Fundamentals of Artificial Intelligence

Principal Component Analysis



Shyamanta M Hazarika

Mechanical Engineering
Indian Institute of Technology Guwahati
s.m.hazarika@iitq.ac.in

http://www.iitg.ac.in/s.m.hazarika/

Machine Learning



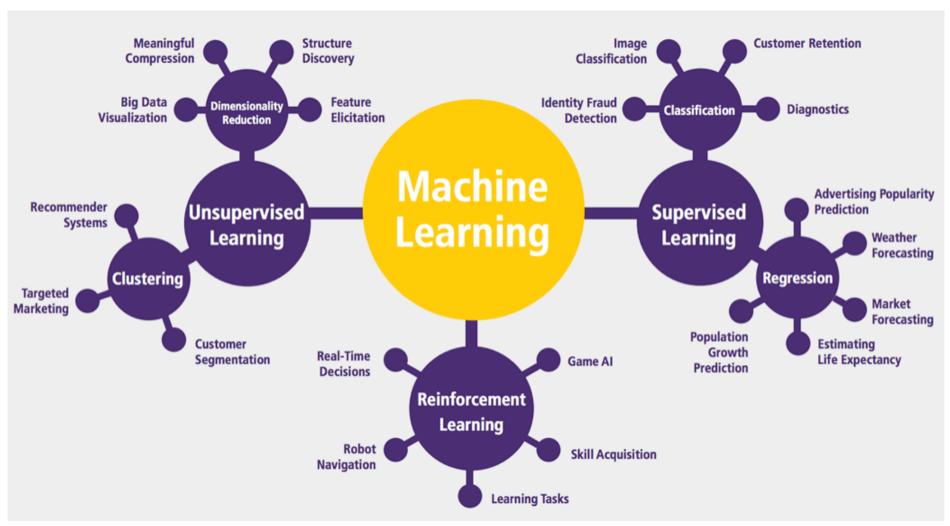


Image Source: DHL, Artificial Intelligence in Logistics, 2018.

Dimensionality Reduction



Dimensionality is the number of variables, characteristics or features present in the dataset. In most cases, the features are correlated and, therefore, there is some information that is redundant which increase the dataset's noise.

This redundant information impacts negatively in Machine Learning model's training and performance and that is why using dimensionality reduction methods becomes of paramount importance.

Dimensionality reduction is the process of reducing the number of random variables under consideration, by obtaining a set of principal variables.

Dimensionality Reduction



Categories:

Dimension reduction: to reduce the training complexity; E.g., dataset representation, data pre-processing.

- **a. Feature selection:** Find a subset of the original set of variables, or features, to get a smaller subset which can be used to model the problem.
- **b. Feature extraction**: Reduces the data in a high dimensional space to a lower dimension space, i.e. a space with lesser no. of dimensions. The output features will not be the same as the originals.

When using feature extraction, we project the data into a new feature space, so the new features will be combinations of the original features, compressed in a way that they will retain the most relevant information.

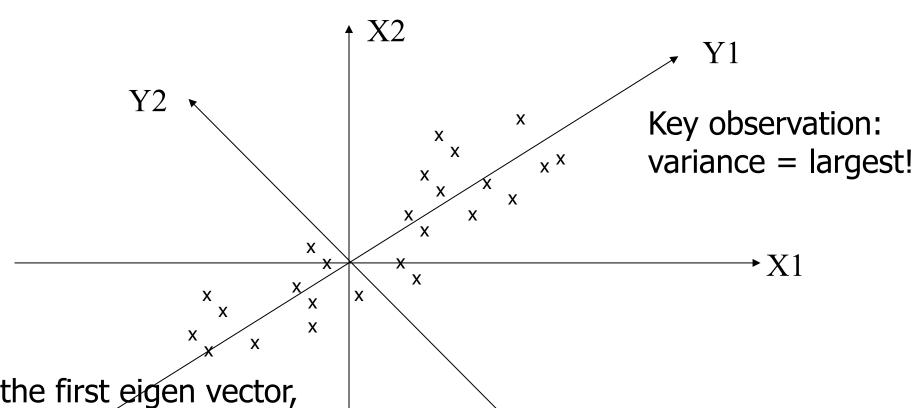


□ An exploratory technique used to reduce the dimensionality of the data set.

Exploratory Data Analysis (EDA) is a process of describing the data by means of statistical and visualization techniques in order to bring important aspects of that data into focus for further analysis. This involves inspecting the dataset from many angles, describing & summarizing it without making any assumptions about its contents.

- ☐ Can be used to:
 - Reduce number of dimensions in data
 - Find patterns in high-dimensional data
 - Visualize data of high dimensionality
- □ Example applications:
 - Face recognition
 - Image compression
 - Gene expression analysis





Note: Y1 is the first eigen vector, Y2 is the second eigen vector.

Y2 ignorable.



- Does the data set 'span' the whole of d dimensional space?
 - For a matrix of *n* samples x *n* instances, create a new covariance matrix of size *n* x *n*.
 - Transform some large number of variables into a smaller number of uncorrelated variables called principal components (PCs).
 - Developed to capture as much of the variation in data as possible!





Goal: Find r-dim projection that best preserves variance

- 1. Compute mean vector μ and covariance matrix Σ of original points
- 2. Compute eigenvectors and eigenvalues of Σ
- 3. Select top r eigenvectors
- 4. Project points onto subspace spanned by them:

$$y = A(x - \mu)$$

where y is the new point, x is the old one, and the rows of A are the eigenvectors



Question: how much spread is in the data along the axis? (distance to the mean)

□ Variance=Standard deviation^2

$$s^{2} = \frac{\sum_{i=1}^{n} (X_{i} - \overline{X})^{2}}{(n-1)}$$

Temperature	
42	
40	
24	
30	
15	
18	
15	
30	
15	
30	
35	
30	



Covariance:

measures the correlation between X and Y

- cov(X,Y)=0: independent
- cov(X,Y)>0: move same dir
- cov(X,Y)<0: move oppo dir

	$\sum_{i=1}^{n} (X_i - \overline{X})(Y_i - \overline{Y})$
cov(X,Y) =	$\frac{i=1}{(n-1)}$

X=Temperature	Y=Humidity
40	90
40	90
40	90
30	90
15	70
15	70
15	70
30	90
15	70
30	70
30	70
30	90



Contains covariance values between all possible dimensions (attributes):

$$C^{nxn} = (c_{ij} \mid c_{ij} = \text{cov}(Dim_i, Dim_j))$$

 \square Example for three attributes (x,y,z):

$$C = \begin{pmatrix} \cos(x, x) & \cos(x, y) & \cos(x, z) \\ \cos(y, x) & \cos(y, y) & \cos(y, z) \\ \cos(z, x) & \cos(z, y) & \cos(z, z) \end{pmatrix}$$



In linear algebra, it is often important to know which vectors have their directions unchanged by a given linear transformation. An eigenvector (/aɪgen-/ EYE-gen-) or characteristic vector is such a vector. Thus an eigenvector \mathbf{v} of a linear transformation T is scaled by a constant factor λ when the linear transformation is applied to it: $T\mathbf{v} = \lambda \mathbf{v}$. The corresponding eigenvalue, characteristic value, or characteristic root is the multiplying factor λ .

- \square Vectors **x** having same direction as A**x** are called eigenvectors of A (A is an n by n matrix).
- \square In the equation $A\mathbf{x} = \lambda \mathbf{x}$, λ is called an *eigenvalue* of A.



- $\square A\mathbf{x} = \lambda \mathbf{x} \Leftrightarrow (A \lambda \mathbf{I})\mathbf{x} = 0$
- \square How to calculate **x** and λ :
 - Calculate $det(A-\lambda I)$, yields a polynomial (degree n)
 - Determine roots to $det(A-\lambda I)=0$, roots are eigenvalues λ
 - Solve $(A \lambda I) \mathbf{x} = 0$ for each λ to obtain eigenvectors \mathbf{x}

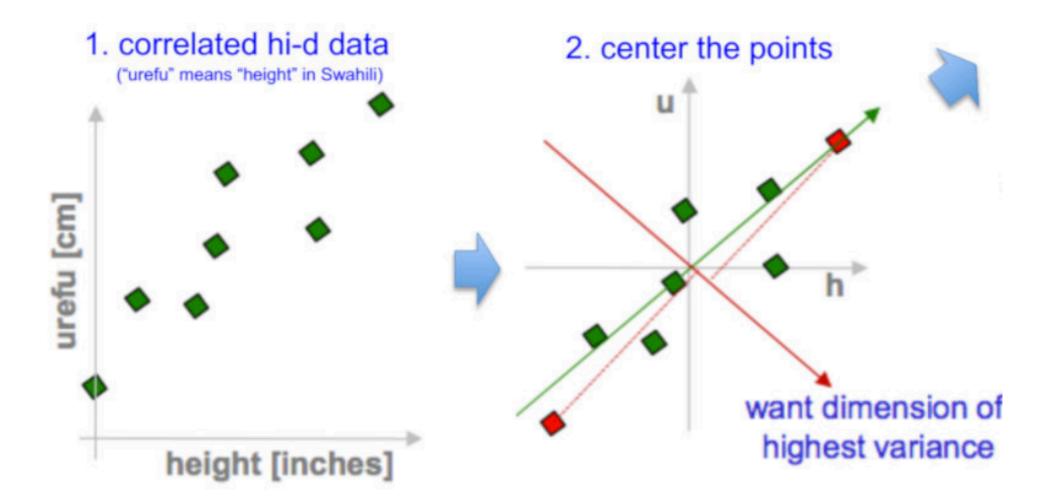


- ☐ 1st Principal Component (PC1)
 - The eigenvalue with the largest absolute value will indicate that the data have the largest variance along its eigenvector, the direction along which there is greatest variation
- ☐ 2nd Principal Component (PC2)
 - The direction with maximum variation left in data, orthogonal to the 1st PC
- □ In general, only few directions manage to capture most of the variability in the data.



- \square Let X be the mean vector (taking the mean of all rows)
- \square Adjust the original data by the mean $X' = X \overline{X}$
- □ Compute the covariance matrix C of adjusted X
- Find the eigenvectors and eigenvalues of C.









3. compute covariance matrix

h u
h 2.0 0.8 cov(h,u) =
$$\frac{1}{n} \sum_{i=1}^{n} h_i u_i$$
u 0.8 0.6

4. eigenvectors + eigenvalues

$$\begin{pmatrix}
2.0 & 0.8 \\
0.8 & 0.6
\end{pmatrix} \begin{pmatrix} e_h \\ e_u \end{pmatrix} = \lambda_e \begin{pmatrix} e_h \\ e_u \end{pmatrix} \\
\begin{pmatrix}
2.0 & 0.8 \\
0.8 & 0.6
\end{pmatrix} \begin{pmatrix} f_h \\ f_u \end{pmatrix} = \lambda_f \begin{pmatrix} f_h \\ f_u \end{pmatrix} \\
eig(cov(data))$$



