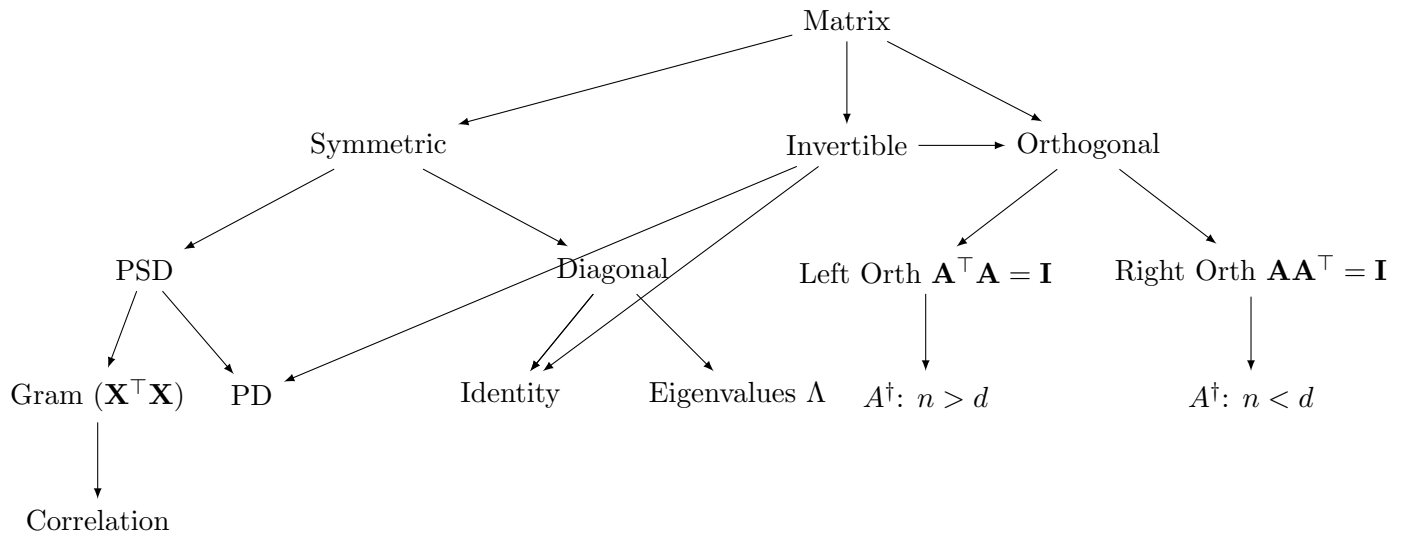


Special Matrices and their Properties



Term	Definition	Unique Attributes / Key Properties
Diagonal	$a_{ij} = 0$ for $i \neq j$	<ul style="list-style-type: none"> - Determinant is product of diagonal entries - Eigenvalues are diagonal entries - \mathbf{A}^k is diagonal with entries raised to k
Symmetric	$\mathbf{A} = \mathbf{A}^T$, i.e., $a_{ij} = a_{ji}$	<ul style="list-style-type: none"> - $\mathbf{x}^T \mathbf{A} \mathbf{x} = (\mathbf{A} \mathbf{x})^T \mathbf{x}$ for all \mathbf{x} if \mathbf{A} is symmetric - $\mathbf{v}^T \mathbf{A} \mathbf{v} \leq \lambda_{\max}(\mathbf{A}) \ \mathbf{v}\ ^2$ - All eigenvalues are real - Eigenvectors for distinct eigenvalues are orthogonal - Diagonalizable via orthogonal matrices
Identity (I)	$\mathbf{I}_{ij} = \delta_{ij}$	<ul style="list-style-type: none"> - $\mathbf{A} \mathbf{I} = \mathbf{I} \mathbf{A} = \mathbf{A}$ - $\mathbf{I}^{-1} = \mathbf{I}$ - All eigenvalues are 1
Invertible (Non-singular)	Exists \mathbf{A}^{-1} such that $\mathbf{A} \mathbf{A}^{-1} = \mathbf{A}^{-1} \mathbf{A} = \mathbf{I}$	<ul style="list-style-type: none"> - $\det(\mathbf{A}) \neq 0$ - Linearly independent rows and columns - No zero eigenvalues
Singular	A square matrix with $\det(\mathbf{A}) = 0$	<ul style="list-style-type: none"> - Not invertible - Linearly dependent rows or columns - At least one zero eigenvalue
Orthogonal	$\mathbf{A}^{-1} = \mathbf{A}^T$, so $\mathbf{A}^T \mathbf{A} = \mathbf{I}$	<ul style="list-style-type: none"> - Rows and columns form an orthonormal set - Preserves lengths and angles - $\det(\mathbf{A}) = \pm 1$
Left Orthogonal	$\mathbf{A}^T \mathbf{A} = \mathbf{I}$ (tall matrix, $n \geq d$)	<ul style="list-style-type: none"> - Columns are orthonormal - $\mathbf{A}^\dagger = \mathbf{A}^T$ (left pseudoinverse) - Used when \mathbf{A} has full column rank - Condition: $\text{rank}(\mathbf{A}) = d$ where $\mathbf{A} \in \mathbb{R}^{n \times d}$
Right Orthogonal	$\mathbf{A} \mathbf{A}^T = \mathbf{I}$ (wide matrix, $n \leq d$)	<ul style="list-style-type: none"> - Rows are orthonormal - $\mathbf{A}^\dagger = \mathbf{A}^T$ (right pseudoinverse) - Used when \mathbf{A} has full row rank - Condition: $\text{rank}(\mathbf{A}) = n$ where $\mathbf{A} \in \mathbb{R}^{n \times d}$

Pseudoinverse (Moore–Penrose)	Generalized inverse \mathbf{A}^\dagger satisfying the four Penrose conditions	<ul style="list-style-type: none"> - Always exists and is unique for any matrix - Full column rank ($n \geq d$, $\text{rank}(\mathbf{A}) = d$): $\mathbf{A}^\dagger = (\mathbf{A}^T \mathbf{A})^{-1} \mathbf{A}^T$ (left pseudoinverse) - Full row rank ($n \leq d$, $\text{rank}(\mathbf{A}) = n$): $\mathbf{A}^\dagger = \mathbf{A}^T (\mathbf{A} \mathbf{A}^T)^{-1}$ (right pseudoinverse) - Square and invertible: $\mathbf{A}^\dagger = \mathbf{A}^{-1}$ - Rank deficient: Computed via SVD decomposition
Positive Definite	$\mathbf{x}^T \mathbf{A} \mathbf{x} > 0$ for all non-zero \mathbf{x}	<ul style="list-style-type: none"> - All eigenvalues are positive - $\det(\mathbf{A}) > 0$ - Always defines an inner product: for any PD matrix, there exists a unique inner product - For any inner product, there exists a PD matrix \mathbf{A} such that $\langle \mathbf{x}, \mathbf{y} \rangle = \mathbf{x}^T \mathbf{A} \mathbf{y}$ - Invertible
Positive Semi-Definite	$\mathbf{A} = \mathbf{A}^T$, $\mathbf{x}^T \mathbf{A} \mathbf{x} \geq 0$ for all \mathbf{x}	<ul style="list-style-type: none"> - All eigenvalues are non-negative - $\det(\mathbf{A}) \geq 0$ - Always symmetric - Can always be written as $\mathbf{X}^T \mathbf{X}$ for some \mathbf{X} (Gram matrix) - Defines a semi-inner product
Triangular (Upper / Lower)	Upper: $a_{ij} = 0$ for $i > j$; Lower: $a_{ij} = 0$ for $i < j$	<ul style="list-style-type: none"> - Determinant is product of diagonal entries - Eigenvalues are diagonal entries - Solves systems efficiently via substitution
Skew-Symmetric	$\mathbf{A} = -\mathbf{A}^T$, so $a_{ii} = 0$	<ul style="list-style-type: none"> - Eigenvalues are 0 or purely imaginary - $\mathbf{x}^T \mathbf{A} \mathbf{x} = 0$ for all \mathbf{x}
Idempotent	$\mathbf{A}^2 = \mathbf{A}$	<ul style="list-style-type: none"> - Used in projection operations - Eigenvalues are 0 or 1
Nilpotent	$\mathbf{A}^k = 0$ for some $k \in \mathbb{N}$	<ul style="list-style-type: none"> - All eigenvalues are 0
Orthogonal Projection	Linear transformation \mathbf{p} where $\mathbf{p}^2 = \mathbf{p}$ and $\mathbf{p} = \mathbf{p}^T$	<ul style="list-style-type: none"> - Projects onto a subspace along its orthogonal complement - Minimizes distance to the subspace (best approximation) - $\text{Im}(\mathbf{p})$ is a subspace; $\text{Ker}(\mathbf{p}) = \text{Im}(\mathbf{I} - \mathbf{p})$
Linear Map (Transformation)	Function $T : V \rightarrow W$ satisfying $T(a\mathbf{x} + b\mathbf{y}) = aT(\mathbf{x}) + bT(\mathbf{y})$	<ul style="list-style-type: none"> - Represented by a matrix in finite dimensions - Preserves linear structure - Kernel and image define fundamental subspaces
Fundamental Subspaces	Column space, row space, null space, left null space	<ul style="list-style-type: none"> - Column space: span of columns (range of \mathbf{A}) - Row space: span of rows = col space of \mathbf{A}^T - Null space: solutions to $\mathbf{A} \mathbf{x} = 0$ - Left null space: null space of \mathbf{A}^T
Unitary	$\mathbf{U}^\dagger = \mathbf{U}^{-1}$, where \mathbf{U}^\dagger is the conjugate transpose of \mathbf{U}	<ul style="list-style-type: none"> - $\mathbf{U}^\dagger \mathbf{U} = \mathbf{U} \mathbf{U}^\dagger = \mathbf{I}$ - Preserves inner products: $\langle \mathbf{U} \mathbf{x}, \mathbf{U} \mathbf{y} \rangle = \langle \mathbf{x}, \mathbf{y} \rangle$ - All eigenvalues lie on the unit circle: $\lambda = 1$ - Generalization of orthogonal matrices to complex space
Gram Matrix	$\mathbf{G} = \mathbf{X}^T \mathbf{X}$ for some matrix \mathbf{X}	<ul style="list-style-type: none"> - Always positive semi-definite - Symmetric by construction - Entries are inner products: $G_{ij} = \langle \mathbf{x}_i, \mathbf{x}_j \rangle$ - Used in least squares and quadratic forms
Eigenvalue Matrix	Matrix with known eigenvalues $\lambda_1, \dots, \lambda_n$	<ul style="list-style-type: none"> - Can be diagonalized as $\mathbf{A} = \mathbf{p} \mathbf{\Lambda} \mathbf{p}^{-1}$ - $\mathbf{\Lambda}$ is diagonal matrix of eigenvalues - \mathbf{p} contains corresponding eigenvectors as columns - Powers: $\mathbf{A}^k = \mathbf{p} \mathbf{\Lambda}^k \mathbf{p}^{-1}$

Eigenvalue Matrix (Λ)	Diagonal matrix $\Lambda = \text{diag}(\lambda_1, \dots, \lambda_n)$	<ul style="list-style-type: none"> - Contains eigenvalues on the diagonal - Result of eigendecomposition/PCA - $\Lambda_{ii} = \lambda_i$, $\Lambda_{ij} = 0$ for $i \neq j$ - Used in spectral analysis and dimensionality reduction
Covariance Matrix	$\text{Cov}(\mathbf{X}) = \frac{1}{n-1}(\mathbf{X} - \mu)^T(\mathbf{X} - \mu)$ (unbiased)	<ul style="list-style-type: none"> - Always positive semi-definite - Symmetric by construction - Diagonal entries are variances - Off-diagonal entries are covariances
Correlation Matrix	Normalized covariance matrix with unit diagonal	<ul style="list-style-type: none"> - Positive semi-definite - Symmetric with $\rho_{ii} = 1$ - Entries satisfy $-1 \leq \rho_{ij} \leq 1$ - Used in statistics and data analysis
Householder Matrix	$H = I - 2\frac{vv^T}{v^Tv}$ for vector v	<ul style="list-style-type: none"> - Symmetric and orthogonal - $H^2 = I$ (involutory) - Reflects vectors across hyperplane - Used in QR decomposition
Permutation Matrix	Matrix with exactly one 1 in each row and column	<ul style="list-style-type: none"> - Orthogonal matrix - Determinant is ± 1 - Reorders rows/columns when multiplied - $P^T P = I$ and $P^{-1} = P^T$
Circulant Matrix	Each row is cyclic shift of previous row	<ul style="list-style-type: none"> - Diagonalized by Discrete Fourier Transform - Eigenvalues given by DFT of first row - Used in signal processing - Fast matrix-vector multiplication via FFT
Toeplitz Matrix	Constant along each diagonal: $a_{ij} = a_{i-j}$	<ul style="list-style-type: none"> - Determined by $2n - 1$ parameters - Includes circulant matrices as special case - Used in time series and signal processing - Fast algorithms available for solving systems
Hankel Matrix	Constant along each anti-diagonal: $a_{ij} = a_{i+j}$	<ul style="list-style-type: none"> - Symmetric if square - Related to Toeplitz matrices - Used in system identification - Connection to moment problems