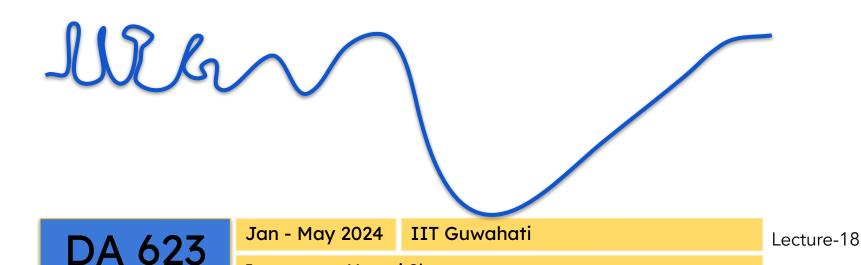
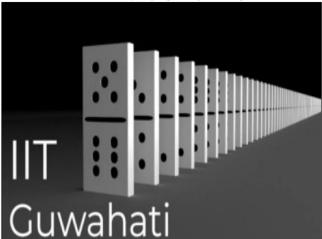
Computing with Signals



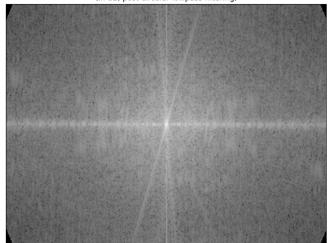
Instructors: Neeraj Sharma

Using Convolution to Design Linear Image Filters

Lowpass filtered image (the cutoff frequency is gradually increasing)



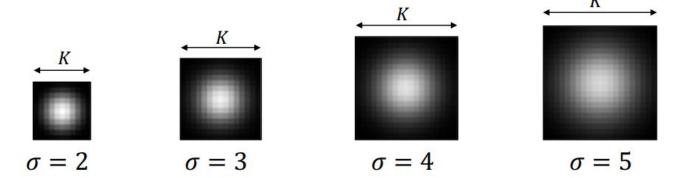
2-D Fourier Spectrum
(in dB. post circular lowpass filtering)



Gaussian Kernel

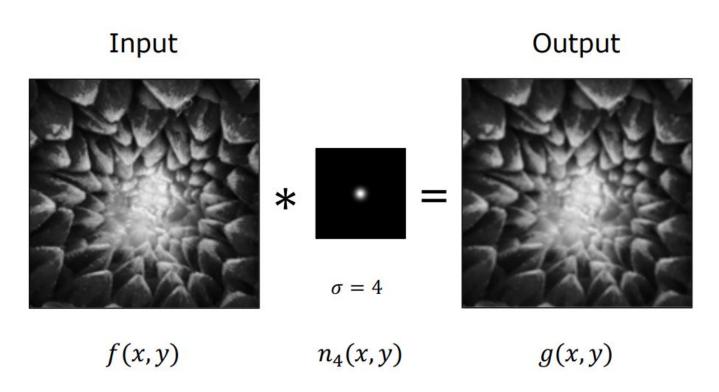
$$n_{\sigma}[i,j] = \frac{1}{2\pi\sigma^2} e^{-\frac{1}{2}\left(\frac{i^2+j^2}{\sigma^2}\right)}$$
 [1]

 σ^2 : Variance



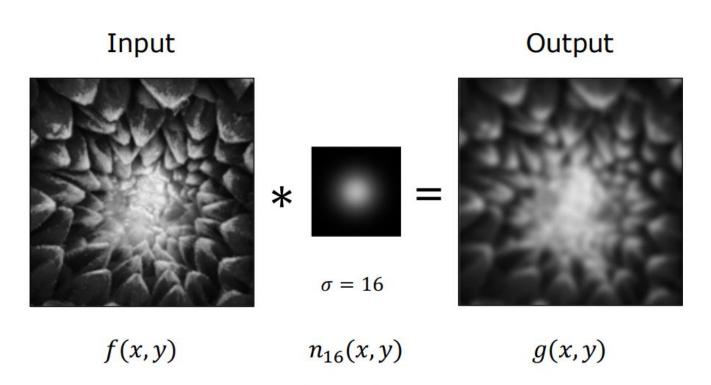
Rule of thumb: Set kernel size $K \approx 2\pi\sigma$

Gaussian Smoothing



Larger the kernel (or σ), more the blurring Reference:

Gaussian Smoothing



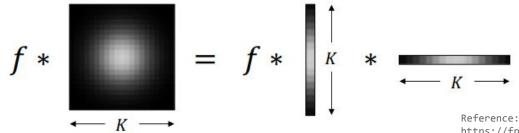
Larger the kernel (or σ), more the blurring

Gaussian Smoothing is Separable

$$g[i,j] = \frac{1}{2\pi\sigma^2} \sum_{m=1}^K \sum_{n=1}^K e^{-\frac{1}{2} \left(\frac{m^2 + n^2}{\sigma^2}\right)} f[i - m, j - n]$$

$$g[i,j] = \frac{1}{2\pi\sigma^2} \sum_{m=1}^{K} e^{-\frac{1}{2}\left(\frac{m^2}{\sigma^2}\right)} \cdot \sum_{m=1}^{K} e^{-\frac{1}{2}\left(\frac{n^2}{\sigma^2}\right)} f[i-m,j-n]$$

Using One 2D Gaussian Filter ≡ Using Two 1D Gaussian Filters



https://fpcv.cs.columbia.edu/Monographs

Gaussian Smoothing is Separable

Using One 2D Gaussian Filter ≡ Using Two 1D Gaussian Filters

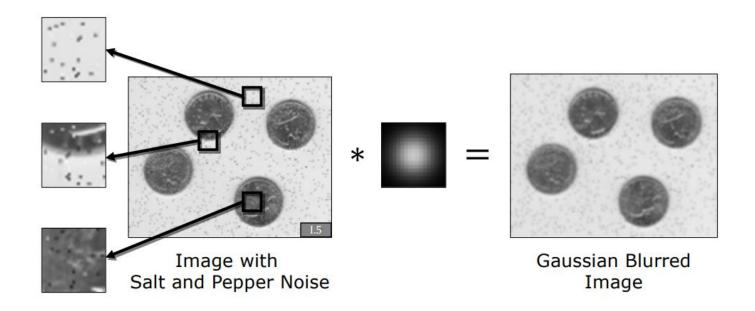
Which one is faster? Why?

$$K^2$$
 Multiplications $2K$ Multiplications K^2-1 Additions $2(K-1)$ Additions

https://fpcv.cs.columbia.edu/Monographs

Non-Linear Image Filters

Smoothing to Remove Image Noise



Problem with Smoothing:

- Does not remove outliers (Noise)
- Smooths edges (Blur)

Median Filtering

- 1. Sort the K^2 values in window centered at the pixel
- 2. Assign the Middle Value (Median) to pixel



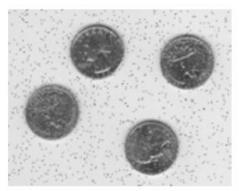


Image with Salt and Pepper Noise



Median Filtered Image (K = 3)

Non-linear Operation
(Cannot be implemented using convolution)

Median Filtering

Not Effective when Image Noise is not a Simple Salt and Pepper Noise.

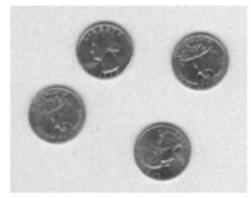
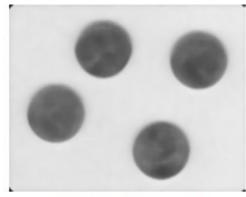


Image with Noise



Median Filtered Image (K = 11)

Larger K causes blurring of image detail





Template

How do we locate the template in the image? Minimize:

$$E[i,j] = \sum_{m} \sum_{n} (f[m,n] - t[m-i,n-j])^{2}$$





Template

How do we locate the template in the image? Minimize:

$$E[i,j] = \sum_{m} \sum_{n} (f[m,n] - t[m-i,n-j])^{2}$$

$$E[i,j] = \sum_{m} \sum_{n} (f^{2}[m,n] + t^{2}[m-i,n-j] - \underbrace{\frac{1}{2f[m,n]t[m-i,n-j]}}_{\text{Maximize}}$$





Template

How do we locate the template in the image? Maximize:

$$R_{tf}[i,j] = \sum_{m} \sum_{n} f[m,n]t[m-i,n-j] = t \otimes f$$

(Cross-Correlation)

Convolution vs. Correlation

Convolution:

$$g[i,j] = \sum_{m} \sum_{n} f[m,n] \underline{t[i-m,j-n]} = t * f$$

Correlation:

$$R_{tf}[i,j] = \sum_{m} \sum_{n} f[m,n] \underline{t[m-i,n-j]} = t \otimes f$$

No Flipping in Correlation

Problem with Cross-Correlation

$$R_{tf}[i,j] = \sum \sum f[m,n]t[m-i,n-j] = t \otimes f$$

$$f: \coprod_{A} \xrightarrow{B} C$$

$$R_{tf}(C) > R_{tf}(B) > R_{tf}(A)$$

We need $R_{tf}(A)$ to be the maximum!

Normalized Cross-Correlation

Account for energy differences

$$N_{tf}[i,j] = \frac{\sum_{m} \sum_{n} f[m,n] t[m-i,n-j]}{\sqrt{\sum_{m} \sum_{n} f^{2}[m,n]} \sqrt{\sum_{m} \sum_{n} t^{2}[m-i,n-j]}}$$

$$f: \begin{array}{c|c} & & & \\ \hline \\ \hline \\ A & B & C \\ \hline \end{array}$$

$$N_{tf}(A) > N_{tf}(B) > N_{tf}(C)$$

Normalized Cross-Correlation

Account for energy differences

$$N_{tf}[i,j] = \frac{\sum_m \sum_n f[m,n] t[m-i,n-j]}{\sqrt{\sum_m \sum_n f^2[m,n]} \sqrt{\sum_m \sum_n t^2[m-i,n-j]}}$$







