```
import cv2
import numpy as np
import os
#callback of trackbar
def nothing(x):
#reading the input image
filename = "/home/akshay/Downloads/CV/ps-3-g/ps3-images/gear.png"
input image = cv2.imread("/home/akshay/Downloads/CV/ps-3-g/ps3-images/gear.png")
cv2.namedWindow('image', cv2.WINDOW KEEPRATIO)
# create trackbars for color change
cv2.createTrackbar('aperture','image',1,2,nothing)
#0-False,1-True for L2norm
cv2.createTrackbar('L2norm','image',0,1,nothing)
cv2.createTrackbar('threshold1','image',0,255,nothing)
cv2.createTrackbar('threshold2','image',0,255,nothing)
#aperture size limited in (3,5,7) in Canny function
#so the result from trackbar aperture is modified as
#2*aperture+3
threshold1,threshold,L2,aperture = 0,0,0,0
#Infinite loop activated whenever a trackbar value is changed
while(1):
   # get current positions of four trackbars
    threshold1 = cv2.getTrackbarPos('threshold1','image')
    threshold2 = cv2.getTrackbarPos('threshold2','image')
    aperture = cv2.getTrackbarPos('aperture','image')
    L2 = bool(cv2.getTrackbarPos('L2norm', 'image'))
    #applying cv2 canny
    new image = cv2.Canny(input image,threshold1,threshold2,apertureSize=2*aperture+3,L2gradient=L2)
    new image = np.uint8(np.where(new image>127,0,255))
    cv2.imshow("image", new image)
    k = cv2.waitKey(1) \& 0xFF
   if k == 27:
       break
cv2.destroyAllWindows()
#saving the image
first name = os.path.basename(filename)
first name = first name.split('.',1)[0]
write filename = first name + "-canny.png"
```

```
print(threshold1,threshold2,aperture,L2)
if(cv2.imwrite(write_filename,new_image)):
    print("Successfully saved")
else:
    print("Save Unsuccessfull")
```