Errors, pivot growth and backward stability

- Wilkinson's matrix is defined as follows: 1 on the diagonal, -1 everywhere below the main diagonal, 1 in the last column, and 0 everywhere else. Write a MATLAB function W = Wilkinson(n) that generates Wilkinson's matrix W of size n using MATLAB functions eye, tril and ones.
 - (a) For n=32, pick a random x and then compute b:=W*x. Solve Ax=b using MATLAB backslash command and compute the error $||x-\hat{x}||_{\infty}/||x||_{\infty}$ (type help norm for more info about computing norm). Does the size of the error confirm that GEPP is unstable for this system? Also compute $\operatorname{cond}(A)$. Can the poor answer be attributed to ill-conditioning of the matrix W? Repeat the test for n=64.
 - (b) Repeat the experiment in part (a) using QR decomposition. It is easy in matlab. The command [Q,R] =qr(A) gives unitary Q and upper triangular R such that A = QR. Solve Wx = b using QR decomposition and compare the results with those in part(a). Which of the two methods appear to give a better answer?
 - (c) Pivot growth of Gaussian elimination with partial pivoting (GEPP) is given by $PG(A) = \max_{ij} |U(i,j)|/\max_{ij} |A(i,j)|$, which influences the accuracy of computed solution. Use MATLAB function [L, U, p] = lu(A) for computing LU decomposition of a nonsingular matrix A and compute the pivot growth ${\tt rho} = PG(A)$. Use commands max and abs.

It is well known that the pivot growth factor for GEPP satisfies $PG(A) \leq 2^{n-1}$ which is attained by the Wilkinson matrix. Verify this graphically by doing the following:

First plot the graph of 2^{n-1} in $\log 10$ scale for n=10:.5:505 by setting $X=2.^{(n-1)}$ and then typing semilogy(n,X,'r'). Hold this plot by typing hold on and type the following sequence of commands (which assumes that the Wilkinson matrix of size n is generated by the function W=Wilkinson(n)).

```
n = 10:20:500; m = length(n); G = zeros(m,1);
for i = 1:m
W = Wilkinson(n(i)); [L,U,p] = lu(W);
G(i) = max(max(abs(U)))/(max(max(abs(W))));
end
semilogy(n,G,'b*')
```

The second plot should come in the form of blue dots that fall on the red curve produced by the earlier plot.

However, statistics suggest that for most practical examples, $PG(A) \leq n^{2/3}$ for GEPP. Verify this graphically by generating random matrices instead of Wilkinson matrices in the sequence of commands given above.

(d) There is no strong correlation between pivot growth and the ill-conditioning of a matrix. This is illustrated by a Golub matrix. A Golub matrix A of size n is an illconditioned integer matrix whose LU factorization without pivoting fails to reveal that A is ill-conditioned. The matrix A is given by A := LU, where L unit lower triangular with random integer entries and U is unit upper triangular with random integer entries. The function golub given below generates a Golub matrix of size n:

```
function A = golub(n)
s = 10;
L = tril(round(s*randn(n)),-1)+eye(n);
U = triu(round(s*randn(n)),1)+eye(n);
A = L*U;
```

Compute LU factorization of A using your function [L, U] = GENP(A). Also, compute the pivot growth PG(A) and the condition number $cond(A) = ||A||_2 ||A^{-1}||_2$ using MATLAB command cond(A). If cond(A) is large then the system Ax = b is ill-conditioned and in such a case A is called ill-conditioned. Does PG(A) reflect the ill-conditioning of A?

2. **Assignment:** Your task is to generate test matrices having pre-specified condition numbers. Write a matlab function to generate an n-by-n matrix with 2-norm condition number ka:

```
function A = matgen(n, ka)
```

To obtain such a matrix proceed as follows. Choose random orthogonal matrices U and Vfrom QR factorization of random matrices: [U, R] = qr(rand(n)) and [V,R] = qr(rand(n)). Generate a diagonal matrix $D = \operatorname{diag}(d_i)$ with $d_i := \operatorname{ka}^{-(i-1)/(n-1)}$ and then set A := UDV^* . Then the 2-norm condition number of A is equal to ka.

Check that the matrix A generated by your function matger has the condition number ka (call MATLAB function cond(A) to compute the condition number of A).

Test the stability of algorithms specified below and analyze the accuracy of solutions returned by them. For this purpose, proceed as follows:

- 1. For each $ka = 10^4, 10^8, 10^{12}, 10^{16}$, use your matgen function to generate a random matrix A of size n = 100 with condition number ka.
- 2. Compute b = A*ones(n,1). Then x =ones(n,1) is the solution of Ax = b.

Now consider the following algorithms:

```
1. ALG1: Solve Ax = b using backslash command (GEPP)
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- 2. ALG2: Solve Ax = b using GECP
- 3. ALG3: Solve Ax = b using GENP
- 4. ALG4: Solve Ax = b by $A^{-1}b$ (MATLAB command inv computes inverse of a matrix).

For each of the above algorithms, prepare a table giving values of the following quantities:

```
ka, bkerr, err, errbd
```

where

- bkerr is the backward error (= $||Ax b||_2/||A||_2||x||_2$)
- err is the relative error in the solution
- errbd is the relative error bound of the solution. [If r = b Ax then (A+E)x = b where $E = rx^*/\|x\|_2^2$. Now for error bound, invoke perturbation theory.]

Based on your results comment on the backward stability of ALG1, ALG2, ALG3, ALG4, and the accuracy of the solutions returned by these methods. Use the MATLAB commands tic, toc (type help tic for more information) to determine the time taken by each of these methods to solve the problems.

10 marks

**********End*******