

# CS 343 - Operating Systems

## Module-3F

### Deadlocks Avoidance, Detection & Recovery



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# Overview of Deadlock Management Section

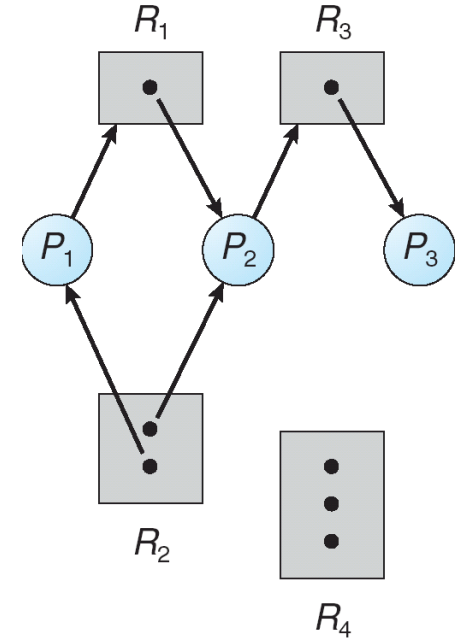
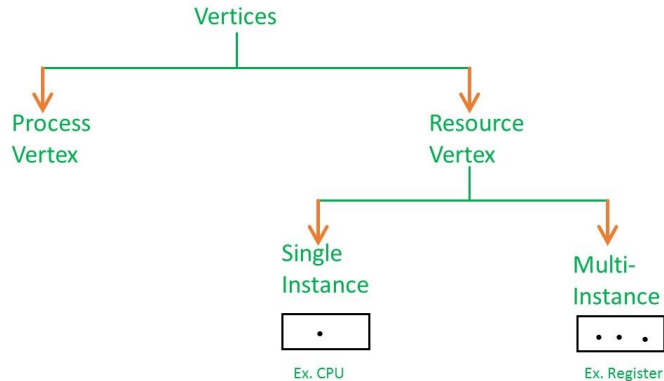
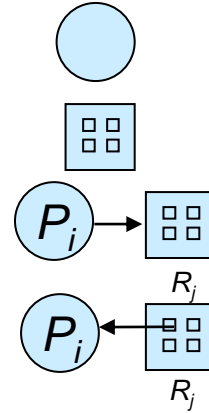
- ❖ System Model
- ❖ Deadlock Characterization
- ❖ Methods for Handling Deadlocks
- ❖ Deadlock Prevention
- ❖ Deadlock Avoidance
- ❖ Deadlock Detection
- ❖ Recovery from Deadlock

# Deadlock Characterization

- ❖ Deadlock can arise if the following four conditions hold simultaneously.
- ❖ **Mutual exclusion**
- ❖ **Hold and wait**
- ❖ **No preemption**
- ❖ **Circular wait**

# Resource-Allocation Graph

- ❖ Process
- ❖ Resource Type with 4 instances
- ❖  $P_i$  requests an instance of  $R_j$
- ❖  $P_i$  is holding an instance of  $R_j$



# Deadlock Avoidance

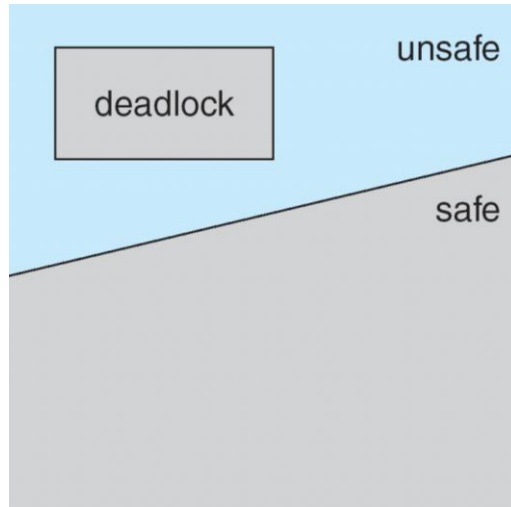
- ❖ Requires that the system has some additional ***a priori*** information available
- ❖ Simplest and most useful model requires that each process declare the ***maximum number*** of resources of each type that it may need
- ❖ The deadlock-avoidance algorithm dynamically examines the resource-allocation state to ensure that there can never be a circular-wait condition
- ❖ Resource-allocation *state* is defined by the number of available and allocated resources, and the maximum demands of the processes

# Safe State

- ❖ When a process requests an available resource, system must decide if immediate allocation leaves the system in a safe state
- ❖ System is in **safe state** if there exists a sequence  $\langle P_1, P_2, \dots, P_n \rangle$  of ALL the processes in the systems such that for each  $P_i$ , the resources that  $P_i$  can still request can be satisfied by currently available resources + resources held by all the  $P_j$ , with  $j < i$
- ❖ That is:
  - ❖ If  $P_i$  resource needs are not immediately available, then  $P_i$  can wait until all  $P_j$  have finished
  - ❖ When  $P_j$  is finished,  $P_i$  can obtain needed resources, execute, return allocated resources, and terminate
  - ❖ When  $P_i$  terminates,  $P_{i+1}$  can obtain its needed resources, and so on

# Safe State & Deadlock

- ❖ If a system is in safe state  $\Rightarrow$  no deadlocks
- ❖ If a system is in unsafe state  $\Rightarrow$  possibility of deadlock
- ❖ Avoidance  $\Rightarrow$  ensure that a system will never enter an unsafe state.



# Avoidance Algorithms

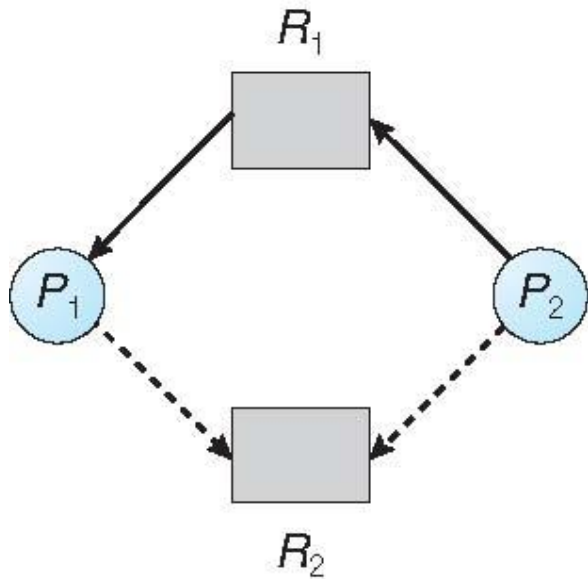
- ❖ Single instance of a resource type
  - ❖ Use a resource-allocation graph
- ❖ Multiple instances of a resource type
  - ❖ Use the banker's algorithm



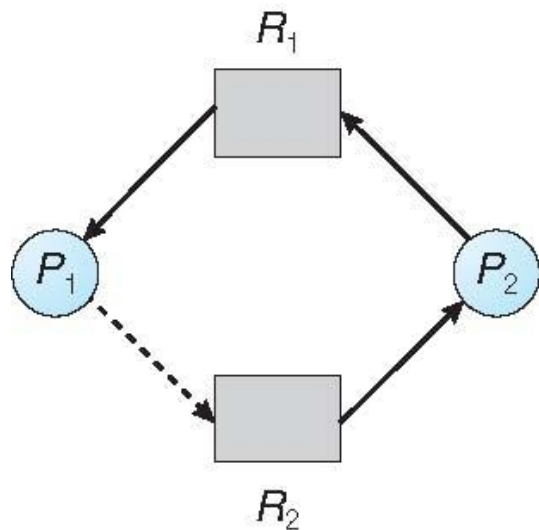
# Resource-Allocation Graph Scheme

- ❖ **Claim edge**  $P_i \rightarrow R_j$  indicated that process  $P_i$  may request resource  $R_j$
- ❖ Claim edge is represented by a dashed line
- ❖ Claim edge converts to request edge when a process requests a resource
- ❖ Request edge converted to an assignment edge when the resource is allocated to the process
- ❖ Resources must be claimed *a priori* in the system

# Resource-Allocation Graph & Unsafe State



Resource-Allocation Graph  
with Claim Edges



Unsafe State In  
Resource-Allocation Graph

# Resource-Allocation Graph Algorithm

- ❖ Suppose that process  $P_i$  requests a resource  $R_j$
- ❖ The request can be granted only if converting the request edge to an assignment edge does not result in the formation of a cycle in the resource allocation graph

# Banker's Algorithm

- ❖ Multiple instances
- ❖ Each process must apriori claim maximum use
- ❖ When a process requests a resource it may have to wait
- ❖ When a process gets all its resources it must return them in a finite amount of time

# Data Structures for the Banker's Algorithm

- ❖ Let  $n$  = number of processes, and  $m$  = number of resources type
- ❖ **Available:** Vector of length  $m$ . If  $available[j] = k$ , there are  $k$  instances of resource type  $R_j$  available
- ❖ **Max:**  $n \times m$  matrix. If  $Max[i,j] = k$ , then process  $P_i$  may request at most  $k$  instances of resource type  $R_j$
- ❖ **Allocation:**  $n \times m$  matrix. If  $Allocation[i,j] = k$  then  $P_i$  is currently allocated  $k$  instances of  $R_j$
- ❖ **Need:**  $n \times m$  matrix. If  $Need[i,j] = k$ , then  $P_i$  may need  $k$  more instances of  $R_j$  to complete its task
  - ❖  $Need[i,j] = Max[i,j] - Allocation[i,j]$

# Safety Algorithm

1. Let **Work** and **Finish** be vectors of length  $m$  and  $n$ , respectively.

Initialize: **Work = Available**

**Finish [i] = false for  $i = 0, 1, \dots, n-1$**

2. Find an  $i$  such that both:

(a) **Finish [i] = false**

(b)  **$\text{Need}_i \leq \text{Work}$**

If no such  $i$  exists, go to step 4

3.  **$\text{Work} = \text{Work} + \text{Allocation}_i$**   
**Finish[i] = true**  
go to step 2

4. If **Finish [i] == true** for all  $i$ , then the system is in a safe state

# Resource-Request Algorithm for Process $P_i$

- ❖ **Request<sub>i</sub>** = request vector for process  $P_i$ .
- ❖ If **Request<sub>i</sub> [j] = k** then process  $P_i$  wants **k** instances of resource type  $R_j$ 
  1. If **Request<sub>i</sub> ≤ Need<sub>i</sub>** go to step 2. Otherwise, raise error condition, since process has exceeded its maximum claim
  2. If **Request<sub>i</sub> ≤ Available**, go to step 3. Otherwise  $P_i$  must wait, since resources are not available
  3. Pretend to allocate requested resources to  $P_i$  by modifying the states
$$\begin{aligned}\mathbf{Available} &= \mathbf{Available} - \mathbf{Request}_i; \\ \mathbf{Allocation}_i &= \mathbf{Allocation}_i + \mathbf{Request}_i; \\ \mathbf{Need}_i &= \mathbf{Need}_i - \mathbf{Request}_i;\end{aligned}$$
- ❖ If safe  $\Rightarrow$  the resources are allocated to  $P_i$
- ❖ If unsafe  $\Rightarrow P_i$  must wait, and the old resource-allocation state is restored

# Example of Banker's Algorithm

- ❖ 5 [  $P_0$  -  $P_4$  ] & 3 resource types: A (10), B (5), and C (7)
- ❖ Snapshot at time  $T_0$ :

<u>Allocation</u>	<u>Max</u>	<u>Available</u>
A B C	A B C	A B C
$P_0$ 0 1 0	7 5 3	3 3 2
$P_1$ 2 0 0	3 2 2	
$P_2$ 3 0 2	9 0 2	
$P_3$ 2 1 1	2 2 2	
$P_4$ 0 0 2	4 3 3	



## Example of Banker's Algorithm contd...

- ❖ The content of the matrix **Need** is defined to be **Max – Allocation**

Need

A B C

P<sub>0</sub> 7 4 3

P<sub>1</sub> 1 2 2

P<sub>2</sub> 6 0 0

P<sub>3</sub> 0 1 1

P<sub>4</sub> 4 3 1

The system is in a safe state since the sequence  $\langle P_1, P_3, P_4, P_2, P_0 \rangle$  satisfies safety criteria

## Example: $P_1$ Request (1,0,2)

- ❖ Check that Request  $\leq$  Available (that is,  $(1,0,2) \leq (3,3,2) \Rightarrow$  true

	<u>Allocation</u>	<u>Need</u>	<u>Available</u>
	A B C	A B C	A B C
$P_0$	0 1 0	7 4 3	2 3 0
$P_1$	3 0 2	0 2 0	
$P_2$	3 0 2	6 0 0	
$P_3$	2 1 1	0 1 1	
$P_4$	0 0 2	4 3 1	

- ❖ Executing safety algorithm shows that sequence  $\langle P_1, P_3, P_4, P_0, P_2 \rangle$  satisfies safety requirement

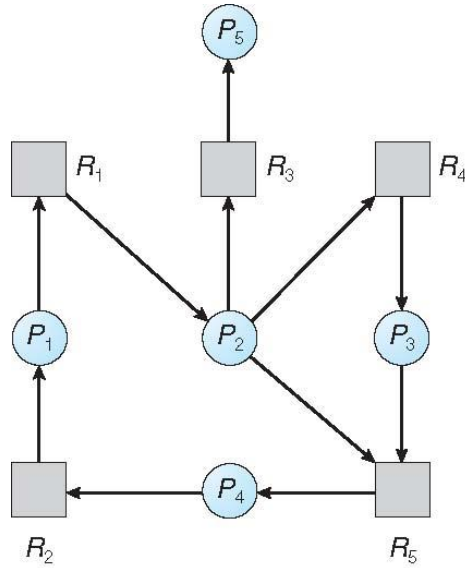
# Deadlock Detection

- ❖ Allow system to enter deadlock state
- ❖ Detection algorithm
- ❖ Recovery scheme

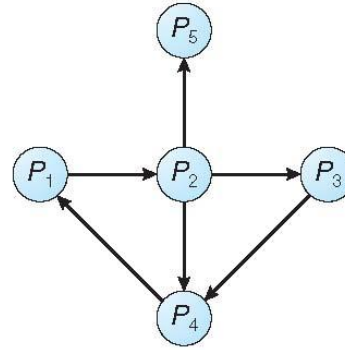
# Detection in Single Instance Resource Types

- ❖ Maintain **wait-for** graph
  - ❖ Nodes are processes
  - ❖  $P_i \rightarrow P_j$  if  $P_i$  is waiting for  $P_j$
- ❖ Periodically invoke an algorithm that searches for a cycle in the graph. If there is a cycle, there exists a deadlock
- ❖ An algorithm to detect a cycle in a graph requires an order of  $n^2$  operations, where  $n$  is the number of vertices in the graph

# Resource-Allocation Graph and Wait-for Graph



(a)



(b)

Resource-Allocation Graph

Corresponding wait-for graph

# Several Instances of a Resource Type

- ❖ **Available:** A vector of length  $m$  indicates the number of available resources of each type
- ❖ **Allocation:** An  $n \times m$  matrix defines the number of resources of each type currently allocated to each process
- ❖ **Request:** An  $n \times m$  matrix indicates the current request of each process. If **Request**  $[i][j] = k$ , then process  $P_i$  is requesting  $k$  more instances of resource type  $R_j$ .

# Detection Algorithm

1. Let **Work** and **Finish** be vectors of length **m** and **n**, respectively Initialize:
  - (a) **Work = Available**
  - (b) For **i = 1, 2, ..., n**, if **Allocation<sub>i</sub> ≠ 0**, then **Finish[i] = false**; otherwise, **Finish[i] = true**
2. Find an index **i** such that both:
  - (a) **Finish[i] == false**
  - (b) **Request<sub>i</sub> ≤ Work**

If no such **i** exists, go to step 4

## Detection Algorithm contd..

3. **Work = Work + Allocation<sub>i</sub>**  
**Finish[i] = true**  
go to step 2
4. If **Finish[i] == false**, for some  $i$ ,  $1 \leq i \leq n$ , then the system is in deadlock state. Moreover, if **Finish[i] == false**, then **P<sub>i</sub>** is deadlocked

Algorithm requires an order of  $O(m \times n^2)$  operations to detect whether the system is in deadlocked state



# Example of Detection Algorithm

- ❖ Five processes  $P_0$  through  $P_4$ ; three resource types A (7 instances), B (2 instances), and C (6 instances)
- ❖ Snapshot at time  $T_0$ :

	<u>Allocation</u>	<u>Request</u>	<u>Available</u>
	A B C	A B C	A B C
$P_0$	0 1 0	0 0 0	0 0 0
$P_1$	2 0 0	2 0 2	
$P_2$	3 0 3	0 0 0	
$P_3$	2 1 1	1 0 0	
$P_4$	0 0 2	0 0 2	

# Example of Detection Algorithm contd..

- ❖  $P_2$  requests an additional instance of type **C**

Request

A B C

$P_0$  0 0 0

$P_1$  2 0 2

$P_2$  0 0 1

$P_3$  1 0 0

$P_4$  0 0 2

- ❖ State of system? :
- ❖ Can reclaim resources held by process  $P_0$ , but insufficient resources to fulfill other processes; requests
  - Deadlock exists, consisting of processes  $P_1$ ,  $P_2$ ,  $P_3$ , and  $P_4$

# Detection-Algorithm Usage

- ❖ When, and how often, to invoke depends on:
  - ❖ How often a deadlock is likely to occur?
  - ❖ How many processes will need to be rolled back?
    - ❖ one for each disjoint cycle
- ❖ If detection algorithm is invoked arbitrarily, there may be many cycles in the resource graph and so we would not be able to tell which of the many deadlocked processes caused the deadlock.

# Recovery from Deadlock: Process Termination

- ❖ Abort all deadlocked processes
- ❖ Abort one process at a time until the deadlock cycle is eliminated
- ❖ In which order should we choose to abort?
  1. Priority of the process
  2. How long process has computed, and how much longer to completion?
  3. Resources the process has used
  4. Resources process needs to complete
  5. How many processes will need to be terminated?
  6. Is process interactive or batch?

# Recovery from Deadlock: Resource Preemption

- ❖ **Selecting a victim** – minimize cost
- ❖ **Rollback** – return to some safe state, restart process for that state
- ❖ **Starvation** – same process may always be picked as victim, include number of rollback in cost factor



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