SVD, Moore-Penrose Pseudo-inverse, and LSP

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Outline

- Moore-Penrose pseudo-inverse
- SVD based method for LSP

Definition: Let $D \in \mathbb{C}^{m \times n}$ be diagonal. Then the Moore-Penrose pseudoinverse of D denoted by D^+ is defined to be the matrix obtained by transposing D and reciprocating each nonzero diagonal entries of D.

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$$D^{+} = \begin{bmatrix} 1/d_1 & & & & \\ & \ddots & & & 0 \\ & & 1/d_r & & \\ \hline & 0 & & 0 \end{bmatrix}^{\top} \in \mathbb{C}^{n \times m}.$$

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This is a dream come true - invert what you can and ignore the rest!!!



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- The MATLAB command pinv(A) computes the pseduo-inverse A^+ of an $m \times n$ matrix A.
- If $U_r:=egin{bmatrix} u_1 & \cdots & u_r \end{bmatrix}, \ V_r:=egin{bmatrix} v_1 & \cdots & v_r \end{bmatrix}$ and $\Sigma_r=\mathrm{diag}(\sigma_1,\cdots,\sigma_r)$ then

$$A = U_r \Sigma_r V_r^* = \sigma_1 u_1 v_1^* + \dots + \sigma_r u_r v_r^* \text{ and } A^+ = V_r \Sigma_r^{-1} U_r^* = \frac{v_1 u_1^*}{\sigma_1} + \dots + \frac{v_r u_r^*}{\sigma_r}.$$



The Moore-Penrose pseudoinverse A^+ defines a bijective mapping from $R(A^*)$ to R(A) and annihilates the vectors in $N(A^*)$. Indeed, consider the SVD $A = U \begin{bmatrix} \Sigma_r & 0 \\ 0 & 0 \end{bmatrix} V^*$. Let U, V, Σ_r be given by $U = \begin{bmatrix} u_1 & \cdots & u_m \end{bmatrix}, V = \begin{bmatrix} v_1 & \cdots & v_n \end{bmatrix}$ and $\Sigma_r = \operatorname{diag}(\sigma_1, \cdots, \sigma_r)$.

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Then $AV = U\Sigma$ and $A^+U = V\Sigma^+$ show that

$$A: v_1 \longmapsto \sigma_1 u_1 \qquad A^+: u_1 \longmapsto v_1/\sigma_1$$
 $\vdots \qquad \vdots \qquad \vdots$
 $A: v_r \longmapsto \sigma_r u_r$
 $A: v_{r+1} \longmapsto 0 \qquad \text{and} \qquad A^+: u_r \longmapsto v_r/\sigma_r$
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Note that $A^+Ax = x$ for $x \in R(A^*)$ and $AA^+y = y$ for $y \in R(A)$. Conversely, A^+ can be defined as the bijective mapping from $R(A^*)$ to R(A) that annihilates vectors in $N(A^*)$.

Let $U = \begin{bmatrix} U_r & U_{m-r} \end{bmatrix}$ and $V = \begin{bmatrix} V_r & V_{n-r} \end{bmatrix}$ be column partition of U and V. Then the mapping $A^+u_j = v_j/\sigma_j$ for j=1:r and $A^+u_j = 0$ for j=r+1:m can be rewritten as

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Fact: Let $A \in \mathbb{C}^{m \times n}$ and A^+ be the pseudoinverse of A. Then the following hold:

- $AA^{+}A = A$ and $A^{+}AA^{+} = A^{+}$.
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Proof: Use the SVD $A = U\Sigma V^*$ and the fact that $A^+ = V\Sigma^+ U^*$.



Theorem: Let $A \in \mathbb{C}^{m \times n}$ and $b \in \mathbb{C}^m$. Suppose rank(A) = r. Let

$$A = U \begin{bmatrix} \Sigma_r & 0 \\ 0 & 0 \end{bmatrix} V^*, \quad U = \begin{bmatrix} U_r & U_{m-r} \end{bmatrix}, \quad V = \begin{bmatrix} V_r & V_{n-r} \end{bmatrix}$$

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Proof: Set
$$\begin{bmatrix} z \\ y \end{bmatrix} := V^*x$$
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$$||Ax - b||_2 = ||U^*(Ax - b)||_2 = \left\| \begin{bmatrix} \Sigma_r & 0 \\ 0 & 0 \end{bmatrix} V^*x - U^*b \right\|_2$$

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$$= \left\| \begin{bmatrix} \Sigma_r z - c \\ -d \end{bmatrix} \right\|_2 = \sqrt{||\Sigma_r z - c||_2^2 + ||d||_2^2} = ||d||_2$$

$$\Leftrightarrow z = \Sigma_r^{-1}c. \text{ Hence } x = V \begin{bmatrix} \Sigma_r^{-1}c \\ y \end{bmatrix} \text{ is a solution for any } y.$$

Thus
$$x = V \begin{bmatrix} \Sigma_r^{-1} c \\ y \end{bmatrix} = V_r \Sigma_r^{-1} c + V_{n-r} y = V_r \Sigma_r^{-1} U_r^* b + V_{n-r} y = A^+ b + V_{n-r} y$$
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Remark: We have $x = A^+b + V_{n-r}y$ and $A^+b \perp V_{n-r}y$. Hence $||x||_2 = \sqrt{||A^+b||_2^2 + ||y||_2^2}$ $\implies x = A^+b$ is a unique solution of the LSP $Ax \approx b$ having the smallest norm.

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Algorithm: Solution of LSP $Ax \approx b$ when rank(A) = r.

- 1. Compute SVD $A = U \begin{bmatrix} \Sigma_r & 0 \\ 0 & 0 \end{bmatrix} V^*$
- 2. Set $\begin{bmatrix} c \\ d \end{bmatrix} := U^*b$, where $c \in \mathbb{C}^r$ and $d \in \mathbb{C}^{m-r}$.
- 3. Set $x = V(:, 1:r)\sum_{r=1}^{r-1} c$. Then x is a unique least norm solution of the LSP.
- 4. Compute the residual $||d||_2$.

Thus
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 is a solution of the LSP $Ax \approx b$ for any $y \in \mathbb{C}^{n-r}$. \blacksquare

As range(A+) = span(v1, v2, ..., vr) & V(n-r)^* y = L.C of v(r+1), v(r+2)...., v(n). Since V is unitary, vi perpendicular to vj, for i!= j

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- 3. Set $x = V(:, 1:r)\Sigma_r^{-1}c$. Then x is a unique least norm solution of the LSP.
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Remark: Now $x = A^+b = V_r \Sigma_r^{-1} U_r^*b = \frac{v_1 u_1^*b}{\sigma_1} + \dots + \frac{v_r u_r^*b}{\sigma_r}$ shows the effect of small singular values on the solution of the LSP $Ax \approx b$..



$$\begin{bmatrix} 1 \\ 1 \end{bmatrix}^+ = \frac{1}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix}^\top = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \end{bmatrix}$$

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Using the result, for full column matrix, $A+ = (A*A)^{-1} A*$

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Since $||Ax||_2 = ||b||_2 \cos \theta$, we have

$$\frac{\|x - \hat{x}\|_2}{\|x\|_2} \le \frac{\text{cond}(A)}{\cos \theta} \, \frac{\|\Delta b\|_2}{\|b\|_2}.$$



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$$\frac{\|x - \hat{x}\|_{2}}{\|x\|_{2}} \lesssim \operatorname{cond}(A)^{2} \frac{\|\Delta A^{*}\|_{2}}{\|A\|_{2}} \frac{\|r\|_{2}}{\|A\|_{2}\|x\|_{2}} + \operatorname{cond}(A) \frac{\|\Delta A\|_{2}}{\|A\|_{2}}$$
$$\lesssim \left(\operatorname{cond}(A)^{2} \tan(\theta) + \operatorname{cond}(A)\right) \frac{\|\Delta A\|_{2}}{\|A\|_{2}},$$

where r := b - Ax.



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Suppose that $\operatorname{rank}(A) = r$. Then $A^+ = V \Sigma^+ U^* = \sum_{j=1}^r v_j u_j^* / \sigma_j$, where $v_j := V(:,j)$ and $u_j := U(:,j)$. Hence

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- For example, $A = \operatorname{diag}(1,0)$ is rank deficient. For $b = [1,1]^{\top}$, LSP $Ax = b \Rightarrow x = [1,0]^{\top}$. For tiny ϵ , $A + \Delta A = \operatorname{diag}(1,\epsilon)$ is nonsingular. Now LSP $(A + \Delta A)\hat{x} = b \Rightarrow \hat{x} = [1,1/\epsilon]^{\top}$ shows that $||x \hat{x}||_2/||x||_2 = 1/\epsilon$.



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Conclusion: If implemented properly, the SVD based method produces a solution of the LSP $(A + \Delta A)\hat{x} = b + \Delta b$ with

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Combining this with the perturbation bounds we get error bounds for the (smallest norm) solution of the least squares problem.

