

Waymo Fleet Profitability Optimizer

Aksel Kretsinger-Walters Alena Chan Andrey Aksyutkin Blake Sisson *

Problem Statement

One of the most promising and revolutionary applications of reinforcement learning is in the domain of autonomous robots, specifically self-driving cars. There are many challenges in this domain: intellectual, ethical, technical, and more. For our project, we've decided to narrow our focus to the specific problem of optimizing the profitability of a fleet of self-driving cars.

*Collaborator(s): Aksel Kretsinger-Walters ([adk2164](#)), Alena Chan ([ac5477](#)), Andrey Aksyutkin ([aa5499](#)), Blake Sisson ([mbs2246](#))