Heuristic Analysis

Artificial Intelligence Nanodegree | Project Planning

Documentation of Metrics

1.1 Metrics for Non-Heuristic Planning Solution Searches

| | breadth_first_search | | | depth_first_graph_sea rch | | | depth_limited_search | | | uniform_cost_search | | |
|---------------------|----------------------|-------|--------|------------------------------|--------|--------|----------------------|--------------|----|---------------------|--------|--------|
| air_cargo_* | p1 | p2 | р3 | p1 | p2 | р3 | p1 | p2 | рЗ | p1 | p2 | р3 |
| node_expansi ons | 43 | 3343 | 14663 | 12 | 1669 | 3664 | 101 | | | 55 | 4852 | 18235 |
| goal_tests | 56 | 4609 | 18098 | 13 | 1670 | 3665 | 271 | | | 57 | 4854 | 18237 |
| newnodes | 180 | 30509 | 128605 | 48 | 14863 | 29381 | 414 | > 10 mins | | 224 | 44030 | 158272 |
| Time_elapsed (s) | 0.148 | 46.53 | 275.07 | 0.041 | 30.792 | 58.775 | 0.375 | | | 0.181 | 62.505 | 279.08 |
| optimality | 6 | 9 | 12 | 12 | 1444 | 195 | 50 | | | 6 | 9 | 12 |

1.2 Metrics for A* Planning Searches with heuristics

| | A* with ignore_preconditions | | | A* with level-sum | | | |
|------------------|------------------------------|--------|--------|-------------------|--------|----------|--|
| air_cargo_* | p1 | p2 | р3 | p1 | p2 | р3 | |
| node_expansions | 41 | 1450 | 5040 | 11 | 86 | 389 | |
| goal_tests | 43 | 1452 | 5042 | 13 | 88 | 391 | |
| newnodes | 170 | 13303 | 44769 | 50 | 841 | 3567 | |
| Time_elapsed (s) | 0.153 | 18.535 | 77.865 | 1.0497 | 164.95 | 1245.107 | |
| optimality | 6 | 9 | 12 | 6 | 9 | 12 | |

Written Analysis

2.1 Optimal Plans

| air_cargo_* | р | 1 | р | 2 | р3 | | |
|---------------------|--|------------------------------|---|---|---|---|--|
| | Best | Worst | Best | Worst | Best | Worst | |
| node_expansion s | A* with level-sum | depth_limited_s earch | A* with level sum | Depth_limited_s earch / uniform_cost | A* with level sum | Depth_limited_s earch / uniform_cost | |
| goal_tests | A* with level-sum / depth_first_grap h_search | uniform_cost_se arch | A* with level sum | Depth_limited_s earch / uniform_cost | A* with level sum | Depth_limited_s earch / uniform_cost | |
| newnodes | depth_first_grap h_search | uniform_cost_se arch | A* with level sum | Depth_limited_s earch / uniform_cost | A* with level sum | Depth_limited_s earch / uniform_cost | |
| Time_elapsed | depth_first_grap h_search | A* with level_sum | A* with ignore_preconditions | Depth_limited_s earch / A* with level sum | A* with ignore_preconditions | Depth_limited_s earch / A* with level sum | |
| optimality | All except depth_first_grap h_search | depth_first_grap h_search | Depth_first_gra ph_search / A* with ignore_precondi tions | Depth_limited_s earch / A* with level sum | Depth_first_gra ph_search / A* with ignore_precondi tions | Depth_limited_s earch / A* with level sum | |
| Plan: | A* with ignore | _preconditions | A* with I | evel sum | A* with level sum | | |

Table. Best and worst by each statistic for each problem

By analyzing the results, we find that A* searches with heuristics give us significantly better results than non-heuristic search plans. We also notice that for Problem 1, the results of non-heuristic and heuristic searches are similar. However, as the complexity of the problem increases, both A* with ignore_preconditions heuristic and A* with level_sum heuristic, perform much better. It can also been seen from the table that depth_first_graph seems to perform well in terms of number of nodes expanded and time, however, it provides a non-optimal solution in the end.

2.2 Best Heuristic

Both A* searches gave significantly better results than the non-heuristic searches. However, for smaller problems, the A* searches took more time than a search such as breadth_first. We can also see that as we increase the complexity of the heuristic - like in the level_sum A* search, the time taken by the search increases. At the same time, this heuristic performed better and was much more efficient than its counterpart with the ignore_predconditiions heuristic. Hence, there can be no size fits all and choosing a search plan should be based on the complexity of the problem itself, the memory available as well as the time constraints.