Householder QR factorization

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Outline

- Reflector
- Householder reflector
- Householder QR factorization

Orthogonal projection

Let $P \in \mathbb{C}^{n \times n}$. Then P is called a projection (or idempotent) if $P^2 = P$. If P is a projection then $\mathbb{C}^n = R(P) \oplus N(P)$. Indeed, x = Px + (I - P)x.

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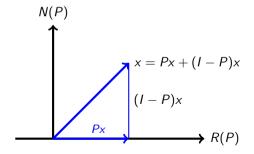
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Centering projection: Set $\mathbf{e} := \begin{bmatrix} 1 & \cdots & 1 \end{bmatrix}^{\top} \in \mathbb{C}^n$. Then $P := I - \frac{1}{n} \mathbf{e} \mathbf{e}^{\top}$ is an orthogonal projection. The projection P is also called a centering matrix as it projects a vector to a zero mean vector.

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Indeed, let
$$\mathbf{x} = \begin{bmatrix} x_1 & \cdots & x_n \end{bmatrix}^\top \in \mathbb{R}^n$$
 and $\mu := \frac{x_1 + \cdots + x_n}{n} = \frac{\mathbf{e}^\top \mathbf{x}}{n}$. Then

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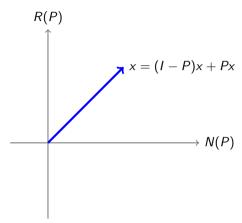
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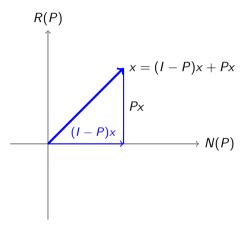
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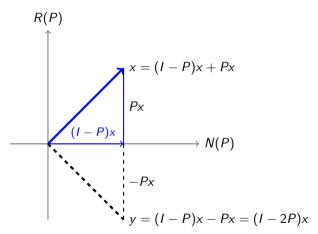
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$$P\mathbf{x} = \mathbf{x} - \frac{1}{n} \mathbf{e} \mathbf{e}^{\top} \mathbf{x} = \mathbf{x} - \mathbf{e} \mu = \begin{bmatrix} x_1 - \mu & \cdots & x_n - \mu \end{bmatrix}^{\top}.$$

Note that if $\mathbf{y} = P\mathbf{x}$ then $\mu_y := \frac{y_1 + \dots + y_n}{n} = \frac{\mathbf{e}^\top \mathbf{y}}{n} = 0$. Hence \mathbf{y} has zero mean.

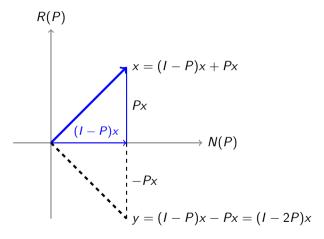








Let P be an orthogonal projection, that is, $P^2 = P$ and $R(P) \perp N(P)$.



Then H := I - 2P is a reflector. Hx is a reflection of x through N(P).

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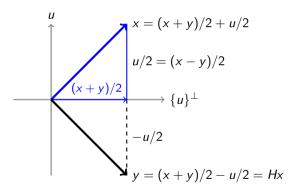


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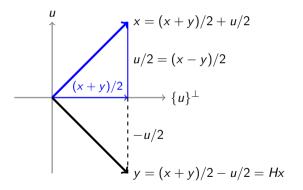
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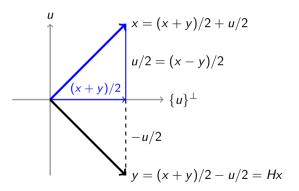


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Note that $u \perp (x + y)$. Hence Hu = -u and H(x + y) = x + y. Now $x = \frac{1}{2}(u + x + y) \Rightarrow Hx = \frac{1}{2}(Hu + H(x + y)) = \frac{1}{2}(-u + x + y) = y$.

Let
$$x := \begin{bmatrix} x_1 & x_2 & \cdots & x_n \end{bmatrix}^{\top} \in \mathbb{R}^n$$
. Define $y := \begin{bmatrix} -\sigma & 0 & \cdots & 0 \end{bmatrix}^{\top} \in \mathbb{R}^n$, where $\sigma := \operatorname{sign}(x_1) \|x\|_2$. Set $u := \begin{bmatrix} x_1 + \sigma & x_2 & \cdots & x_n \end{bmatrix}^{\top}$.

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$$H = I - \alpha u u^{\top} = \begin{bmatrix} I_{i-1} & 0 \\ 0 & I_{n-i+1} - \alpha \hat{u} \hat{u}^{\top} \end{bmatrix} = \begin{bmatrix} I_{i-1} & 0 \\ 0 & \widehat{H} \end{bmatrix}.$$

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$$H = I - \alpha u u^{\top} = \begin{bmatrix} I_{i-1} & 0 \\ 0 & I_{n-i+1} - \alpha \hat{u} \hat{u}^{\top} \end{bmatrix} = \begin{bmatrix} I_{i-1} & 0 \\ 0 & \widehat{H} \end{bmatrix}.$$

This shows that for $w \in \mathbb{R}^n$, the first i-1 components of Hw remain unchanged.



Let $x := \begin{bmatrix} x_1 & x_2 & \cdots & x_n \end{bmatrix}^\top \in \mathbb{R}^n$ and $y := \begin{bmatrix} x_1 & \cdots & x_{i-1} & -\sigma_i & 0 & \cdots & 0 \end{bmatrix}^\top$, where $\sigma_i := \operatorname{sign}(x_i) \sqrt{x_i^2 + \cdots + x_n^2}$. Then $||x||_2 = ||y||_2$ and $x \neq y$.

Set $u := x - y = \begin{bmatrix} 0 & \cdots & 0 & x_i + \sigma_i & x_{i+1} & \cdots & x_n \end{bmatrix}^\top$. Then $H := I - \alpha u u^\top$ is a unique reflector such that Hx = y, where $\alpha = 2/\|u\|_2^2 = 1/\sigma_i(x_i + \sigma_i) = 1/\sigma_i u_i$.

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This shows that for $w \in \mathbb{R}^n$, the first i-1 components of Hw remain unchanged. Similarly, for $A \in \mathbb{R}^{n \times n}$, the first i-1 rows of HA and the first i-1 columns of AH remain unchanged.



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Hence we have $H_n \cdots H_2 H_1 A = R \Rightarrow A = H_1 H_2 \cdots H_n R = QR$.



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Since $H_k = \begin{bmatrix} I_{k-1} & 0 \\ 0 & \widehat{H}_k \end{bmatrix}$, $A \leftarrow H_k A$ performs transformation on A(k:m,k:n), which dominates the computation and requires 4(m-k)(n-k) flops.

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$$\sum_{k=1}^{n} 4(m-k)(n-k) = 4 \int_{0}^{n} (m-x)(n-x) dx = 2mn^{2} - 2n^{3}/3 \text{ flops.}$$



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    u(1) = u(1) + sigma;
    alpha = 1/(conj(sigma)*u(1));
    % Update the k-th column.
    A(k:m,k) = 0; A(k,k) = -sigma;
```

```
% update A(k:m,k+1:n) and assemble Q
v = u'*A(k:m, k+1:n);
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A(k:m, k+1:n) = A(k:m,k+1:n)- (alpha * u) * v;
Q(k:m, k:m) = Q(k:m, k:m)- (alpha * u) * w;
end % end of if
end % end of for loop
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Remark: The matrix Q is usually not required and hence is never assembled. It is more efficient to store the Householder vectors for computing Qb for any vector b.

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The MATLAB function hqr can be modified to store the Householder vectors in the lower triangular part of A and $-\sigma_1, \ldots, -\sigma_n$ can be stored in an additional array sigma.

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% update A(k:m,k+1:n) and assemble Q v = u'*A(k:m, k+1:n); w = u'*Q(k:m, k:n); A(k:m, k+1:n) = A(k:m,k+1:n) - (alpha * u) * v; Q(k:m, k:m) = Q(k:m, k:m) - (alpha * u) * w; end % end of if end % end of for loop R = A;
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The MATLAB function hqr can be modified to store the Householder vectors in the lower triangular part of A and $-\sigma_1, \ldots, -\sigma_n$ can be stored in an additional array sigma. In such a case,

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R = diag(sigma) + triu(A, 1).
```



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The total cost for solving the LSP Ax = b by Householder QR factorization is $2mn^2 - \frac{2n^3}{3}$ flops.

