_plus = z.copy()
       z plus[i, j] += EPS
       obj_plus = obj(z_plus)
       z_minus = z.copy()
       z_minus[i, j] -= EPS
       obj_minus = obj(z_minus)
        empirical = (obj_plus - obj_minus) / (2.0 * EPS)
        rel = relative_error(empirical, loss_derivative[i, j])
        if rel > 1e-4:
            print(
                "The loss derivative has a relative error of {}, which is too⊔
 →large.".format(
                    rel
                )
           return False
   print("The loss derivative looks OK.")
   return True
def check_param_gradient(
   model: Model, param_name: str, input_batch: np.ndarray, target_batch: np.
 ⊶ndarray
```

```
):
   activations = model.compute_activations(input_batch)
    expanded_target_batch = model.indicator_matrix(target_batch)
   target_mask = expanded_target_batch.reshape(
        -1, model.context_len, len(model.vocab)
   ).sum(axis=-1, keepdims=True)
   loss_derivative = model.compute_loss_derivative(
        activations.output_layer, expanded_target_batch, target_mask
   param_gradient = model.back_propagate(input_batch, activations,__
 ⇒loss derivative)
   def obj(model: Model):
        activations = model.compute_activations(input_batch)
        return model.compute_loss(activations.output_layer,_
 →expanded_target_batch)
   dims = t.cast(np.ndarray, getattr(model.params, param_name)).shape
    is_matrix = len(dims) == 2
   if getattr(param_gradient, param_name).shape != dims:
       print(
            "The gradient for {} should be size {} but is actually {}.".format(
                param_name, dims, getattr(param_gradient, param_name).shape
            )
        )
        return
   for count in range(1000):
        if is_matrix:
            slc = np.random.randint(0, dims[0]), np.random.randint(0, dims[1])
        else:
            slc = np.random.randint(dims[0])
        model_plus = model.copy()
        getattr(model_plus.params, param_name)[slc] += EPS
        obj_plus = obj(model_plus)
       model_minus = model.copy()
        getattr(model_minus.params, param_name)[slc] -= EPS
        obj_minus = obj(model_minus)
        empirical = (obj_plus - obj_minus) / (2.0 * EPS)
        exact = getattr(param_gradient, param_name)[slc]
       rel = relative_error(empirical, exact)
        if rel > 3e-4:
            import pdb
```

```
pdb.set_trace()
            print(
                "The loss derivative has a relative error of \{\}, which is too\sqcup
 →large for param {}.".format(
                    rel, param name
                )
            )
            return False
    print("The gradient for {} looks OK.".format(param_name))
def load_partially_trained_model():
    obj = pickle.load(open(PARTIALLY_TRAINED_MODEL, "rb"))
    params = Params(
        obj["word_embedding_weights"],
        obj["embed_to_hid_weights"],
        obj["hid_to_output_weights"],
        obj["hid_bias"],
        obj["output_bias"],
    )
    vocab = obj["vocab"]
    return Model(params, vocab)
def check_gradients():
    """Check the computed gradients using finite differences."""
    np.random.seed(0)
    np.seterr(all="ignore") # suppress a warning which is harmless
    model = load_partially_trained_model()
    data_obj = pickle.load(open(data_location, "rb"))
    train_inputs = data_obj["train_inputs"]
    input_batch = train_inputs[:100, :]
    mask = model.sample_input_mask(input_batch.shape[0])
    input_batch_masked = input_batch * (1 - mask)
    target_batch_masked = input_batch * mask
    if not check_output_derivatives(model, input_batch_masked,__
 →target_batch_masked):
        return
    for param_name in [
        "word_embedding_weights",
        "embed_to_hid_weights",
```

```
"hid_to_output_weights",
        "hid_bias",
        "output_bias",
   ]:
        input_batch_masked = input_batch * (1 - mask)
        target_batch_masked = input_batch * mask
        check_param_gradient(model, param_name, input_batch_masked,_
 starget_batch_masked)
def print_gradients():
    """Print out certain derivatives for grading."""
   np.random.seed(0)
   model = load partially trained model()
   data_obj = pickle.load(open(data_location, "rb"))
   train inputs = data obj["train inputs"]
    input_batch = train_inputs[:100, :]
   mask = model.sample_input_mask(input_batch.shape[0])
    input batch masked = input batch * (1 - mask)
   activations = model.compute_activations(input_batch_masked)
   target_batch_masked = input_batch * mask
   expanded_target_batch = model.indicator_matrix(target_batch_masked)
   target_mask = expanded_target_batch.reshape(
        -1, model.context_len, len(model.vocab)
   ).sum(axis=-1, keepdims=True)
   loss_derivative = model.compute_loss_derivative(
        activations.output_layer, expanded_target_batch, target_mask
   )
   param_gradient = model.back_propagate(input_batch, activations,__
 ⇒loss derivative)
   print("loss derivative[2, 5]", loss derivative[2, 5])
   print("loss_derivative[2, 121]", loss_derivative[2, 121])
   print("loss_derivative[5, 33]", loss_derivative[5, 33])
   print("loss_derivative[5, 31]", loss_derivative[5, 31])
   print()
   print(
        "param_gradient.word_embedding_weights[27, 2]",
       param_gradient.word_embedding_weights[27, 2],
   )
   print(
        "param_gradient.word_embedding_weights[43, 3]",
       param_gradient.word_embedding_weights[43, 3],
   )
   print(
```

```
"param_gradient.word_embedding_weights[22, 4]",
              param_gradient.word_embedding_weights[22, 4],
          )
          print(
              "param_gradient.word_embedding_weights[2, 5]",
              param_gradient.word_embedding_weights[2, 5],
          )
          print()
          print(
              "param_gradient.embed_to_hid_weights[10, 2]",
              param gradient.embed to hid weights[10, 2],
          )
          print(
              "param_gradient.embed_to_hid_weights[15, 3]",
              param_gradient.embed_to_hid_weights[15, 3],
          )
          print(
              "param_gradient.embed_to_hid_weights[30, 9]",
              param_gradient.embed_to_hid_weights[30, 9],
          )
          print(
              "param_gradient.embed_to_hid_weights[35, 21]",
              param_gradient.embed_to_hid_weights[35, 21],
          )
          print()
          print("param_gradient.hid_bias[10]", param_gradient.hid_bias[10])
          print("param_gradient.hid_bias[20]", param_gradient.hid_bias[20])
          print()
          print("param_gradient.output_bias[0]", param_gradient.output_bias[0])
          print("param_gradient.output_bias[1]", param_gradient.output_bias[1])
          print("param gradient.output_bias[2]", param gradient.output_bias[2])
          print("param_gradient.output_bias[3]", param_gradient.output_bias[3])
[90]: # Run this to check if your implement gradients matches the finite difference
      ⇔within tolerance
      # Note: this may take a few minutes to go through all the checks
      check gradients()
     The loss derivative looks OK.
     The gradient for word_embedding_weights looks OK.
     The gradient for embed_to_hid_weights looks OK.
     The gradient for hid to output weights looks OK.
     The gradient for hid_bias looks OK.
     The gradient for output bias looks OK.
[91]: # Run this to print out the gradients
      print_gradients()
```

```
loss_derivative[2, 5] 0.0
loss_derivative[2, 121] 0.0
loss_derivative[5, 33] 0.0
loss_derivative[5, 31] 0.0
param gradient.word embedding weights[27, 2] 0.0
param gradient.word embedding weights [43, 3] 0.01159689251148945
param_gradient.word_embedding_weights[22, 4] -0.022267062381729714
param gradient.word embedding weights[2, 5] 0.0
param_gradient.embed_to_hid_weights[10, 2] 0.3793257091930164
param_gradient.embed_to_hid_weights[15, 3] 0.01604516132110911
param_gradient.embed_to_hid_weights[30, 9] -0.4312854367997418
param_gradient.embed_to_hid_weights[35, 21] 0.06679896665436336
param_gradient.hid_bias[10] 0.023428803123345162
param_gradient.hid_bias[20] -0.02437045237887423
param_gradient.output_bias[0] 0.000970106146902794
param gradient.output bias[1] 0.1686894627476322
param_gradient.output_bias[2] 0.0051664774143909235
param gradient.output bias[3] 0.1509622647181436
```

### 5.3 2.4 Run model training [2pts]

Once you've implemented the gradient computation, you'll need to train the model. The function train implements the main training procedure. It takes two arguments:

- embedding\_dim: The number of dimensions in the distributed representation.
- num\_hid: The number of hidden units

As the model trains, the script prints out some numbers that tell you how well the training is going. It shows:

- The cross entropy on the last 100 mini-batches of the training set. This is shown after every 100 mini-batches.
- The cross entropy on the entire validation set every 1000 mini-batches of training.

At the end of training, this function shows the cross entropies on the training, validation and test sets. It will return a *Model* instance.

```
[92]: data_obj = pickle.load(open(data_location, "rb"))
    type(data_obj["vocab"])

[92]: list

[93]: _train_inputs: np.ndarray = np.array([])
    _train_targets: np.ndarray = np.array([])
    _vocab = []
```

```
DEFAULT_TRAINING_CONFIG = {
    "batch_size": 100, # the size of a mini-batch
    "learning_rate": 0.1, # the learning rate
    "momentum": 0.9, # the decay parameter for the momentum vector
    "epochs": 50, # the maximum number of epochs to run
    "init_wt": 0.01, # the standard deviation of the initial random weights
    "context_len": 4, # the number of context words used
    "show_training_CE_after": 100, # measure training error after this many_
 ⇔mini-batches
    "show validation CE after": 1000, # measure validation error after this.
 →many mini-batches
}
def find_occurrences(word1: str, word2: str, word3: str):
    """Lists all the words that followed a given tri-gram in the training set \sqcup
 \hookrightarrow and the number of
    times each one followed it."""
    # cache the data so we don't keep reloading
    global _train_inputs, _train_targets, _vocab
    if _train_inputs is None:
        data obj = pickle.load(open(data location, "rb"))
        _vocab = data_obj["vocab"]
        _train_inputs, _train_targets = (
            data_obj["train_inputs"],
            data_obj["train_targets"],
        )
    if word1 not in _vocab:
        raise RuntimeError('Word "{}" not in vocabulary.'.format(word1))
    if word2 not in _vocab:
        raise RuntimeError('Word "{}" not in vocabulary.'.format(word2))
    if word3 not in _vocab:
        raise RuntimeError('Word "{}" not in vocabulary.'.format(word3))
    idx1, idx2, idx3 = _vocab.index(word1), _vocab.index(word2), _vocab.
 →index(word3)
    idxs = np.array([idx1, idx2, idx3])
    matches = np.all(_train_inputs == idxs.reshape((1, -1)), 1)
    if np.any(matches):
        counts = collections.defaultdict(int)
        for m in np.where(matches)[0]:
            counts[_vocab[_train_targets[m]]] += 1
```

```
word_counts = sorted(list(counts.items()), key=lambda t: t[1],__
 →reverse=True)
        print(
            'The tri-gram "\{\} \{\}" was followed by the following words in the
 ⇔training set:'.format(
                word1, word2, word3
        )
        for word, count in word_counts:
            if count > 1:
                print(" {} ({} times)".format(word, count))
            else:
                          {} (1 time)".format(word))
                print("
    else:
        print(
            'The tri-gram "{} {} {}" did not occur in the training set.'.format(
                word1, word2, word3
            )
        )
def train(embedding_dim: int, num_hid: int, config: dict = u
 ⇔DEFAULT_TRAINING_CONFIG):
    """This is the main training routine for the language model. It takes two_\sqcup
 ⇔parameters:
    embedding_dim, the dimension of the embedding space
    num_hid, the number of hidden units."""
    # For reproducibility
    np.random.seed(123)
    # Load the data
    data_obj = pickle.load(open(data_location, "rb"))
    vocab = data_obj["vocab"]
    train inputs = data obj["train inputs"]
    valid_inputs = data_obj["valid_inputs"]
    test_inputs = data_obj["test_inputs"]
    # Randomly initialize the trainable parameters
    model = Model.random_init(
        config["init_wt"], vocab, config["context_len"], embedding_dim, num_hid
    )
    # Variables used for early stopping
    best_valid_CE = np.inf
    end_training = False
```

```
# Initialize the momentum vector to all zeros
  delta = Params.zeros(len(vocab), config["context_len"], embedding_dim,__
→num_hid)
  this_chunk_CE = 0.0
  batch count = 0
  for epoch in range(1, config["epochs"] + 1):
       if end_training:
           break
      print()
      print("Epoch", epoch)
      for m, (input_batch) in enumerate(
           get_batches(train_inputs, config["batch_size"])
      ):
           batch_count += 1
           # For each example (row in input_batch), select one word to mask out
           mask = model.sample_input_mask(config["batch_size"])
           input_batch_masked = input_batch * (
               1 - mask
           ) # We only zero out one word per row
           target_batch_masked = (
               input_batch * mask
           ) # We want to predict the masked out word
           # Forward propagate
           activations = model.compute_activations(input_batch_masked)
           # Compute loss derivative
           expanded_target_batch = model.indicator_matrix(target_batch_masked)
           loss_derivative = model.compute_loss_derivative(
               activations.output_layer, expanded_target_batch, mask[:, :, np.
∽newaxisl
           loss_derivative /= config["batch_size"]
           # Measure loss function
           cross_entropy = (
               model.compute_loss(activations.output_layer,__
→expanded_target_batch)
               / config["batch_size"]
           this_chunk_CE += cross_entropy
           if batch_count % config["show_training_CE_after"] == 0:
               print(
```

```
"Batch {} Train CE {:1.3f}".format(
                      batch_count, this_chunk_CE /_

¬config["show_training_CE_after"]
              )
              this chunk CE = 0.0
          # Backpropagate
          loss_gradient = model.back_propagate(
              input_batch, activations, loss_derivative
          )
          # Update the momentum vector and model parameters
          delta = config["momentum"] * delta + loss_gradient
          model.params -= config["learning_rate"] * delta
          # Validate
          if batch_count % config["show_validation_CE_after"] == 0:
              print("Running validation...")
              cross_entropy = model.evaluate(valid_inputs)
              print("Validation cross-entropy: {:1.3f}".format(cross_entropy))
              if cross_entropy > best_valid_CE:
                  print("Validation error increasing! Training stopped.")
                  end_training = True
                  break
              best_valid_CE = cross_entropy
  print()
  train_CE = model.evaluate(train_inputs)
  print("Final training cross-entropy: {:1.3f}".format(train_CE))
  valid_CE = model.evaluate(valid_inputs)
  print("Final validation cross-entropy: {:1.3f}".format(valid_CE))
  test_CE = model.evaluate(test_inputs)
  print("Final test cross-entropy: {:1.3f}".format(test_CE))
  return model
```

Run the training.

```
[94]: embedding_dim = 16
num_hid = 128
trained_model = train(embedding_dim, num_hid)
```

```
Epoch 1
Batch 100 Train CE 4.793
```

```
Batch 200 Train CE 4.645
Batch 300 Train CE 4.649
Batch 400 Train CE 4.629
Batch 500 Train CE 4.633
Batch 600 Train CE 4.648
Batch 700 Train CE 4.617
Batch 800 Train CE 4.607
Batch 900 Train CE 4.606
Batch 1000 Train CE 4.615
Running validation...
Validation cross-entropy: 4.615
Batch 1100 Train CE 4.615
Batch 1200 Train CE 4.624
Batch 1300 Train CE 4.608
Batch 1400 Train CE 4.595
Batch 1500 Train CE 4.611
Batch 1600 Train CE 4.598
Batch 1700 Train CE 4.577
Batch 1800 Train CE 4.578
Batch 1900 Train CE 4.568
Batch 2000 Train CE 4.589
Running validation...
Validation cross-entropy: 4.589
Batch 2100 Train CE 4.573
Batch 2200 Train CE 4.611
Batch 2300 Train CE 4.562
Batch 2400 Train CE 4.587
Batch 2500 Train CE 4.589
Batch 2600 Train CE 4.587
Batch 2700 Train CE 4.561
Batch 2800 Train CE 4.544
Batch 2900 Train CE 4.521
Batch 3000 Train CE 4.524
Running validation...
Validation cross-entropy: 4.496
Batch 3100 Train CE 4.504
Batch 3200 Train CE 4.449
Batch 3300 Train CE 4.384
Batch 3400 Train CE 4.352
Batch 3500 Train CE 4.324
Batch 3600 Train CE 4.261
Batch 3700 Train CE 4.267
Epoch 2
Batch 3800 Train CE 4.208
Batch 3900 Train CE 4.168
Batch 4000 Train CE 4.117
```

Running validation...

```
Validation cross-entropy: 4.112
Batch 4100 Train CE 4.105
Batch 4200 Train CE 4.049
Batch 4300 Train CE 4.008
Batch 4400 Train CE 3.986
Batch 4500 Train CE 3.924
Batch 4600 Train CE 3.897
Batch 4700 Train CE 3.857
Batch 4800 Train CE 3.790
Batch 4900 Train CE 3.796
Batch 5000 Train CE 3.773
Running validation...
Validation cross-entropy: 3.776
Batch 5100 Train CE 3.766
Batch 5200 Train CE 3.714
Batch 5300 Train CE 3.720
Batch 5400 Train CE 3.668
Batch 5500 Train CE 3.668
Batch 5600 Train CE 3.639
Batch 5700 Train CE 3.571
Batch 5800 Train CE 3.546
Batch 5900 Train CE 3.537
Batch 6000 Train CE 3.511
Running validation...
Validation cross-entropy: 3.531
Batch 6100 Train CE 3.494
Batch 6200 Train CE 3.495
Batch 6300 Train CE 3.477
Batch 6400 Train CE 3.455
Batch 6500 Train CE 3.435
Batch 6600 Train CE 3.446
Batch 6700 Train CE 3.411
Batch 6800 Train CE 3.376
Batch 6900 Train CE 3.419
Batch 7000 Train CE 3.375
Running validation...
Validation cross-entropy: 3.386
Batch 7100 Train CE 3.398
Batch 7200 Train CE 3.383
Batch 7300 Train CE 3.371
Batch 7400 Train CE 3.355
Epoch 3
Batch 7500 Train CE 3.320
Batch 7600 Train CE 3.315
Batch 7700 Train CE 3.342
Batch 7800 Train CE 3.293
Batch 7900 Train CE 3.285
```

```
Batch 8000 Train CE 3.296 Running validation...
```

Validation cross-entropy: 3.294

Batch 8100 Train CE 3.271

Batch 8200 Train CE 3.291

Batch 8300 Train CE 3.287

Batch 8400 Train CE 3.274

Batch 8500 Train CE 3.228

Batch 8600 Train CE 3.256

Batch 8700 Train CE 3.250

Batch 8800 Train CE 3.256

Batch 8900 Train CE 3.266

Batch 9000 Train CE 3.221

Running validation...

Validation cross-entropy: 3.233

Batch 9100 Train CE 3.248

Batch 9200 Train CE 3.229

Batch 9300 Train CE 3.224

Batch 9400 Train CE 3.216

Batch 9500 Train CE 3.206

Batch 9600 Train CE 3.201

Batch 9700 Train CE 3.195

Batch 9800 Train CE 3.234

Batch 9900 Train CE 3.183

Batch 10000 Train CE 3.179

Running validation...

Validation cross-entropy: 3.175

Batch 10100 Train CE 3.169

Batch 10200 Train CE 3.168

Batch 10300 Train CE 3.170

Batch 10400 Train CE 3.201

Batch 10500 Train CE 3.173

Batch 10600 Train CE 3.174

Batch 10700 Train CE 3.140

Batch 10800 Train CE 3.179 Batch 10900 Train CE 3.190

Batch 11000 Train CE 3.105

Running validation...

Validation cross-entropy: 3.147

Batch 11100 Train CE 3.168

### Epoch 4

Batch 11200 Train CE 3.154

Batch 11300 Train CE 3.136

Batch 11400 Train CE 3.139

Batch 11500 Train CE 3.150

Batch 11600 Train CE 3.119

Batch 11700 Train CE 3.117

```
Batch 11800 Train CE 3.162
```

Batch 11900 Train CE 3.110

Batch 12000 Train CE 3.141

Running validation...

Validation cross-entropy: 3.119

Batch 12100 Train CE 3.132

Batch 12200 Train CE 3.134

Batch 12300 Train CE 3.126

Batch 12400 Train CE 3.105

Batch 12500 Train CE 3.075

Batch 12600 Train CE 3.142

Batch 12700 Train CE 3.126

Batch 12800 Train CE 3.135

Batch 12900 Train CE 3.093

Batch 13000 Train CE 3.116

Running validation...

Validation cross-entropy: 3.093

Batch 13100 Train CE 3.105

Batch 13200 Train CE 3.087

Batch 13300 Train CE 3.093

Batch 13400 Train CE 3.093

Batch 13500 Train CE 3.074

Batch 13600 Train CE 3.068

Batch 13700 Train CE 3.080

Batch 13800 Train CE 3.080

Batch 13900 Train CE 3.081

Batch 14000 Train CE 3.079

Running validation...

Validation cross-entropy: 3.078

Batch 14100 Train CE 3.083

Batch 14200 Train CE 3.105

Batch 14300 Train CE 3.141

Batch 14400 Train CE 3.083

Batch 14500 Train CE 3.074

Batch 14600 Train CE 3.142

Batch 14700 Train CE 3.094

Batch 14800 Train CE 3.066

Batch 14900 Train CE 3.083

### Epoch 5

Batch 15000 Train CE 3.049

Running validation...

Validation cross-entropy: 3.055

Batch 15100 Train CE 3.096

Batch 15200 Train CE 3.070

Batch 15300 Train CE 3.090

Batch 15400 Train CE 3.099

Batch 15500 Train CE 3.058

```
Batch 15600 Train CE 3.074
Batch 15700 Train CE 3.070
Batch 15800 Train CE 3.082
Batch 15900 Train CE 3.076
Batch 16000 Train CE 3.080
Running validation...
Validation cross-entropy: 3.083
Validation error increasing! Training stopped.
Final training cross-entropy: 3.063
Final validation cross-entropy: 3.072
Final test cross-entropy: 3.075
```

To convince us that you have correctly implemented the gradient computations, please include the following with your assignment submission:

- ☐ You will submit hw1\_code\_<YOUR\_UNI>.ipynb through CourseWorks. You do not need to modify any of the code except the parts we asked you to implement.
- ☐ In your PDF file, include the output of the function print\_gradients. This prints out part of the gradients for a partially trained network which we have provided, and we will check them against the correct outputs. **Important:** make sure to give the output of print\_gradients, not check\_gradients.

Since we gave you a gradient checker, you have no excuse for not getting full points on this part.

## 6 Part 3: Arithmetics and Analysis (8pts)

In this part, you will perform arithmetic calculations on the word embeddings learned from previous models and analyze the representation learned by the networks with t-SNE plots.

#### 6.1 3.1 t-SNE

You will first train the models discussed in the previous sections; you'll use the trained models for the remainding of this section.

**Important**: if you've made any fixes to your gradient code, you must reload the a1-code module and then re-run the training procedure. Python does not reload modules automatically, and you don't want to accidentally analyze an old version of your model.

These methods of the Model class can be used for analyzing the model after the training is done: \*tsne\_plot\_representation creates a 2-dimensional embedding of the distributed representation space using an algorithm called t-SNE. (You don't need to know what this is for the assignment, but we may cover it later in the course.) Nearby points in this 2-D space are meant to correspond to nearby points in the 16-D space. \*display\_nearest\_words lists the words whose embedding vectors are nearest to the given word \*word\_distance computes the distance between the embeddings of two words

Plot the 2-dimensional visualization for the trained model from part 3 using the method tsne\_plot\_representation. Look at the plot and find a few clusters of related words. What do the words in each cluster have in common? Plot the 2-dimensional visualization for the GloVe model from part 1 using the method tsne\_plot\_GLoVe\_representation. How do the t-SNE

embeddings for both models compare? Plot the 2-dimensional visualization using the method plot\_2d\_GLoVe\_representation. How does this compare to the t-SNE embeddings? Please answer in 2 sentences for each question and show the plots in your submission.

```
[]: from sklearn.manifold import TSNE
     def tsne_plot_representation(model: Model):
         """Plot a 2-D visualization of the learned representations using t-SNE."""
         mapped_X = TSNE(n_components=2).fit_transform(model.params.
      ⇔word embedding weights)
         pylab.figure(figsize=(12, 12))
         for i, w in enumerate(model.vocab):
             pylab.text(mapped_X[i, 0], mapped_X[i, 1], w)
         pylab.xlim(mapped_X[:, 0].min(), mapped_X[:, 0].max())
         pylab.ylim(mapped_X[:, 1].min(), mapped_X[:, 1].max())
         pylab.show()
     def tsne_plot_GLoVE_representation(W_final: np.ndarray, b_final: np.ndarray):
         """Plot a 2-D visualization of the learned representations using t-SNE."""
         mapped_X = TSNE(n_components=2).fit_transform(W_final)
         pylab.figure(figsize=(12, 12))
         data obj = pickle.load(open(data location, "rb"))
         for i, w in enumerate(data_obj["vocab"]):
             pylab.text(mapped_X[i, 0], mapped_X[i, 1], w)
         pylab.xlim(mapped_X[:, 0].min(), mapped_X[:, 0].max())
         pylab.ylim(mapped_X[:, 1].min(), mapped_X[:, 1].max())
         pylab.show()
     def plot 2d GLoVE representation(W final: np.ndarray, b final: np.ndarray):
         """Plot a 2-D visualization of the learned representations."""
         mapped_X = W_final
         pylab.figure(figsize=(12, 12))
         data_obj = pickle.load(open(data_location, "rb"))
         for i, w in enumerate(data_obj["vocab"]):
             pylab.text(mapped_X[i, 0], mapped_X[i, 1], w)
         pylab.xlim(mapped_X[:, 0].min(), mapped_X[:, 0].max())
         pylab.ylim(mapped_X[:, 1].min(), mapped_X[:, 1].max())
         pylab.show()
```

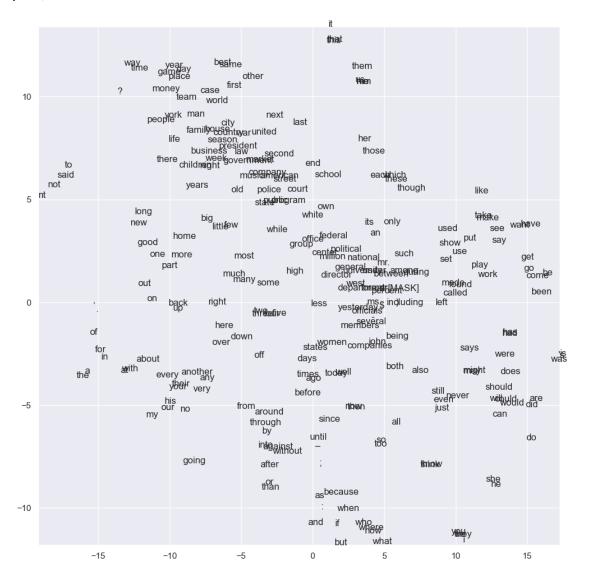
- 3.1 Answer: 1. tsne\_plot\_representation I think this grouping represents an undertrained model, as there's some cooccurance but is missing semantic relationships. There are lots of "head scratchers" in this chart
  - 2. tsne\_plot\_GLoVE\_representation This chart is definitely more semantically meaningful, with some clear clusters of related words. In addition, ther distances between words are less

uniform (more deliberate)

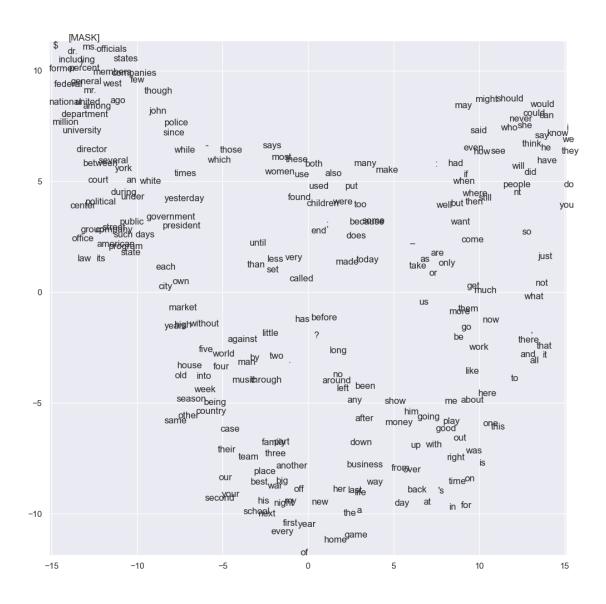
3. plot\_2d\_GLoVe\_representation This plot is is very densely clustered around the origin, with lower spread than the tsne plots. It's harder to make out the meaning of the clusters without the t-SNE algorithm

## [103]: tsne\_plot\_representation(trained\_model)

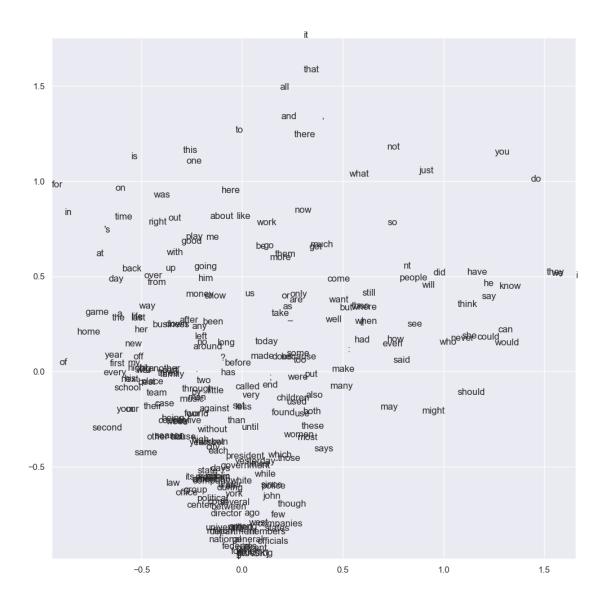
(251, 16)



[104]: tsne\_plot\_GLoVE\_representation(W\_final\_2d, b\_final\_2d)



[105]: plot\_2d\_GLoVE\_representation(W\_final\_2d, b\_final\_2d)



# 7 What you have to submit

For reference, here is everything you need to hand in. See the top of this handout for submission directions.

- Please make sure you finish the solve problems and submit your answers and codes according to the submission instruction:
- □ Part 1: Questions 1.1, 1.2, 1.3, 1.4. Completed code for grad\_GLoVE function.
- □ Part 2: Completed code for compute\_loss\_derivative() (2.1), back\_propagate() (2.2) functions, and the output of print\_gradients() (2.3) and (2.4)
- □ Part 3: Questions 3.1

[]: