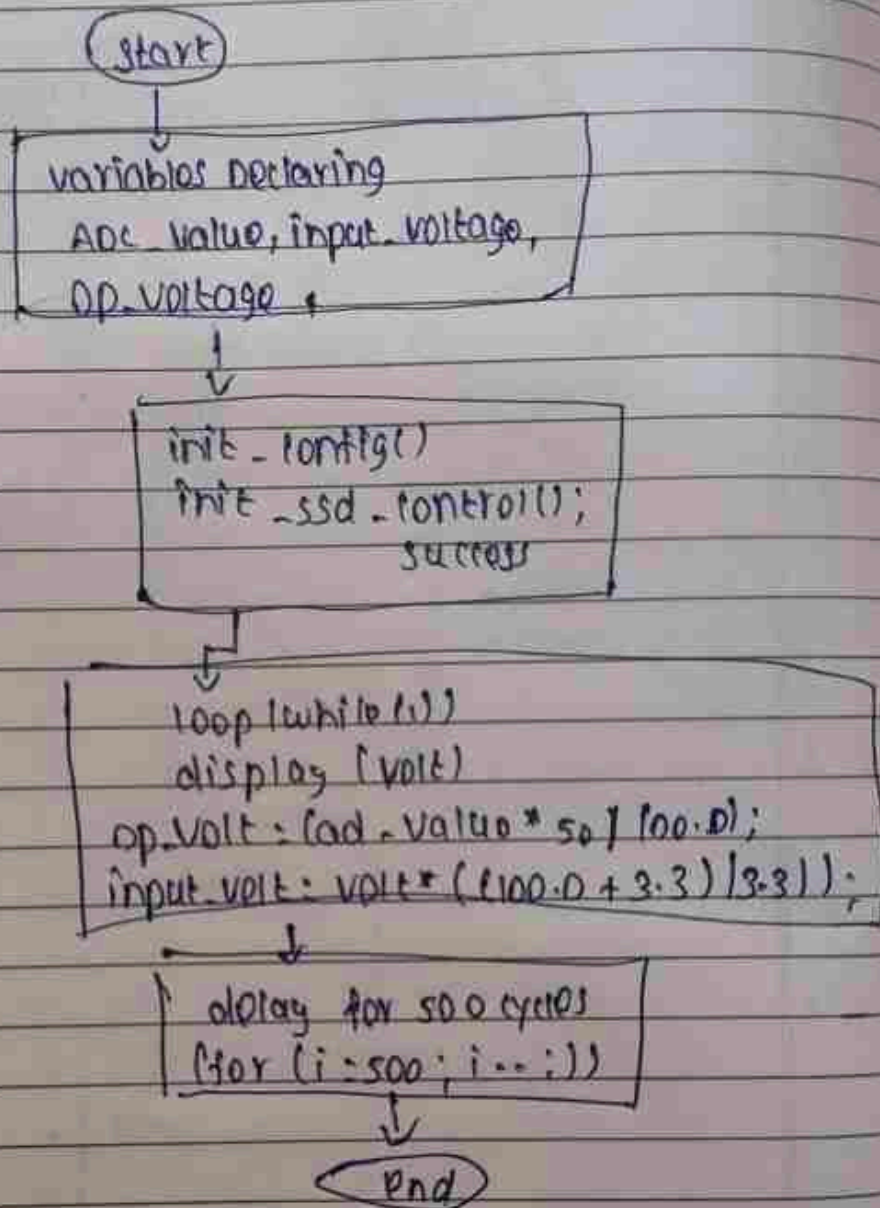


measure 0 to 100 DC using microcontroller



Algorithm:

Step 1: Header files including

Step 2: x86 compiler selecting.

Step 3: New file creation

Step 4: including required header files.

Step 5: initializing variables.

Step 6: calling init-config() in main

Step 7: ssd_control() inside init_config().

Step 8: infinite loop running

Step 9: display function calling.

Step 10: performing operation.

Step 11: Adding delay.